

DISTRIBUTION OF STRESS AROUND A
TUNNEL CAVITY, USING THE
FINITE ELEMENT METHOD

By

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NOMENCLATURE

$[A]$	Rectangular matrix; function of position coordinates of a point within the element
$[B]$	Strain displacement transformation matrix
$[C]$	Rectangular matrix of elasticity coefficients
$\{e\}$	Column vector of total strains within an element
$[K]$	Structure stiffness matrix
$[k]$	Element stiffness matrix
$[M]$	Mass matrix
$[m]$	Rectangular matrix of displacement functions
$[P]$	Column vector of nodal point loads
$\{Q\}$	Column vector of displacements at nodal points
$\{q\}$	Column vector of displacements within an element
$[R]$	Rectangular matrix; function of position coordinates of nodal points
U_0	Strain energy density
V	Volume
$\{\alpha\}$	Column vector of generalized displacements
δU	Virtual strain energy
δW	Virtual work of external forces
$\{\epsilon\}$	Column vector of elastic strains

$\{\mathbf{e}_0\}$

Column vector of initial strains

 $\{\boldsymbol{\sigma}\}$

Column vector of element stresses

CHAPTER I

INTRODUCTION

1.1 General

Engineers concerned with the design and construction of buried structures have long been preoccupied with the problems of structure-medium interactions. With the advent of thermonuclear weapons, which may subject buried structures to severe ground motions and very high loads, a clear understanding of structure-medium interaction has become vitally important. Conventional methods, of empirical nature, used in the design of culverts and pipelines, cannot be used in the design of buried structures which have to withstand nuclear effects, as this would result in extremely costly structures. In an effort to reduce and control the magnitude of the forces applied to the buried structure by blast loadings, comprehensive studies were conducted both in the field and laboratory of structure-medium interactions.

A technique employed is to isolate the structure from the effects of nuclear blast by surrounding it with an energy absorbing medium called "packing." Such a packing material is normally elasto-plastic with a low yield strength and high compressibility. The packing is intended to absorb part of the shock energy and to redistribute the pressure around the structure, thereby reducing the loads applied to it.

1.2 Statement of Problem

This study is an effort to evaluate the feasibility of applying the finite element technique to the solution of structure-medium interaction problems and to investigate the magnitude and distribution of pressures around a lined or unlined horizontal tunnel subjected to a static uniform over-pressure on the ground surface. The structural liner considered in this study is made of reinforced concrete, although other materials could have served just as well, and is encased in a packing material placed between the liner and the face of the tunnel cavity.

An assumption made in the study is that the surrounding medium behaves as a continuous, elastic, isotropic and homogeneous medium. Using the well established theory of elasticity then, it is possible to determine the displacements and, hence, the stresses throughout the medium. A condition of plane-strain along the axis of the tunnel was considered, as most field observations from conventional installations such as culverts and pipelines approximately conform to such conditions.

1.3 Previous Work

The composition of various materials that could be satisfactorily used as back-packing for shock isolation of buried structures has interested several authorities and institutions for the past few years, and has been the subject of a number of experimental and theoretical studies.

During operation "plumbbob," in 1957, Vaile (1) studied the effects of violent ground motions on buried vertical concrete pipes,

some of which had glass bottles for back-packing, while others had soil and served as control pipes. Vaile observed that the accelerations, velocities and displacements produced in the isolated pipes were markedly reduced compared to those of the control pipes. The reduction was due partly to the collapse and crushing of the bottles, which resulted in the dissipation of some of the shock energy.

Sevin (2) has performed studies on small scale structures and points out the effectiveness of the packing materials even when stressed only to the elastic region of the stress-strain curve. He also notes that "at sufficiently high stress levels this form could also be expected to behave as a dissipative isolation system." This study was primarily concerned with the redistribution of soil pressure around the structure-packing system.

DaDeppo and Werner (3) studied the influence on the response of a buried cylinder, with a crushable material placed adjacent to the cylinder. The packing material, they observed, greatly reduced the magnitude of the loads reaching the cylinder. The results of this study also indicated the effects of the softness of the packing material on the stress redistribution around the structure.

More recently, numerous studies have also dealt with the static and dynamic analyses of lined and unlined tunnels (4) and (5). The usual assumptions of linear elasticity, homogeneity and isotropy were made. It was observed, in these and other studies, that the displacements and stresses from a dynamic analysis obtained by an assumed plane stress wave of a certain amplitude were about 20% higher than the displacements and stresses obtained from a static analysis of the same amplitude (as that of plane wave stress). Because of the close

agreements then, it is possible to predict the behavior of such cylindrical structures under dynamic conditions from studies of their behavior under static conditions.

1.4 The Finite Element Method

The finite element method is, basically, a process by which a complex structure is idealized as an assemblage of a finite number of structural elements of appropriate size and shape, interconnected by a finite number of nodes, and retaining all the material properties of the original structure. This model of the actual structure is used in all subsequent structural analyses and the accuracy of the results will depend on how well the behavior of the model simulates that of the actual structure; i.e., actions and deformations of the nodes are interpreted to be the actions and displacements of the corresponding points on the structures.

Idealization of a structure as an assemblage of structural elements is not new. The slope-deflection method of structural analysis, for example, is an idealization where the structural elements are one-dimensional in character. What is new in the finite element method is that the idealization is extended by the use of two- or three-dimensional elements to represent an elastic continuum.

Most of the approximate methods of structural analysis (such as finite differences) depend for their solution on approximate mathematical procedures. The only approximation involved in the finite element method, however, is that of replacing the actual structure by an articulated structural model, but there is no need to use an approximate mathematical analysis of the model.

Matrices representing element characteristics, such as force-displacement or stress-strain relationships, are obtained from an assumed displacement (or stress) function throughout the element. Once these matrices are derived, the behavior of the entire structure may then be determined by satisfying simultaneously the equilibrium, compatibility and force-deflection relationships at the nodes.

Of the force and displacement methods of analysis, the latter is more suitable for computer programming and has been used in this study.

1.5 Liner-Packing Materials and Configurations

Figures 1 and 2 show a liner-packing system and its finite element idealization, respectively. The liner material is shown to be concrete, but steel liners would work just as well.

1.5.1 Reinforced Concrete Liners

The behavior of a structure under load depends, to a large extent, on the stress-strain relationship of the materials from which it is made. For the liner under consideration, therefore, typical stress-strain curves for concrete under compressive loads are shown in Figure 3, for various cylinder strengths, f'_c . Each curve starts with an initial nearly straight elastic portion, then begins to curve to the horizontal and attains a maximum stress at a strain of approximately 0.002 in. per in., and follows a steep downward path beyond the peak stress, probably indicating internal disintegration of the material. It is noted that concretes of lower strength are less brittle than high strength concretes. Tests have shown that unit strains of 0.003 to

0.0045 occur before a beam fails. For concretes of cylinder strength f'_c over 6000 psi, the maximum observed strains range from 0.0025 to 0.0040. For high strength concretes, therefore, a maximum strain of 0.003 is considered the limit of usefulness.

The modulus of elasticity E_c , which is the slope of the initial straight portion, is seen to vary with the strength of the concrete; the higher the strength, the larger the modulus. The ACI Code (15) recommends the use of an empirical formula for the computation of the modulus of elasticity and is given by

$$E = 33\omega^{1.5} f'_c$$

where ω = weight of the concrete in pounds per cubic foot.

When stressed in one direction, concrete expands in the transverse direction and the Poisson's ratio, for concretes stressed up to $0.7 f'_c$, varies from 0.15 to 0.20.

The tensile strength of concrete is very small compared to its compressive stress and is usually neglected.

1.5.2 Back-packing

The most important characteristic that a back-packing material should have is that it be highly compressible with a low yield stress. It should also be capable of dissipating a large portion of the shock energy. Several materials, with the desired characteristics, have been developed for use as back-packing; a few of which are foamed plastics, honeycombs, insulating concretes, and various granular materials.

The choice of back-packing materials will depend largely on the type and location of the structure, the assumed loading and, above all,

the cost of material. Generally speaking, the granular materials are the least expensive. Typical stress-strain curves are shown in Figures 4 and 5 for elasto-plastic and plasto-elastic materials. To facilitate calculations, both of these curves have been approximated as shown on the same figures, although only the elastic range is of interest in this study.

The material used in this study is cellular concrete which is elasto-plastic with a yield stress of 40 psi..

1.5.3 Surrounding Medium

Soils and rocks, in general, possess non-linear stress-strain characteristics. A typical stress-strain curve for playa silt, in one-dimensional compression, is given in Figure 6. As a result of compaction and cementation that takes place, the initial part of the curve is concave downward up to the point A. As the stress is increased, the initial stiffness due to compaction and cementation is destroyed, and the curve begins to increase with the stress level and becomes concave upward. The one-dimensional modulus is determined as a tangent of such a stress-strain curve or from measurements of wave propagation through the medium.

1.5.4 Assumed Behavior of Materials

For the purpose of analysis, the above materials have been idealized as being continuous, isotropic and homogeneous. The study, however, will be restricted to the initial regions of the stress-strain curves where the behavior is almost linearly elastic in nature.

CHAPTER II

FORMULATION OF MODEL

2.1 Formation of Structure Matrices

A structural model assembled from a finite number of discrete elements is substituted for the continuous structure. These elements are separated by imaginary lines and are interconnected by a finite number of nodes, as shown in Figures 2, 7 and 8. The equations of elasticity for the continuous structure are formulated in matrix form using these elements.

2.2 Development of Element Stiffness Matrix

It is assumed that the displacements at any point within the element can be related to the displacements at the nodes by an equation of the form:

$$\{q\} = [A] \{Q\} \quad (2.1)$$

where $\{q\} = \{q_x, q_y\}$ is a column matrix of internal displacements at a point in the element, $\{Q\} = \{Q_1, Q_2, \dots, Q_n\}$ is a column matrix of displacements of the nodal points, and $[A] = [A(x, y, z)]$ is a rectangular matrix which is a function of the position coordinates of the point. With the displacements at any point within the element given, the corresponding total strains are obtained by differentiating Equation (2.1)

and

$$\{e\} = [B] \{Q\} = \text{the total strain} \quad (2.2)$$

$$= \{\epsilon\} + \{\epsilon_0\} \quad (2.3)$$

where

$[B]$ = the strain-displacement transformation matrix ;

$\{\epsilon\}$ = elastic strains

$\{\epsilon_0\}$ = initial strains due to temperature changes, pre-stress, etc.

Assuming linear elastic behavior for the material, the stresses are related to the elastic strains by the generalized Hooke's Law:

$$\{\sigma\} = [C] (\{e\} - \{\epsilon_0\}) . \quad (2.4)$$

Substituting Equation (2.2) into Equation (2.4) gives

$$\{\sigma\} = [C][B]\{Q\} - [C]\{\epsilon_0\} . \quad (2.5)$$

where $\{\sigma\} = \{\sigma_x, \sigma_y, \sigma_z; \tau_{xy}, \tau_{xz}, \tau_{yz}\}$ is a column matrix of stresses, and $[C]$ is a square matrix of elasticity coefficients.

For virtual nodal displacements $\delta\{Q\}$, the corresponding virtual displacements at any point within the element are obtained from Equation (2.1).

$$\delta\{q\} = [A] \delta\{Q\} \quad (2.6)$$

and from Equation (2.2) the virtual strains become

$$\delta\{\epsilon\} = \delta\{e\} = [B] \delta\{Q\} . \quad (2.7)$$

The governing finite element equations for a unit length of the structure will be developed from a consideration of the principle of virtual work

which takes the form:

$$\delta U = \delta W \quad (2.8)$$

where

δU = virtual strain-energy;

δW = virtual work of all external forces.

2.3 Virtual Strain Energy

The strain energy may be expressed as

$$U = \int_V U_0 \, dV \quad (2.9)$$

where U_0 = strain energy density, and V = volume.

If now, virtual displacements are imposed on the structure, there will be accompanying virtual strains, and the variation of the strain energy density will be given by:

$$\delta U_0 = \delta \{\epsilon\}^t \{\sigma\}. \quad (2.10)$$

Consequently, the variation of the strain energy will be

$$\delta U = \int_V \delta U_0 \, dV = \int_V \delta \{\epsilon\}^t \{\sigma\} \, dV. \quad (2.11)$$

Substitution of Equations (2.5) and (2.7) into Equation (2.11) yields

$$\delta U = \int_V \delta \{Q\}^t ([B]^t [C] [B]) \{Q\} \, dV - \int_V \delta \{Q\} [B]^t [C] \{\epsilon_0\} \, dV. \quad (2.12)$$

2.4 Virtual Work of External Forces

The structure is assumed to be subjected to a system of surface forces $\{T\}$, body forces $\{X\}$, and a set of concentrated forces $\{P\}$

applied at the nodes interconnecting the boundaries of the elements.

The virtual work of external forces, due to virtual displacements at the nodes, is then given by:

$$\delta W = \int_V \delta \{q\}^t \{X\} dV + \int_S \delta \{q\}^t \{T\} ds + \delta \{Q\}^t \{P\}, \quad (2.13)$$

where s = surface area, and

$$\{X\} = \{X_x, X_y, X_z\};$$

$$\{T\} = \{T_x, T_y, T_z\};$$

$$\{P\} = \{P_x, P_y, P_z\}.$$

Substitution of Equation (2.6) into (2.13) yields

$$\delta W = \int_V \delta \{Q\}^t [A]^t \{X\} dV + \int_S \delta \{Q\}^t [A]^t \{T\} ds + \delta \{Q\}^t \{P\}. \quad (2.14)$$

2.5 The Governing Equation

Equating the Equations (2.12) and (2.14) as required by Equation (2.8) results in

$$\begin{aligned} & \int_V \delta \{Q\}^t [B]^t [C] [B] \{Q\} dV - \int_V \delta \{Q\}^t [B]^t [C] \{\epsilon_0\} \\ & \quad = \int_V \delta \{Q\}^t [A]^t \{X\} + \int_S \delta \{Q\}^t [A]^t \{T\} ds + \delta \{Q\}^t \{P\} \end{aligned} \quad (2.15)$$

This equation is valid for any value of virtual displacements. Whence

$$\begin{aligned} [k] \{Q\} &= \{P\} + \int_V [B]^t [C] \{\epsilon_0\} dV + \int_V [A]^t \{X\} dV \\ & \quad + \int_S [A]^t \{T\} ds \end{aligned} \quad (2.16)$$

where

$$[k] = \int_V [B]^t [C] [B] = \text{element stiffness matrix.}$$

Addition of these elemental matrices yields the stiffness matrix for the entire structure. Equation (2.16) then becomes

$$\begin{aligned} [K] \{Q\} &= \{P\} + \int_V [B]^t [C] \{\epsilon_0\} dV + \int_V [A]^t \{X\} dV \\ &+ \int_S [A]^t \{T\} ds \end{aligned} \quad (2.17)$$

where $[K]$ = structure stiffness matrix.

2.6 Displacement Function

The structural element considered is a quadrilateral element of unit thickness. A convenient way of calculating its stiffness properties is one proposed by Turner et al (7). The method consists of subdividing the quadrilateral into four triangular elements and combining the stiffnesses of the triangles to obtain that of the quadrilateral.

A typical triangular element subjected to inplane loads is shown in Figure 9. The displacements within the element can be expressed by an assumed displacement function as

$$\{q\} = [m(x, y, z)] \{\alpha\} \quad (2.18)$$

where $[m(x, y, z)]$ is a rectangular matrix of displacement functions and $\{\alpha\}$ is a column matrix of generalized coordinates representing the amplitudes of the displacement functions.

The number of generalized coordinates chosen must be at least equal to the number of independent nodal point displacement components. Since a triangular element has six degrees of freedom of nodal

displacements, the displacements at any point $P(x, y)$ within the element will be taken as

$$\left. \begin{aligned} u_x &= \alpha_1 + \alpha_2 x + \alpha_3 y \\ u_y &= \alpha_4 + \alpha_5 x + \alpha_6 y \end{aligned} \right\} , \quad (2.19)$$

expressed in standard matrix form, Equation (2.17) becomes

$$\{q\} = \begin{Bmatrix} u_x \\ u_y \end{Bmatrix} = \begin{bmatrix} 1 & x & y & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & x & y \end{bmatrix} \begin{Bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \\ \alpha_4 \\ \alpha_5 \\ \alpha_6 \end{Bmatrix} . \quad (2.20a)$$

Symbolically,

$$\{q\} = [m] \{\alpha\} . \quad (2.20b)$$

The six constants $\alpha_1 \dots \alpha_6$ can be obtained from a consideration of the displacements at the nodes, given by:

$$\{Q\} = \begin{Bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \\ u_5 \\ u_6 \end{Bmatrix} = \begin{bmatrix} 1 & x_1 & y_1 & & & \\ & & & 1 & x_1 & y_1 \\ & & & & & \\ 1 & x_2 & y_2 & & & \\ & & & 1 & x_2 & y_2 \\ & & & & & \\ 1 & x_3 & y_3 & & & \\ & & & 1 & x_3 & y_3 \end{bmatrix} \begin{Bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \\ \alpha_4 \\ \alpha_5 \\ \alpha_6 \end{Bmatrix} \quad (2.21a)$$

Symbolically,

$$\{Q\} = [R] \{\alpha\} \quad (2.21b)$$

$\{\alpha\}$ is now calculated in terms of $\{Q\}$ and substituted into Equation (2.20) to yield:

$$\begin{aligned}
\{q\} &= [m] [R]^{-1} \{Q\} \\
&= [A] \{Q\} \\
&= \begin{bmatrix} d_1 & 0 & d_2 & 0 & d_3 & 0 \\ 0 & d_1 & 0 & d_2 & 0 & d_3 \end{bmatrix} \{Q\}
\end{aligned} \tag{2.22a}$$

where

$$\begin{aligned}
d_1 &= a_1 + b_1x + c_1y \\
d_2 &= a_2 + b_2x + c_2y \\
d_3 &= a_3 + b_3x + c_3y
\end{aligned} \tag{2.22b}$$

and

$$\begin{aligned}
a_1 &= \frac{1}{2\Delta} (x_2y_3 - x_3y_2) \\
b_1 &= \frac{1}{2\Delta} (y_2 - y_3) = y_{23}/2\Delta \\
c_1 &= \frac{1}{2\Delta} (x_3 - x_2) = y_{32}/2\Delta
\end{aligned} \tag{2.22c}$$

a_2, b_2, c_2 and a_3, b_3, c_3 are obtained by a cyclic permutation of the subscripts in the order 1, 2, 3.

$$2\Delta = \text{DET} \begin{vmatrix} 1 & x_1 & y_1 \\ 1 & x_2 & y_2 \\ 1 & x_3 & y_3 \end{vmatrix} = 2(\text{Area of triangle } \textcircled{1}, \textcircled{2}, \textcircled{3}).$$

2.7 The Stiffness Matrix $[K]$

Equation (2.22a) is now differentiated to give the total strains at any point within the element

$$\{e\} = \begin{Bmatrix} e_x \\ e_y \\ \gamma_{xy} \end{Bmatrix} = \begin{Bmatrix} \frac{\partial u_x}{\partial x} \\ \frac{\partial u_y}{\partial y} \\ \frac{\partial u_x}{\partial y} + \frac{\partial u_y}{\partial x} \end{Bmatrix} = \begin{bmatrix} b_1 & 0 & b_2 & 0 & b_3 & 0 \\ 0 & c_1 & 0 & c_2 & 0 & c_3 \\ c_1 & b_1 & c_2 & b_2 & c_3 & b_3 \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \\ u_5 \\ u_6 \end{Bmatrix} \quad (2.23)$$

Symbolically,

$$\{e\} = [B] \{Q\}$$

The stiffness matrix for the triangular element can now be obtained from the relationship

$$[k] = \iiint [B]^t [C] [B] dx dy dz .$$

Since the element being considered is of unit width, the above reduces to

$$[k] = \iint [B]^t [C] [B] dx dy , \quad (2.24)$$

the integration being carried over the area of the triangle. The matrices $[B]$ and $[C]$ are independent of x and y and are, therefore, taken out of the integral sign and the resulting integral becomes the volume (vol) of the triangle.

Hence

$$[k] = [B]^t [C] [B] \cdot (\text{vol}) . \quad (2.25)$$

To obtain the stiffness matrix for the quadrilateral element, consider the quadrilateral element as built up from four triangular elements as shown in Figure 10. The stiffness matrices $[k]$ of the

triangles are of order 6 x 6. By adding appropriate rows and columns of zeros, the order of these matrices is increased to 10 x 10. It is now possible to superimpose these stiffness matrices to obtain for the quadrilateral a relationship of the form:

$$\left\{ \begin{array}{c} P_1 \\ P_2 \\ P_3 \\ \\ \\ \\ P_8 \\ P_9 \\ P_{10} \end{array} \right\} = \left[\begin{array}{ccc|ccc|ccc} a_{11} & a_{12} & & & & & a_{1,8} & a_{1,9} & a_{1,10} \\ a_{21} & a_{22} & & & & & a_{2,8} & a_{2,9} & a_{2,10} \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & a_{8,8} & a_{8,9} & a_{8,10} \\ a_{9,1} & & & & & & & a_{9,9} & a_{9,10} \\ a_{10,1} & & & & & & & a_{10,9} & a_{10,10} \end{array} \right] \left\{ \begin{array}{c} u_1 \\ u_2 \\ \\ \\ \\ \\ u_8 \\ u_9 \\ u_{10} \end{array} \right\} \quad (2.26)$$

$$\{P''\} = \left\{ \begin{array}{c} P \\ P' \end{array} \right\} = \left[\begin{array}{cc|cc} k_{11} & k_{12} \\ k_{21} & k_{22} \end{array} \right] \left\{ \begin{array}{c} Q \\ Q' \end{array} \right\}$$

where $\{P''\}$ is the column matrix of nodal forces. Since the forces applied to the quadrilateral element are acting at the nodes ①, ②, ③, and ④, it is necessary to impose the conditions $P_9 = 0$ and $P_{10} = 0$; i. e.,

$$\{P'\} = \left\{ \begin{array}{c} 0 \\ 0 \end{array} \right\}.$$

Hence,

$$\{0\} = [k_{21}] \{Q\} + [k_{22}] \{Q'\}$$

which gives

$$\{Q'\} = -[k_{22}]^{-1} [k_{21}] \{Q\}, \quad (2.27)$$

$$\{P\} = \left([k_{11}] - [k_{12}] [k_{22}]^{-1} [k_{21}] \right) \{Q\},$$

i. e.,

$$\{P\} = [k] \{Q\}. \quad (2.28)$$

The matrix $[k]$ in Equation (2.28) is the required stiffness matrix of the quadrilateral element.

A more convenient way of obtaining the $[k]$ matrix without having to invert any matrix is as follows. The rows (and columns) corresponding to $P_9 = 0$ and $P_{10} = 0$ are eliminated one at a time. Thus, for the 10th row:

$$0 = \sum_{j=1}^9 a_{10,j} \cdot u_j + a_{10,10} \cdot u_{10},$$

from which

$$u_{10,10} = -\frac{1}{a_{10,10}} \sum_{j=1}^9 a_{10,j} \cdot u_j,$$

and

$$\begin{aligned} P_i &= \sum_{j=1}^9 \left(a_{ij} - \frac{a_{i,10} \cdot a_{10,j}}{a_{10,10}} \right) \cdot u_j \quad (i = 1, 2, \dots, 9), \\ &= \sum_{j=1}^9 a'_{ij} \cdot u_j. \end{aligned}$$

The above procedure can be repeated to obtain

$$\begin{aligned}
 P_i &= \sum_{j=1}^8 \left(a'_{ij} - \frac{a'_{i,9} a'_{9,j}}{a'_{9,9}} \right) \cdot u_j \quad (i = 1, 2, \dots, 8), \\
 &= \sum_{j=1}^8 k_{ij} \cdot u_j . \quad (2.29)
 \end{aligned}$$

The matrix $[k_{ij}]_{8 \times 8}$ in Equation (2.29) is the required stiffness matrix for the quadrilateral element in terms of the four external nodes. The proper matrix addition of all the elemental stiffnesses in accordance with the nodal numbering of each element produces the overall structural matrix $[K]$ shown in Equation (2.17).

CHAPTER III

STRUCTURAL IDEALIZATION

3.1 Description of Model

A uniform over-pressure of 100 psi was assumed to act on the surface of the ground and the investigation dealt with the following cases:

1. Stress distribution in the undisturbed medium.
2. Stress distribution around an unlined tunnel cavity.
3. Stress distribution around a tunnel with liner-packing system.
4. Stress distribution around a tunnel with a cracked liner (one or three cracks).

The tunnel cavity was considered at a depth of $5D$ below the ground surface, where D is the diameter of the tunnel cavity. It was assumed that (due to St. Venant's theory) the tunnel would not cause appreciable change on the stress distribution at distances of $2D$ or more from the tunnel cavity. The investigations for the lined and unlined tunnels were, therefore, based on the models shown in Figures 7 and 8, respectively. Due to symmetry of structure and loading, only one-half of the model is shown. In each case, the vertical boundary was considered fixed in the X-direction but free to displace in the Y-direction, and the horizontal boundary at the bottom was considered fixed in the Y-direction but free to displace in the X-direction.

3.2 Finite Element Idealization

The finite element idealization of the structure was carried out on the model. For each case, the model was divided by a number of radial lines and concentric circles. In both the lined and unlined tunnel studies, the radii of the circles, in the surrounding medium, were chosen with a weighting factor so as to obtain, wherever possible, a mesh of well proportioned quadrilateral elements. Due to the storage limitations of the computer, the maximum number of radial lines, for the lined tunnel, was kept at 49 which gave rise to a maximum of 945 nodes and 914 elements. Starting with the first line and going clockwise, every other line was extended beyond the tunnel cavity to end at the boundary of the model (see Figures 7 and 8). A systematic order was then followed in numbering the nodal points and elements, with the restriction that the maximum difference between the numbers of any two nodes in any one element be less than a predetermined number, 55 in this case. This, in essence, subdivided the structure into partitions containing a maximum of 55 nodes.

The unlined tunnel required only 25 radial lines starting at the cavity and ending on the boundary of the model (see Figure 8). Also shown in Figure 8 is the system followed in numbering the nodes and the elements.

The sizes of the elements in the surrounding medium grow progressively larger due to the weighting factor used. In the case of the unlined cavity, the elements in the surrounding medium adjacent to the cavity are quadrilateral, while in the lined tunnel these elements are triangular and serve as a transition zone from the smaller elements in the packing to the larger elements in the medium.

CHAPTER IV

THE COMPUTER PROGRAM

4.1 Description

The nodal displacements were determined by solving Equation (2.17) on an IBM computer system 360/50. The main program is made sufficiently flexible to handle two dimensional plane strain or plane stress problems with a maximum of 950 nodes and 930 elements.

