

MAE 4344- Senior Design Capstone

Group 2b- Dolphin Blowhole Simulator

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Introduction / Background / Problem Statement:

The use of drones have been proposed for the collection of biological samples in marine mammals, specifically marine biologists need to obtain samples of dolphin "blow" from their blowhole discharge in the wild. These non-invasive techniques are needed to assess biological health such as reproductive and adrenal functions. While the techniques have been demonstrated on whales, dolphins have proven more difficult to obtain samples from due to their speed and apprehensiveness to typical quadcopter drone. Thus, quiet fixed wing vehicles are proposed. In order to assess the feasibility to capture a sample, a blowhole simulator is needed that mimics the intermittent outflow characteristics of the blowhole jet, including flow rate, jet velocity, height, and spread.

Detailed list of project requirements / deliverables:

From the problem statement a list of deliverables and project goals were created for completion by the end of the semester. The first deliverable was providing a working simulator. This simulator would need to simulate a dolphins blow as closely as possible according to the following empirical measurements: flow rate, exit velocity, height of blow, and width of blow. The simulator needed to have lateral movement capabilities that could mimic those of a dolphin in the wild. Finally, engineering design calculations for the simulator design and results from the simulator testing were to be delivered with the final product.



Plan of attack / Approach to Solving the Problem - Summary:

Before the first design iteration could be made for the deliverables in the problem statement, initial research needed to be conducted in order to find out what empirical data we would need to meet. Initial research was done by each team member in order to find the blow height, width, flow rate, and exit velocity. This data proved to be difficult to find and professional corroboration was sought out to confirm the data we had found. Researchers and Marine Biologist from Purdue and UC Davis were contacted in order to confirm the empirical data we had found on the blow characteristics as well as to get extra background information on the dolphin blow process in general. Specific measurements on blow hole diameters and shape were collected by marine biologist in the field from Hawaii, Bermuda, and Oahu. Once this initial research was done, the parameters for our first design were made and the first iteration for the blow hole simulator was made. This first iteration proved to be undesirable for its high pressure system and limited shot capabilities. The next step in the plan of attack was for each team member to individually research a new design that would implement a low pressure system with multi-shot capabilities. This design matrix then underwent a pro/con evaluation for review by each team member and our funders. From this design matrix, our final design was chosen. This final design was to be a pneumatic piston system that would push air through an open pipe with an exit “blowhole” at the end of it. A water system would be integrated mechatronically with the pneumatic system in order to time the water delivery with the air delivery, thus mimicking a “blow” by a dolphin. After the design was finalized on paper, a parts list was assembled and parts bought. Then the simulator was assembled and testing of the simulator was done by the team.



Detailed Description of Work / Key Decisions made - with reasons:

Initial research showed that the design needed to be capable of high exit velocity and high flow rate achieved over a small time interval. This flow and speed would be accompanied by a pressure drop that would also need to be constant as the blow was “exhaled”. The team compared five different designs in order to determine which design would best meet the desired criteria.

Design Option #1 & #2

The first two designs were similar to what is shown to the right. This design utilized high pressure in order to achieve the large flow rates and exit velocities that the dolphin exhibits in its “explosive” breathing. The usage of high pressure threaded pipe created an easy, compact pressure vessel for holding the equivalent volume of the dolphin exhale.

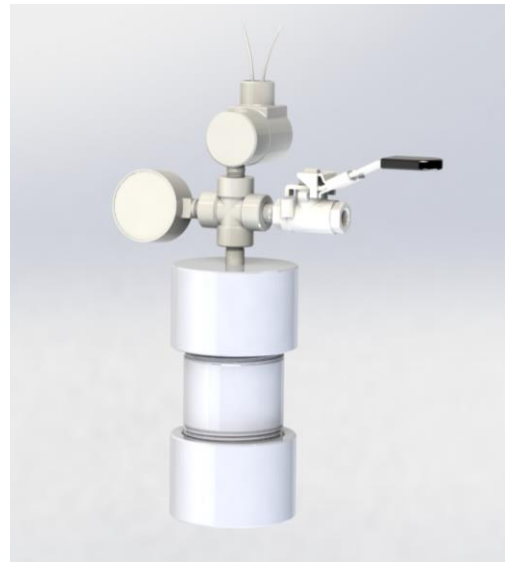


Figure 1

Attached to the top of the larger body pressure vessel is a small connecting pipe that would need to be drilled into and welded onto the cap of one side of the pressure vessel. Proceeding from this connecting piece would be a cross fitting that allowed for a fill valve, a pressure gauge, and a solenoid valve at the top for release of the high pressure air inside. The downside of this design, however, is the use of extremely high pressures, which in turn would force the air out of the solenoid valve at a rate much higher than desired. Consequently, this would require more piping or attachments downstream from the solenoid in order to slow the air back down before exiting. After



further consideration and meeting with our sponsors, the high pressure system shown above was abandoned. Next, each team member pursued a different, unique design on their own in order to come back together with a design matrix, and hopefully arrive at the best available option for our project. The proposed designs are as follows:

Design Option #3

The third design option involved using a high volume low pressure fan to match the flow rate and exit velocity required to model a dolphin blowhole. This option proved in theory to be the cheapest, and most efficient option due to the fans low power requirements, compact size, and

miniscule weight. However, finding a fan that is small enough, and efficient enough to match the required flow rates of a dolphin blowhole proved difficult. Two fan options were pursued in this design.

