# AN ANALYTICAL AND EXPERIMENTAL INVESTIGATION OF A MONOLITHIC TRAPEZOIDAL SHEAR PANEL SUBJECTED TO MECHANICAL LOADING

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Thesis Approved:

Thesis Adviser

Dean of the Graduate College

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#### CHAPTER I

#### INTRODUCTION

The purpose of this document is to present the results of an analytical and experimental investigation of a monolithic trapezoidal shear panel under mechanical loading and to recommend additional investigations which would extend the field of knowledge about this important structural element. The trapezoidal shear panel was chosen because limited analytical work had been done on the stress or strain distribution in this configuration. Ayres (Reference 2) and Stone (Reference 13) have considered multiweb monolithic panels. Although Ayres has investigated the details of the stress distribution within the individual web elements, his study was limited to rectangular elements. Stone, on the other hand, has investigated a panel with symmetrical trapezoidal web elements, but the primary purpose of his investigation was extension of the force method. Figure 1 shows the geometry of the panel used in the investigation along with a sketch showing where a panel of this type is used in an aerospace structure.

The experimental investigation was intended to provide a set of data which could be used to verify not only the analytical results of this investigation, but also refined



(a) Actual Sheet-Stringer Panel





Figure 1. Panel Geometry

analytical investigations in the future. Although the investigation described here is limited to mechanical loading, additional experimental data could be readily obtained for thermal loading to be used in verifying thermal analysis methods.

In order to obtain the most accurate experimental data possible, it was decided that the test panel should be monolithic. This type of construction eliminates the difficult to determine effects of joint and fastener friction. In addition, the panel was made symmetric with respect to the median plane of the web to minimize the effects of lateral bending due to eccentricity of loading. This symmetric, monolithic construction corresponds to the assumptions normally made in developing methods of analysis. It should, therefore, provide consistent experimental data that can be used to validate these methods. To the author's knowledge, this was the first simulated built-up structural model constructed in this manner.

The analytical investigation had a two-fold purpose:

- 1. To compare the two most commonly used methods of structural analysis - the displacement method and the force method - and to determine the relative accuracy of the methods for the structure being considered. The comparison is made for a series of mathematical models of the panel with various subelement sizes. It was expected that the two methods would yield identical results for the larger sub-element sizes but that, the results would differ for the smaller sub-element sizes.
- 2. To determine, if possible, the optimum sub-element size for each method.

"Optimum" is intended to mean the largest sub-element size that would yield results of the accuracy required for both analysis and design.

The most important consideration in the analytical investigation was the selection of a mathematical model, or models. In the past, the majority of the comparisons of the two methods have been based on analyses of different mathematical models of a specified structure. To insure that the comparison to be made in this investigation would be affected only by computational accuracy, the same model was used for both analyses. The model selected is the one most generally used in displacement analyses, finite elements connected only at their common nodal points. The two significant developments which were required in the analytical investigation are:

> 1. The derivation of a stiffness matrix for a trapezoidal plate element. Previous analyses of structures with this type of element have used four triangles joined at the centroid of the trapezoid to approximate the element stiffness. The disadvantages of the four-triangle method are that the size of the stiffness matrix is increased and the stress distribution within the plate cannot be determined.

2. The derivation of a set of self-equilibrating redundant force systems for plate elements which are not separated by stiffener elements. This development was necessary in order to be able to use the displacement-type mathematical model for the force analysis. This development not only increases the accuracy of the force method for sheet-stringer panel structures, but also makes possible the analysis of shell structures by the force method.

The two methods of matrix structural analysis - the displacement and force methods - are discussed in Chapters II and III, respectively. The details of the development of the digital computer programs are given in Appendices A and B. The experimental program is outlined in Chapter IV and the results of this program are presented in Appendix C. In Chapter V, the results of the two analyses are compared and then the analytical and experimental results are compared. The conclusions regarding the results of the investigation and the degree to which the objectives were attained are presented in Chapter VI along with recommendations for additional investigations.

#### CHAPTER II

#### THE MATRIX DISPLACEMENT METHOD

Displacement methods of structural analysis are based on the following premise: of all the geometrically compatible displacement configurations of a loaded structure, the correct configuration is the one for which every element of the structure is in equilibrium. Although it is possible to satisfy the above conditions at the infinitesimal level in simple structures, most thin-web structures are far too complex for analysis at this level. Therefore, in order to analyze structures of this type, it is necessary to subdivide the structure into a number of relatively simple elements (usually bars, beams, and plates). While equilibrium of each element is maintained, compatibility of displacements is enforced only at the assumed joints, or nodes.