Referring to the program flow chart given in Figure 11, the elastic constants of materials used were first read in as data, followed by the automatic generation and storage of the nodal coordinates in the global system. For the lined tunnel, the generation of the nodal coordinates was carried out in two stages: the nodes in the liner-packing system first, followed by the nodes in the surrounding medium. In each stage, only the first and last nodal numbers on each radial line were read in as input, after which, the numbering of the intermediate nodes and the corresponding coordinates, together with information as to whether load or displacement is prescribed and its magnitude, were generated automatically. For nodes not on radial lines, the coordinates and other relevant information were read in from punched cards.

The generation of the elements, material properties, and the associated nodal numbers was automatic and accomplished in two stages, as mentioned above. Each element, whether quadrilateral or triangular, had four nodal numbers associated with it; in the case of a

triangular element, one of the nodal numbers was recorded twice. In a string of quadrilateral elements, only the first and last elements and their four nodal numbers were read in, after which, the intermediate elements with their four nodes and material properties were generated. For triangular elements, all the pertinent data had to be provided as input. All the input or generated data were then printed out for checking. A listing of typical input data is shown in Appendix C.

Next in order of execution was the calculation of the element stiffnesses. Each quadrilateral element is assumed to be made up of four triangles by introducing an extra node in the middle of the quadrilateral. The coordinates of the auxiliary node are the average of the other four nodal coordinates. The stiffness matrix obtained by adding the stiffnesses of the four triangles is of order 10×10 . This is reduced to an 8×8 matrix by eliminating the extra node introduced to yield the required element stiffness matrix for the quadrilateral. These element stiffnesses are then added in accordance with the nodal numbering to obtain the structure stiffness matrix. The structure load column matrix is formed next by adding all the element nodal loads according to the nodal numbering. Before going on with the calculation of displacements, the structure stiffness matrix and load vector were revised to account for the prescribed displacements. The resulting simultaneous equations were solved for the other displacements using the Gaussian elimination method for banded matrices. Finally, the displacements of each node were printed.

The average global stresses in each quadrilateral element were calculated from the average of the strains of the four triangles making up the quadrilateral element. In order to do this, the element stiffness

matrix had to be regenerated for each element and used to calculate the displacement of the middle node. A 10 x 1 displacement vector was thus produced which made it possible to calculate the average of the strains on the four triangular elements. The global stresses were then determined from Equation (2.5), with $\{\epsilon_0\}$ set to zero. The global stresses were used to calculate the principal stresses and directions.

The output consisted of the coordinates of the middle node, the global stresses, the principal stresses and directions, for each element in the mesh. A typical computer output is shown in Appendix D.

4.2 Input of Parameters and Elastic Constants

The material properties and other pertinent parameters entered as data are given below.

Concrete Liner

Modulus of Elasticity	3×10^6	psi
Cylinder Strength (f'_c)	4000	psi
Poisson's Ratio	0.15	

Steel Reinforcement

Modulus of Elasticity	30×10^6	psi
Poisson's Ratio	0.3	

Packing Material (Cellular Concrete)

Modulus of Elasticity	1.5×10^4	psi
Poisson's Ratio	0.1	

Surrounding Medium

Modulus of Elasticity	4.0×10^4	psi
Poisson's Ratio	0.33	

Inner Radius of Liner	36 in.
Outer Radius of Liner	44 in.
Radius of Tunnel Cavity	68 in.

A flow chart showing the logic of computations is shown on page 38 and a program for one of the cases considered is given in Appendix B.

CHAPTER V

DISCUSSION OF RESULTS

5.1 General

As mentioned in Chapter III, the output for each of the cases studied consisted of the stresses in the continuum together with the principal stresses and principal directions for each element of the mesh. The principal stresses were plotted, to a convenient scale, directly on the mesh and from these, contours of principal stress directions and contours of major and minor principal stresses were drawn. In the following few sections, the results obtained for each case will be discussed in turn.

5.2 Stress Distribution in Undisturbed Medium

This case was considered primarily to serve as a check on the computational procedures and the program developed. The finite element mesh was made up of square elements and the output for this case showed that the directions of the principal stresses coincided with the axes of the coordinate system used and that the principal stress in the Y-direction was 100 psi compression, as would be expected. No figures are given for this case as it is self-explanatory.

5.3 Stress Distribution Around an Unlined Tunnel Cavity

Figure 12 shows the relative magnitudes and the directions of principal stresses for this case. Figure 13 shows the direction contours of the principal stresses. In Figures 14 and 15 are given the contours of equal stresses of the major and minor principal stresses, respectively. These figures indicate that at distances far from the tunnel cavity, the minor principal stress is not appreciably different from the applied loading, both in magnitude and direction. The stresses at the crown, side and bottom of the tunnel are about 55 psi, 233 psi and 56 psi, all compression, respectively.

5.4 Stress Distribution Around a Tunnel with a Liner-Packing System

The magnitudes and directions of the principal stresses for this case are as shown in Figure 16. Figure 17 shows the direction contours of the principal stresses, and Figures 18 and 19 show contours of equal stress, of major and minor principal stresses. It is observed, again, that the stresses are all compressive and that the directions and magnitudes of the stresses at sections far from the tunnel boundary do not differ by a great deal from the applied loading of 100 psi. The maximum compressive stresses at the crown, the side, and bottom of the cavity are 77 psi, 130 psi, and 77 psi, respectively. The presence of a liner-packing system has increased the stresses at the crown and bottom of the cavity by about 40%, while the stresses on the side have been reduced by about 45%, compared to those of an unlined tunnel. The compressive stresses in the packing at the crown, the side and the bottom of the cavity are about 80 psi, 42 psi and 77 psi, respectively.

5.5 Stress Distribution Around a Tunnel with a Cracked Liner

There were two studies made of this case; a liner with just one crack at the crown and a liner with three cracks, one at the crown and one on each side of the crown along a radial line making an angle of 30° with the vertical through the crown. The cracks were introduced into the liner by specifying the ultimate moment that would develop at the section when it fails. The moment is produced by a couple whose forces are applied at the nodes of the steel elements. The two cases are discussed separately.

5.5.1 Liner with One Crack

Figure 20 shows the principal stresses and their directions plotted on the mesh. Contours of principal stress directions and contours of equal stresses for the major and minor stresses are shown in Figures 21, 22, and 23. The stresses far from the cavity are about the same as the applied compressive stress of 100 psi. The compressive stresses at the crown, side, and bottom of the cavity are about 124 psi, 128 psi, and 90 psi, respectively. The crack at the crown of the liner has increased the stresses there by about 60%, at the bottom of the cavity by about 15%, but has not affected the side stresses as compared to those of an uncracked liner. The stresses far from the cavity are still nearly equal to the applied loading. Compressive stresses in the packing range from 130 psi to 320 psi for elements at the crown, about 42 psi at the side, and about 100 psi at the bottom.

5.5.2 Liner with Three Cracks

In Figure 24, the magnitude and directions of the principal stresses are given. Figure 25 shows the direction contours, and Figures 26 and 27 show the equal stress contours for the principal major and minor stresses. Far from the cavity, the stresses are nearly the same as the applied loads. Some tensile stresses have developed at the cavity boundary about 25° - 30° from the crown and the maximum tensile stress produced is about 122 psi. The maximum compressive stress in the crown, the sides, and the bottom are 530 psi, 120 psi, and 86 psi. While there are no appreciable increases in the stresses on the side and bottom of the cavity, there seems to be a sharp rise in the stress at the crown. The stresses in the packing at the crown range from 600 psi to 1400 psi, about 60 psi at the side, and about 88 psi at the bottom.

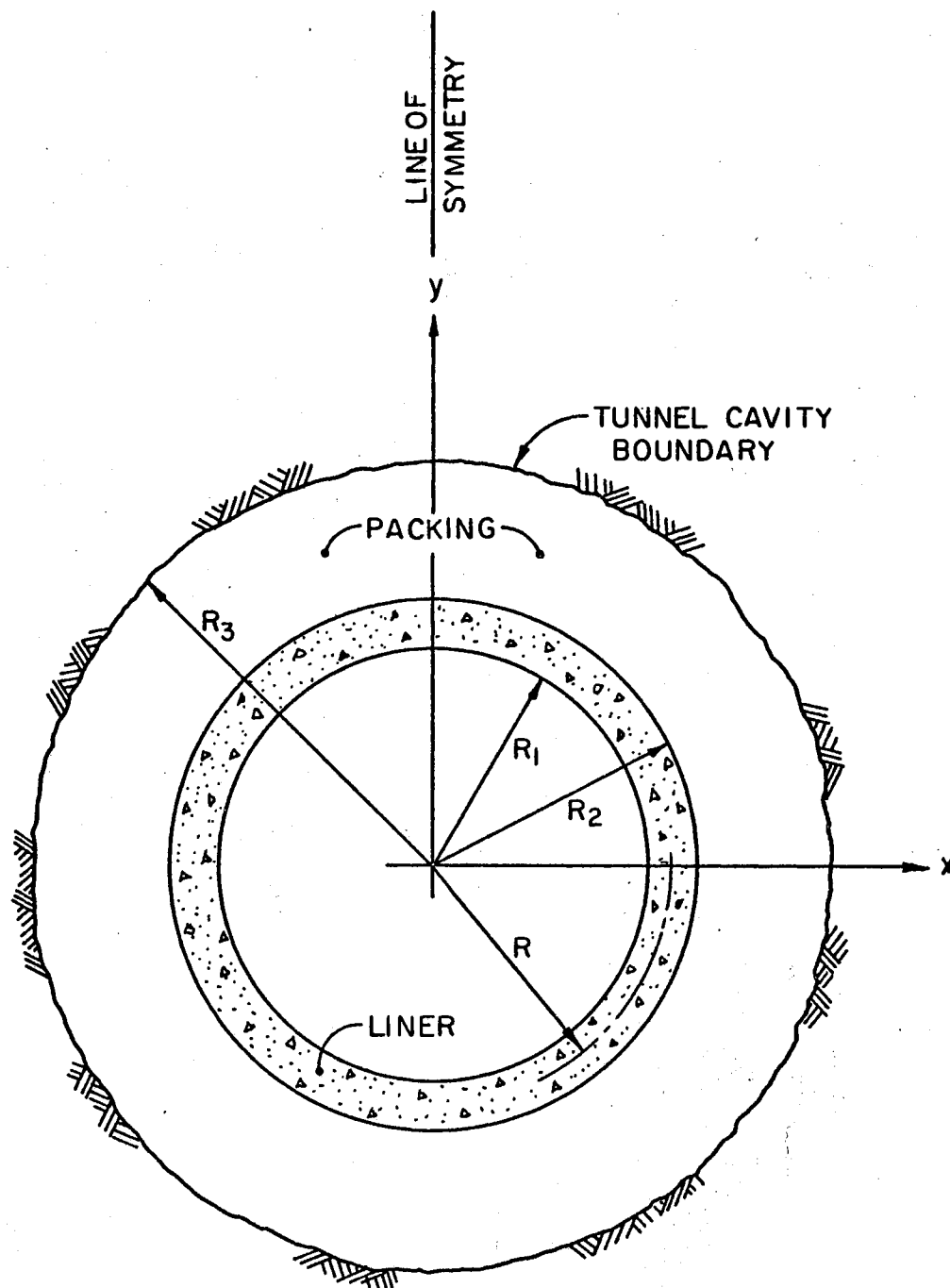


Figure 1. Liner-Packing System

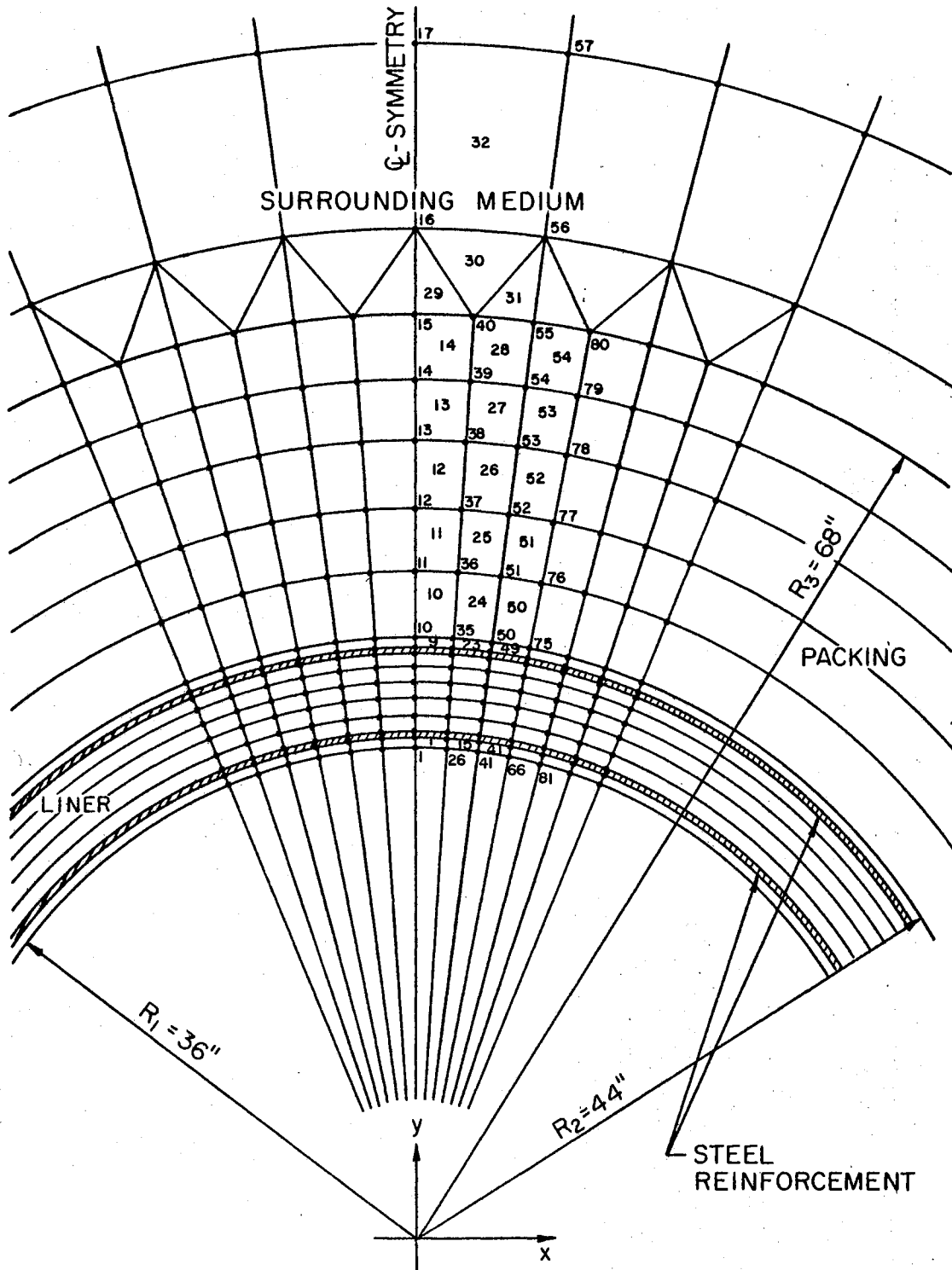


Figure 2. Finite Element Idealization of Liner-Packing System

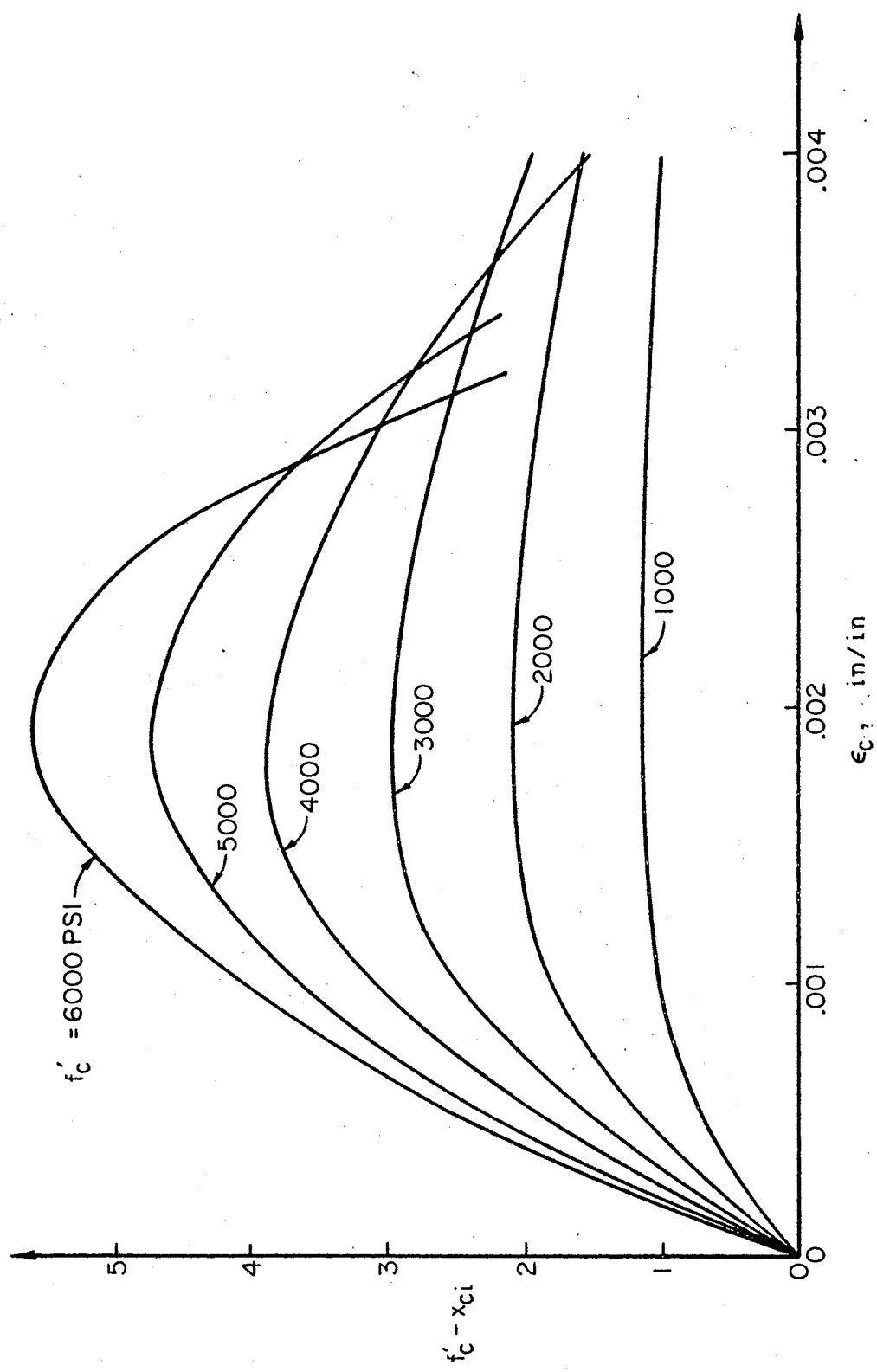


Figure 3. Typical Concrete Stress-Strain Curve

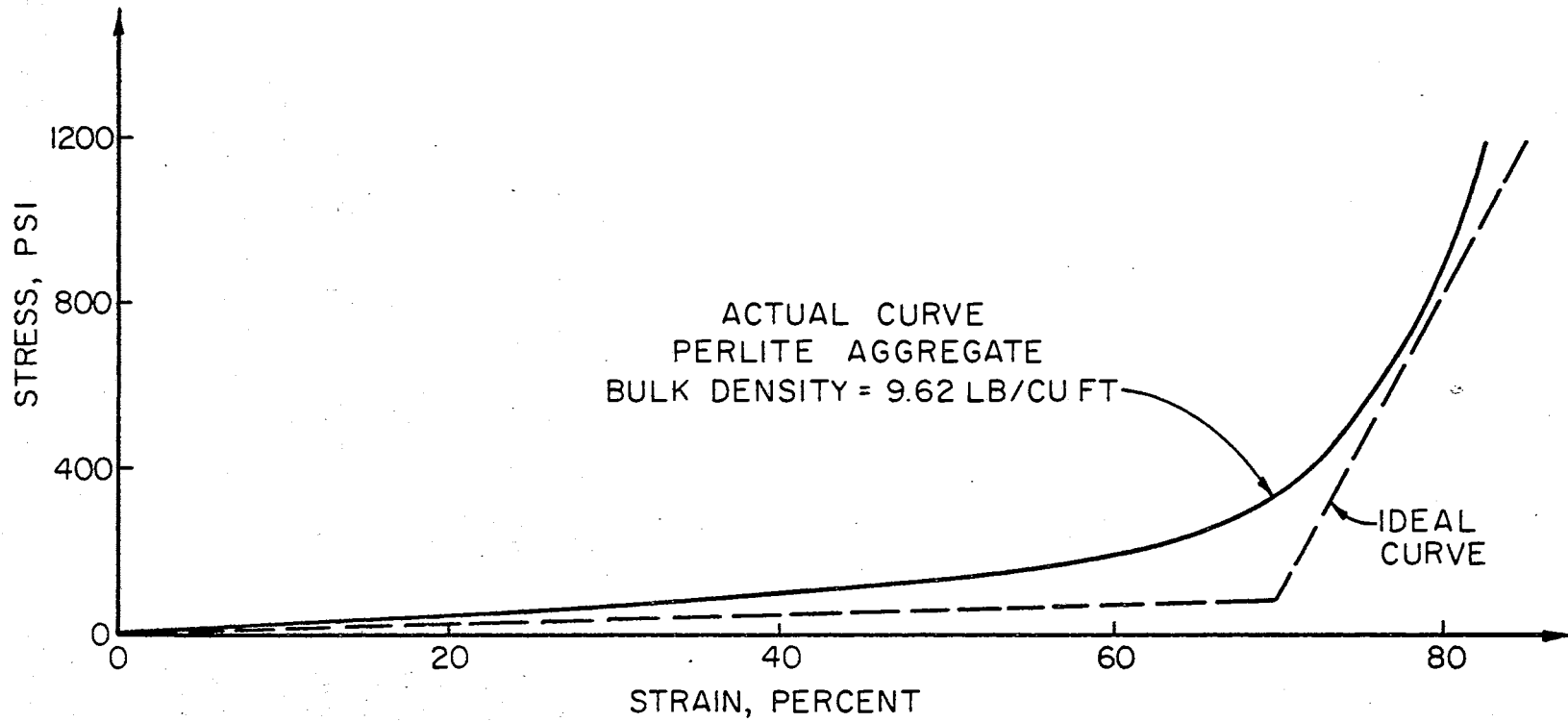


Figure 4. Typical Stress-Strain Curve for a Plasto-Elastic Material.