The first, was a low power, lightweight, equipment cooling fan. Although this fan

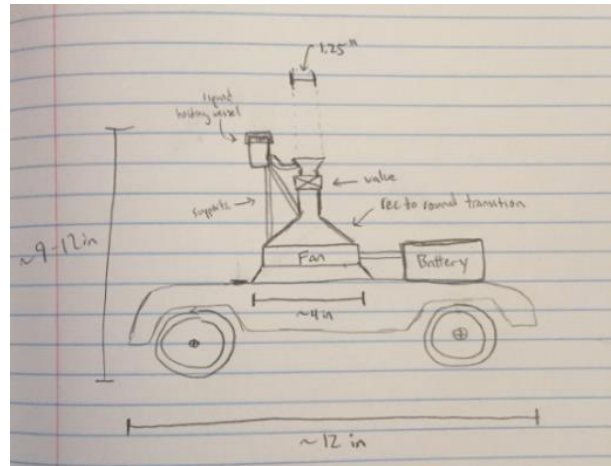



Figure 2

would allow for the correct amount of flow unchoked, whenever it is choked to the appropriate diameter, the fan will not meet the required flow rate. Constancy of flow cannot be assumed for an open atmospheric fan. The pressure calculations needed to approach a solution to this problem could not be done either, do to most manufactures not listing the pressure drop across their fans. This is most likely due to it being a negligible number. The second option pursued was a blower fan, although this proved to require too much power and weigh more than desired.





| 12V DC Blower, 105 CFM @ 0 in. of Water | |
|---|---------------------------------|
| Inlet Shape | Round |
| Wheel Diameter | 3" |
| Overall | |
| Height | 5 1/2" |
| Width | 5" |
| Depth | 6 3/4" |
| Power Source | Hardwire |
| Voltage | 12V DC |
| Current | 4.3A |
| Motor Enclosure Type | Totally Enclosed |
| Min. Temperature | Not Rated |
| Maximum Temperature | 130° F |
| Housing Material | Polypropylene Plastic |
| Wheel Material | Acetal Plastic |
| Mounting Fasteners Included | No |
| Mounting Hole Diameter | 1/4" |
| Includes | Multidirection Mounting Bracket |

Figure 3.a



| Low-Voltage Equipment-Cooling Fan | |
|---|------------------------------|
| 12V DC with Wire Leads, 3.62" Square x 1.26" Deep Overall, 50 CFM | |
| Shape | Square |
| Overall | |
| Height | 3.62" (92 mm) |
| Width | 3.62" (92 mm) |
| Depth | 1.26" (32 mm) |
| Airflow | 50 cfm |
| Volume | 43 dB |
| Voltage | 12V DC |
| Current | 0.23 A |
| Power Source | Electric |
| Electrical Connection | Wire Leads |
| Frame Material | Plastic |
| Blade Material | Plastic |
| Thermostat Included | No |
| Mounting Fasteners Included | No |
| Mounting Hole Diameter | 0.17" (4.3 mm) |
| Specifications Met | CSA Certified, UL Recognized |

Figure 3.b

Calculations:

This first table shows the calculations for finding the exit hole diameter given a flow rate and a desired velocity. The flow rate of 24L/s has been shown to be the peak output of a bottlenose dolphin. This kind of output velocity, even with half of the flow, is out of the scope of a small HVLP fan's capabilities.

| Flow rate (L/s) | Flow rate(in ³ /s) | Time interval | Exhale flow equivalent (in ³ /s) |
|------------------------|-------------------------------|--------------------------------|---|
| 24 | 1464.569858 | 0.15 | 219.6854787 |
| area of blowhole | exit speed (in/s) | exit speed(ft/s) | |
| 0.785398163 | 1864.74826 | 155.3956883 | |
| Required exit velocity | Required Flow Rate | Area Needed (in ²) | Blow Hole Diameter (in.) |
| 69.06475035 | 1464.569858 | 21.20575041 | 5.196152423 |
| 100 | | 14.64569858 | 4.318273103 |

Figure 4

The second table, below, is the ideal exit velocity calculations for the blower and fan found on McMaster Carr's website. However, choking the flow of a fan, unless in a system of constant flow rate, does not increase its velocity to the desired output of the blowhole simulator. The blower fan, although capable of the output desired, will require too much power, as shown in the picture of its specs above in figure 3.



*Calculations on pressure were assumed unnecessary due to already existing issues with velocity & flow.

| From McMaster-Carr - 12 v DC blower | | | | | |
|--|--------------------------|---------------------|------------------------------|----------------------|----------------------------|
| Flow (CFM) | Flow(in ³ /s) | exit diameter (in) | exit area (in ²) | Exit velocity (in/s) | Ideal Exit velocity (ft/s) |
| 105 | 3024 | 3 | 7.068583471 | 427.808487 | 35.65070725 |
| Adding a choke to reduce the cross sectional area | | | | | |
| Flow (CFM) | Flow(in ³ /s) | exit diameter (in) | exit area (in ²) | Exit velocity (in/s) | Ideal Exit velocity (ft/s) |
| 105 | 3024 | 2 | 3.141592654 | 962.5690958 | 80.21409132 |
| | | | | | |
| From McMaster-Carr - equipment cooling fans (square) | | | | | |
| Flow (CFM) | Flow(in ³ /s) | equiv diameter (in) | exit area (in ²) | Exit velocity (in/s) | Ideal Exit velocity (ft/s) |
| 50 | 1440 | 3.96 | 7.068583471 | 203.7183272 | 16.97652726 |
| Adding a choke to reduce the cross sectional area | | | | | |
| Flow (CFM) | Flow(in ³ /s) | equiv diameter (in) | exit area (in ²) | Exit velocity (in/s) | Ideal Exit velocity (ft/s) |
| 50 | 1440 | 1.25 | 1.22718463 | 1173.417564 | 97.78479704 |

Figure 4



Design Option #4

$$p_2 + \rho \frac{V_2^2}{2} = p_1 + \rho \frac{V_1^2}{2}$$

Design Characteristics

| | |
|---|-------------|
| Starting Flow (L/s) | 24 |
| 1L = in ³ | 61.0237 |
| 1.5in Diameter (Area in ²) | 1.767145868 |
| Air Velocity (in/s) | 828.7764054 |
| Air Velocity (ft/s) | 69.06470045 |
| Tank Height(in) | 5 |
| Tank Size (in ³) | 8.835729338 |
| density of air (slugs/ft ³) | 0.00238 |
| (lbs/ft ³) | 0.0765 |
| (lbs/in ³) | 4.42708E-05 |
| atm (psia) | 14.7 |
| Assuming negligible temperature change: | |
| mass flow rate (lbs/s): | 0.064837681 |
| $\dot{m} = \rho \cdot V \cdot A$ | |
| (in ³ /s) | 0.847551389 |
| time for full discharge(s) | 0.095923195 |

Pressure Tank Calculations:

Pressure in Tank (psia):