Numerous methods have been developed for the analysis of structures using the procedure outlined above. The large scale digital computer has made the matrix methods the most widely accepted for complex structures. Two matrix methods are currently in use. The basic difference between the two methods is the way in which the support conditions, or constraints, are taken into account. The methods and their differences are:

- 1. The Direct Stiffness Method The support conditions are ignored until the stiffness matrix of the unrestrained structure has been determined. This singular matrix is then made nonsingular by taking the support conditions into account. The nonsingular matrix can then be inverted to obtain the flexibility matrix of the structure.
- 2. The Indirect Stiffness Method The constraints on the structure are considered from the beginning. When the stiffness matrix is determined it is already nonsingular and can be inverted immediately to obtain the flexibility matrix.

The direct stiffness method was chosen for the analysis presented here primarily because of the ease with which the method could be programmed for solution on a digital computer. This method was originally presented in a paper by Turner, et al (Reference 14), which remains the best available document on the method. A recent book by Martin (Reference 9) presents additional information on the analysis of framed structures; however, thin-web structures are not considered. An excellent exposition of the indirect method is presented by Pestel and Leckie in Reference 10, Chapter 10.

The direct stiffness method can be stated in terms of the two equations,

$$\{p_{g}\} = [k_{g}] \{V_{g}\}$$
 and (1)  
 $\{f\} = [K] \{d\}$ , (2)

where

- [Kg] = the singular stiffness matrix of the g<sup>th</sup> element,
- {f} = the column matrix of the external forces
   acting on the structure,
- {d} = the column matrix of the absolute displacements of the structure, and
- [K] = the singular stiffness matrix of the structure.

If the element stiffness matrices are available, Equation 1 can be used to determine the force-displacement relationship for each element of the structure. The force-displacement relationship for the entire structure can then be determined by combining these element stiffnesses. Since the sum of the internal forces at a node must equal the external forces, and the element displacements at a node must equal the actual displacements of the node, the stiffness of the structure [K] can be obtained by summing the element stiffnesses. Examples of this procedure are given in Reference 14.

The singular stiffness matrix [K] can readily be made nonsingular by striking out the rows and columns corresponding to the constraints on the structure. The justification for this simple procedure is given in Reference 14. An alternate method of making the stiffness matrix nonsingular is discussed in Appendix A.

#### The Mathematical Model

In order to apply the direct stiffness method to the experimental panel, it is necessary to replace the actual panel with a mathematical model composed of a number of discrete elements joined only at the nodes. Since the main purpose of the investigation is to determine the effect of element size on the accuracy of the predicted stresses, a total of seven models have been studied. The method of subdividing the panel for each model is illustrated in Figure 2. The subdivided panels will be identified both by the model number (1-7) and the number of rows (M) and columns (N) of nodes. The assumed support conditions and loads are shown in Figure 3.

The first model (M = N = 2) contains the minimum number of elements, four stiffener elements and one plate element. It is assumed that these elements are connected only at the nodes. Therefore the forces on each element are as shown in Figure 4. Since there is no shear tie between the stiffeners and the plate element, the load in each stiffener is constant over the length of the member. A stiffness matrix for this type of element is derived in Reference 14.

A stiffness matrix was not available, however, for a trapezoidal plate element; therefore, such a stiffness matrix was derived for this investigation. The derivation is presented in a later section.

It is obvious that the results of an analysis of Model No. 1 cannot accurately predict the stiffener stresses, and



Figure 2. Panel Subdivisions for the Mathematical Models







Figure 4. Internal Forces in Model No. 1

it is unlikely that the web stresses can be determined with accuracy except at points well away from the edges of the element. Therefore, Models 2 through 7 are divided into successively smaller elements in order to study the effect of element size. The smallest element size, Model No. 7, was dictated by two considerations:

- 1. Since there are two degrees of freedom at each node, the stiffness matrix is of order 2 x M x N. For Model No. 7 this necessitates the inversion of a 162 x 162 matrix. The largest matrix which could be inverted on the available equipment was 200 x 200; therefore, it was impractical to use smaller subelements.
- 2. The derivation of the stiffness matrix for a trapezoidal plate is based on the assumption of a state of plane stress, i.e., that the thickness of the plate is small in comparison to its other dimensions. A finer element breakdown would undoubtedly reduce the size of the elements to the point where this assumption would not be valid.