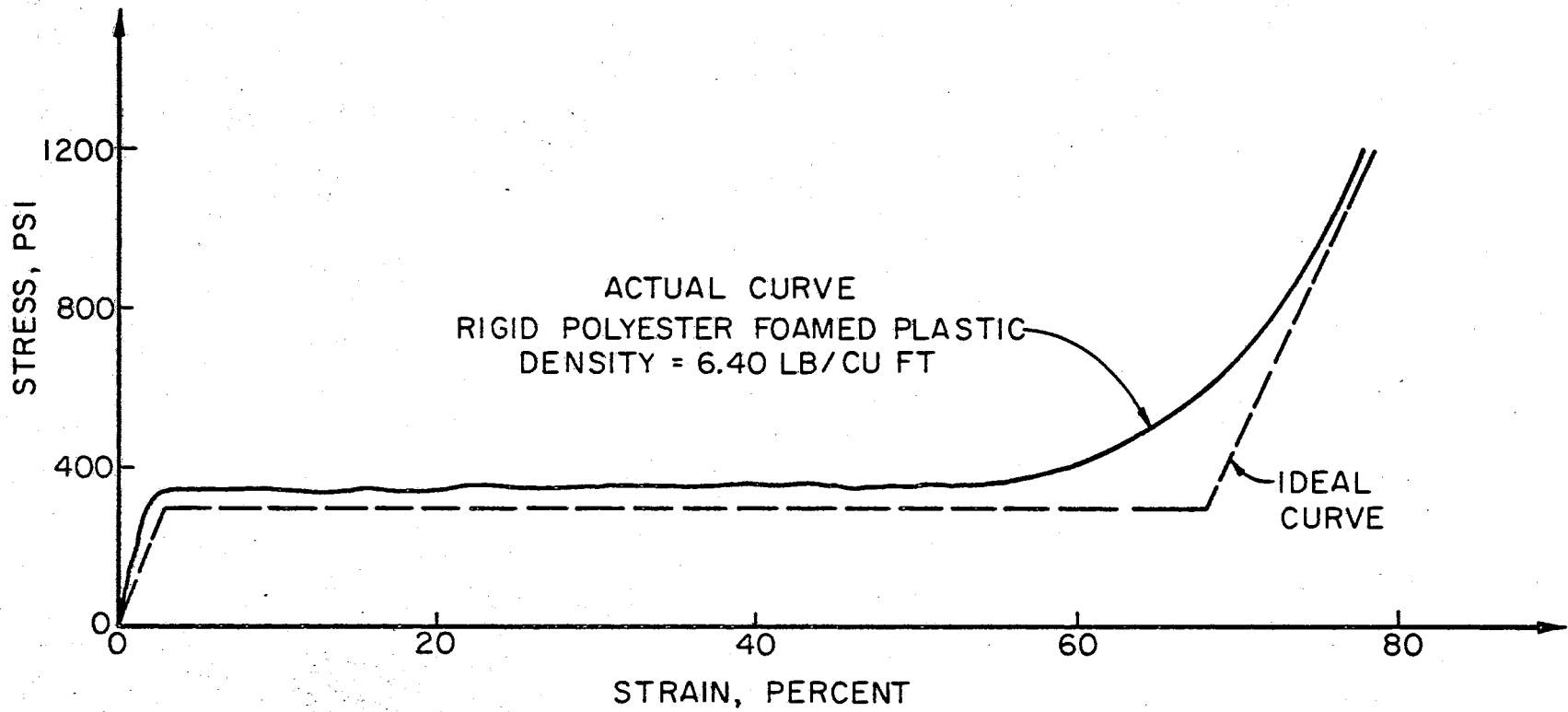


Figure 5. Typical Stress-Strain Curve for an Elasto-Plastic Material

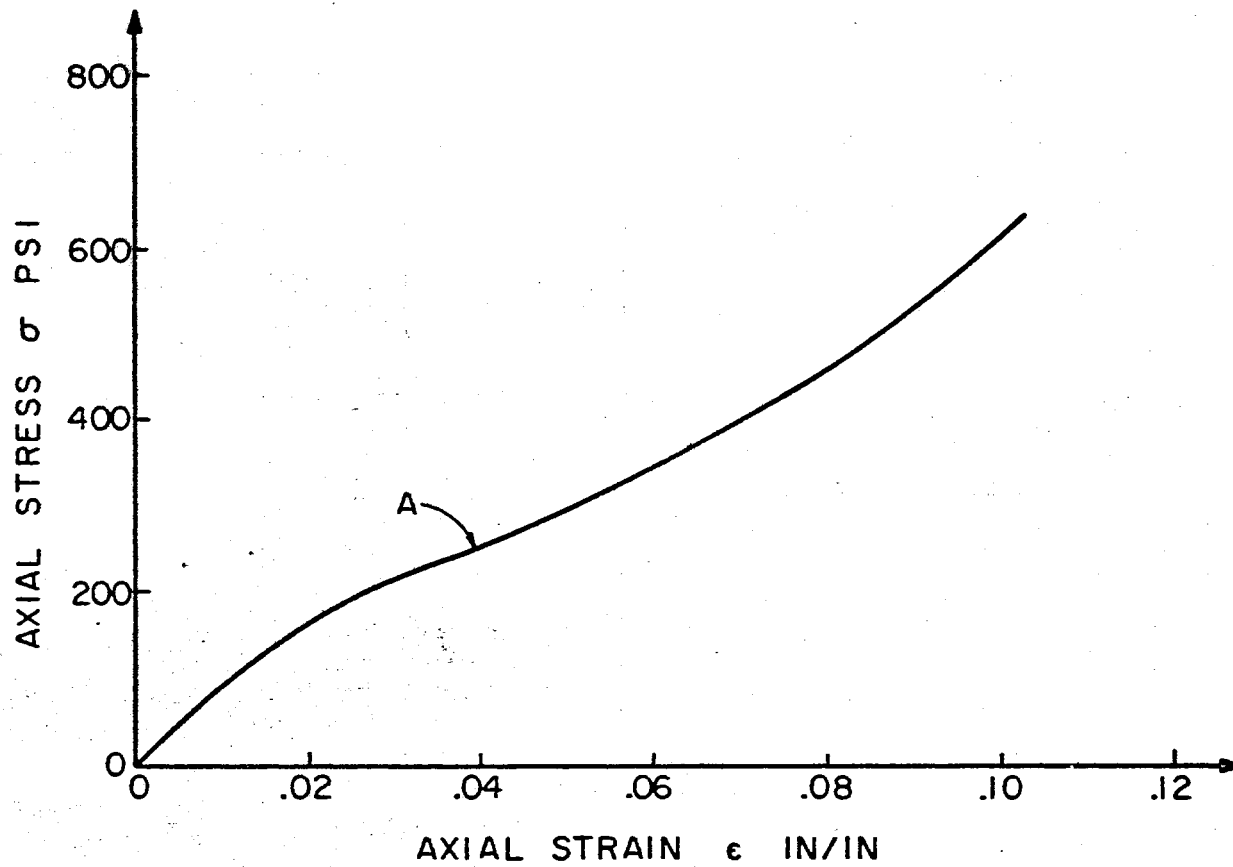


Figure 6. Stress-Strain Curve for Playa Silt in One-Dimensional Compression

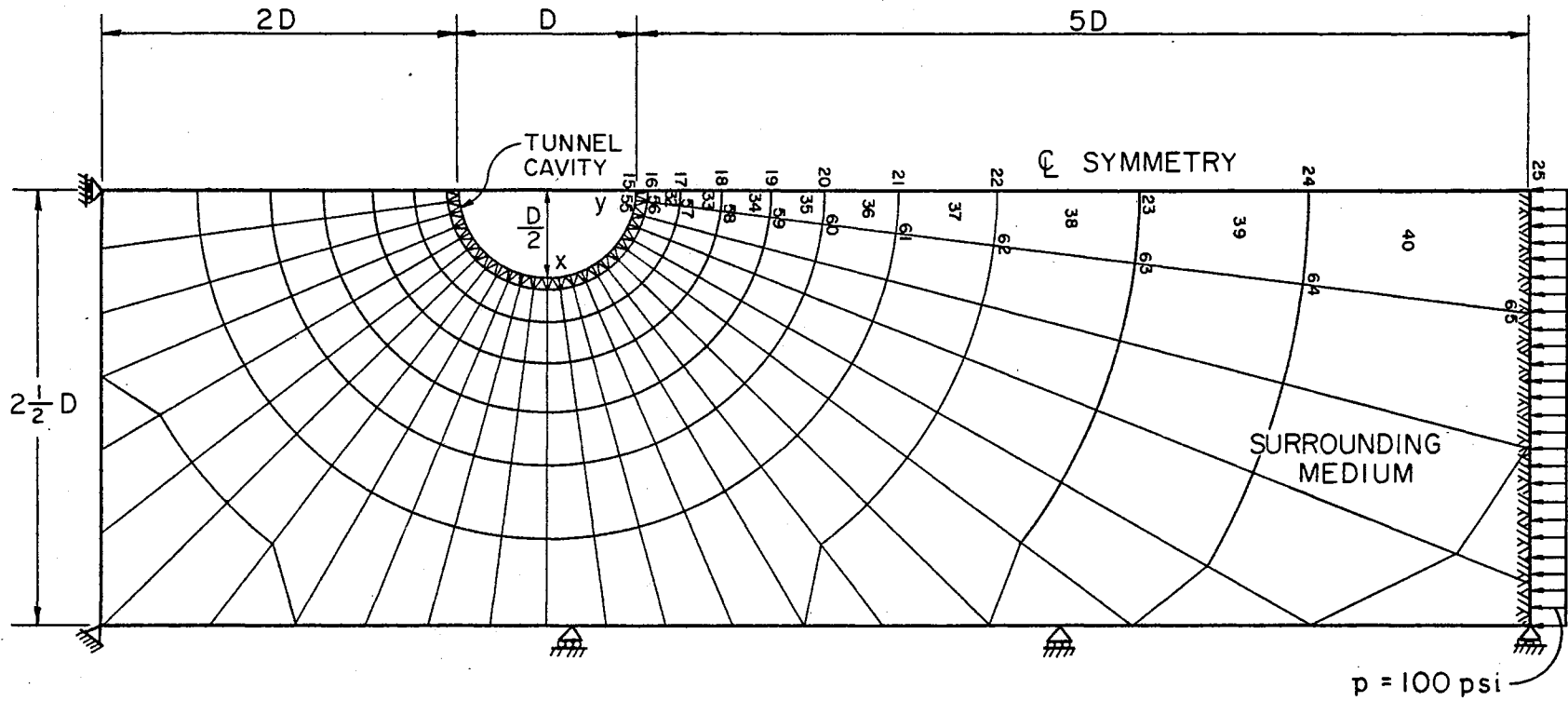


Figure 7. Finite Element Idealization of Surrounding Medium (Tunnel with Liner-Packing System)

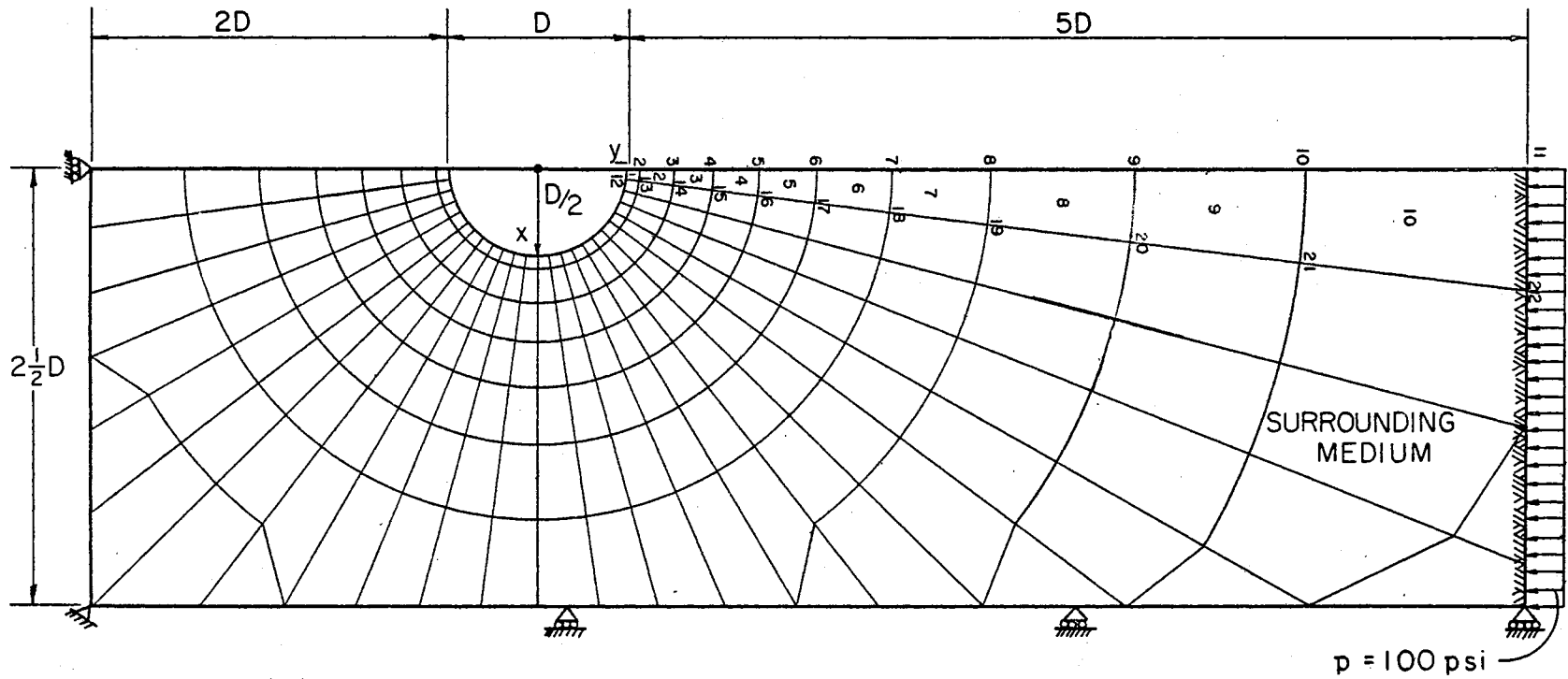


Figure 8. Finite Element Idealization of Surrounding Medium (Tunnel without Liner)

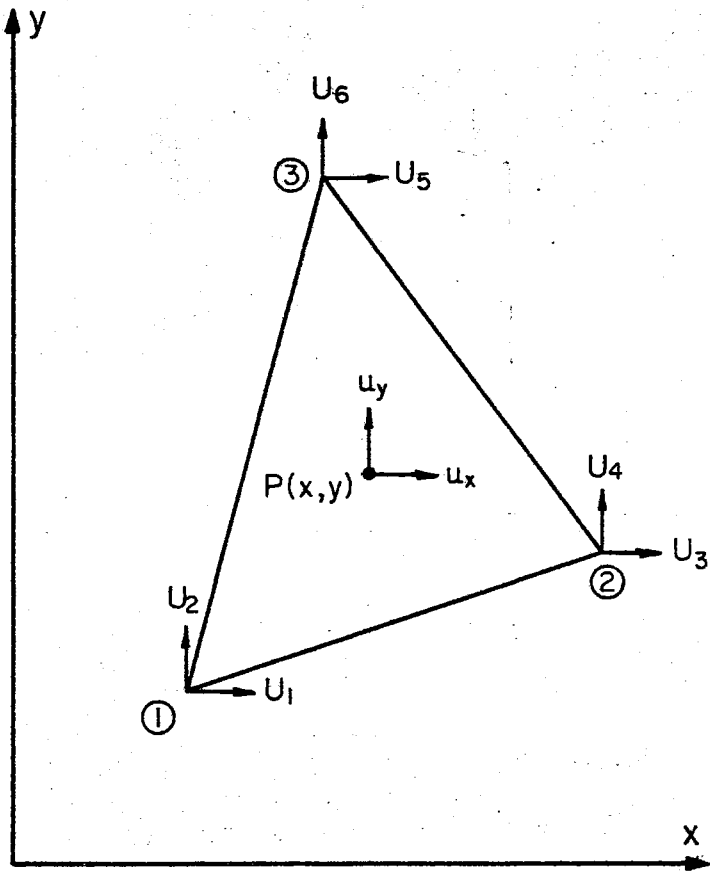


Figure 9. Triangular Element

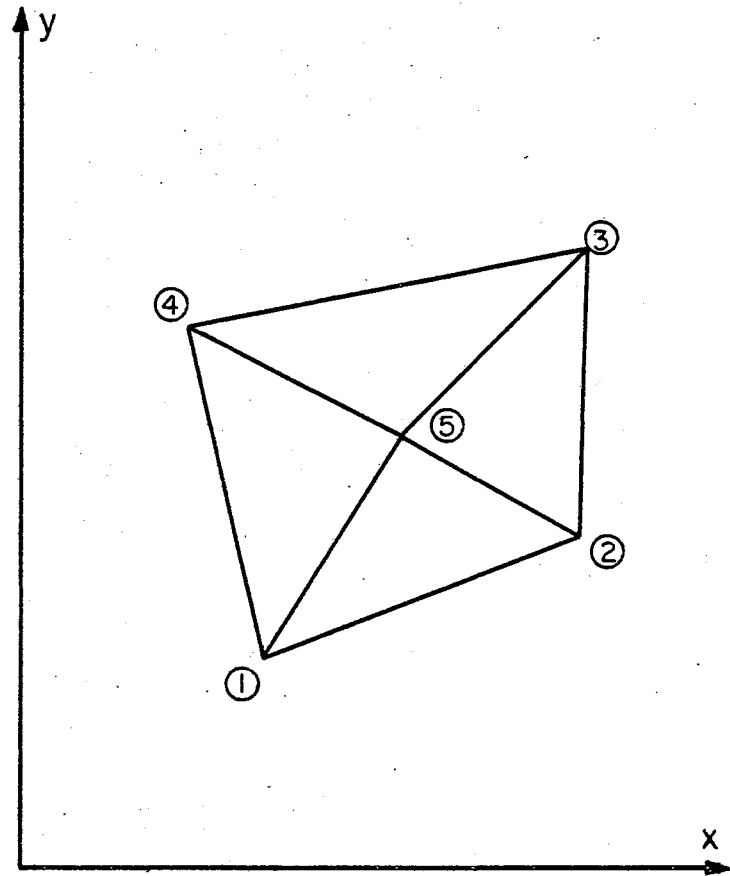


Figure 10. Quadrilateral Element

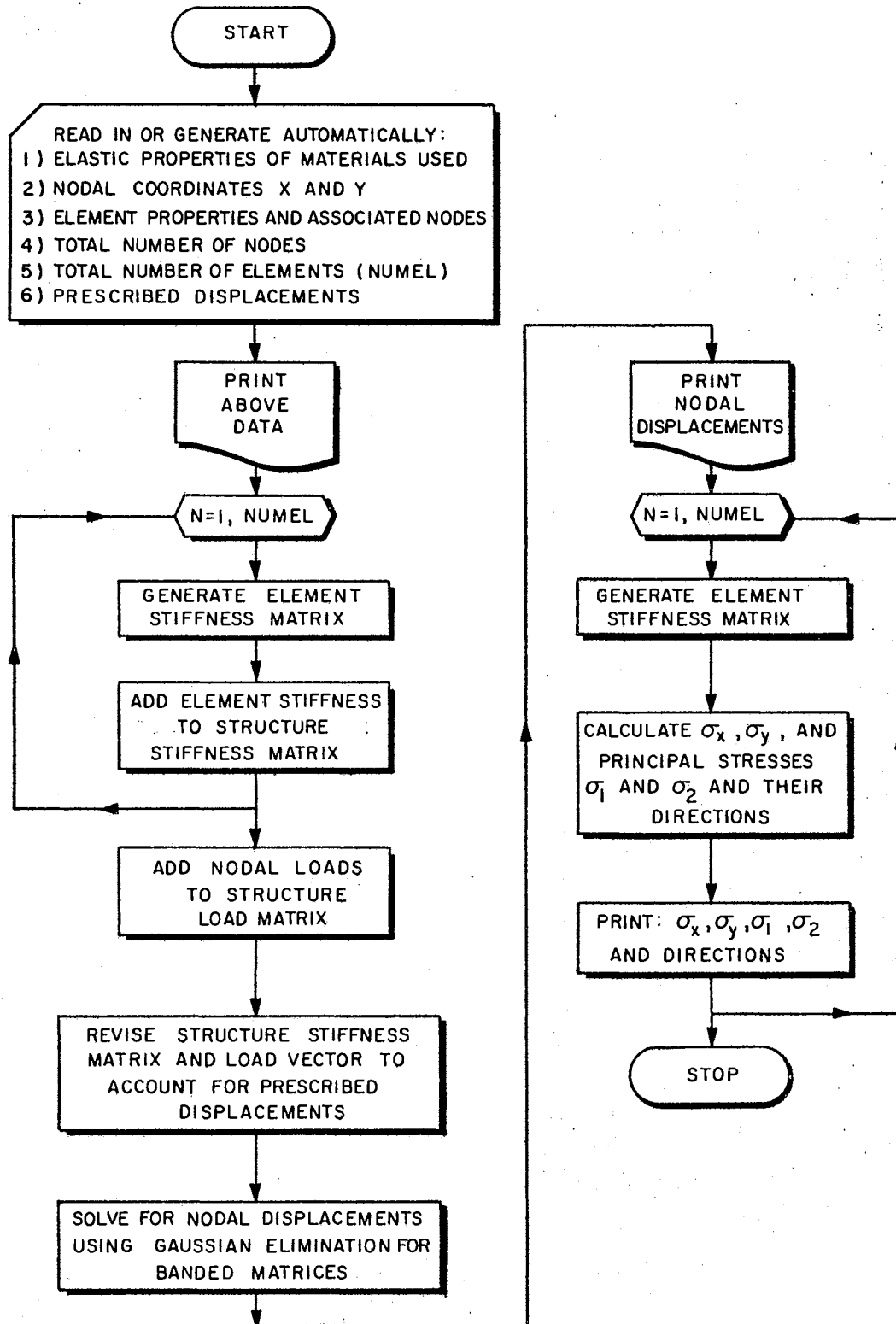


Figure 11. Flow Chart for Computer Program

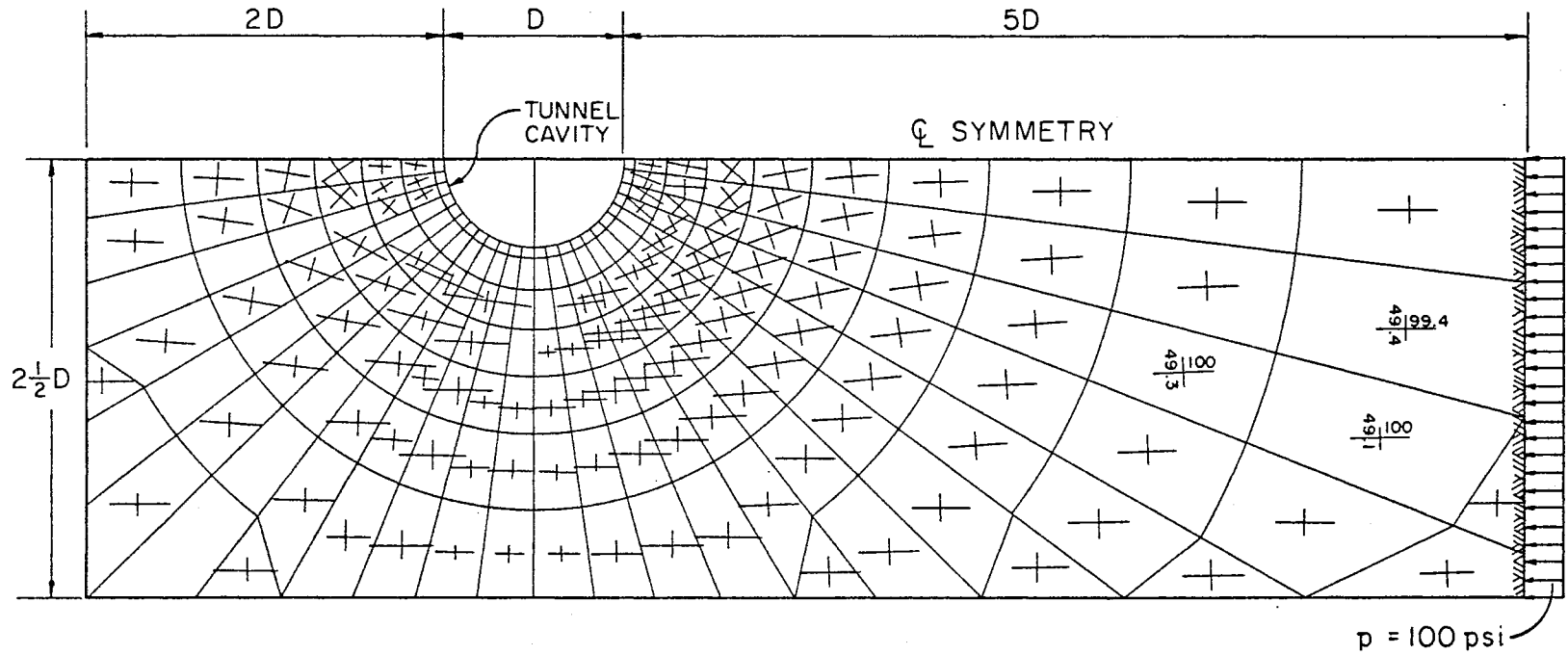


Figure 12. Principal Stresses in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel without Liner)

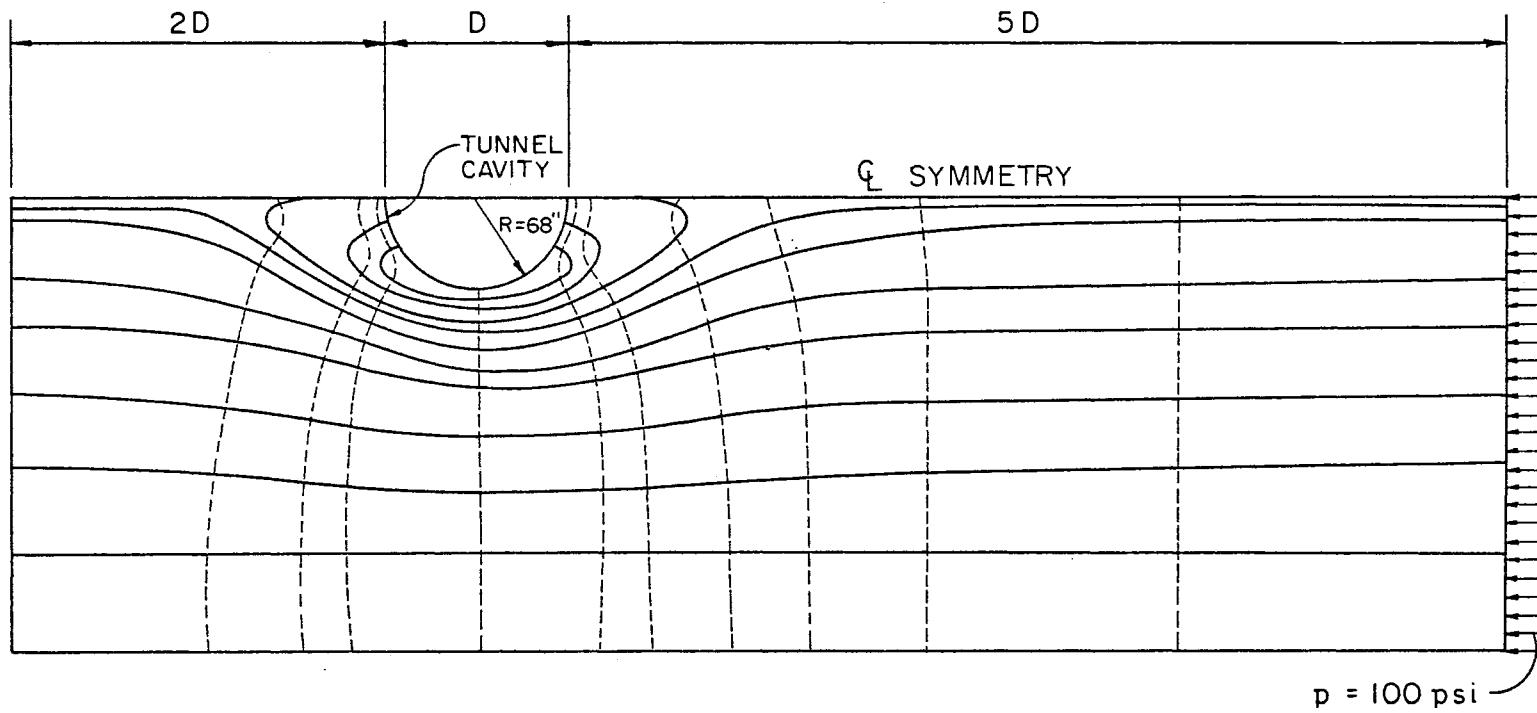


Figure 13. Principal Stress Directions in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel without Liner)

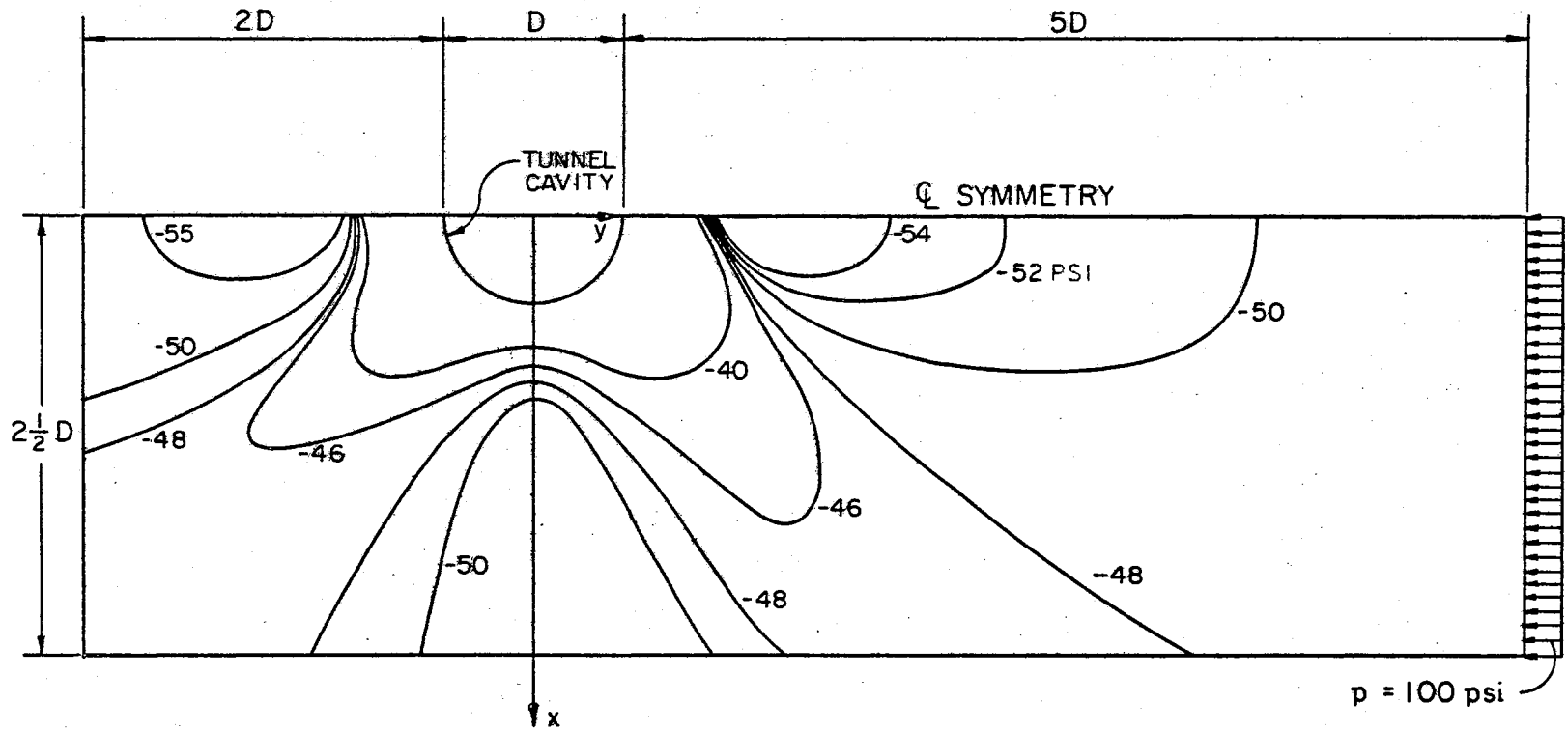


Figure 14. Major Principal Stress in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel without Liner)