29.904161

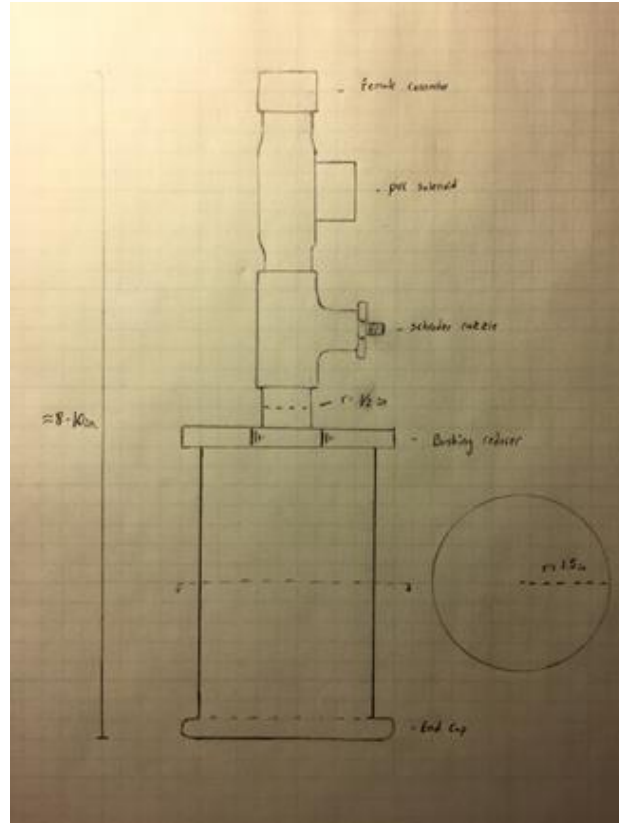


Figure 5

Figure7

The fourth design, most similar to our original design, involved the use of high pressure air in order to achieve the flow rate necessary to match that of a dolphins. There is one distinct difference in this design in comparison to our original, this is the characteristic of the flow that we show priority. If our original design we prioritized the volume of the dolphin and worked to be able to expel the full volume of a dolphin's lungs in a certain time, while in this design the prioritized characteristic is the velocity of the flow and flow rate itself.

Given the max flow rate of the dolphin blowhole exit, and given the area of the orifice, you can back calculate to find that the pressure needed to achieve the necessary max



flow is only 30 psi, drastically lower than our original design. Due to this pressure difference we are able to downgrade on our materials, using PVC for that majority of our pressure vessel, connectors, and even valves. This design would have three individually controlled discharges that would simulate the “blow” of the dolphin. Each of these pressure vessels could be charged individually in order to have full control over the pressures, and in turn velocities and spread. This design is very simple and very easy to modify if there is a need to remodel the “blow” in a way we didn't originally anticipate. In addition, low pressures ensure that the design is very flexible and can be charged quickly with something as simple as a bike pump. This design excels in portability and flexibility. One downfall of this design would be the lack of continual usage. This design would only be able to discharge as many times as you have pressure vessels in the system before returning to the user to recharge the tanks. This will limit the time you would be able to run your trials consistently. However because of the low pressure and low volumes, the recharge time would be much shorter when compared to recharging a large tank for many trials.

One of the questions that has plagued this design is the idea of a transient pressure drop on the outside of the orifice during the “blow”. This would imply that the flow through the orifice would not be consistent throughout the discharge time. Because of a pressure being released from a vessel, the pressure drop would be higher upon initial release of pressure than any other time during discharge. However, while the pressure drop across the orifice of our designed pressure vessel might not be constant, it achieves the time, velocity and flow rate of our estimated dolphin blow. In addition, there is no empirical data signifying that the pressure drop across the exit flow of a dolphin



blowhole is static. It is quite possible that it would be subject to change throughout the discharge of its breath, similar to

our proposed design.

Due to the decreased strength of

materials our design is much

lighter weight and much more

cost efficient. The total cost of

our design is estimated to cost less than \$500 and would be less than 10lbs. Again the

simplicity, flexibility, portability, cost effectiveness, and decrease in weight are all

strengths of this design and should be taken into consideration.

Further Calculations:

Using the ideal gas law we can estimate the volume of air that we are compressing into

our pressure vessel given the pressure vessel dimensions and the desired pressure

within the pressure vessel.

| | |
|-----------|--|
| \$ 2.41 | Thick-Wall PVC Pipe Nipple for Water, Threaded on Both Ends, 1-1/2 NPT, 4" Long |
| \$ 5.08 | Thick-Wall PVC Pipe Fitting for Water, Bushing Reducing Adapter, 1-1/2 x 1-1/2 NPT |
| \$ 6.95 | Plastic Water Solenoid Valve - 12V - 1/2" Nominal |
| \$ 3.76 | Thick-Wall PVC Pipe Fitting for Water, Tee Connector, 1-1/2 NPT Female |
| \$ 4.90 | Thick-Wall PVC Pipe Fitting for Water, Cap, 1-1/2 NPT Female |
| \$ 50.00 | Battery 12V/DC |
| \$ 200.00 | RC Car |

Figure 8

| | | | |
|---------------------------|----------|--------------------------------------|----------|
| Pressure Vessel: | | Atmospheric Values: | |
| height (in) | 5 | volume equivalent (in ³) | 32.05707 |
| radius (in) | 1 | pressure (psi) | 14.7 |
| volume (in ³) | 15.70796 | | |
| pressure (psi) | 30 | | |