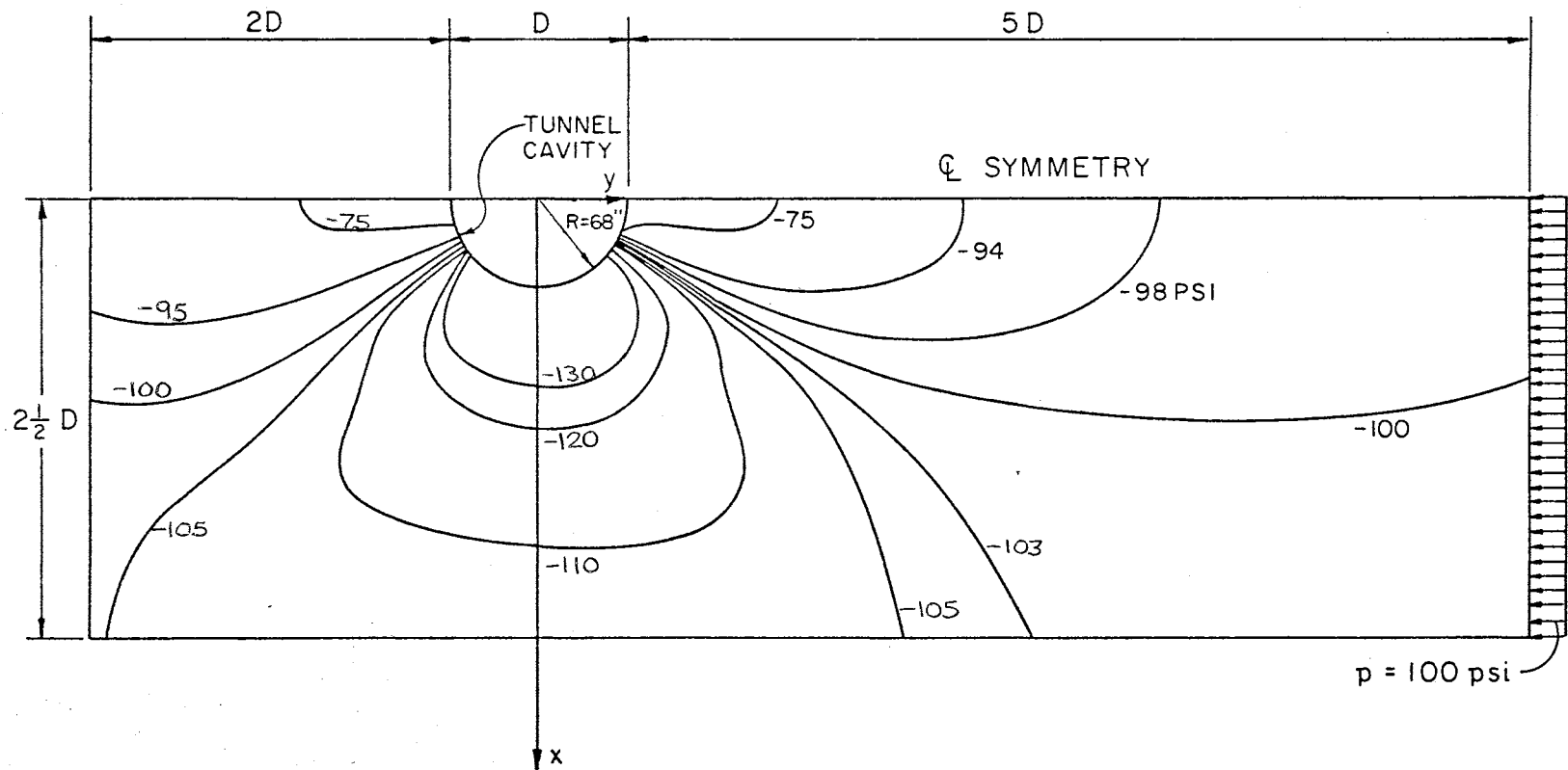


Figure 15. Minor Principal Stress in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel without Liner)

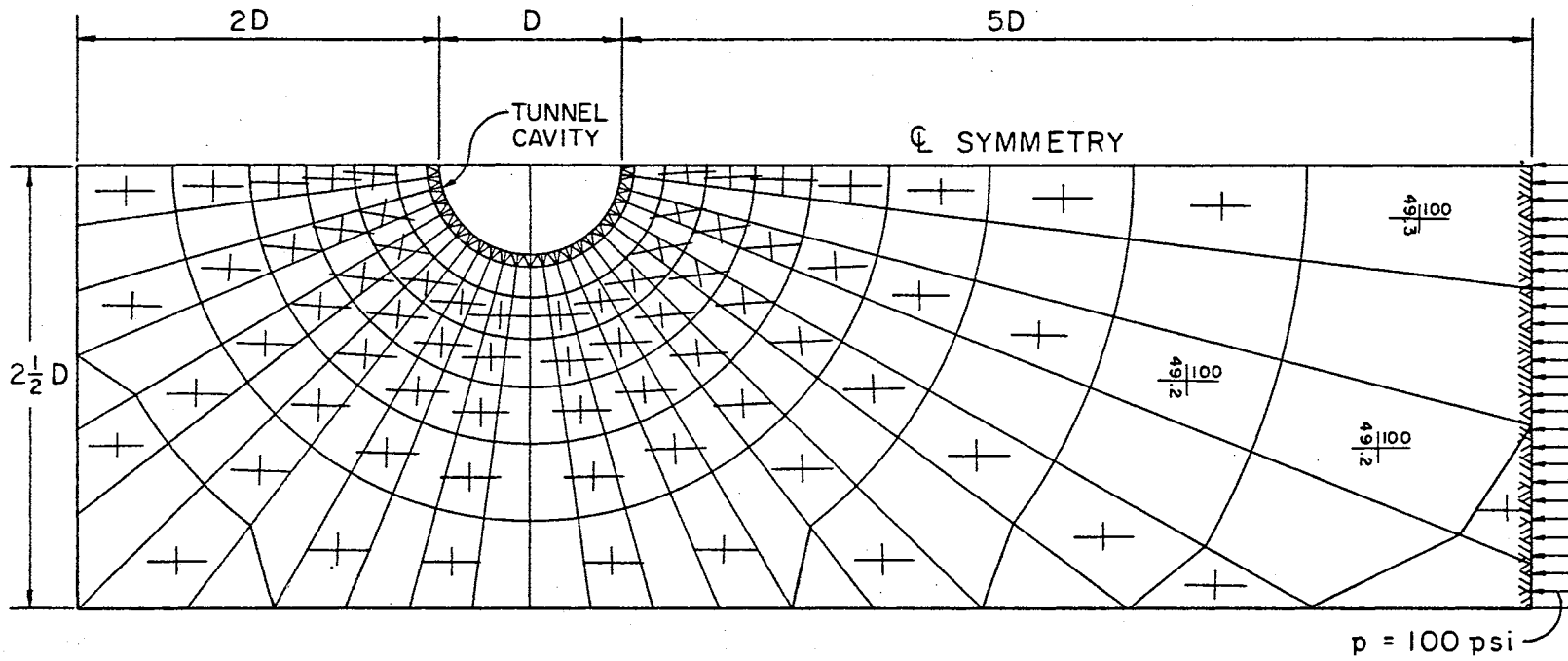


Figure 16. Principal Stresses in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel with Liner-Packing System)

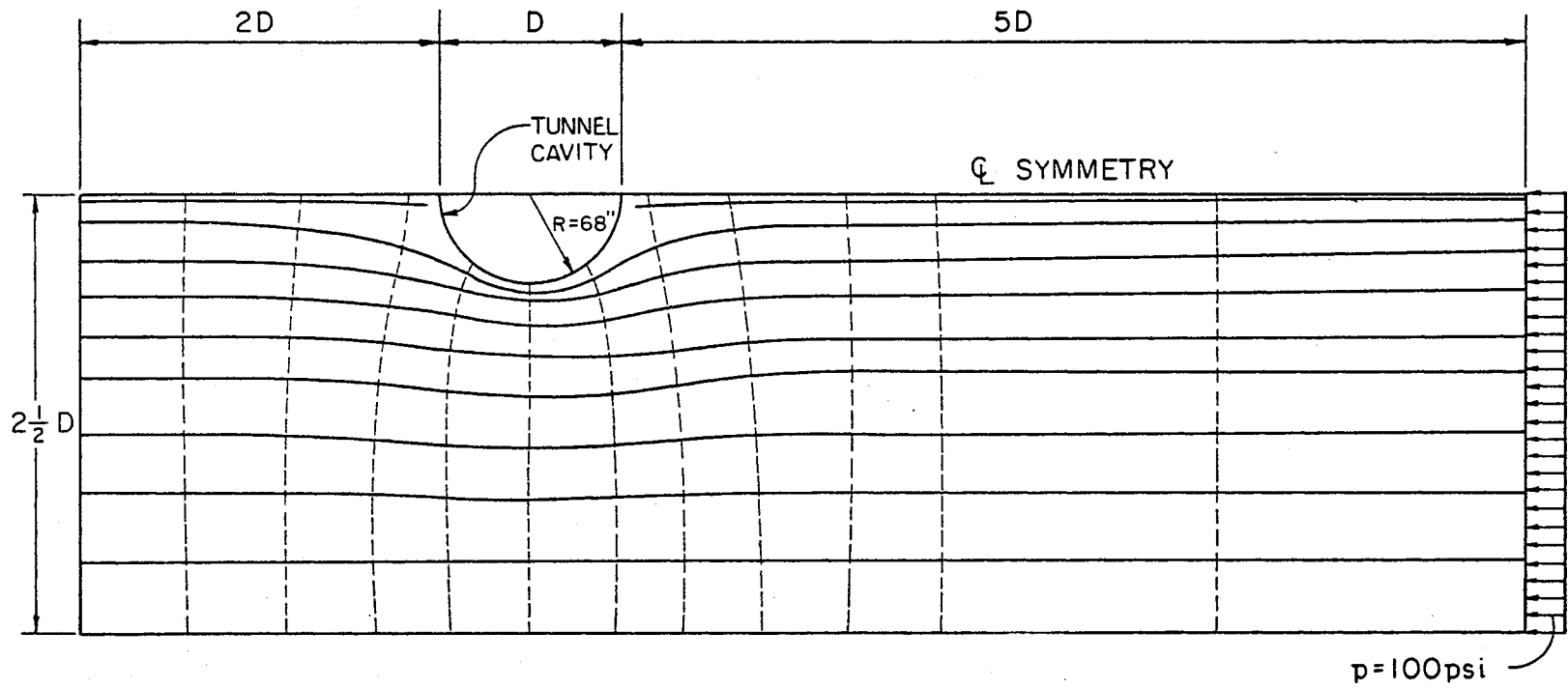


Figure 17. Principal Stress Directions in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel with Liner-Packing System)

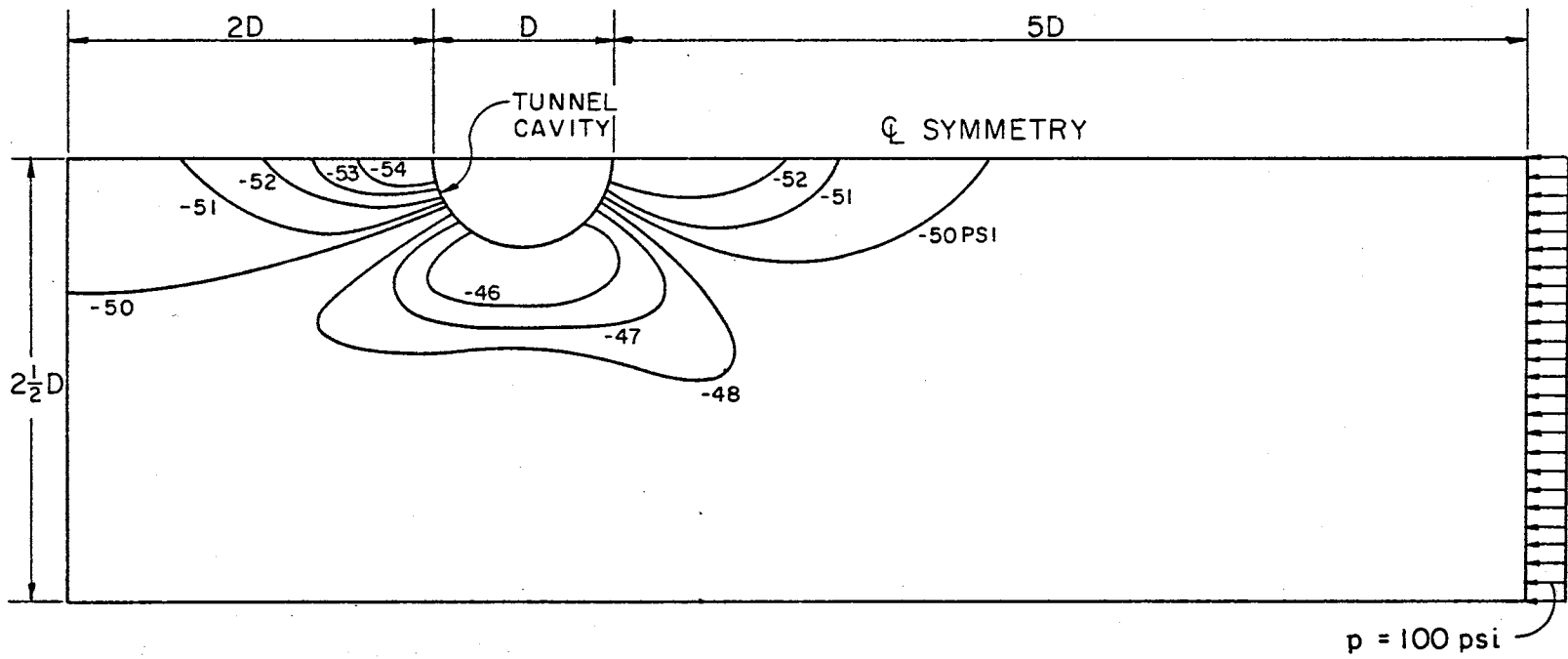


Figure 18. Major Principal Stress in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel with Liner-Packing System)

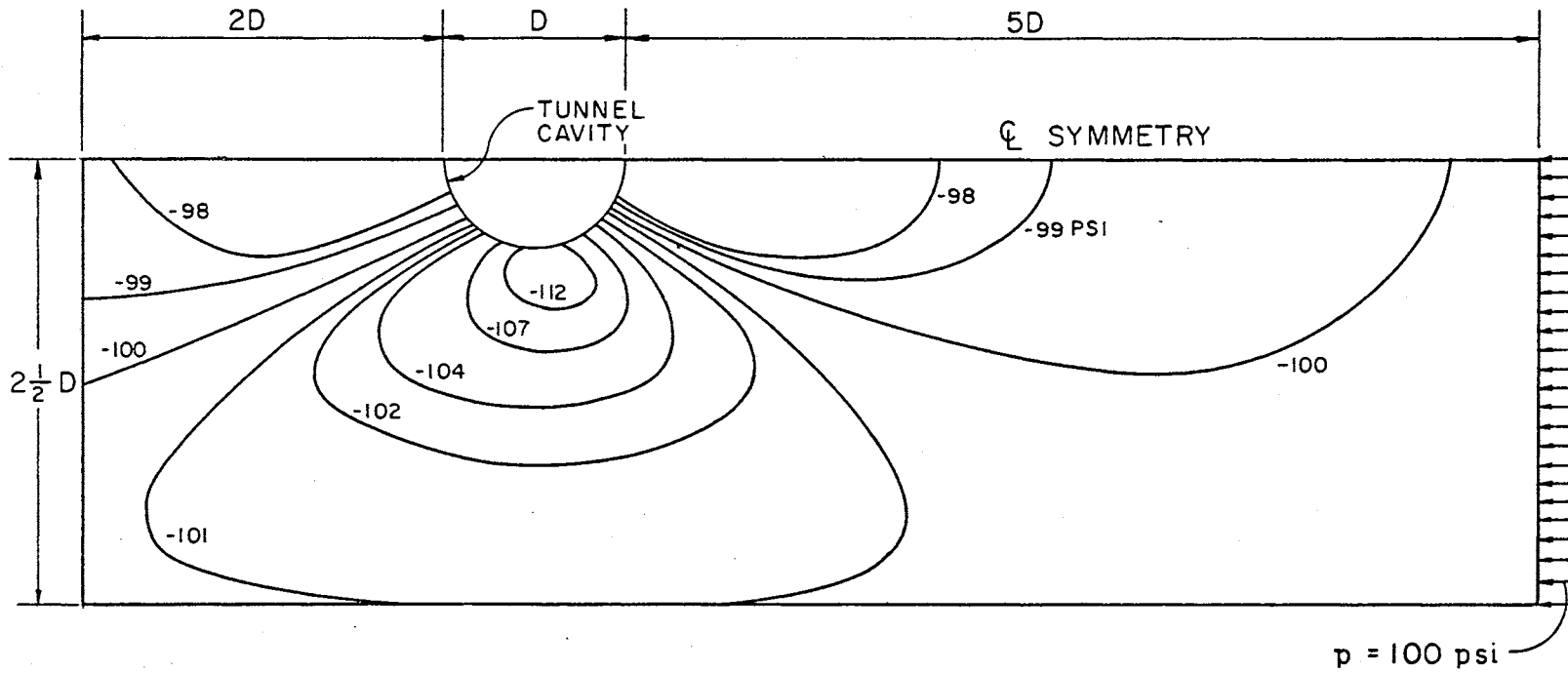


Figure 19. Minor Principal Stresses in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel with Liner-Packing System)

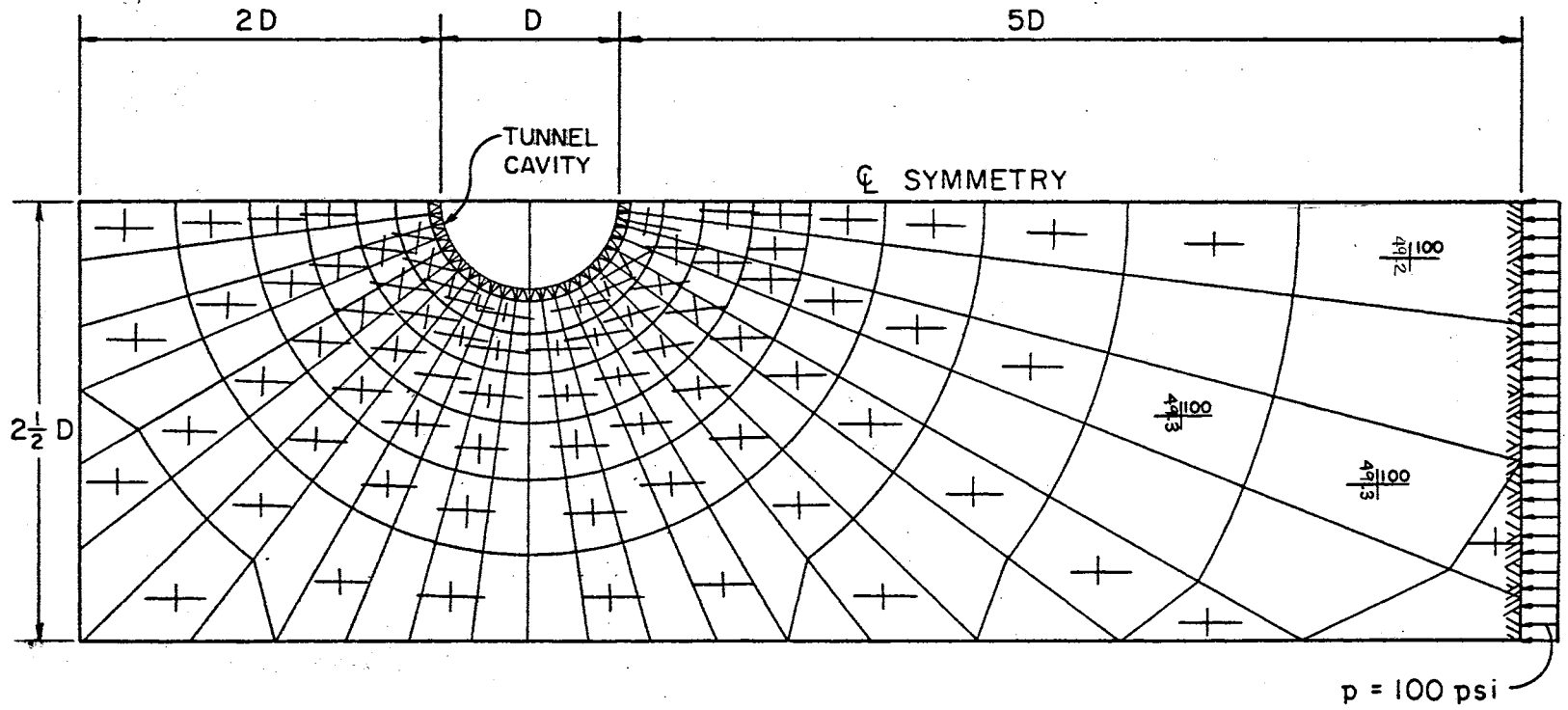


Figure 20. Principal Stresses in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel with Cracked Liner--One Crack)

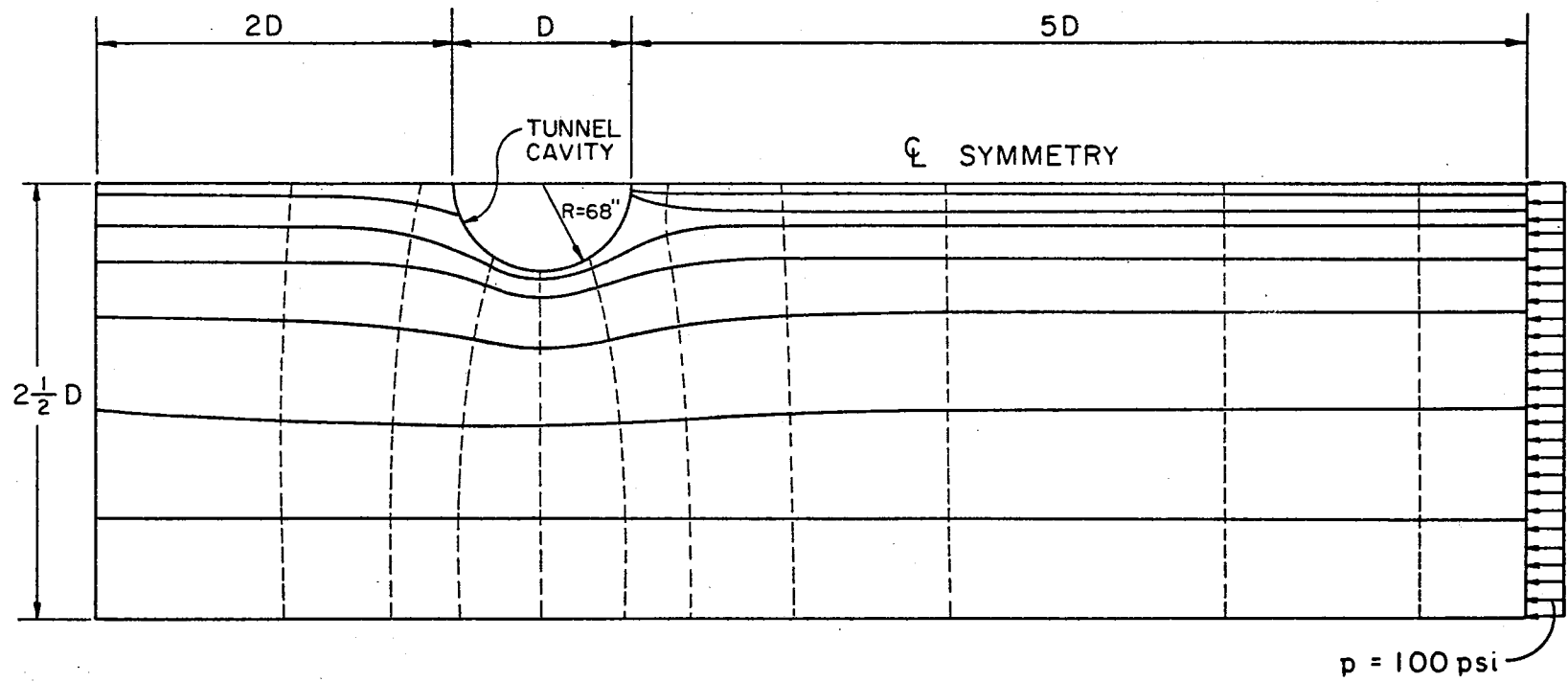


Figure 21. Principal Stress Directions in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel with Cracked Liner--One Crack)