Figure 9



Design Option #5

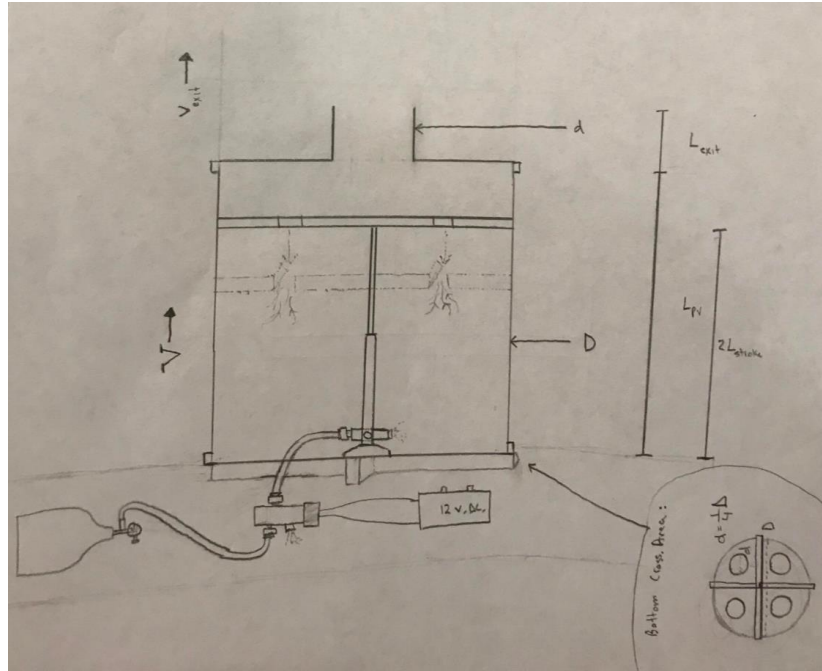


Figure 10

The fifth design option involves a mechanical system using a linear piston powered by a pneumatic cylinder. This design idea has the ability to perform multiple shots in one run (20+) and was preferred by our sponsors due to its very simple and easy concept and ability to be modified and model different magnitudes of excretion. This piston design allows complete control over all speeds, pressures, and in turn velocities and spread. This design also allows for the exit velocity and pressure drop to be constant for the duration of the shot which could not be achieved with the other design concepts.

Most of the work done for this design was in finding how to power the piston. The team initially thought to use an electrically powered linear actuator but after calculations, we could not find any linear actuators that met the appropriate stroke speed need to mimic a dolphin's exit velocity. The team next looked into a spring



powered piston but this approach needed many hand fabricated pieces to shoot the piston and pull it back into place. Our sponsors ideally desired a continuous shot system that would require no physical interaction to “recharge” the shot. In order to achieve this, the design would also entail having a linear actuator to remotely pull the piston into the starting position. The third and final design possibility was powering the piston with a single action pneumatic cylinder. This cylinder uses pressurized air to shoot the piston and an internal spring to pull it back in place. This is a little heavier and more expensive than the other options, however it is able to achieve more design characteristics that we found to be important in our blowhole design.

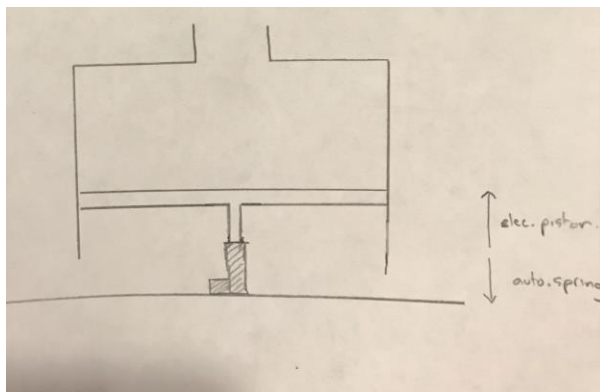


Figure 11

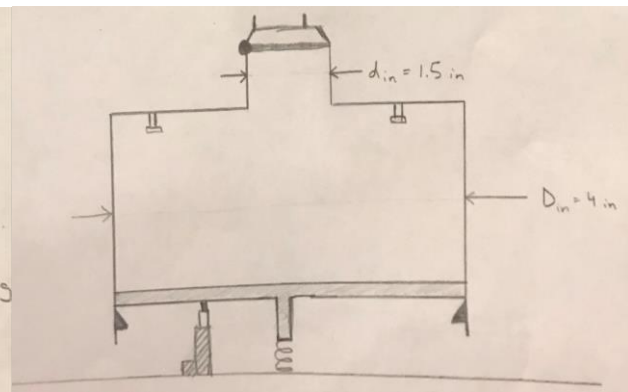


Figure 12

The table below shows calculations used to iteratively figure out what piston dimensions, pneumatic cylinder size, and pressure requirements were needed in our design to most closely match the exit velocity of a dolphins blow while remaining in a realistic flow rate range. The “Blowhole Calculations” section in the figure below is specifically used to find how much water is needed to match what normally pools up in a dimple of the average bottlenose dolphin's blowhole.



| | Equation Table | Vessel Calculations | Pneumatic Calculations |
|----|---|--|------------------------------|
| 1 | $V_1A_1 = V_2A_2$ | Air Density (lb/ft ³) 0.077 | Stroke Speed (ft/s) 3.2 |
| 2 | $Q = AV$ | Gravity (ft/s ²) 32.174 | Power Factor 0.6 |
| 3 | $P = F/A$ | Piston mass (lb) 0.454 | Stroke Force (lbs) 42 |
| 4 | $P_1 + (1/2)\rho v_1^2 + \rho gh_1 = P_2 + (1/2)\rho v_2^2 + \rho gh_2$ | Length.stroke (in) 6 | Pressure.Cyl (Psi) 70 |
| 5 | $P_{cyl} = F/Power.fac$ | Length.PV (in) 13.5 | |
| 6 | $\Delta V = Stoke.Length * Piston.Area$ | Length.Exit (in) 2 | |
| 7 | | Diam.Big (in) 5 | |
| 8 | | Diam.Small (in) 1 | |
| 9 | | Area.Big (in ²) 19.63 | |
| 10 | | Area.Small (in ²) 0.785 | |
| | | | Blowhole Calculations |
| 11 | | Vel.Big (ft/s) 3.2 | Avg. Length (cm) 2.0 |
| 12 | | ^^^^ (m/s) 0.97536 | Avg. Width (cm) 3.4 |
| 13 | | Vel.Small (ft/s) 80 | Avg. Dimple. D (cm) 1.2 |
| 14 | | ^^^^^^ (m/s) 24.384 | Volume of Water (mL) 8.2 |
| 15 | | Flowrate.exit (ft ³ /s) 0.436 | |
| 16 | | ^^^^^^^^^^ (L/s) 12.36 | |
| 17 | | Force.Big (lb) 42 | |
| 18 | | Pressure.Big (Psi) 2.139 | |
| 19 | | Pressure.Small (Psi) 0.009 | |
| 20 | | Force.Small (lb) 0.007 | |

Figure 13

Design five, the pneumatic powered linear piston design was chosen. This design was selected for its ability to perform multiple shots in one run (20+) and the fact that it was preferred by our sponsors for its very simple and easy concept and ability to be modified and model different magnitudes of excretion. This piston design allows complete control over all speeds, pressures, and in turn velocities and spread. This design also allows for the exit velocity and pressure drop to be constant for the duration of the shot which could not be achieved with the other design concepts.

With the key design decision made, many other smaller design decisions had to be made. The biggest decisions involved finding available parts to regulate pressures and erect the main structure of our design. The new design selected allowed for the replacement of specialty parts with more generic and readily available parts. Major design decisions made included: making the body out of PVC, using a provided air collector, abandonment of self-mobility systems, and the integration of a self-milled piston head. After organizing a new parts list, the online ordering process began while



more available parts were purchased directly from the Lowe's in Stillwater. The fabrication and assembly process began immediately following those purchases. This process began with fabrication of the outer PVC shell. Proper lengths of PVC pipes were cut, the piston head was milled from a half inch thick aluminum sheet, PVC end caps and the piston head were drilled and tapped to accommodate threaded fittings, and major PVC components were connected with teflon tape or PVC specific cement. In addition, developments in the water delivery system were made. A water delivery flap was fabricated and implemented into the exhaust pipes.



Figure 14

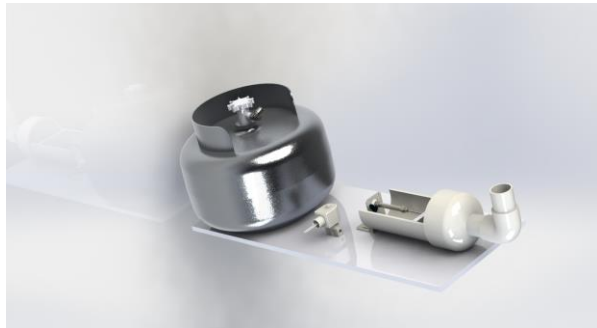


Figure 15

Below are the progress pictures of the assembly of the main body (6 inch PVC) with the one way valves and exhaust pipes. There are two models. One has an exit diameter of 1.5 inches and the other has a 1 inch diameter exit. At the base of the two models is the milled aluminum plate (0.5 inch thick, 6 inch diameter) that will be attached to the pneumatic piston. The board they sit on is the base in which all of our design would be securely held to. The prototype water delivery flap was fairly successful. The flap is hinged in the tube with a wire and held horizontally, from below, by a crossing wire to prevent the flap from getting flipped upstream by the vacuum created during piston



retraction. The flap holds water sufficiently, and testing of the pneumatic cylinder revealed the flow output is strong enough to blow open the flap.



Figure 16



Figure 17



Figure 18



Detailed Description of the final Design:



Figure 20

Water tower & solenoid- Water tower suspends water at a higher height than that of the water flag allowing our system to run on a gravity fed water delivery system. The use and timing of the water delivery solenoid allows for the continual use of our design without having to refill the system or recharge.

Air chamber with 1" exit orifice (Dolph 2)- This test air chamber is used for the collection of further data on a variation of the exit diameter of the orifice. This allows for further testing and the confirmation of the design's success in reaching it's standards as well as the allowal of further testing on variations of dolphin size.



Arduino microcontroller- The arduino microcontroller is used for the implementation of the system's control logic. The arduino is used to time the solenoids that drive the system, and initiate the operator control.

Pneumatic solenoid- The pneumatic solenoid is used to release the regulated air into the pneumatic piston air chamber in order to drive the piston head.

Aesthetic design- Aesthetic design was added for visual appeal

Water delivery flap- The water delivery flap allows for the implementation of our water delivery system. The flap allows water to rest on top until a "blow" is fired and the flap is allowed to revolve and throw the water into the flow of the air. This replicates how water will rest on the surface of the blowhole of a dolphin and then will be caught up in the flow.

Air chamber with 1.5" exit diameter (Dolph 1)- This air chamber is used to replicate the exit orifice of a male adult bottlenose dolphin. Having a similarly sized exit orifice allows for accurate replication of a dolphin "blow".

Pneumatic piston- The pneumatic piston when pressurized moves the piston through the air chamber and pushes air out of the exit orifice. The piston when depressurized retracts using a spring to its original resting position.



Air pressure regulator- The air pressure regulator takes the high pressure stored in the HPA tank and regulates it down to a working pressure that can be adjusted for testing purposes. This regulated pressure is then used to drive the pneumatic piston.

HPA tank- The HPA tank is able to store air up to 125 psi and the volume allows for enough air to be stored for many trials of the design. This tank has to be charged by an external pressure source.

Evaluation of the final Design (design Calculations):

| | Equation Table | Vessel Calculations |
|----|---|--|
| 1 | $V_1A_1 = V_2A_2$ | Air Density (lb/ft ³) 0.077 |
| 2 | $Q = AV$ | Gravity (ft/s ²) 32.174 |
| 3 | $P = F/A$ | Piston mass (lb) 0.454 |
| 4 | $P_1 + (1/2)\rho v_1^2 + \rho gh_1 = P_2 + (1/2)\rho v_2^2 + \rho gh_2$ | Length.stroke (in) 6 |
| 5 | $P_{cyl} = F/Power_{fac}$ | Length.PV (in) 13.5 |
| 6 | $\Delta V = Stoke.Length * Piston.Area$ | Length.Exit (in) 2 |
| 7 | $\Delta P = K * (\rho v^2 / 2)$ | Diam.Big (in) 6 |
| 8 | $h_L = K * (v^2 / 2g)$ | Diam.Small (in) 1.5 |
| 9 | | Area.Big (in ²) 28.27 |
| 10 | | Area.Small (in ²) 1.767 |
| 11 | | Vel.Big (ft/s) 5 |
| 12 | | Vel.Big (m/s) 1.524 |
| 13 | | Vel.Small (ft/s) 80 |
| 14 | | Vel.Small (m/s) 24.384 |
| 15 | | Flowrate.exit (ft ³ /s) 0.982 |
| 16 | | Flowrate.exit (L/s) 27.80 |
| 17 | | Force.Big (lb) 42 |
| 18 | | Pressure.Big (Psi) 1.485 |
| 19 | | Pressure.Small (Psi) 0.009 |
| 20 | | Force.Small (lb) 0.016 |