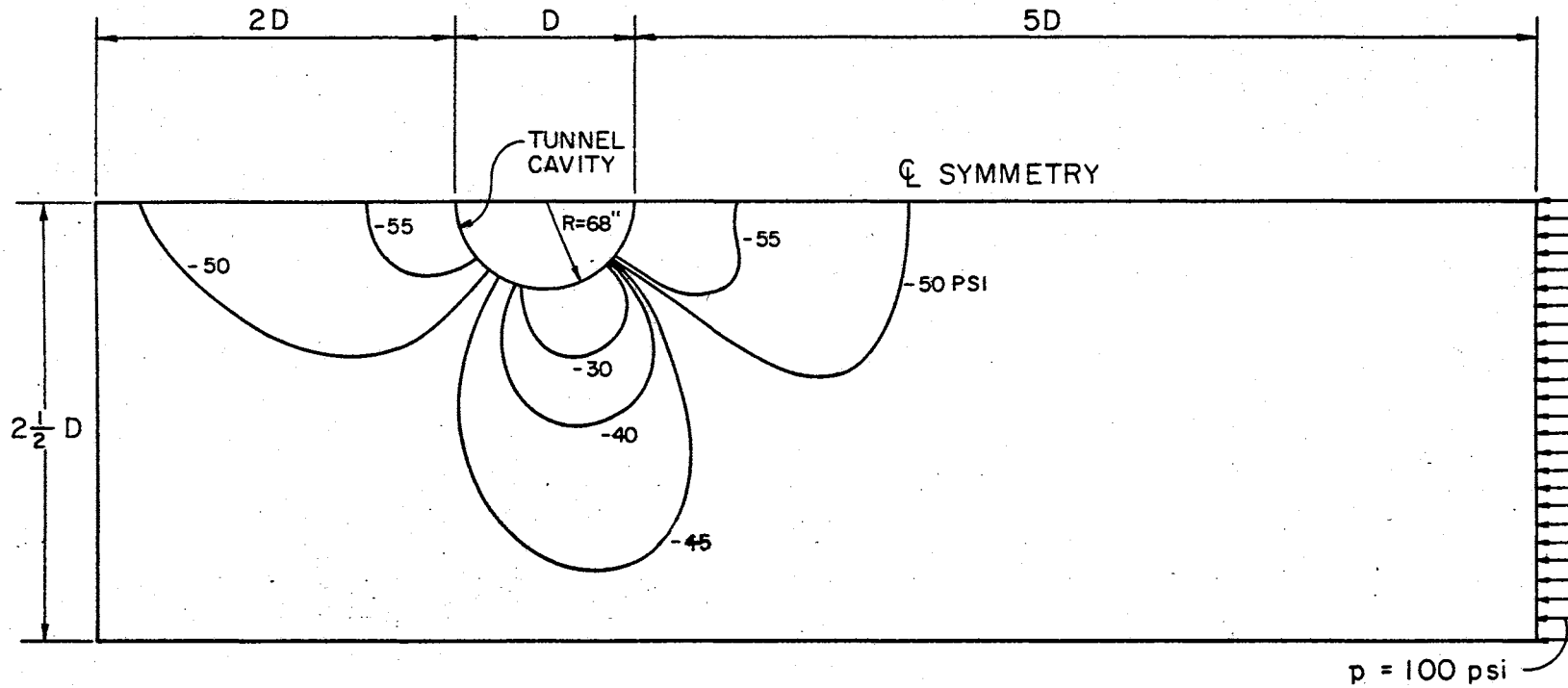


Figure 22. Major Principal Stresses in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel with Cracked Liner--One Crack)

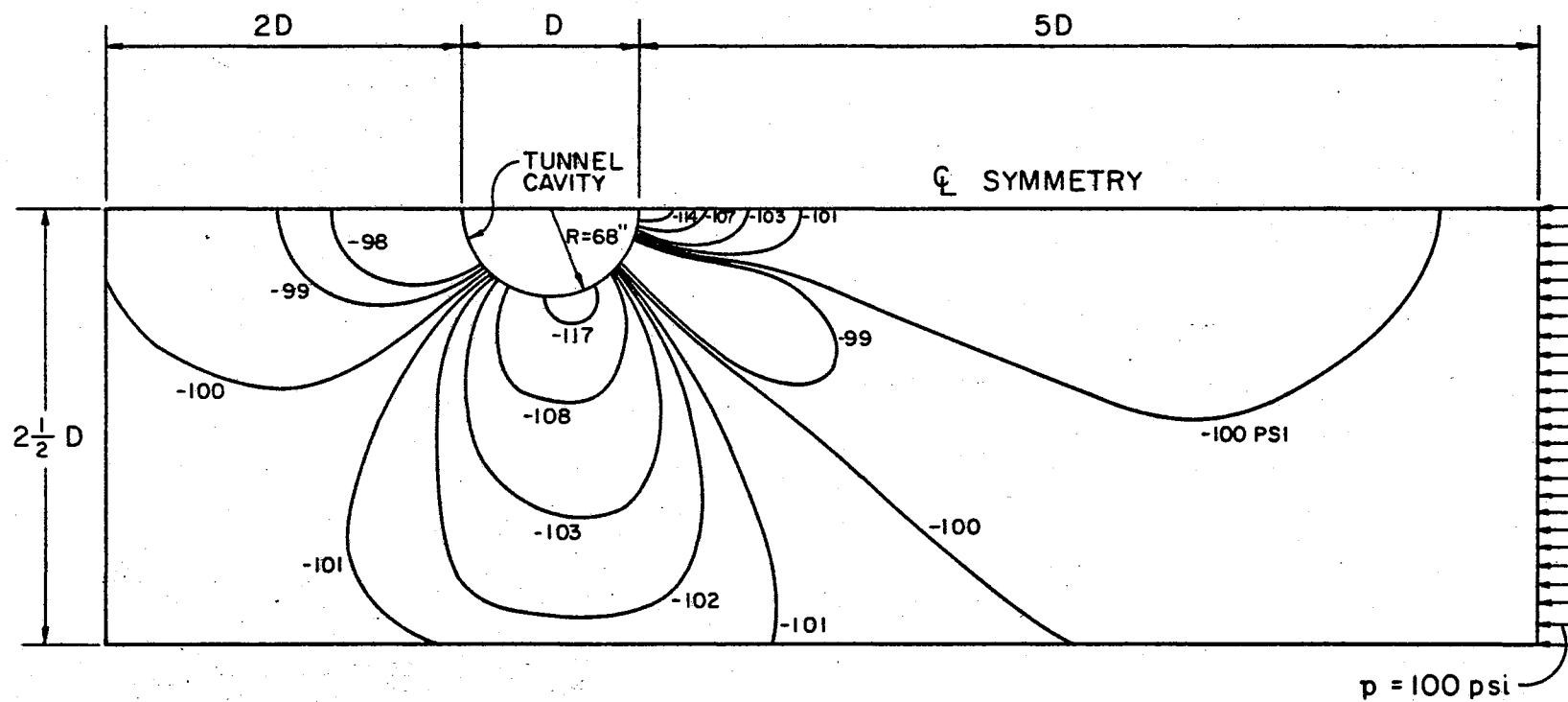


Figure 23. Minor Principal Stresses in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel with Cracked Liner--One Crack)

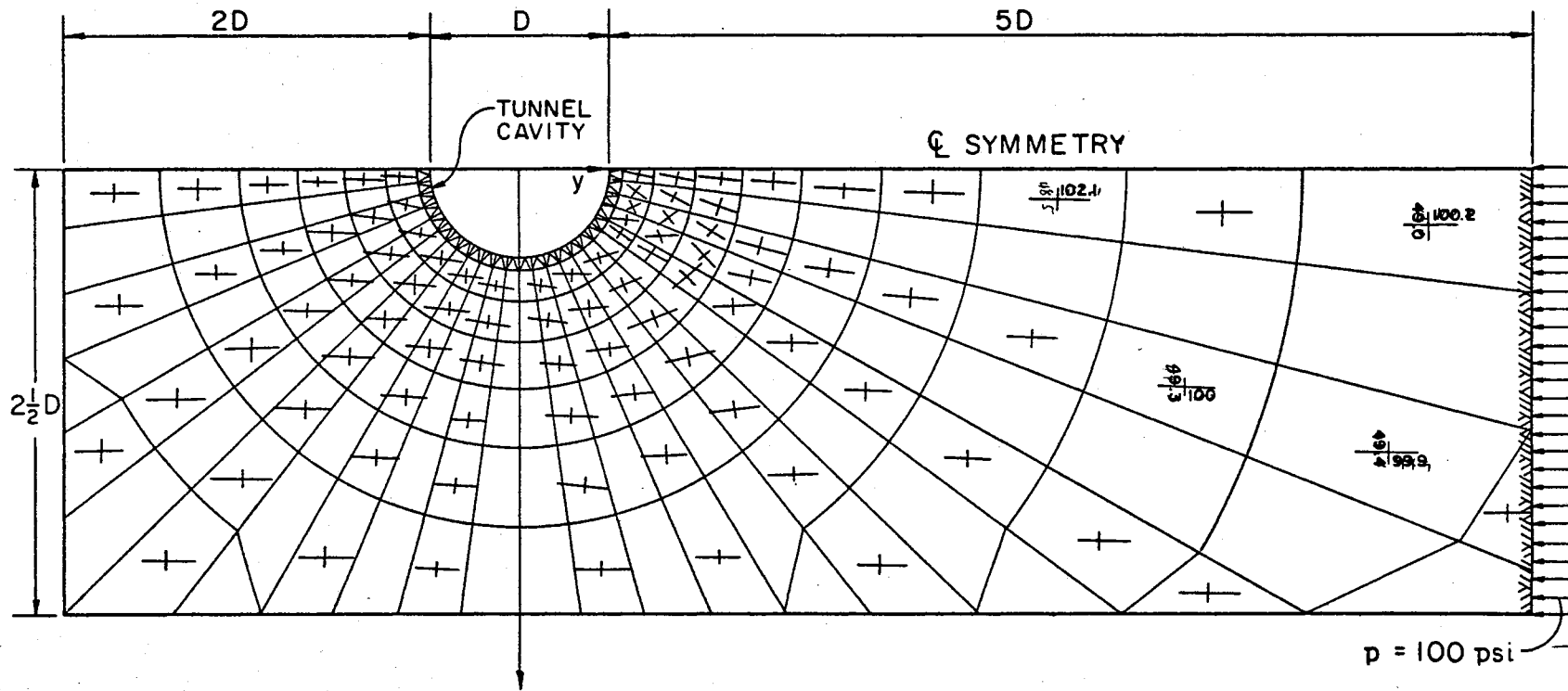


Figure 24. Principal Stresses in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel with Cracked Liner--Three Cracks)

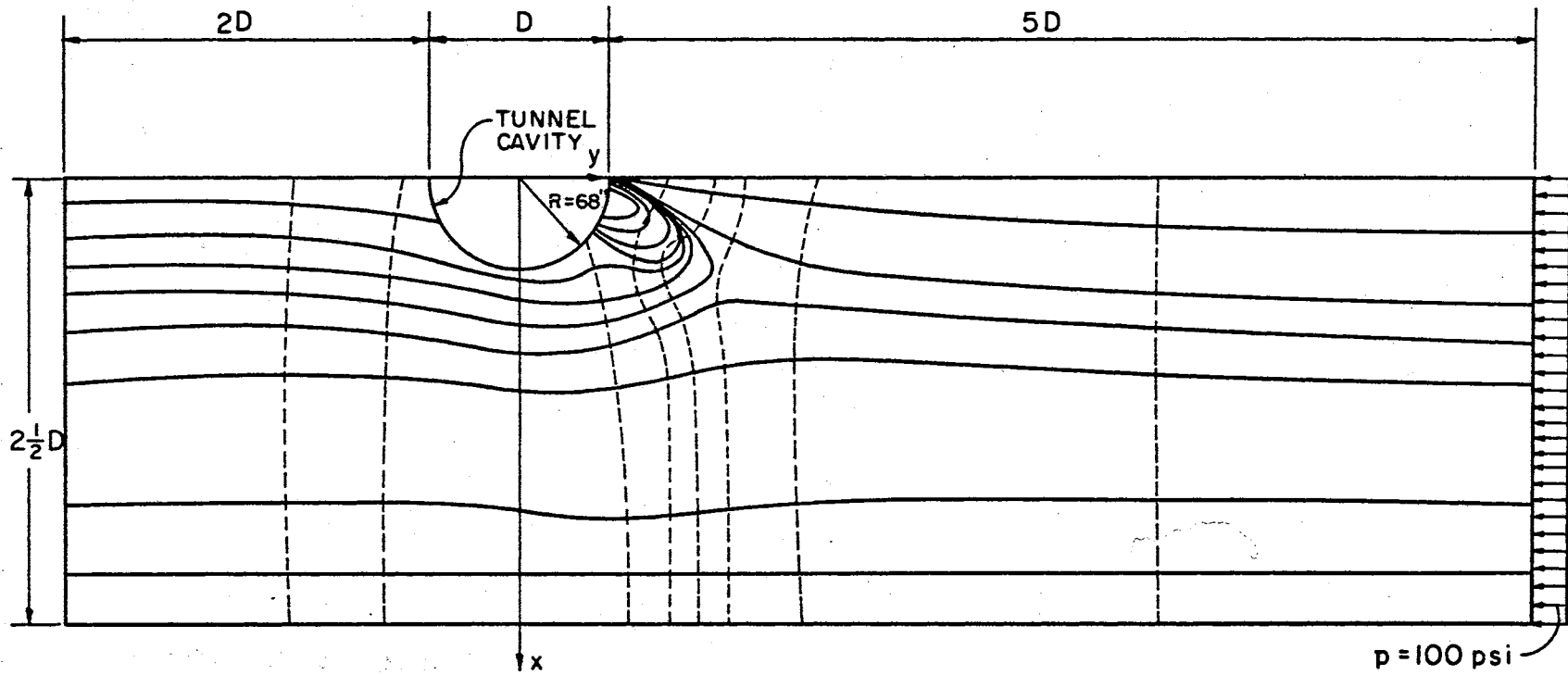


Figure 25. Principal Stress Directions in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel with Cracked Liner--Three Cracks)

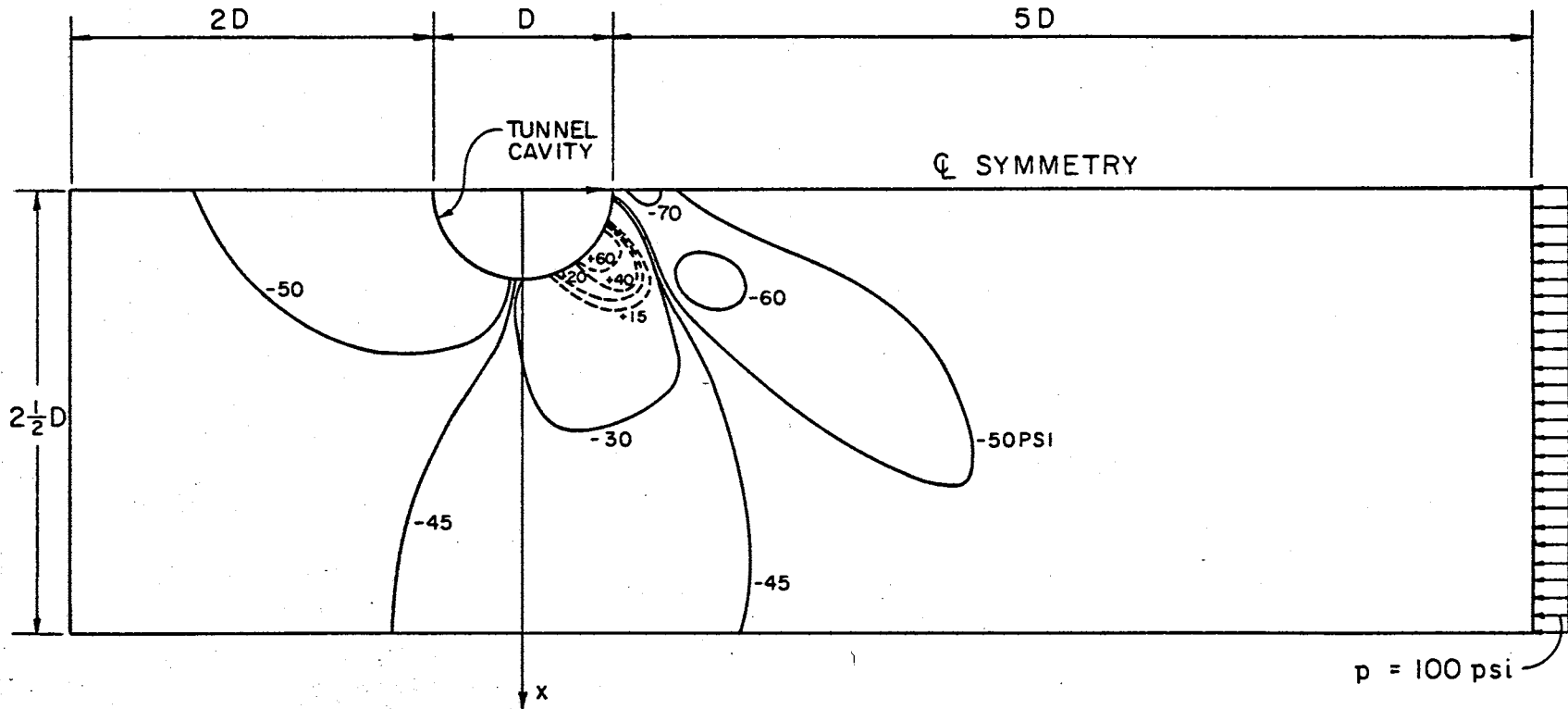


Figure 26. Major Principal Stresses in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel with Cracked Liner--Three Cracks)

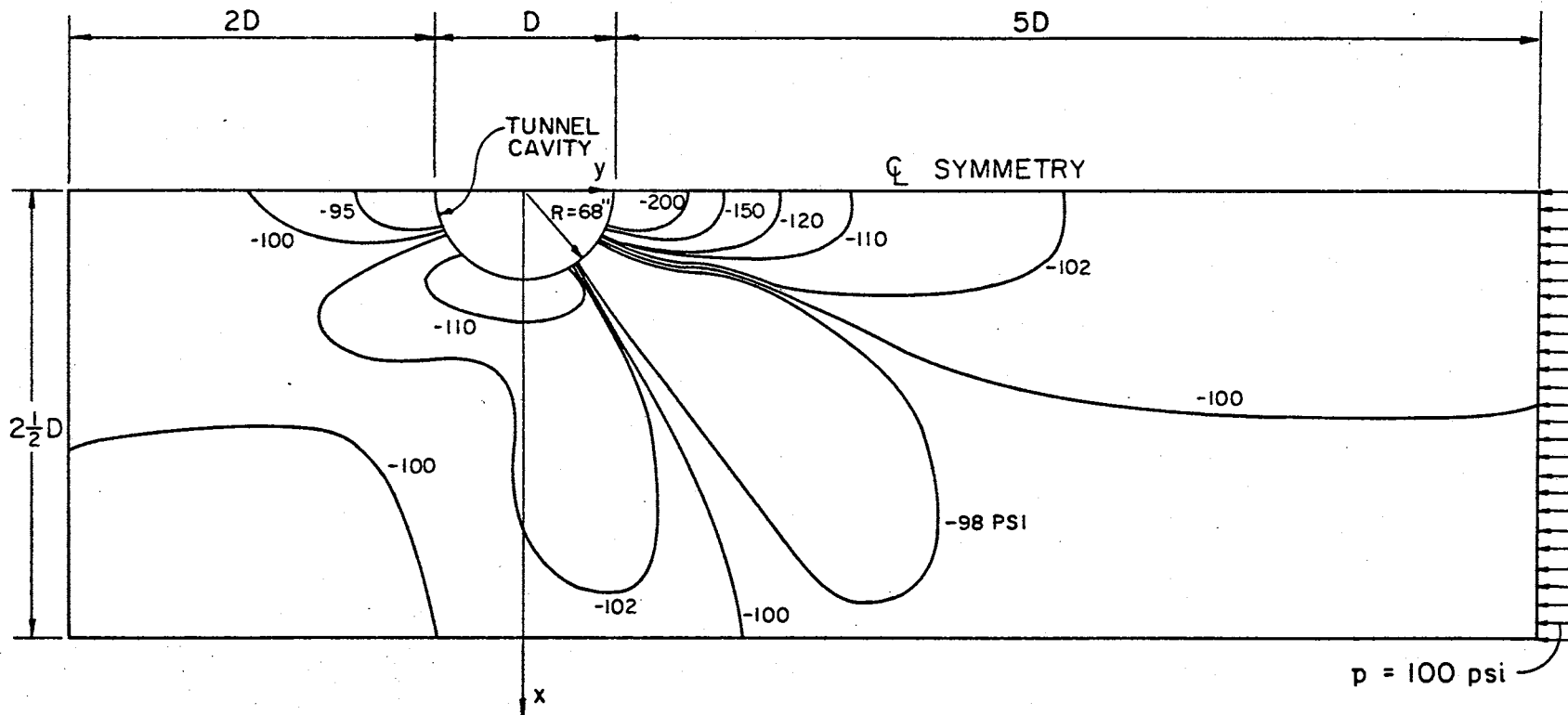


Figure 27. Minor Principal Stresses in Surrounding Medium due to a Uniform Over-Pressure of 100 psi (Tunnel with Cracked Liner--Three Cracks)

CHAPTER VI

SUMMARY AND CONCLUSIONS

6.1 Summary

The objective of this study was to evaluate the feasibility of using the finite element method in the investigation of stress distribution around a tunnel cavity with or without lining due to a uniform overpressure applied at the surface of the surrounding medium, under conditions of plane strain. It was assumed that the tunnel was at a depth of 5 tunnel diameters, which was just over 28 feet. For the cases studied the surrounding medium was assumed to be continuous and linearly elastic. For the purposes of analysis, the actual situation was approximated by a structural model made up of a finite number of elements interconnected at a finite number of nodes. This model was to simulate the actual situation, in its actions and deformations. The boundary of the surrounding medium was assumed to be about 2 diameters from cavity boundaries.

6.2 Conclusions

It was stated in Chapter III that the study was restricted to the nearly linear initial regions of the stress-strain curves of the materials used. Stress conditions obtained for some of the studied cases, however, show that this assumption is violated. The yield stress of the packing medium is about 40 psi. For the tunnel with an uncracked

liner, the stresses at the top and bottom of the packing medium range from 2 to $2\frac{1}{2}$ times the yield stress of the material. This ratio is much higher for the cracked liner. In the case of a liner with three cracks, the stresses in the surrounding medium, next to the liner at about 30° from the vertical, are tensile. This state of stress is undesirable since rocks and soils are either weak in tension or incapable of resisting tension. The analysis is, therefore, unrealistic.

These situations can be remedied by improvement on the analysis. For cases where tensile stresses occur and cracks take place, any crack can be represented by separating the elements on each side of the crack and assigning them different nodal numbers (12). Another approach would be iterative in nature, consisting of the following steps (14):

- a. An analysis is carried out and elements are noted in which tension occurs.
- b. Principal tensile stresses are eliminated and the effect of their omission balanced by external "equivalent" nodal forces.
- c. The elastic analysis is repeated to remove the balancing nodal forces and a check for tensile stresses is made again.
- d. Steps b. and c. are repeated until no tension remains.

For non-linear elastic cases, the stresses can be calculated by applying the load in a stepwise fashion until the desired loading is reached. References (8) and (9) give details of the various approaches that can be used to account for yielding of the material.

The major drawback to using the finite element method in this study was that for the large number of nodal displacements to be calculated, the time required for computer run was excessive. An attempt

was made by the writer to apply the finite element method to the determination of the dynamic response of a tunnel liner-packing system. The approach taken is summarized in Appendix A. This had to be abandoned at an early stage, however, because the computer time required made the cost prohibitive. It is hoped that this would set the stage for further investigation in this area.

It must be concluded, therefore, that with the present computer facilities at Oklahoma State University, the finite element method does not lend itself feasible cost-wise to the type of studies attempted in this investigation.

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APPENDIX A

DYNAMIC RESPONSE OF TUNNEL LINER-PACKING SYSTEM

The possibility of investigating the dynamic response of a tunnel liner-packing system using the finite element technique was examined. A computer program was written for this study, but had to be abandoned early, as the required computer run-time was prohibitive. The following is a brief outline of the procedure used.

A.1 Derivation of Element Stiffness Matrix

The liner-packing system was idealized as shown in Figure 2. It was assumed that the displacements $\{q\}$ at any point in the continuous structure could be related to a finite number of displacements at some arbitrarily selected points on the structure and expressed in the form

$$\{q\} = [A] \{Q\} \quad (A.1)$$

where

$$\{q\} = \{q_x, q_y, q_z\} \quad = \text{matrix of internal displacements;}$$

$$\{Q\} = \{Q_1, Q_2, Q_3 \dots Q_n\} = \text{matrix of nodal displacements;}$$

$$[A] = [A](x, y, z) \quad = \text{function of position coordinates.}$$

Strictly speaking, Equation (A.1) is not valid, but would give a very good approximation if a large number of displacements calculated

from dynamic equations are considered (9).

Differentiation of Equation (A.1) yields the total strains at the point:

$$\begin{aligned}\{e\} &= [B] \{Q\} \\ &= \{\epsilon\} + \{\epsilon_0\}\end{aligned}\quad (A.2)$$

where $[B]$ is a strain-displacement transformation matrix, $\{\epsilon\}$ is the elastic strain component, and $\{\epsilon_0\}$ is a prestrain component which may be caused by temperature changes or some mechanical means.

Using Hooke's Law, the stresses are expressed as

$$\{\sigma\} = [C] \{\epsilon\} = [C]([B] \{Q\} - \epsilon_0). \quad (A.3)$$

The virtual work principle, modified to include inertia forces, is given by

$$\delta U = \delta W - \int_V \rho \delta \{q\}^t \{\ddot{q}\} dv \quad (A.4)$$

where the second term on the right hand side of the equality represents the virtual work due to inertia forces.

The virtual strain energy is given by:

$$\delta U = \int_V \delta \{\epsilon\}^t \{\sigma\} dv \quad (A.5)$$

and the virtual work of all external, surface and body forces is given by:

$$\delta W = \delta \{Q\}^t \{P_e\} + \int_S \{q\}^t \{T\} ds + \int_V \delta \{q\}^t \{X\} dv. \quad (A.6)$$

From Equations (A.1) and (A.2), the virtual displacements and the virtual strains become

$$\delta \{q\} = [A] \delta \{Q\} \quad (A.7)$$

$$\delta \{\epsilon\} = \delta \{e\} = [B] \delta \{Q\}. \quad (A.8)$$

Substituting Equations (A.7) and (A.8) into (A.4), noting that

$$\{q\} = [A] \{\ddot{Q}\},$$

and rearranging, the following is obtained:

$$\begin{aligned} & \int_V \rho \{Q\}^t [A]^t [A] \{\ddot{Q}\} dv + \int_V \delta \{Q\}^t [B]^t [C] [B] \{Q\} dv \\ & = \delta \{Q\}^t \{P_e\} + \int_S \delta \{Q\}^t [A]^t \{T\} ds \\ & + \int_V \delta \{Q\}^t [A]^t \{X\} dv + \int_V \delta \{Q\}^t [B]^t [C] \{\epsilon_0\} dv. \end{aligned} \quad (A.9)$$

Since the virtual displacements are arbitrarily chosen, Equation (A.9) may be expressed as

$$[M] \{\ddot{Q}\} + [K] \{Q\} = \{P\} \quad (A.10)$$

where

$$[M] = \int_V \rho [A]^t [A] dv \quad (\text{mass matrix}), \quad (A.11)$$

$$[k] = \int_V [B]^t [C] [B] dv \quad (\text{stiffness matrix}), \quad (A.12)$$

and

$$\{P\} = \{P_e\} + \int_V [A]^t \{T\} ds + \int_V [A]^t \{X\} dv + \int_V [B]^t [C] \{\epsilon_0\} dv. \quad (A.13)$$

Equation (A.10) represents the equation of motion.