Figure 21

| Work order using the equations | |
|-------------------------------------|------------------------|
| Eq.1. Find V.Big | V = 5 |
| Eq.2. Find Q | Q = 0.982 |
| N/A Assume Vel.Small | V = 80 |
| N/A Assume Force.Big (stroke force) | F = 42 |
| Eq.4. Find Pressure.Small | P = 0.0088 |
| Eq.4. Find Force.Small | F = 0.0155 |
| Eq.5. Find Pressure.Cyl | P.cyl = 70 |
| Eq.6. Find pressure vessel Δvolume | ΔV = 0.0982 |
| N/A Find flowrate of actual piston | Q.act = 0.1178 |
| Eq.7. Find Pressure loss in fitting | ΔP = 73.44 |
| Eq.8. Find Head loss in fitting | h _L = 29.84 |

Figure 22

Once finding the desired value for the exit velocity to be 24 m/s and the exit flow rate to be around 24 L/s, vessel and “L” piece calculations were performed to iteratively optimize the dimensions of the PVC dolphin body. All the necessary equations can be found in the equation table and our thought process can be followed under the yellow



work order list. The first calculation performed is at the top of the work order list and the last is at the bottom.

| Pneumatic Calculations | |
|--------------------------|-------|
| Stroke Speed (ft/s) | 5 |
| Power Factor | 0.6 |
| Stroke Force (lbs) | 42 |
| Pressure.Cyl (Psi) | 70 |
| Pressure.Vessel.ΔV (ft³) | 0.098 |
| Actual flowrate (ft³/s) | 0.118 |
| AAAAAAAAAAAA (L/s) | 3.34 |
| | |
| Blowhole Calculations | |
| Avg. Length (cm) | 2.0 |
| Avg. Width (cm) | 3.4 |
| Avg. Dimple. D (cm) | 1.2 |
| Volume of Water (mL) | 8.2 |
| | |
| "L" Piece Calculations | |
| Diam. (in) | 1.50 |
| Elbow.Height/Length (in) | 3.125 |
| Horiz.Length (in) | 0.0 |
| Vert. Height (in) | 3.0 |
| Total Length (in) | 3.125 |
| Total Height (in) | 6.125 |
| 90° PVC Elbow K.value | 0.3 |

| Blowhole Measurements (Hawaii) | | | |
|--------------------------------|-------------|------------|-------------------|
| Animal | Length (cm) | Width (cm) | Dimple Depth (cm) |
| 1 | 2.4 | 3.8 | 0.7 |
| 2 | 2.1 | 3.6 | 1.3 |
| 3 | 1.7 | 3.3 | 1.5 |
| 4 | 2.2 | 3.1 | 1 |
| 5 | 2 | 3.5 | 1.5 |
| 6 | 2.5 | 3.6 | 1.7 |
| 7 | 1.3 | 3.4 | 1.1 |
| 8 | 2 | 3.5 | 1.1 |
| 9 | 2 | 3.3 | 1 |
| 10 | 3.5 | 3.9 | 1.2 |
| 11 | 1.3 | 3.2 | 1.5 |

| Blowhole Measurements (Bermuda) | | | |
|---------------------------------|-------------|------------|-------------------|
| Animal | Length (cm) | Width (cm) | Dimple Depth (cm) |
| 1 | 2.3 | 3.6 | 1.2 |
| 2 | 1.5 | 3.5 | 0.5 |
| 3 | 2 | 3 | 1.2 |
| 4 | 1.7 | 3.2 | 1.2 |
| 5 | 2 | 3.3 | 1 |
| 6 | 2 | 3.5 | 1 |
| 7 | 2 | 3 | 1 |
| 8 | 2 | 3.8 | 1.3 |
| 9 | 1.7 | 3.5 | 1 |
| 10 | 1.6 | 2.8 | 1 |

| Blowhole Measurements (Oahu) | | | |
|------------------------------|-------------|------------|-------------------|
| Animal | Length (cm) | Width (cm) | Dimple Depth (cm) |
| 1 | 2.2 | 3.7 | 1.5 |
| 2 | 1.7 | 3.3 | 1 |
| 3 | 2.1 | 3.6 | 1 |
| 4 | 2.3 | 3.5 | 1.5 |
| 5 | 2.4 | 3.4 | 1.5 |
| 6 | 2.4 | 4 | 1.3 |

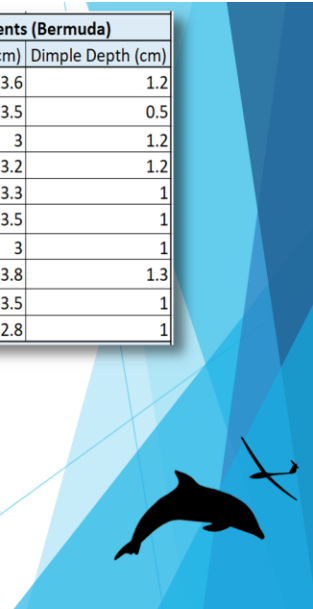


Figure 23

Figure 24

Blowhole measurements were taken by marine biologists in the field and emailed to Dr. Bruck for water collection data. By taking the average dimple sizes of these dolphins, we decided that 8.2 mL of water would be collected and sprayed with every shot. Our final design is calculated to deliver and exit velocity of 24.4 m/s and an exit flow rate of 27.8 L/s when the pneumatic piston is fed 70 psi of pressurized air. The pneumatic piston delivers 42 lbs of force with an internal flow rate of 3.34 L/s when shot at 70 psi.