A.2 Mass Matrix, [M]

It was pointed out earlier that Equation (A.1) was not valid, because, for general dynamic conditions, the matrix $[A]$ does not exist, except for very few special cases. The mass matrix $[M]$ as given by Equation (A.11) is, therefore, approximate. In order to facilitate

computations in generating the mass matrix, it was further assumed that the mass of the elements was equally distributed among the nodes of the element, resulting in a diagonal mass matrix.

A.3 Stiffness Matrix, $[K]$

The discussion given in page 14 of the text also applies to this case.

A.4 Description of Forcing Function

A high energy explosion creates a shock wave which, for mathematical analysis, can be expressed as a displacement wave. The wave may produce elastic or plastic deformations, depending on the type of soil through which it propagates. Since the nature of the wave is not known precisely, it was idealized by the sketch shown in Figure 28. By varying the parameters shown in the sketch, a wide range of pulse shapes can be simulated.

The effect of the shock wave on the system is given by specifying the displacements of the nodes on the tunnel cavity. The time it takes for the wave front from the moment it arrives at one end of the diameter of symmetry to reach the j^{th} node is given by

$$t_{\text{ex}} = \frac{R_3 + X_j}{V} \quad (\text{A.14})$$

where

R_3 = radius of tunnel cavity ;

V = velocity of wave propagation ;

X_j = the X-coordinate of the j^{th} node.

It is assumed that for $t \leq t_{ex}$ each node on the cavity boundary is unaffected and for $t > t_{ex}$ each node translates in the direction of the wave freely.

The translation of the j^{th} node is obtained from the displacement curve as one of the following expressions:

letting $t_a = t - t_{ex}$, then for

$$t_a \leq t_1 \quad \left\{ \begin{array}{l} S_{xj} = (t_a/t_1)A_1 \\ S_{yj} = 0 \end{array} \right. ;$$

$$t_1 \leq t_a \leq t_2 \quad \left\{ \begin{array}{l} S_{xj} = A_1 \\ S_{yj} = 0 \end{array} \right. ;$$

$$t_2 \leq t_a \leq t_3 \quad \left\{ \begin{array}{l} S_{xj} = A_1 + \left(\frac{t_a - t_2}{t_3 - t_2} \right) (A_2 - A_1) \\ S_{yj} = 0.0 \end{array} \right. ;$$

$$t_3 \leq t_a \quad \left\{ \begin{array}{l} S_{xj} = A_2 \\ S_{yj} = 0 \end{array} \right. .$$

It is assumed that successive wave fronts follow within a few milliseconds of each other or that the system has come to rest after the passage of the last front, and the effects are superimposed.

A.5 Methods of Solution

In evaluating the response of a structural system to arbitrary dynamic loads, the actual distributed mass system requires partial differential equations to describe its equilibrium state. However, the assumption (11) that the mass properties of the system are separate

from its elastic properties, permits the idealization of the structure as a lumped mass system whose equilibrium state can be formulated by a finite number of simultaneous differential equations. These equations may then be solved by either of the following methods:

1. The modal superposition method which requires the-determination of the eigenmodes of the system and superimposing these to calculate the response of the system.

2. The step-by-step method (10) which essentially uses recurrence formulas that involve the direct numerical integration of the equilibrium equations. The latter is a very useful method which can be used to deal with linear, damped or non-linear systems, and is the one followed in this study.

A.6 The Step-by-Step Recurrence Formulas

Referring to Equation (A.10), the equilibrium of the lumped mass system, without damping, at time t can be expressed as:

$$[M] \{\ddot{Q}\}_t + [K] \{Q\}_t = \{P\}_t \quad (A.15)$$

where

$\{\ddot{Q}\}_t$ = acceleration of the system at "t";

$\{Q\}_t$ = displacement of the system at "t";

$\{P\}_t$ = force on the system at "t";

$[M]$ = mass matrix;

$[K]$ = stiffness matrix.

It will be assumed that the variation of the acceleration for each mass point of the system is linear over the time increment, Δt , as shown in Figure 29.

A simple integration over the time interval for all mass points yields the following matrix equations for the velocity and displacement at the end of the time interval, Δt .

$$\begin{aligned}\{\dot{\mathbf{Q}}\}_t &= \{\dot{\mathbf{Q}}\}_{t-\Delta t} + \frac{\Delta t}{2} \{\ddot{\mathbf{Q}}\}_{t-\Delta t} + \frac{\Delta t}{2} \{\ddot{\mathbf{Q}}\}_t \\ &= \{\mathbf{a}\} + \frac{\Delta t}{2} \{\ddot{\mathbf{Q}}\}_t\end{aligned}\quad (\text{A. 16})$$

and

$$\begin{aligned}\{\mathbf{Q}\}_t &= \{\mathbf{Q}\}_{t-\Delta t} + \Delta t \{\dot{\mathbf{Q}}\}_{t-\Delta t} + \frac{(\Delta t)^2}{3} \{\ddot{\mathbf{Q}}\}_{t-\Delta t} + \frac{(\Delta t)^2}{6} \{\ddot{\mathbf{Q}}\}_t \\ &= \{\mathbf{b}\} + \frac{(\Delta t)^2}{6} \{\ddot{\mathbf{Q}}\}_t\end{aligned}\quad (\text{A. 17})$$

where

$$\{\mathbf{a}\} = \{\dot{\mathbf{Q}}\}_{t-\Delta t} + \frac{\Delta t}{2} \{\ddot{\mathbf{Q}}\}_{t-\Delta t}\quad (\text{A. 18})$$

and

$$\{\mathbf{b}\} = \{\mathbf{Q}\}_{t-\Delta t} + \Delta t \{\dot{\mathbf{Q}}\}_{t-\Delta t} + \frac{(\Delta t)^2}{3} \{\ddot{\mathbf{Q}}\}_{t-\Delta t}.\quad (\text{A. 19})$$

Substitution of Equations (A. 16) and (A. 17) into Equation (A. 15) yields

$$[\mathbf{M}] \{\ddot{\mathbf{Q}}\}_t + [\mathbf{K}] \left(\{\mathbf{b}\} + \frac{(\Delta t)^2}{6} \{\ddot{\mathbf{Q}}\}_t \right) = \{\mathbf{P}\}_t$$

or rearranging

$$\left[[\mathbf{M}] + \frac{(\Delta t)^2}{6} [\mathbf{K}] \right] \{\ddot{\mathbf{Q}}\}_t = \left\{ \{\mathbf{P}\}_t - [\mathbf{K}] \{\mathbf{b}\} \right\}.\quad (\text{A. 20})$$

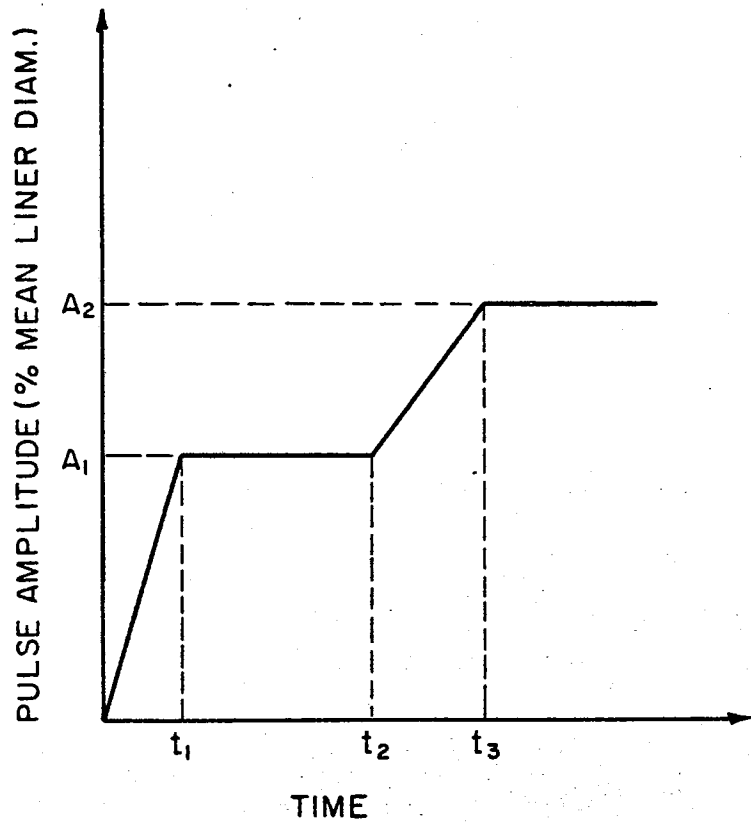


Figure 28. Forcing Function (5)

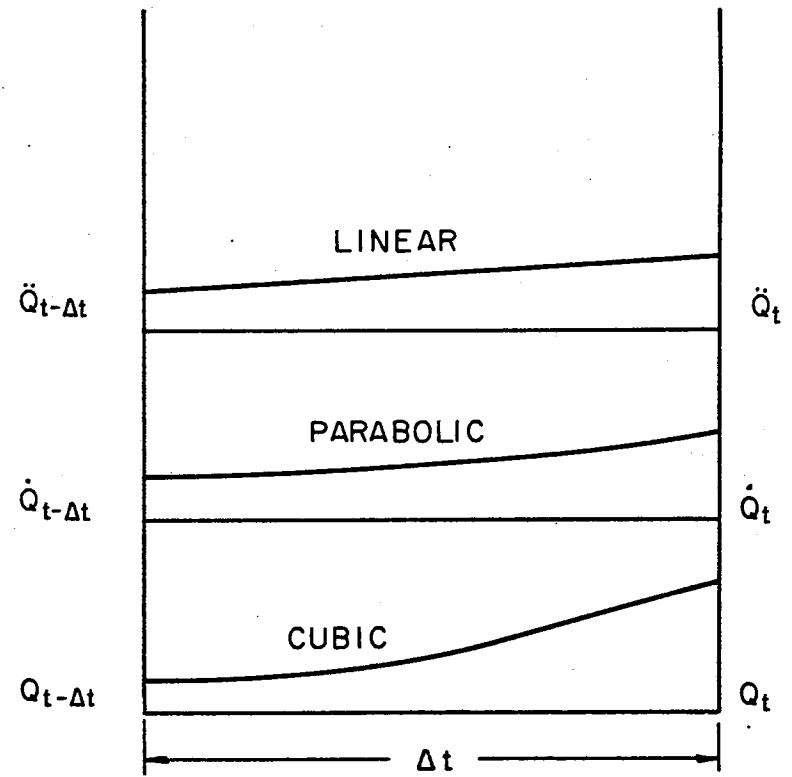


Figure 29. Displacement Functions

Equation (A.20) is the required recurrence formula which expresses the accelerations at the end of an interval in terms of displacements, velocities, and accelerations at the beginning of the interval. Using Equations (A.16) and (A.17), it is now possible to calculate velocities and displacements to be used in determining the accelerations at the end of the next time interval, and so on.

It was at this stage of development that the study had to be discontinued because of the excessive computer time needed.

```

C*****
C*
C* STRESS DISTRIBUTION AROUND A TUNNEL CAVITY
C* USING THE FINITE ELEMENT METHOD
C*
C* PROGRAMMER
C*
C* YOHANNES WOLDENARIAM
C* GRADUATE STUDENT
C* SCHOOL OF CIVIL ENGINEERING
C* OKLAHOMA STATE UNIVERSITY
C* STILLWATER , OKLAHOMA
C*
C* PARAMETERS USED IN THIS PROGRAM
C*
C* NUMNP = TOTAL NUMBER OF NODAL POINTS
C* NUMEL = TOTAL NUMBER OF ELEMENTS
C* NP = INDICATOR NP=1 UNDISTURBED MEDIUM
C* NP=2 UNLINED TUNNEL
C* NP=3 LINED TUNNEL
C*
C* X,Y = NODAL POINT COORDINATES
C* K1,K2,K3 = NUMBER OF DIVISIONS IN LINER-PACKING SYSTEM
C* NR = TOTAL NUMBER OF RADIAL LINES
C* DP = CONCRETE COVER
C* DS = DIAMETER OF STEEL
C* PS = PERCENTAGE OF STEEL
C* FC , FY = STRENGTHS OF CONCRETE AND STEEL RESPECTIVELY
C* E = MODULUS OF ELASTICITY
C* PR = POISSON'S RATIO
C* S = ELEMENT STIFFNESS MATRIX
C* C = ELASTICITY MATRIX
C* P = ELEMENT LOAD VECTOR
C* A = STRUCTURE STIFFNESS MATRIX
C* B = STRUCTURE LOAD VECTOR
C* UXTYPE,UYTYPE = PRESCRIBED LOAD OR DISP. IN X OR Y DIRECTION
C* UX ,UY = VALUE OF PRESCRIBED QUANTITY
C* IX(N,J) = NUMBER OF NODE J OF ELEMENT NUMBER N
C* O,DD,H,HH,F,TP = VARIOUS MATRICES EMPLOYED IN PROGRAM
C* XX(J),XXX(J),YY(J),YYY(J) = NOMENCLATURES SYNONIMOUS WITH THE
C* COORDINATES OF NODE J IN VARIOUS
C* PARTS OF PROGRAM
C*
C*****
C*
C*
C*****
C* MAIN PROGRAM
C*****
0001 IMPLICIT REAL*8(A-H,O-Z)
0002 REAL*8 DFLOAT,DCOS,DSIN
0003 COMMON TYPE(8),HED(18),E(8),X(950) ,Y(950) ,UX(950) ,UY(950) ,VOL,
1UXTYPE(950) ,UYTYPE(950) ,PR(8),
2MTYPE(930),NUMNP,NUMEL,NUMAT,N
0004 COMMON /ARG/ XXX(3),YYY(5),S(10,10),DD(3,3),HH(6,10),P(10),XX(4),
1YY(4),C(4,4),H(6,10),D(6,6),F(6,10),TP(6),
2DK(2,2),TYPE1,TYPE2,TEST1,TEST2,SIG(10),IX(930,4),LM(4),NR
0005 COMMON /BANARG/ A(220,110),B(220),MBAND,NUMBLK
    
```

COMPUTER PROGRAM

APPENDIX B

```

C*****
C*      READ AND WRITE OF CONTROL INFORMATION & MAT PROPERTIES *
C*****
0006      READ(5,1000) HED,TYPE,NUMAT
0007      1000 FORMAT(18A4,/,8A3,/,I5)
0008      WRITE(6,2000) HED,TYPE,NUMAT
0009      20000FORMAT(1H1,4X,18A4,/,5X,8A3/,3X,
130H NUMBER OF DIFF. MATERIALS...I3,/)
0010      READ(5,1001) ( E(M),PR(M),M=1,NUMAT)
0011      1001 FORMAT(2E14.4)
0012      WRITE(6,2001)
0013      20010FORMAT(6X,50HMAT MODULUS OF POISSON'S
16X,49HND. ELASTICITY RATIO
0014      WRITE(6,2002) ( M,E(M),PR(M),M=1,NUMAT)
0015      2002 FORMAT(5X,I3,1P2D12.3)
C*****
C*      INPUT OF NODAL POINTS DATA *
C*****
0016      READ(5,50) NP
0017      50 FORMAT(6X,I5)
0018      IF(NP-2) 510,322,60
0019      60 PI=3.141592653589793
0020      READ(5,402) SP,DS
0021      402 FORMAT(2F10.4)
C
0022      E(2)={(PI*DS)/(4.*SP)}*E(2)
C
0023      READ(5,430) R1,R2,R3,DP,NR,K1,K2,K3
0024      430 FORMAT(4E14.4,4I6)
0025      READ(5,433) FC,FY
0026      433 FORMAT(10X,2F13.3)
0027      PB=(0.72*FC*90000)/(FY*(90000+FY))
0028      AS=PI*(DS**2)/4.0
0029      DEP= R2-R1-DP-(DS/2.)
0030      PS=AS/(DEP*SP)
0031      IF(PS.GT.PB)GO TO 434
0032      MU=PS*FY*SP*(DEP**2)*(1.-0.59*PS*FY/FC)
0033      GO TO 436
0034      434 MU=AS*FY*(DEP-DP)
0035      436 FO= MU/(DEP-DP-(DS/2.))
0036      FS=FO/2
0037      PRINT 438
0038      438 FORMAT(/,10X,59H          AS          PS          PB          FC
1          FY)
0039      PRINT 439, AS, PS, PB, FC, FY
0040      439 FORMAT(/,10X,1P5D13.4)
0041      WRITE(6,435)
0042      435 FORMAT(/,13X,2HR1,12X,2HR2,12X,2HR3,12X,2HDP,12X,2HDS,8X,2HNR,4X,
12HK1,4X,2HK2,4X,2HK3,/)
0043      WRITE(6,432) R1,R2,R3,OP,DS,NR,K1,K2,K3
0044      432 FORMAT(5X,1P5D14.4,4I6)
0045      DR1=DP/DFLOAT(K1)
0046      DR2=(R2-R1-2.0*(DP+DS))/DFLOAT(K2)
0047      DR3=(R3-R2)/DFLOAT(K3)
0048      ALPHA=PI/DFLOAT(NR-1)
0049      NRM=((NR-1)/2)+1
0050      NUMNP=0
0051      NRS=NRM+1

```

```

0052      NRN=NR+1
0053      NRC=(NR-1)/6)+1
0054      NCR=NRC+1

      C
0055      DO 320 I=1,NRN
0056      READ(5,450) N1,N2
0057      450  FORMAT( 10X,2I6)
0058      IF(I-NCR) 451,453,452
0059      451  THETA=ALPHA*DFLOAT(I-1)
0060      GO TO 453
0061      452  THETA=ALPHA*DFLOAT(I-2)
0062      453  DO 310 J=N1,N2
0063      NUMNP=NUMNP+1
0064      JR=N1+K1
0065      IF(J.GT.JR) GO TO 455
0066      R=R1+DR1*DFLOAT(J-N1)
0067      GO TO 445
0068      455  JR=N1+K1+1
0069      IF(J.GT.JR) GO TO 465
0070      R=R1+DP+DS
0071      GOTO445
0072      465  JR=N1+K1+K2+1
0073      IF(J.GT.JR) GO TO 470
0074      R=R1+DP+DS+DR2*DFLOAT(J-N1-K1-1)
0075      GOTO445
0076      470  JR=N1+K1+K2+2
0077      IF(J.GT.JR) GO TO 485
0078      R=R2-DP
0079      GOTO445
0080      485  IF(I.NE.NCR) GO TO 486
0081      R=R2
0082      GO TO 445
0083      486  JR=N2-K3
0084      IF(J.GT.JR) GO TO 490
0085      R=R2-DP+DR1*DFLOAT(J-K1-K2-N1-2)
0086      GOTO445
0087      490  R=R3-DR3*DFLOAT(N2-J)
0088      445  IF(I.EQ.NRS.OR.I.EQ.NRN) GO TO 446
0089      X(J)=R*DSIN(THETA)
0090      Y(J)=R*DCOS(THETA)
0091      GO TO 466
0092      446  IF(I.EQ.NRN) GO TO 447
0093      X(J)=R
0094      Y(J)=0.0
0095      GO TO 466
0096      447  X(J)=0.0
0097      Y(J)=-R
0098      466  IF(I.EQ.1.OR.I.EQ.NRC.OR.I.EQ.NCR) GO TO 469
0099      IF(X(J).EQ.0.0) GO TO 467
0100      UXTYPE(J)=TYPE1
0101      UX(J)=0.0
0102      GO TO 468
0103      467  UXTYPE(J)=TYPE2
0104      UX(J)=0.0
0105      GO TO 468
0106      469  IF(I.GT.1) GO TO 471
0107      JRL= N1+2*K1+K2+2
0108      IF(J.GT.JRL) GO TO 467

```



```

0109      471 UXTYPE(J)=TYPE1
0110          JK1= N1+K1
0111          JK2= N1+K1+1
0112          JK3= N1+K1+K2+1
0113          JK4= N1+K1+K2+2
0114          IF(J.EQ.JK1.OR.J.EQ.JK2.OR.J.EQ.JK3.OR.J.EQ.JK4) GO TO 473
0115          UX(J)=0.0
0116          GO TO 468
0117      473 IF(I.EQ.NCR) GO TO 475
0118          IF(J.EQ.JK1.OR.J.EQ.JK2) GO TO 472
0119          GO TO 474
0120      472 UX(J)=-FS*DCOS(THETA)
0121          UYTYPE(J)=TYPE1
0122          UY(J)= FS*DSIN(THETA)
0123          GO TO 310
0124      474 UX(J)= FS*DCOS(THETA)
0125          UYTYPE(J)=TYPE1
0126          UY(J)=-FS*DSIN(THETA)
0127          GO TO 310
0128      475 IF(J.EQ.JK3.OR.J.EQ.JK4) GO TO 472
0129          GO TO 474
0130      468 UYTYPE(J)=TYPE1
0131          UY(J)=0.0
0132      310 CONTINUE
0133      320 CONTINUE
0134          IF(NP.EQ.3) GO TO 330
0135      322 READ(5,325) R3,NR
0136      325 FORMAT( 1CX, F10.3, 16 )
0137          PI=3.141592653589793
0138          ALPHA=PI/DFLOAT(NR-1)
0139          NUMNP=0
0140          NRM=((NR-1)/2)+1
0141      330 DIA=2.*R3
0142          NR1=(3*(NR-1)/4)+1
0143          READ(5,326) D1,D2,D3,RT,F1,F2,F3
0144      326 FORMAT( 1CX, 7F10.3)
0145          WRITE(6,328)
0146      328 FORMAT(1CX,66H      D1      D2      D3      RT      F1
1 F2      F3,/)
0147          WRITE(6,326) D1,D2,D3,RT,F1,F2,F3
0148          XT=(F2+0.5)*DIA
0149          YT=(F1+0.5)*DIA
0150          YB=(F3+0.5)*DIA
0151          READ(5,327) PRS
0152      327 FORMAT( 1CX,F10.3 )
0153          DO 375 I=1,NR
0154          IF(NP.EQ.2) GO TO 336
0155          K=MOD(I,2)
0156          IF(K) 336,375,336
0157      336 READ(5,450) N1,N2
0158          THETA=ALPHA*DFLOAT(I-1)
0159          DO 374 J=N1,N2
0160          IF(NP.EQ.2) GO TO 338
0161          IF(J.EQ.N1) GO TO 374
0162      338 NUMNP=NUMNP+1
0163          IF(J.EQ.N2) GO TO 361
0164          IF(J-N1) 342,342,344
0165      342 R=R3

```

```
0166          GO TO 354
0167      344  IF(I-N1-1) 346,346,348
0168      346  R=R+D1
0169          GO TO 354
0170      348  IF(I-N1-2) 332,332,352
0171      332  R=R+D2
0172          GO TO 354
0173      352  KE=(J-N1-3)
0174          RI=D3*(RT**KE)
0175          R=R+RI
0176      354  IF(I.EQ.NRM.OR.I.EQ.NR) GO TO 356
0177          X(J)=R*DSIN(THETA)
0178          Y(J)=R*DCOS(THETA)
0179          GO TO 358
0180      356  IF(I.EQ.NR) GO TO 357
0181          X(J)=R
0182          Y(J)=0.0
0183          GO TO 358
0184      357  X(J)=0.0
0185          Y(J)=-R
0186      358  IF(X(J).EQ.0.OR.X(J).EQ.XT) GO TO 359
0187          UXTYPE(J)=TYPE1
0188          UX(J)=0.0
0189          GO TO 362
0190      359  UXTYPE(J)= TYPE2
0191          UX(J)=0.0
0192      362  UYTYPE(J)=TYPE1
0193          UY(J)=0.0
0194          GO TO 374
0195      361  IF(I-NRM) 341,347,349
0196      341  IF(THETA-(PI/3.)) 373,345,345
0197      373  XN=YT*DTAN(THETA)
0198          IF(XN-XT) 343,343,345
0199      343  X(N2)=XN
0200          Y(N2)=YT
0201          GO TO 355
0202      345  BETA=(PI/2.)-THETA
0203          X(N2)=XT
0204          Y(N2)=XT*DTAN(BETA)
0205          GO TO 355
0206      347  X(N2)= XT
0207          Y(N2)=0.0
0208          GO TO 355
0209      349  THETA=PI-THETA
0210          IF(THETA-(PI/3.)) 305,305,353
0211      305  IF(I.EQ.NR) GO TO 306
0212          IF(I.EQ.NR1) GO TO 307
0213          XN=YB*DTAN(THETA)
0214          IF(XN-XT) 351,351,353
0215      351  X(N2)=XN
0216          GO TO 308
0217      307  X(N2)=XT
0218      308  Y(N2)=-YB
0219          GO TO 355
0220      306  X(N2)=0.0
0221          Y(N2)=-YB
0222          GO TO 355
0223      353  BETA=(PI/2.)-THETA
```

```

0224      X(N2)=XT
0225      Y(N2)=-XT*DTAN(BETA)
0226      355  IF(X(N2).EQ.0.OR.X(N2).EQ.XT) GO TO 382
0227      UXTYPE(N2)=TYPE1
0228      UX(N2)=0.0
0229      GO TO 363
0230      382  UXTYPE(N2)=TYPE2
0231      UX(N2)=0.0
0232      363  IF(Y(N2).EQ.YT.OR.Y(N2).EQ.(-YB)) GO TO 365
0233      364  UYTYPE(N2)=TYPE1
0234      UY(N2)=0.0
0235      GO TO 374
0236      365  IF(Y(N2).EQ.YT) GO TO 366
0237      UYTYPE(N2)=TYPE2
0238      UY(N2)=0.0
0239      GO TO 374
0240      366  IF(NP.EQ.3) GO TO 386
0241      IF(I-3) 367,368,368
0242      367  GAMMA=0.0
0243      GO TO 369
0244      368  GAMMA=ALPHA*DFLOAT(I-2)
0245      369  DELTA=ALPHA*DFLOAT(I)
0246      GO TO 377
0247      386  IF(I-5) 387,388,388
0248      387  GAMMA=0.0
0249      GO TO 376
0250      388  GAMMA=ALPHA*DFLOAT(I-3)
0251      376  DELTA=ALPHA*DFLOAT(I+1)
0252      377  X1=Y*DTAN(GAMMA)
0253      X2=Y*DTAN(DELTA)
0254      IF(X2-XT) 370,370,371
0255      370  PR1=-PRS*0.5*(X2-X1)
0256      GO TO 372
0257      371  PR1=-PRS*0.5*(XT-X1)
0258      372  UYTYPE(N2)=TYPE1
0259      UY(N2)=PR1
0260      374  CONTINUE
0261      375  CONTINUE
0262      READ(5,380) NS
0263      380  FORMAT( 10X, I6 )
0264      DO 390 I=1,NS
0265      NUMNP=NUMNP+1
0266      READ(5,385) J,X(J),Y(J),UXTYPE(J),UX(J),UYTYPE(J),UY(J)
0267      385  FORMAT(15,5X,2F10.3,6X,A4,F10.3,6X,A4,F10.3)
0268      390  CONTINUE
0269      GO TO 560
0270      510  READ(5,515) N1,N2,XT,YT,PRS
0271      515  FORMAT( 10X,2I6,3F10.3)
0272      WRITE(6,525)
0273      525  FORMAT(10X,44H      N1      N2      XT      YT      PRS,/)
0274      WRITE(6,530) N1,N2,XT,YT,PRS
0275      530  FORMAT(10X,15,3X,15,3X,3F10.3,/)
0276      DR1=Y/N1
0277      DR2=XT/N2
0278      NR=N1+1
0279      KN=N2+1
0280      NUMNP=KN*NR
0281      DO 550 I=1,NR