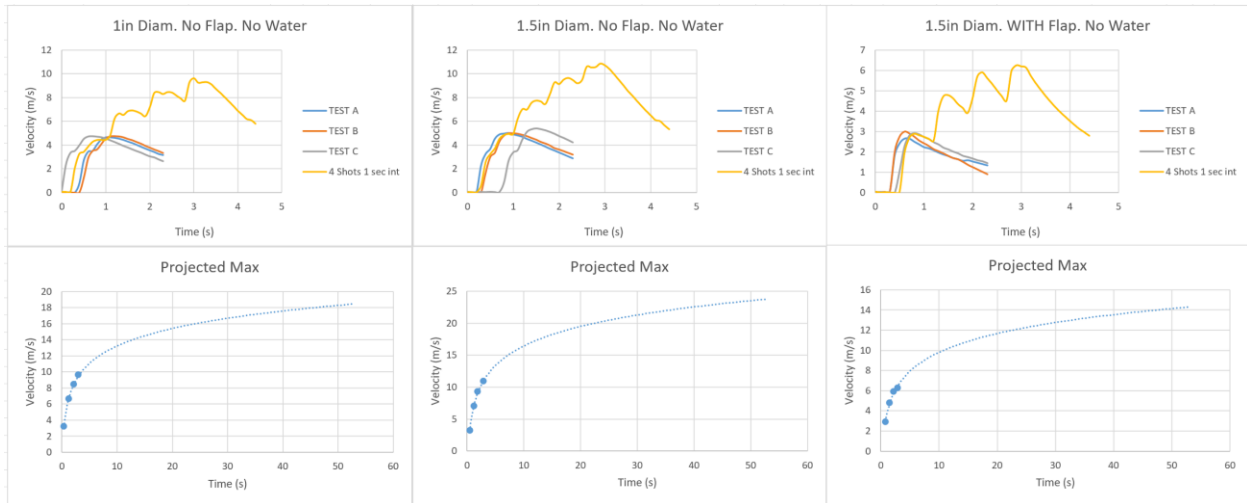


Figure 25

| Avg Max (m/s): 4.70581 | | Avg Max (m/s): 5.13687 | | Avg Max (m/s): 2.8493 | |
|-------------------------------|-------------|-------------------------------|------------|------------------------------|------------|
| 4 Shot Max Values | | 4 Shot Max Values | | 4 Shot Max Values | |
| 0.4 | 3.231048584 | 0.5 | 3.23104858 | 0.8 | 2.89001465 |
| 1.3 | 6.643676758 | 1.2 | 7.02209473 | 1.5 | 4.79125977 |
| 2.2 | 8.448028564 | 1.9 | 9.28878784 | 2.2 | 5.91278076 |
| 3 | 9.617614746 | 2.9 | 10.8856201 | 2.9 | 6.2538147 |
| PROJ Max (m/s): 18.5 | | PROJ Max (m/s): 24 | | PROJ Max (m/s): 15 | |

Figure 26

Figure 27

Figure 28

Initial test readings were gathered with the use of a traditional anemometer that was borrowed from Dr. Jacob. 4 different tests were performed with 3 different exit pipes. All velocity readings for single shots were found to be between 2.8 and 5.13 m/s which were very low. The team concluded that these readings were low due to our anemometers inability to read instantaneous velocities. The anemometer needed a few seconds of constant flow to accurately read velocities. To overcome this challenge, the team fired off 4 shots consecutively with 1 second intervals in between each shot. This simulated a flow that was longer than one explosive shot and gave the anemometer more time to warm up and more accurately measure the exit velocity. The results of this



test were graphed, matched with a logarithmic trend line, and projected max velocities were found to be between 15 and 24 m/s. These results were much closer to the desired values of our design but more testing was done to measure the exit velocity more accurately.

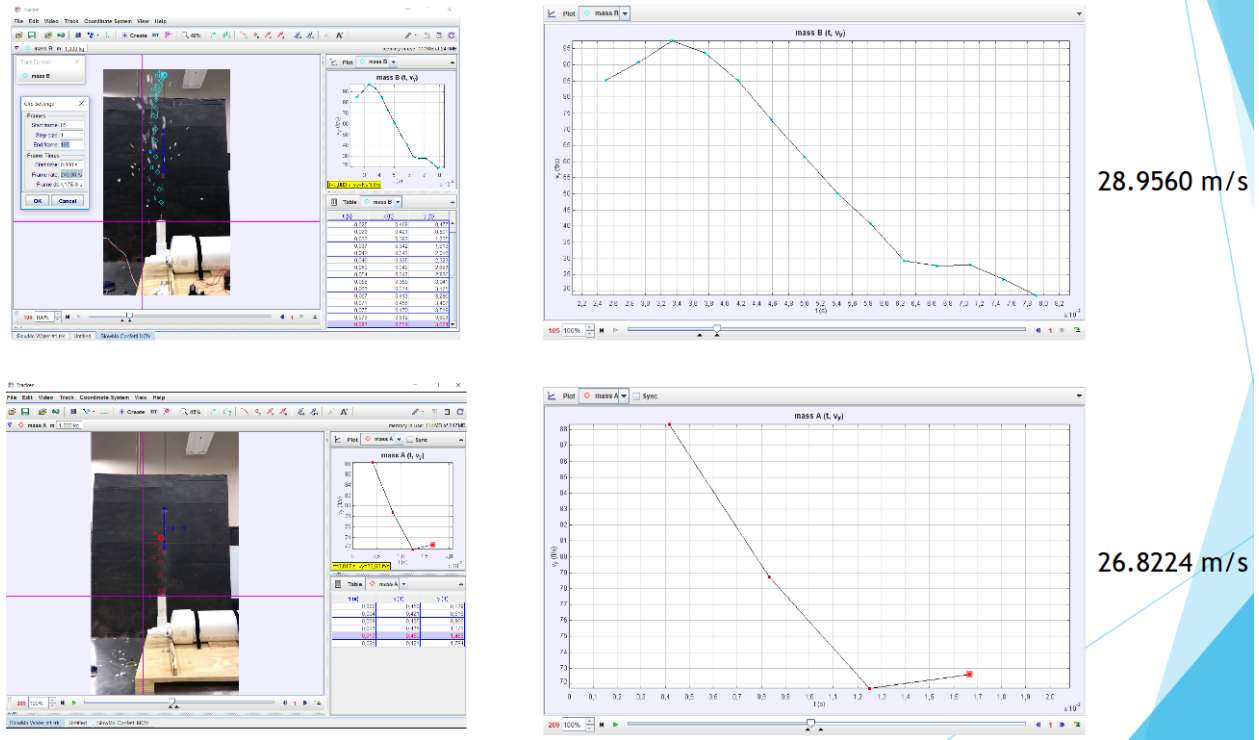


Figure 29

Videos of our test shots with water and confetti were analyzed for velocity readings. Confetti and water droplets were tracked frame by frame to find that our design shot water at 26.8 m/s and confetti at 28.9 m/s. These are higher than the desired 24 m/s which shows that our design can match what a dolphin can do in the wild. To lower the exit velocity of these shots to 24 m/s, reduce the amount of pressurized air that goes into the pneumatic cylinder from 70 psi to 60 psi.