```

```
0282      L1=KN*(I-1)+1
0283      L2=KN*I
0284      DO 545 J=L1,L2
0285      X(J)=DR2*DFLOAT(J-L1)
0286      Y(J)=DR1*DFLOAT(I-1)
0287      IF(J.EQ.L1.OR.J.EQ.L2) GO TO 517
0288      UXTYPE(J)=TYPE1
0289      UX(J)=0.0
0290      IF(I.EQ.1.OR.1.EQ.NR) GO TO 516
0291      GO TO 518
0292      516 IF(I.NE.NR) GO TO 520
0293      UYTYPE(J)=TYPE1
0294      UY(J)=-PRS*DR2
0295      GO TO 545
0296      517 UXTYPE(J)=TYPE2
0297      UX(J)=0.0
0298      IF(I.EQ.1.OR.1.EQ.NR) GO TO 519
0299      518 UYTYPE(J)=TYPE1
0300      UY(J)=0.0
0301      GO TO 545
0302      519 IF(I.NE.NR) GO TO 520
0303      UYTYPE(J)=TYPE1
0304      UY(J)=-0.5*PRS*DR2
0305      GO TO 545
0306      520 UYTYPE(J)=TYPE2
0307      UY(J)=0.0
0308      545 CONTINUE
0309      550 CONTINUE
0310      NUMEL=0
0311      DO 220 I=1,N1
0312      N3=N2*(I-1)+1
0313      N4=N2*I
0314      DO 210 J=N3,N4
0315      IX(J,1)=J+I-1
0316      IX(J,2)=IX(J,1)+1
0317      IX(J,3)=IX(J,2)+KN
0318      IX(J,4)=IX(J,3)+KN
0319      MTYPE(J)=1
0320      NUMEL=NUMEL+1
0321      210 CONTINUE
0322      220 CONTINUE
0323      GO TO 595
0324      560 LK=NR-1
0325      NUMEL=0
0326      DO 590 I=1,LK
0327      KK=MOD(I,2)
0328      563 READ(5,564) KF,KL
0329      564 FORMAT( 10X,2I6)
0330      M=KF-1
0331      565 READ(5,566) N,(IX(N,J),J=1,4)
0332      566 FORMAT( 10X, 5I8 )
0333      M=M+1
0334      NUMEL=NUMEL+1
0335      IF(N-M) 580,571,568
0336      568 DO 570 K=1,4
0337      570 IX(M,K)=IX(M-1,K)+1
0338      571 IF(NP.EQ.2) GO TO 573
0339      IF(KK-1) 572,572,576
```

```

0340      572 JL=KF+K1
0341      JH=JL+K2+1
0342      JP=JH+K1+1
0343      IF(M.EQ.JL.OR.M.EQ.JH) GO TO 574
0344      IF(M.GE.JP) GO TO 575
0345      573 MTYPE(M)=1
0346      GO TO 577
0347      574 MTYPE(M)=2
0348      GO TO 577
0349      575 MTYPE(M)=3
0350      GO TO 577
0351      576 MTYPE(M)=4
0352      577 IF(N-M) 580,578,567
0353      578 IF(KL-N) 580,585,565
0354      580 WRITE(6,2005) N
0355      2005 FORMAT(21H0 EL.NO CARD ERROR N=I5)
0356      CALL EXIT
0357      585 IF(NP.EQ.2) GO TO 590
0358      IF(KK-1) 587,590,590
0359      587 KK=KK+2
0360      GO TO 563
0361      590 CONTINUE
0362      595 NM=0
0363      DO 160 N=1,NUMEL
0364      DO 633 M =1,4
0365      DO 633 MM=1,4
0366      KK=IABS(IX(N,M)-IX(N,MM))
0367      IF(KK-NM) 633,633,631
0368      631 NM=KK
0369      IF(NM-55) 633,634,634
0370      634 WRITE(6,628) N
0371      628 FORMAT(33H0 BAND WIDTH EXCEEDS ALLOWABLE N=I5)
0372      CALL EXIT
0373      633 CONTINUE
0374      160 CONTINUE
0375      MBAND=2*NM+2
0376      WRITE(6,440)
0377      440 OFORMAT ( 50H1      NODE      X-ORDINATE  Y-ORDINATE  X-LOAD
1      29H OR DISPL.  Y-LOAD OR DISPL. )
0378      WRITE(6,2004) (J,X(J),Y(J),UXTYPE(J),UX(J),UYTYPE(J),UY(J),
1J=1,NUMNP )
0379      2004 FORMAT( 10X,I5,3X,1P2D12.3,4X,A4,1PD12.4,2X,A4,1PD12.4)
0380      WRITE(6,605)
0381      605 FORMAT(1H1,10X , 56HEL.NO      J1      J2      J3      J4
1      MAT.NO)
0382      WRITE(6,650) (N,(IX(N,J),J=1,4),MTYPE(N),N=1,NUMEL)
0383      650 FORMAT( 10X,I5,5I10)
C
C*****
C*          FORM STIFFNESS MATRIX          *
C*****
C
0384      CALL STIFF
C
C*****
C          SOLVE FOR DISPLACEMENTS          *
C*****
C

```

```

0385      CALL BANSOL
          C
          C*****
          C*          PRINT DISPLACEMENTS          *
          C*****
0386      PRINT 2009
0387      2009 FORMAT ( 45H1      NODE NO.      X-DISPLACEMENT
          1      20H      Y-DISPLACEMENT,/)
0388      K=0
0389      DO 350 NB=1,NUMBLK
0390      DO 350 NM=111,220,2
0391      K=K+1
0392      PRINT 2010,K,A(NM,NB),A(NM+1,NB)
0393      2010 FORMAT (10X,15,10X,1PD15.6,10X,1PD15.6)
0394      IF(K-NUMNP) 350,360,360
0395      350 CONTINUE
          C
          C*****
          C          COMPUTE STRESS          *
          C*****
0396      360 CALL STRESS
          C
          C
0397      STOP
0398      END
    
```

TOTAL MEMORY REQUIREMENTS 0028DC BYTES

```

C
C
C
0001      SUBROUTINE STIFF
0002      IMPLICIT REAL*8(A-H,D-Z)
0003      COMMON TYPE(8),HED(18),E(8),X(950),Y(950),UX(950),UY(950),VOL,
          1UXTYPE(950),UYTYPE(950),PR(8),
          2HTYPE(930),NUMNP,NUMEL,NUMAT,N
0004      COMMON /ARG/ XXX(5),YYY(5),S(10,10),DD(3,3),HH(6,10),P(10),XX(4),
          1YY(4),C(4,4),HI(6,10),D(6,6),F(6,10),TP(6),
          2DK(2,2),TYPE1,TYPE2,TEST1,TEST2,SIG(10),IX(930,4),LM(4),NR
0005      COMMON /BANARG/ A(220,110),B(220),MBAND,NUMBLK
C*****
C*          INITIALIZATION          *
C*****
0006      REWIND 2
0007      NB=55
0008      ND=2*NB
0009      ND2=2*ND
0010      NUMBLK=0
C
0011      DO 50 N=1,ND2
0012      B(N)=0.0
0013      DO 50 M=1,ND
0014      50  A(N,M)=0.0
C*****
C*          FORM STIFFNESS MATRICES IN BLOCKS          *
C*****
0015      60  NUMBLK=NUMBLK+1
0016      NH=NB*(NUMBLK+1)
0017      NM=NH-NB
0018      NL=NH-NB+1
0019      KSHIFT=2*NL-2
C
0020      DO 210 N=1,NUMEL
0021      IF(MTYPE(N))210,210,65
0022      65  DO 80 I=1,4
0023      IF(IX(N,I)-NL) 80,70,70
0024      70  IF(IX(N,I)-NM) 90,90,80
0025      80  CONTINUE
0026      GO TO 210
0027      90  CALL QUAD
0028      MTYPE(N)=-MTYPE(N)
0029      IF(VOL)142,142,144
0030      142  WRITE(6,2000) N
0031      2000  FORMAT(26HNEGATIVE AREA ELEMENT NO. I4)
0032      CALL EXIT
0033      144  IF(IX(N,3)-IX(N,4)) 145,165,145
C
0034      145  DO 150 II=1,9
0035      CC=S(II,10)/S(10,10)
0036      P(II)=P(II)-CC*P(10)
0037      DO 150 JJ=1,9
0038      150  S(II,JJ)=S(II,JJ)-CC*S(10,JJ)
C
0039      DO 160 II=1,8
0040      CC=S(II,9)/S(9,9)
0041      P(II)=P(II)-CC*P(9)

```

```

0042      DO 160 JJ=1,8
0043      160 S(II,JJ)=S(II,JJ)-CC*S(9,JJ)
C
C*****
C*      ADD ELEMENT STIFFNESSES TO TOTAL STIFFNESS      *
C*****
C
0044      165 DO 166 I=1,4
0045      166 LM(I)=2*IX(N,I)-2
C
0046      DO 200 I=1,4
0047      DO 200 K=1,2
0048      II=LM(I)+K-KSHIFT
0049      KK=2*I-2+K
0050      B(II)=B(II)+P(KK)
0051      DO 200 J=1,4
0052      DO 200 L=1,2
0053      JJ=LN(J)+L-II+1-KSHIFT
0054      LL=2*J-2+L
0055      IF(JJ) 200,200,175
0056      175 IF(MD-JJ) 180,195,195
0057      180 WRITE(6,2001) N
0058      2001 FORMAT(29HOBAND WIDTH EXCEEDS ALLOWABLE I4)
0059      CALL EXIT
0060      195 A(II,JJ)=A(II,JJ)+S(KK,LL)
0061      200 CONTINUE
0062      210 CONTINUE
C
C*****
C*      ADD CONCENTRATED FORCES WITHIN BLOCK      *
C*****
C
0063      DO 250 N=NL,NM
0064      K=2*N-KSHIFT
0065      IF(UYTYPE(N).NE.TYPE1) GO TO 240
0066      B(K) = B(K)+ UY(N)
0067      240 IF(UXTYPE(N).NE.TYPE1) GO TO 250
0068      B(K-1) = B(K-1)+ UX(N)
0069      250 CONTINUE
C
C*****
C      BOUNDARY CONDITIONS
C*****
C
0070      310 DO 400 M=NL,NM
0071      IF (M-NUMNP) 315,315,400
0072      315 U=UX(M)
0073      N=2*M-1-KSHIFT
0074      IF ( UXTYPE(M) .NE. TYPE2 ) GO TO 370
0075      CALL MODIFY ( A, B, ND2, MBAND, N, U )
0076      370 N = N + 1
0077      U = UY(M)
0078      IF ( UYTYPE(M) .NE. TYPE2 ) GO TO 400
0079      CALL MODIFY ( A, B, ND2, MBAND, N, U )
0080      400 CONTINUE
C
C*****
C*      WRITE BLOCK OF EQUATIONS ON TAPE AND SHIFT UP LOWER BLOCK      *

```



```
C*****  
0081      WRITE (2) ( B(N),(A(N,M),M=1,MBAND),N=1,ND )  
C  
0082      DO 420 N=1,ND  
0083          K=N+ND  
0084          B(N)=B(K)  
0085          B(K)=0.0  
0086          DO 420 M=1,ND  
0087              A(N,M)=A(K,M)  
0088          420 A(K,M)=0.0  
C*****  
C*          CHECK FOR LAST BLOCK *  
C*****  
0089      IF (NM-NUMNP) 60,480,480  
0090      480 CONTINUE  
0091      500 RETURN  
0092      END
```

TOTAL MEMORY REQUIREMENTS 000B34 BYTES

```

C
C
C
0001      SUBROUTINE QUAD
0002      IMPLICIT REAL*8(A-H,O-Z)
0003      REAL*8 DCOS,DSIN
0004      COMMON TYPE(8),HED(18),E(8),X(950),Y(950),UX(950),UY(950),VOL,
1UXTYPE(950),UYTYPE(950),PR(8),
2MTYPE(930),NUMNP,NUMEL,NUMAT,N
0005      COMMON /ARG/ XXX(5),YYY(5),S(10,10),DD(3,3),HH(6,10),P(10),XX(4),
1YY(4),C(4,4),H(6,10),D(6,6),F(6,10),TP(6),
2DK(2,2),TYPE1,TYPE2,TEST1,TEST2,SIG(10),IX(930,4),LM(4),NR
0006      COMMON /BANARG/ A(220,110),B(220),MBAND,NUMBLK
0007      I=IX(N,1)
0008      J=IX(N,2)
0009      K=IX(N,3)
0010      L=IX(N,4)
0011      MAT=MTYPE(N)
C*****
C*          STRESS -STRAIN RELATIONS -LINEAR ELASTIC *
C*****
0012      IF(TYPE(4)-TEST1)10,30,10
0013      10 IF(TYPE(4)-TEST2)20,40,20
0014      20 WRITE(6,2000)
0015      2000 FORMAT(38H0 PLANE STRESS OR STRAIN TYPE ERROR )
0016      CALL EXIT
C
0017      30 COMM=E(MAT)/(1.0-PR(MAT)*PR(MAT))
0018      C(1,1)=COMM
0019      C(1,2)=COMM*PR(MAT)
0020      C(1,3)=0.0
0021      C(1,4)=0.0
0022      C(2,1)=C(1,2)
0023      C(2,2)=C(1,1)
0024      C(2,3)=0.0
0025      C(2,4)=0.0
0026      C(3,1)=0.0
0027      C(3,2)=0.0
0028      C(3,3)=0.0
0029      C(3,4)=0.0
0030      C(4,1)=0.0
0031      C(4,2)=0.0
0032      C(4,3)=0.0
0033      C(4,4)=COMM*0.5*(1.0-PR(MAT))
0034      GO TO 50
0035      40 COMM=E(MAT)/((1.0+PR(MAT))*(1.0-2.0*PR(MAT)))
0036      C(1,1)=COMM*(1.0-PR(MAT))
0037      C(1,2)=COMM*PR(MAT)
0038      C(1,3)=0.0
0039      C(1,4)=0.0
0040      C(2,1)=C(1,2)
0041      C(2,2)=C(1,1)
0042      C(2,3)=0.0
0043      C(2,4)=0.0
0044      C(3,1)=C(1,2)
0045      C(3,2)=C(1,2)
0046      C(3,3)=0.0
0047      C(3,4)=0.0

```

```

0048      C(4,1)=0.0
0049      C(4,2)=0.0
0050      C(4,3)=0.0
0051      C(4,4)=COMM*0.5*(1.0-2.0*PR(MAT))
C*****
C*          FORM QUADRILATERAL STIFFNESS MATRIX          *
C*****
0052      50  XXX(5)=(X(I)+X(J)+X(K)+X(L))/4.0
0053          YYY(5)=(Y(I)+Y(J)+Y(K)+Y(L))/4.0
0054          DO 94 M=1,4
0055              MM=IX(N,M)
0056              XXX(M)=X(MM)
0057          94  YYY(M)=Y(MM)
C
0058          DO 100 II=1,10
0059              P(II)=0.0
0060              DO 95 JJ=1,6
0061          95  HH(IJ,II)=0.0
0062              DO 100 JJ=1,10
0063          100 S(II,JJ)=0.0
0064              IF(K-L)125,120,125
0065          120 CALL TRISTF(1,2,3)
0066              XXX(5)=(XXX(1)+XXX(2)+XXX(3))/3.0
0067              YYY(5)=(YYY(1)+YYY(2)+YYY(3))/3.0
0068              GO TO 130
0069          125 VOL=0.0
0070              CALL TRISTF(4,1,5)
0071              CALL TRISTF(1,2,5)
0072              CALL TRISTF(2,3,5)
0073              CALL TRISTF(3,4,5)
C
0074          DO 138 II=1,6
0075              DO 138 JJ=1,10
0076          138 HH(II,JJ)=HH(II,JJ)/4.
C
0077          130 RETURN
0078          END

```

TOTAL MEMORY REQUIREMENTS 00073E BYTES

```

C
C
0001 SUBROUTINE TRISTF(I1,J1,K1)
0002 IMPLICIT REAL*8(A-H,O-Z)
0003 COMMON TYPE(8),HED(18),E(8),X(950),Y(950),UX(950),UY(950),VOL,
      1UXTYPE(950),UYTYPE(950),PR(8),
      2MTYPE(930),NUMNP,NUMEL,NUMAT,N
0004 COMMON /ARG/ XXX(5),YYY(5),SI(10,10),DD(3,3),HH(6,10),P(10),XX(4),
      1YY(4),C(4,4),H(6,10),D(6,6),F(6,10),TP(6),
      2DK(2,2),TYPE1,TYPE2,TEST1,TEST2,SIG(10),IX(930,4),LM(4),NR
0005 COMMON /BANARG/ A(220,110),B(220),MBAND,NUMBLK
C*****
C*          INITIALIZATION          *
C*****
0006 LM(1)=I1
0007 LM(2)=J1
0008 LM(3)=K1
0009 XX(1)=XXX(I1)
0010 XX(2)=XXX(J1)
0011 XX(3)=XXX(K1)
0012 XX(4)=XXX(I1)
0013 YY(1)=YYY(I1)
0014 YY(2)=YYY(J1)
0015 YY(3)=YYY(K1)
0016 YY(4)=YYY(I1)
C
0017 85 DO 100 I=1,6
0018 DO 90 J=1,10
0019 F(I,J)=0.0
0020 90 H(I,J)=0.0
0021 DO 100 J=1,6
0022 100 D(I,J)=0.0
C*****
C*          FORM INTEGRAL(GIT*(C)*(G)          *
C*****
0023 COMM=XX(2)*(YY(3)-YY(1))+XX(1)*(YY(2)-YY(3))+XX(3)*(YY(1)-YY(2))
0024 VOL=VOL+COMM*0.5
0025 IF(COMM)107,500,107
0026 107 D(2,2)=C(1,1)*COMM*0.5
0027 D(2,3)=C(1,4)*COMM*0.5
0028 D(2,5)=D(2,3)
0029 D(2,6)=C(1,2)*COMM*0.5
0030 D(3,3)=C(4,4)*COMM*0.5
0031 D(3,5)=D(3,3)
0032 D(5,5)=D(3,3)
0033 D(6,6)=C(2,2)*COMM*0.5
C
0034 108 DO 110 I=1,6
0035 DO 110 J=1,6
0036 110 D(I,I)=D(I,I)
C*****
C*          FORM COEFFICIENT-DISPLACEMENT TRANSFORMATION MATRIX          *
C*****
0037 DD(1,1)=(XX(2)*YY(3)-XX(3)*YY(2))/COMM
0038 DD(1,2)=(XX(3)*YY(1)-XX(1)*YY(3))/COMM
0039 DD(1,3)=(XX(1)*YY(2)-XX(2)*YY(1))/COMM
0040 DD(2,1)=(YY(2)-YY(3))/COMM
0041 DD(2,2)=(YY(3)-YY(1))/COMM

```

```

0042      DD(2,3)=(YY(1)-YY(2))/COMM
0043      DD(3,1)=(XX(3)-XX(2))/COMM
0044      DD(3,2)=(XX(1)-XX(3))/COMM
0045      DD(3,3)=(XX(2)-XX(1))/COMM
      C
0046      DO 120 I=1,3
0047          J=2*LM(I)-1
0048          H(1,J)=DD(1,I)
0049          H(2,J)=DD(2,I)
0050          H(3,J)=DD(3,I)
0051          H(5,J+1)=DD(2,I)
0052      120 H(6,J+1)=DD(3,I)
      C*****
      C*          FORM ELEMENT STIFNESS MATRIX (H)*T*(D)*(H)          *
      C*****
0053      DO 130 J=1,10
0054      DO 130 K=1,6
0055          IF(H(K,J))128,130,128
0056      128 DO 129 I=1,6
0057      129 F(I,J)=F(I,J)+D(I,K)*H(K,J)
0058      130 CONTINUE
      C
0059      DO 140 I=1,10
0060      DO 140 K=1,6
0061          IF(H(K,I))138,140,138
0062      138 DO 139 J=1,10
0063      139 S(I,J)=S(I,J)+H(K,I)*F(K,J)
0064      140 CONTINUE
      C*****
      C*          FORM STRAIN TRANSFORMATION MATRIX          *
      C*****
      C
0065      400 DO 410 I=1,6
0066          DO 410 J=1,10
0067      410 HH(I,J)=HH(I,J)+H(I,J)
      C
0068      500 RETURN
0069      END

```

TOTAL MEMORY REQUIREMENTS 000796 BYTES

```

0001      SUBROUTINE BANSOL
0002      IMPLICIT REAL*8(A-H,O-Z)
0003      COMMON /BANARG/ A(220,110),B(220),MBAND,NUMBLK
0004      NN=110
0005      NL=NN+1
0006      NH=NN+NN
0007      REWIND 1
0008      REWIND 2
0009      NB=0
0010      MM=MBAND
0011      GO TO 150

C
C*****
C*      REDUCE EQUATIONS BY BLOCKS - SHIFT BLOCK OF EQUATIONS      *
C*****
C
0012      100  NB=NB+1
0013           DO 125 N=1,NN
0014           NN=NN+N
0015           B(N)=B(NM)
0016           B(NM)=0.0
0017           DO 125 M=1,MM
0018           A(N,M)=A(NM,M)
0019           125  A(NM,M)=0.0
C*****
C*      READ NEXT BLOCK OF EQUATIONS INTO CORE      *
C*****
C
0020      IF(NUMBLK-NB) 150,200,150
C
0021      150  READ (2) ( B(N), (A(N,M),M=1,MM),N=NL,NH)
C
0022      IF(NB) 200,100,200
C*****
C*      REDUCE BLOCK OF EQUATIONS      *
C*****
0023      200  DO 300 N=1,NN
0024           IF(A(N,1)) 225,300,225
0025      225  B(N)=B(N)/A(N,1)
0026           DO 275 L=2,MM
0027           IF(A(N,L)) 230,275,230
0028      230  Q=A(N,L)/A(N,1)
0029           I=N+L-1
0030           J=0
0031           DO 250 K=L,MM
0032           J=J+1
0033           250  A(I,J)=A(I,J)-Q*A(N,K)
0034           B(I)=B(I)-A(N,L)*B(N)
0035           A(N,L)=Q
0036           275  CONTINUE
0037           300  CONTINUE
C*****
C*      WRITE BLOCK OF REDUCED EQUATIONS ON TAPE 1      *
C*****
0038      IF(NUMBLK-NB) 375,400,375
0039      375  WRITE (1) (B(N), (A(N,M),M=2,MM),N=1,NN)
0040      GO TO 100
C

```

```
C*****  
C*                                     BACK SUBSTITUTION *  
C*****  
C  
0041      400 DO 450 M=1,NN  
0042          N=NN+1-M  
0043          DO 425 K=2,MM  
0044          L=N+K-1  
0045          425 B(N)=B(N)-A(N,K)*B(L)  
0046          MM=N+NN  
0047          B(NM)=B(N)  
0048          450 A(NM,NB)=B(N)  
0049          NB=NB-1  
0050          IF(NB) 475,500,475  
0051          475 BACKSPACE 1  
0052          READ (1) (B(N), (A(N,M),M=2,MM),N=1,NN)  
0053          BACKSPACE 1  
0054          GO TO 400  
C  
0055      500 RETURN  
0056          END
```

TOTAL MEMORY REQUIREMENTS 000746 BYTES

```
0001      SUBROUTINE MODIFY(A,B,NEQ,MBAND,N,U)
0002      IMPLICIT REAL*8(A-H,O-Z)
0003      DIMENSION A(220,110),B(220)

      C
0004      DO 250 M=2,MBAND
0005          K=N-M+1
0006          IF(K)235,235,230
0007      230      B(K)=B(K)-A(K,M)*U
0008              A(K,M)=0.0
0009      235      K=N-M-1
0010              IF(NEQ-K) 250,240,240
0011      240      B(K)=B(K)-A(N,M)*U
0012              A(N,M)=0.0
0013      250      CONTINUE
0014              A(N,1)=1.0
0015              B(N)=U
0016              RETURN
0017      END
```

TOTAL MEMORY REQUIREMENTS 0002CE BYTES


```

0001      SUBROUTINE STRESS
          C
0002      IMPLICIT REAL*8(A-H,O-Z)
0003      COMMON TYPE(8),HEDI(18),E(8),X(950),Y(950),UX(950),UY(950),VOL,
          IUXTYPE(950),UYTYPE(950),PR(8),
          ZHTYPE(930),NUMNP,NUMEL,NUMAT,N
0004      COMMON /ARG/ XXX(5),YYY(5),S(10,10),DD(3,3),HH(6,10),P(10),XX(4),
          IYY(4),C(4,4),H(6,10),D(6,6),F(6,10),TP(6),
          ZDK(2,2),TYPE1,TYPE2,TEST1,TEST2,SIG(10),IX(930,4),LN(4),NR
0005      COMMON /BANARG/ A(220,110),B(220),MBAND,NUMBLK
          C
          C*****
          C      COMPUTE ELEMENT STRESS
          C*****
          C
0006      MPRINT = 0
0007      PI=3.141592653589793
0008      NN=110
          C
0009      DO 90 M = 1,NUMEL
          C
0010      N = M
0011      MTYPE(N) = IABS(MTYPE(N))
0012      CALL QUAD
          C
0013      DO 10 I = 1,4
0014      II = 2 * I
0015      KK=2*IX(N,I)
0016      NB=KK/NN
0017      NJ=MOD(KK,NN)
0018      IF(NJ) 5,6,5
0019      5 NB=NB+1
0020      JJ=NN+NJ
0021      GO TO 8
0022      6 JJ=2*NN
0023      8 P(II-1)=A(JJ-1,NB)
0024      P(II)=A(JJ,NB)
0025      10 CONTINUE
          C
0026      DO 20 I = 1,2
0027      XX(I) = P(I*8)
0028      DO 20 K = 1,8
0029      20 XX(I) = XX(I) - S(I+8,K) * P(K)
          C
0030      COMM = S(9,9) * S(10,10) - S(9,10) * S(10,9)
0031      IF (COMM) 30,40,30
0032      30 P(9) = (S(10,10) * XX(1) - S(9,10) * XX(2)) / COMM
0033      P(10) = (-S(10,9) * XX(1) + S(9,9) * XX(2)) / COMM
          C
0034      40 DO 50 I = 1,6
0035      TP(I) = 0.0
0036      DO 50 K = 1,10
0037      50 TP(I) = TP(I) + HH(I,K) * P(K)
          C
0038      52 XX(1) = TP(2)
0039      XX(2) = TP(6)
0040      XX(3) = 0.0
0041      XX(4) = TP(3) + TP(5)

```

```

FORTRAN IV G LEVEL 1, MOD 4          STRESS          DATE = 70188          20/30/07          PAGE 0002

0042      56 DO 60 I = 1,4
0043      SIG(I) = 0.
0044      DO 60 K = 1,4
0045      60 SIG(I) = SIG(I) + C(I,K) * XX(K)
0046      RAD= ((SIG(1)-SIG(2))/2.)**2 + (SIG(4))**2
0047      TMAX=DSORT(RAD)
0048      SAVR= ((SIG(1) + SIG(2))/2.)
0049      SIG1= SAVR + TMAX
0050      SIG2= SAVR - TMAX
0051      TAN2A=2.*(SIG(4))/(SIG(1)-SIG(2))
0052      ANG=DATAN(TAN2A)*90.0/PI

C
C*****
C*   OUTPUT STRESSES   *
C*****
C
0053      62 IF (MPRINT) 80,70,80
0054      70 PRINT 2000
0055      MPRINT = 62
0056      80 MPRINT = MPRINT - 1

C
0057      PRINT 2001, N,XXX(5),YYY(5),(SIG(I),I=1,4),SIG1,SIG2,ANG

C
0058      90 CONTINUE

C
0059      RETURN

C
0060      20000FORMAT ( 50H1   EL.    X      Y      X-STRESS  Y-STRESS
1          48H      Z-STRESS  XY-SHEAR  SIG1      SIG2
2          13H      ANG)
0061      2001 FORMAT ( 5X, I3, 2F8.2, 7D13.4 )
0062      END

```

```

FORTRAN IV G LEVEL 1, MOD 4          BLK DATA          DATE = 70188          20/30/07          PAGE 0001

0001      BLOCK DATA
0002      IMPLICIT REAL*8(A-H,O-Z)
0003      COMMON TYPE(8),HED(18),E(8),X(950) ,Y(950) ,UX(950) ,UY(950) ,VOL,
1UXTYPE(950) ,UYTYPE(950) ,PR(8),
2MTYPE(930),NUMNP,NUMEL,NUMAT,N
0004      COMMON /ARG/ XXX(5),YYY(5),S(10,10),DD(3,3),HH(6,10),P(10),XX(4),
1YY(4),C(4,4),H(6,10),D(6,6),F(6,10),TP(6),
2OK(2,2),TYPE1,TYPE2,TEST1,TEST2,SIG(10),IX(930,4),LM(4),NR
0005      COMMON /BANARG/ A(220,110),B(220),MBAND,NUMBLK
0006      DATA TYPE1/4HLOAD/,TYPE2/4HDISP/,TEST1/3HESS/,TEST2/3HAIN/
0007      END

```

APPENDIX C

TYPICAL INPUT DATA

80/80 LIST

```

0000000001111111112222222222333333333344444444445555555555666666666677777777778
12345678901234567890123456789012345678901234567890123456789012345678901234567890
CARD
0001          FINITE ELEMENT ANALYSIS   LINER WITH THREE CRACKS
0002 PLANE STRAIN ANALYSIS
0003      4
0004      0.3500E 07      0.1500E 00
0005      0.3000E 08      0.3000E 00
0006      0.1500E 05      0.1000E 00
0007      0.4000E 05      0.3300E 00
0008      3
0009      12.0      0.625
0010      0.3600E 02      0.4400E 02      0.6800E 02      0.8000E 00      49      1      5      5
0011      4000.      60000.
0012      1      15
0013      26      40
0014      41      55
0015      66      80
0016      81      95
0017      106      120
0018      121      135
0019      147      161
0020      162      176
0021      188      197
0022      198      212
0023      213      227
0024      237      251
0025      252      266
0026      275      289
0027      290      304
0028      313      327
0029      328      342
0030      350      364
0031      365      379
0032      387      401
0033      402      416
0034      424      438
0035      439      453
0036      461      475
0037      476      490
0038      498      512
0039      513      527
0040      535      549
0041      550      564
0042      572      586
0043      587      601
0044      609      623
0045      624      638
0046      646      660
0047      661      675
0048      684      698
0049      699      713
0050      722      736
0051      737      751
0052      760      774
0053      775      789
0054      798      812
0055      813      827
    
```

000000001111111122222222333333334444444455555555666666667777777778
 1234567890123456789012345678901234567890123456789012345678901234567890

CARD	835	849					
0056	835	849					
0057	850	864					
0058	872	886					
0059	887	901					
0060	909	923					
0061	924	938					
0062	6.0		14.0	26.9	1.308	5.0	2.0
0063	100.						
0064	15	25					
0065	55	65					
0066	95	105					
0067	135	146					
0068	176	186					
0069	227	236					
0070	266	274					
0071	304	312					
0072	342	349					
0073	379	386					
0074	416	423					
0075	453	460					
0076	490	497					
0077	527	534					
0078	564	571					
0079	601	608					
0080	638	645					
0081	675	683					
0082	713	721					
0083	751	759					
0084	789	797					
0085	827	834					
0086	864	871					
0087	901	908					
0088	938	945					
0089	1						
0090	187	340.	748.	DISP	0.0	LOAD	-1510.0
0091	1	14					
0092	1	1	26	27	2		
0093	14	14	39	40	15		
0094	15	28					
0095	15	26	41	42	27		
0096	28	39	54	55	40		
0097	29	40					
0098	29	15	40	16	16		
0099	30	16	40	56	56		
0100	31	40	55	56	56		
0101	32	16	56	57	17		
0102	40	24	64	65	25		
0103	41	54					
0104	41	41	66	67	42		
0105	54	54	79	80	55		
0106	55	68					
0107	55	66	81	82	67		
0108	68	79	94	95	80		
0109	69	80					
0110	69	55	80	56	56		

APPENDIX D

TYPICAL OUTPUT

NODE	X-ORDINATE	Y-ORDINATE	X-LOAD OR DISPL.	Y-LOAD OR DISPL.
1	0.0	3.6000 01	LOAD 0.0	LOAD 0.0
2	0.0	3.6800 01	LOAD -1.06160 04	LOAD 0.0
3	0.0	3.7430 01	LOAD -1.06160 04	LOAD 0.0
4	0.0	3.8460 01	LOAD 0.0	LOAD 0.0
5	0.0	3.9490 01	LOAD 0.0	LOAD 0.0
6	0.0	4.0520 01	LOAD 0.0	LOAD 0.0
7	0.0	4.1540 01	LOAD 0.0	LOAD 0.0
8	0.0	4.2580 01	LOAD 1.06160 04	LOAD 0.0
9	0.0	4.3200 01	LOAD 1.06160 04	LOAD 0.0
10	0.0	4.4000 01	LOAD 0.0	LOAD 0.0
11	0.0	4.8800 01	DISP 0.0	LOAD 0.0
12	0.0	5.3600 01	DISP 0.0	LOAD 0.0
13	0.0	5.8400 01	DISP 0.0	LOAD 0.0
14	0.0	6.3200 01	DISP 0.0	LOAD 0.0
15	0.0	6.8000 01	DISP 0.0	LOAD 0.0
16	0.0	7.4000 01	DISP 0.0	LOAD 0.0
17	0.0	8.8000 01	DISP 0.0	LOAD 0.0
18	0.0	1.1490 02	DISP 0.0	LOAD 0.0
19	0.0	1.5010 02	DISP 0.0	LOAD 0.0
20	0.0	1.9610 02	DISP 0.0	LOAD 0.0
21	0.0	2.5630 02	DISP 0.0	LOAD 0.0
22	0.0	3.3500 02	DISP 0.0	LOAD 0.0
23	0.0	4.3800 02	DISP 0.0	LOAD 0.0
24	0.0	5.7270 02	DISP 0.0	LOAD 0.0
25	0.0	7.4800 02	DISP 0.0	LOAD -4.92380 03
26	2.3550 00	3.5920 01	LOAD 0.0	LOAD 0.0
27	2.4070 00	3.6720 01	LOAD 0.0	LOAD 0.0
28	2.4480 00	3.7340 01	LOAD 0.0	LOAD 0.0
29	2.5150 00	3.8370 01	LOAD 0.0	LOAD 0.0
30	2.5820 00	3.9400 01	LOAD 0.0	LOAD 0.0
31	2.6500 00	4.0430 01	LOAD 0.0	LOAD 0.0
32	2.7170 00	4.1460 01	LOAD 0.0	LOAD 0.0
33	2.7850 00	4.2480 01	LOAD 0.0	LOAD 0.0
34	2.8250 00	4.3110 01	LOAD 0.0	LOAD 0.0
35	2.8780 00	4.3910 01	LOAD 0.0	LOAD 0.0
36	3.1920 00	4.8700 01	LOAD 0.0	LOAD 0.0
37	3.5060 00	5.3490 01	LOAD 0.0	LOAD 0.0
38	3.8200 00	5.8270 01	LOAD 0.0	LOAD 0.0
39	4.1330 00	6.3060 01	LOAD 0.0	LOAD 0.0
40	4.4470 00	6.7850 01	LOAD 0.0	LOAD 0.0
41	4.6990 00	3.5690 01	LOAD 0.0	LOAD 0.0
42	4.8030 00	3.6490 01	LOAD 0.0	LOAD 0.0
43	4.8850 00	3.7100 01	LOAD 0.0	LOAD 0.0
44	5.0190 00	3.8130 01	LOAD 0.0	LOAD 0.0
45	5.1540 00	3.9150 01	LOAD 0.0	LOAD 0.0
46	5.2880 00	4.0170 01	LOAD 0.0	LOAD 0.0
47	5.4230 00	4.1190 01	LOAD 0.0	LOAD 0.0
48	5.5570 00	4.2210 01	LOAD 0.0	LOAD 0.0
49	5.6390 00	4.2830 01	LOAD 0.0	LOAD 0.0
50	5.7430 00	4.3620 01	LOAD 0.0	LOAD 0.0
51	6.3700 00	4.8380 01	LOAD 0.0	LOAD 0.0
52	6.9960 00	5.3140 01	LOAD 0.0	LOAD 0.0
53	7.6230 00	5.7900 01	LOAD 0.0	LOAD 0.0
54	8.2490 00	6.2660 01	LOAD 0.0	LOAD 0.0
55	8.8760 00	6.7420 01	LOAD 0.0	LOAD 0.0
56	9.6590 00	7.3370 01	LOAD 0.0	LOAD 0.0
57	1.1490 01	8.7250 01	LOAD 0.0	LOAD 0.0
58	1.5000 01	1.1390 02	LOAD 0.0	LOAD 0.0
59	1.9590 01	1.4880 02	LOAD 0.0	LOAD 0.0
60	2.5600 01	1.9440 02	LOAD 0.0	LOAD 0.0
61	3.3450 01	2.5410 02	LOAD 0.0	LOAD 0.0
62	4.3730 01	3.3220 02	LOAD 0.0	LOAD 0.0
63	5.7170 01	4.3430 02	LOAD 0.0	LOAD 0.0

EL.NO	J1	J2	J3	J4	MAT.NO
1	1	26	27	2	1
2	2	27	28	3	2
3	3	28	29	4	1
4	4	29	30	5	1
5	5	30	31	6	1
6	6	31	32	7	1
7	7	32	33	8	1
8	8	33	34	9	2
9	9	34	35	10	1
10	10	35	36	11	3
11	11	36	37	12	3
12	12	37	38	13	3
13	13	38	39	14	3
14	14	39	40	15	3
15	26	41	42	27	1
16	27	42	43	28	2
17	28	43	44	29	1
18	29	44	45	30	1
19	30	45	46	31	1
20	31	46	47	32	1
21	32	47	48	33	1
22	33	48	49	34	2
23	34	49	50	35	1
24	35	50	51	36	3
25	36	51	52	37	3
26	37	52	53	38	3
27	38	53	54	39	3
28	39	54	55	40	3
29	15	40	16	16	4
30	16	40	56	56	4
31	40	55	56	56	4
32	16	56	57	17	4
33	17	57	58	18	4
34	18	58	59	19	4
35	19	59	60	20	4
36	20	60	61	21	4
37	21	61	62	22	4
38	22	62	63	23	4
39	23	63	64	24	4
40	24	64	65	25	4
41	41	66	67	42	1
42	42	67	68	43	2
43	43	68	69	44	1
44	44	69	70	45	1
45	45	70	71	46	1
46	46	71	72	47	1
47	47	72	73	48	1
48	48	73	74	49	2
49	49	74	75	50	1
50	50	75	76	51	3
51	51	76	77	52	3
52	52	77	78	53	3
53	53	78	79	54	3
54	54	79	80	55	3
55	66	81	82	67	1
56	67	82	83	68	2
57	68	83	84	69	1
58	69	84	85	70	1
59	70	85	86	71	1
60	71	86	87	72	1
61	72	87	88	73	1
62	73	88	89	74	2
63	74	89	90	75	1

NODE NO.	X-DISPLACEMENT	Y-DISPLACEMENT
1	-1.940117D 00	1.844326D 00
2	-1.800966D 00	1.844262D 00
3	-1.689101D 00	1.844378D 00
4	-1.501745D 00	1.844162D 00
5	-1.317465D 00	1.843740D 00
6	-1.133847D 00	1.843357D 00
7	-9.495885D-01	1.842966D 00
8	-7.626980D-01	1.842238D 00
9	-6.512243D-01	1.841037D 00
10	-5.121245D-01	1.840511D 00
11	0.0	1.043168D 00
12	0.0	4.757753D-01
13	0.0	1.013347D-01
14	0.0	-1.759456D-01
15	0.0	-3.916387D-01
16	0.0	-4.486675D-01
17	0.0	-5.576502D-01
18	0.0	-6.804069D-01
19	0.0	-7.821159D-01
20	0.0	-8.838751D-01
21	0.0	-1.000214D 00
22	0.0	-1.142552D 00
23	0.0	-1.322269D 00
24	0.0	-1.552703D 00
25	0.0	-1.849714D 00
26	-1.948005D 00	1.427844D 00
27	-1.806823D 00	1.418039D 00
28	-1.696030D 00	1.409507D 00
29	-1.514190D 00	1.397085D 00
30	-1.331908D 00	1.384999D 00
31	-1.149748D 00	1.372858D 00
32	-9.676352D-01	1.360662D 00
33	-7.860797D-01	1.348777D 00
34	-6.756086D-01	1.342055D 00
35	-5.346938D-01	1.332939D 00
36	-6.443926D-02	8.031676D-01
37	3.400119D-02	3.852796D-01
38	4.096852D-02	5.057170D-02
39	3.097327D-02	-2.063279D-01
40	8.576402D-03	-4.111328D-01
41	-1.981586D 00	1.015359D 00
42	-1.842963D 00	9.967989D-01
43	-1.733566D 00	9.820257D-01
44	-1.554666D 00	9.582206D-01
45	-1.375474D 00	9.344278D-01
46	-1.196200D 00	9.107200D-01
47	-1.017153D 00	8.871158D-01
48	-8.384817D-01	8.635674D-01
49	-7.296390D-01	8.492106D-01
50	-5.912593D-01	8.309999D-01
51	-1.398805D-01	4.580585D-01
52	2.215424D-02	1.609371D-01
53	5.746018D-02	-8.695361D-02
54	4.745914D-02	-2.885672D-01
55	7.884142D-03	-4.495024D-01
56	2.020152D-02	-4.950976D-01
57	1.796850D-02	-5.834169D-01
58	1.218328D-02	-6.910525D-01
59	7.148320D-03	-7.859814D-01
60	4.551697D-03	-8.843116D-01
61	3.215118D-03	-9.984223D-01
62	2.370338D-03	-1.138900D 00

EL.	X	Y	X-STRESS	Y-STRESS	Z-STRESS	XY-SHEAR	SIG1	SIG2	ANG
1	1.19	36.36	0.1028D 05	0.4564D 03	0.1611D 04	-0.2585D 04	0.1092D 05	-0.1822D 03	-0.1388D 02
2	1.21	37.07	0.4627D 04	0.7247D 03	0.1606D 04	0.3787D 03	0.4664D 04	0.6883D 03	0.5492D 01
3	1.24	37.90	0.7085D 04	0.7974D 02	0.1075D 04	0.2473D 04	0.7870D 04	-0.7055D 03	0.1761D 02
4	1.27	38.93	0.1893D 04	-0.6042D 03	0.1933D 03	0.6222D 03	0.2039D 04	-0.7506D 03	0.1325D 02
5	1.31	39.96	-0.1010D 03	-0.9954D 03	-0.1645D 03	0.2191D 03	-0.5017D 02	-0.1046D 04	0.1305D 02
6	1.34	40.99	-0.2026D 04	-0.1452D 04	-0.5218D 03	0.7855D 03	-0.9030D 03	-0.2576D 04	-0.3497D 02
7	1.38	42.01	-0.6353D 04	-0.2287D 04	-0.1296D 04	0.2642D 04	-0.9866D 03	-0.7653D 04	-0.2621D 02
8	1.40	42.84	-0.4840D 04	-0.2822D 04	-0.2299D 04	0.4295D 03	-0.2734D 04	-0.4928D 04	-0.1153D 02
9	1.43	43.55	-0.9392D 04	-0.2565D 04	-0.1794D 04	-0.1857D 04	-0.2093D 04	-0.9865D 04	0.1427D 02
10	1.52	46.35	-0.3945D 03	-0.2078D 04	-0.2472D 03	-0.1762D 03	-0.3763D 03	-0.2096D 04	-0.5911D 01
11	1.67	51.15	-0.2418D 03	-0.1556D 04	-0.1798D 03	-0.2910D 03	-0.1802D 03	-0.1617D 04	-0.1195D 02
12	1.83	55.94	0.3222D 02	-0.1106D 04	-0.1074D 03	-0.1458D 03	0.5061D 02	-0.1124D 04	-0.7186D 01
13	1.99	60.73	0.4430D 02	-0.8333D 03	-0.7890D 02	-0.9132D 02	0.5370D 02	-0.8427D 03	-0.5879D 01
14	2.15	65.53	-0.4125D 01	-0.6615D 03	-0.6656D 02	-0.6645D 02	0.2524D 01	-0.6682D 03	-0.5714D 01
15	3.57	36.21	0.9236D 04	-0.1595D 03	0.1362D 04	-0.5211D 03	0.9265D 04	-0.1883D 03	-0.3165D 01
16	3.64	36.91	0.2584D 04	-0.8318D 03	0.5256D 03	0.5485D 03	0.2670D 04	-0.9178D 03	0.8902D 01
17	3.72	37.74	0.5426D 04	-0.5117D 03	0.7371D 03	0.8311D 03	0.5540D 04	-0.6259D 03	0.7820D 01
18	3.82	38.76	0.2839D 04	-0.3955D 03	0.3665D 03	0.1639D 04	0.3524D 04	-0.1081D 04	0.2269D 02
19	3.92	39.79	0.1991D 03	-0.8253D 03	-0.9393D 02	0.1786D 04	0.1545D 04	-0.2171D 04	0.3700D 02
20	4.02	40.81	-0.2329D 04	-0.1221D 04	-0.5325D 03	0.1838D 04	0.1446D 03	-0.3695D 04	-0.3662D 02
21	4.12	41.84	-0.4749D 04	-0.1038D 04	-0.8680D 03	0.1389D 04	-0.5754D 03	-0.5211D 04	-0.1841D 02
22	4.20	42.66	-0.2545D 04	-0.7024D 03	-0.9741D 03	0.7050D 03	-0.4635D 03	-0.2783D 04	-0.1871D 02
23	4.27	43.37	-0.7960D 04	-0.1115D 04	-0.1361D 04	0.8247D 03	-0.1017D 04	-0.8058D 04	-0.6774D 01
24	4.55	46.15	-0.3227D 03	-0.1247D 04	-0.1569D 03	-0.3479D 03	-0.2064D 03	-0.1363D 04	-0.1849D 02
25	5.02	50.93	-0.2735D 03	-0.1026D 04	-0.1300D 03	-0.4360D 03	-0.7396D 02	-0.1226D 04	-0.2460D 02
26	5.49	55.70	-0.7953D 02	-0.8505D 03	-0.9300D 02	-0.3476D 03	0.5402D 02	-0.9840D 03	-0.2102D 02
27	5.96	60.47	-0.1619D 02	-0.6813D 03	-0.6975D 02	-0.2370D 03	0.5964D 02	-0.7571D 03	-0.1774D 02
28	6.43	65.25	-0.4333D 02	-0.5589D 03	-0.6022D 02	-0.1664D 03	0.5698D 01	-0.6079D 03	-0.1642D 02
29	1.48	69.95	-0.1632D 03	-0.5070D 03	-0.2212D 03	-0.7059D 02	-0.1492D 03	-0.5209D 03	-0.1116D 02
30	4.70	71.74	-0.1693D 03	-0.5351D 03	-0.2325D 03	-0.8034D 02	-0.1525D 03	-0.5520D 03	-0.1186D 02
31	7.66	69.55	-0.1852D 03	-0.3803D 03	-0.1866D 03	-0.1088D 03	-0.1367D 03	-0.4289D 03	-0.2406D 02
32	5.29	80.65	-0.9238D 02	-0.3520D 03	-0.1467D 03	-0.6159D 02	-0.7851D 02	-0.3659D 03	-0.1269D 02
33	6.62	101.02	-0.5433D 02	-0.2153D 03	-0.8897D 02	-0.2822D 02	-0.4952D 02	-0.2201D 03	-0.9663D 01
34	8.65	131.93	-0.4732D 02	-0.1477D 03	-0.6436D 02	-0.1090D 02	-0.4615D 02	-0.1489D 03	-0.6126D 01
35	11.30	172.36	-0.4779D 02	-0.1209D 03	-0.5568D 02	-0.4333D 01	-0.4754D 02	-0.1212D 03	-0.3379D 01
36	14.76	225.24	-0.4806D 02	-0.1097D 03	-0.5206D 02	-0.1873D 01	-0.4801D 02	-0.1098D 03	-0.1739D 01
37	19.30	294.41	-0.4824D 02	-0.1046D 03	-0.5044D 02	-0.8810D 00	-0.4823D 02	-0.1046D 03	-0.8953D 00
38	25.23	384.88	-0.4851D 02	-0.1021D 03	-0.4970D 02	-0.4494D 00	-0.4851D 02	-0.1021D 03	-0.4805D 00
39	32.98	503.22	-0.4884D 02	-0.1008D 03	-0.4937D 02	-0.2378D 00	-0.4884D 02	-0.1008D 03	-0.2623D 00
40	43.31	659.15	-0.4895D 02	-0.1002D 03	-0.4921D 02	-0.1032D 00	-0.4895D 02	-0.1002D 03	-0.1155D 00
41	5.93	35.89	0.6314D 04	-0.1379D 02	0.9451D 03	-0.1383D 03	0.6317D 04	-0.1681D 02	-0.1251D 01
42	6.04	36.60	0.2218D 04	-0.2083D 03	0.6030D 03	0.9567D 03	0.2550D 04	-0.5401D 03	0.1913D 02
43	6.18	37.41	0.3863D 04	-0.4875D 03	0.5063D 03	0.1217D 04	0.4180D 04	-0.8046D 03	0.1461D 02
44	6.34	38.43	0.2290D 04	-0.8371D 03	0.2179D 03	0.1922D 04	0.3204D 04	-0.1751D 04	0.2544D 02
45	6.51	39.44	0.6892D 03	-0.9930D 03	-0.4557D 02	0.2237D 04	0.2238D 04	-0.2542D 04	0.3470D 02
46	6.68	40.46	-0.9700D 03	-0.1042D 04	-0.3019D 03	0.2120D 04	0.1114D 04	-0.3127D 04	0.4451D 02
47	6.85	41.48	-0.2661D 04	-0.1094D 04	-0.5631D 03	0.1724D 04	0.1641D 02	-0.3771D 04	-0.3278D 02
48	6.98	42.29	-0.1633D 04	-0.1078D 04	-0.8133D 03	0.9206D 03	-0.3939D 03	-0.2317D 04	-0.3661D 02
49	7.10	42.99	-0.5105D 04	-0.1059D 04	-0.9246D 03	0.1105D 04	-0.7767D 03	-0.5387D 04	-0.1433D 02
50	7.55	45.76	-0.2728D 03	-0.6626D 03	-0.9354D 02	-0.3806D 03	-0.4011D 02	-0.8953D 03	-0.3144D 02
51	8.34	50.49	-0.2797D 03	-0.5550D 03	-0.8347D 02	-0.4435D 03	0.4700D 02	-0.8817D 03	-0.3638D 02
52	9.12	55.22	-0.1724D 03	-0.4927D 03	-0.6651D 02	-0.3967D 03	0.9526D 02	-0.7604D 03	-0.3401D 02
53	9.90	59.96	-0.1052D 03	-0.4334D 03	-0.5386D 02	-0.3003D 03	0.7295D 02	-0.6115D 03	-0.3068D 02
54	10.68	64.69	-0.8690D 02	-0.3757D 03	-0.4626D 02	-0.2249D 03	0.3598D 02	-0.4986D 03	-0.2865D 02
55	8.26	35.43	0.2695D 04	-0.2257D 03	0.3704D 03	0.2547D 03	0.2717D 04	-0.2478D 03	0.4946D 01
56	8.42	36.12	0.1365D 04	-0.5814D 03	0.2350D 03	0.1188D 04	0.1927D 04	-0.1144D 04	0.2534D 02
57	8.61	36.93	0.2257D 04	-0.8660D 03	0.2087D 03	0.1662D 04	0.2976D 04	-0.1585D 04	0.2339D 02
58	8.84	37.93	0.1803D 04	-0.1172D 04	0.9466D 02	0.2241D 04	0.3005D 04	-0.2374D 04	0.2821D 02
59	9.08	38.93	0.1212D 04	-0.1293D 04	-0.1206D 02	0.2380D 04	0.2649D 04	-0.2729D 04	0.3112D 02
60	9.31	39.94	0.4768D 03	-0.1246D 04	-0.1153D 03	0.2170D 04	0.1950D 04	-0.2719D 04	0.3417D 02
61	9.55	40.94	-0.4218D 03	-0.1037D 04	-0.2189D 03	0.1656D 04	0.9547D 03	-0.2414D 04	0.3974D 02
62	9.73	41.74	-0.3142D 03	-0.7327D 03	-0.3141D 03	0.8977D 03	0.3984D 03	-0.1445D 04	0.3844D 02

VITA ^v

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USING THE FINITE ELEMENT METHOD

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