Recommendations for Future Work:

Short term improvements that should be made include fabricating an improved water flap and reduce the height of the water tower. By implementing a hinge that allows the water flap more range of motion will reduce the dampening effect on the exit velocity and more effectively throw water into the air stream during exhalation. Matching the cross section of the exit piping and the flap more closely will also aid in pooling water more effectively during pre-exhalation. Reducing the height of the water tower provide more air clearance for drone collection methods and improve the visibility of each shot.

Long term improvements include implementing the self-mobility concept and adding mucus or some form of liquid additive for testing purposes. Implementing the concept of self-mobility with an RC car or boat would require fabrication of a similar design on a smaller scale and compacting all the components of this design. Including a liquid additive to future iterations of this design could prove very useful and may be simple to add into the water tower system seen in the current blowhole simulator. However, a vast amount of research would need to be done to understand what additives could and should be used to aid in testing processes.

Revised Gantt Chart:

Multiple changes occurred in our gantt chart throughout the duration of this project. The main impactful changes were to ditch the idea of custom fabricating 3 anatomically correct exit ports with a 3D printer, switching our horizontal motion component from an RC car to a car mount, and time delays encountered while ordering parts. As can be seen between weeks 10 and 11, not much work was completed since



the team was simply waiting on parts to come in. This condensed the time we allocated for building and testing from three weeks each to around one and a half weeks each.

| Project Name | | Members | Project Duration | Project Start Date | Project End Date |
|----------------------------|--|---|------------------|--------------------|------------------|
| Dolphin Blowhole Simulator | | Kevin Quinn Daniel Wigley Jason Fey | 105 | 1/22/2018 | 5/7/2018 |

| YOU CAN CHANGE THESE | | | | | | DO NOT CHANGE -> | | | | | | | | | | | | | | | | |
|----------------------|---|-----|----------------------|------------|-----------|------------------|-----------|----------|-----------|-----------|-----------|----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|----------|
| Task | Task Description | Who | Task Duration (days) | Start Date | End Date | Week - 1 | Week - 2 | Week - 3 | Week - 4 | Week - 5 | Week - 6 | Week - 7 | Week - 8 | Week - 9 | Week - 10 | Week - 11 | Week - 12 | Week - 13 | Week - 14 | Week - 15 | Week - 16 | |
| | | | | | | 1/22/2018 | 1/29/2018 | 2/5/2018 | 2/12/2018 | 2/19/2018 | 2/26/2018 | 3/5/2018 | 3/12/2018 | 3/19/2018 | 3/26/2018 | 4/2/2018 | 4/9/2018 | 4/16/2018 | 4/23/2018 | 4/27/2018 | 4/30/2018 | 5/7/2018 |
| 1 | Blowhole Research | All | 40 | 1/22/2018 | 3/3/2018 | | | | | | | | | | | | | | | | | |
| 2 | Design blowhole system | All | 28 | 1/29/2018 | 2/26/2018 | | | | | | | | | | | | | | | | | |
| 3 | Look into 3 different design approaches | All | 7 | 2/26/2018 | 3/5/2018 | | | | | | | | | | | | | | | | | |
| 4 | Finalize desired approach | All | 14 | 3/5/2018 | 3/19/2018 | | | | | | | | | | | | | | | | | |
| 5 | Implement horizontal motion | All | 14 | 3/12/2018 | 3/26/2018 | | | | | | | | | | | | | | | | | |
| 6 | Order Parts | All | 14 | 4/2/2018 | 4/16/2018 | | | | | | | | | | | | | | | | | |
| 7 | Build | All | 14 | 4/9/2018 | 4/23/2018 | | | | | | | | | | | | | | | | | |
| 8 | Test | All | 7 | 4/20/2018 | 4/27/2018 | | | | | | | | | | | | | | | | | |
| 9 | Final Documentation | All | 7 | 4/23/2018 | 4/30/2018 | | | | | | | | | | | | | | | | | |
| 10 | Logbooks & document collection | All | 7 | 4/30/2018 | 5/7/2018 | | | | | | | | | | | | | | | | | |

Figure 30

Revised Budget Table:

The revised budget table below shows that our project cost right around \$300. This was well below the \$1000 upper limit we set at the beginning of the semester. This is very good, because this shows that the prototype could be made 2 times over without going over our limit. As mentioned above, future iterations of this project on a smaller size will be desired, so the low cost of the whole assembly is important.



| Budget Table | | |
|--------------|---------|---|
| Quantity | Cost | Item |
| 1 | \$31.99 | Cylinder hook-up starter kit |
| 1 | \$37.05 | 7/8 Bore Single-Acting univ.mount |
| 1 | \$13.75 | Flange Mount (5-8/18 (D)(E)(F)) |
| 1 | Free | 12v Battery pack |
| 1 | Free | AA Batteries (20pack) |
| 1 | \$12.20 | quick exhaust valve |
| 1 | \$8.97 | PVC fitting (6in diam. pipe) |
| 4 | \$19.56 | PVC fittings (6in diam. Endcap) |
| 1 | \$3.69 | PVC fitting (1-1/2in diam. Pipe) |
| 1 | \$2.26 | PVC fitting (1in diam. Pipe) |
| 1 | \$8.39 | PVC cement & primer pack |
| 1 | Free | Alluminum plate (for piston head) |
| 1 | \$40.00 | PVC 6 in. diameter 10 ft length |
| 4 | \$3.00 | check valve |
| 1 | \$5.00 | 2x4 Plywood (base support) |
| 1 | Free | Air Accumulator (5-Gallon) |
| 1 | Free | Galvanized Pipe Cross Fitting (1/2 NPT) |
| 3 | \$2.39 | Threaded Reducer (Bushing) |
| 1 | \$10.45 | 1/4 npt pressure gauge |
| 1 | \$79.99 | Air Regulator |
| 1 | \$2.39 | 1/2 npt nipple |
| 1 | \$0.88 | 1/4 npt quick connect |
| 1 | \$5.59 | 1/4 quick connect barrell |
| 1 | \$8.50 | Pvc and miscellaneous plumbing |
| Total | | \$296.05 |

Figure 31