#### Trapezoidal Plate Stiffness Matrix

In order to derive a stiffness matrix for a plate element, it is necessary to assume either a stress distribution or a distribution of the displacements throughout the element. In Reference 14, a stiffness matrix for a triangular plate was derived by assuming a constant stress distribution, i.e.,

$$\sigma_{xx}(x,y) = A, \quad \sigma_{yy}(x,y) = B, \text{ and } \tau_{xy}(x,y) = C$$
 (3)

Although it has not been published, the same stiffness matrix can be derived by assuming a linear displacement function of

the form

$$u(x,y) = A + Bx + Cy$$
 and  $v(x,y) = E + Fx + Hy$  (4)

However, in the case of a plate with more than three nodes, different stiffness matrices result from what appear to be equivalent assumptions for the distribution of stresses or displacements. For instance, References 7 and 14 present a rectangular plate stiffness matrix based on a stress distribution described by

$$\sigma_{xx}(x,y) = Ay + B, \sigma_{yy}(x,y) = Cx + D, \text{ and}$$
 (5)

 $\tau_{xy}(x,y) = E .$ 

In Reference 1, an equivalent matrix is obtained by assuming linear displacements along the boundaries of the plate, i.e.,

$$u(x,y) = A + Bx + Cxy + Dy$$
, and  
(6)  
 $v(x,y) = E + Fx + Gxy + Hy$ .

The resulting stiffness matrices appear different in either symbolic or numerical form for a given plate element. It has been shown, however, that for a typical sheet-stringer panel with rectangular panel elements, the most significant stresses and displacements are essentially the same when either stiffness matrix is used (Reference 4).

Another approach which has been used to derive a rectangular plate stiffness matrix (Reference 14) is to assume an assemblage of four triangular plates joined at

the four corners and at the center of the rectangle. This method has also been the only available method for obtaining the stiffness of a trapezoidal plate element up until this time.

Recently (Reference 13), a flexibility matrix has been derived for a trapezoidal plate; however, this matrix includes the flexibilities of the adjoining stiffeners and cannot be used for the mathematical models shown in Figure 2.

The following derivation was developed to eliminate the necessity of treating a trapezoidal plate element as a group of triangles. There are two major advantages to this approach:

- 1. It eliminates two degrees of freedom for each trapezoidal plate and, consequently, reduces the size of the stiffness matrix which must be inverted. As an example of the magnitude of the reduction - a 290th order matrix would have resulted if each trapezoid of Model 7 had been broken down into four triangles.
- 2. It allows the calculation of the stresses at any point within the trapezoid, while the triangular break-down method yields four sets of constant stresses for the four triangular elements.

In view of the above discussion of triangular and rectangular plates, it is evident that a decision was necessary as to the type of distribution to be assumed - stress or displacement. Since the shear stress in a trapezoidal panel must vary in the direction of the taper, Equations 5 cannot be used. As will be shown later, the shear stress derived using Equations 6 vary in both the x- and y-directions; therefore, Equations 6 will be used in the following derivation. In addition to the assumption of the displacement function, it is also assumed that the plate element is homogeneous, isotropic, and of constant thickness and that small displacement theory holds. The element geometry and nomenclature is shown in Figure 5.

Equations 6 adequately describe the displacements throughout the element; however, each of the constants is a linear function of the displacements of the nodes, ie,

$$A = A(u_1, u_2, u_3, u_4) , \text{ etc.}, \text{ and}$$

$$E = E(v_1, v_2, v_3, v_4) , \text{ etc.}$$
(7)

In order to simplify the derivation, Equations 6 are written in matrix notation as

$$u(\mathbf{x}, \mathbf{y}) = \begin{bmatrix} u_1 & u_2 & u_3 & u_4 \end{bmatrix} \begin{bmatrix} A_1 & B_1 & C_1 & D_1 \\ A_2 & B_2 & C_2 & D_2 \\ A_3 & B_3 & C_3 & D_3 \\ A_4 & B_4 & C_4 & D_4 \end{bmatrix} \begin{bmatrix} 1 \\ \mathbf{x} \\ \mathbf{y} \end{bmatrix}$$
(8)

and

$$\begin{array}{l} \mathbf{v}(\mathbf{x},\mathbf{y}) \;=\; \left[\mathbf{v}_{1} \; \mathbf{v}_{2} \; \mathbf{v}_{3} \; \mathbf{v}_{4}\right] & \begin{bmatrix} \mathbf{E}_{1} \; & \mathbf{F}_{1} \; & \mathbf{G}_{1} \; & \mathbf{H}_{1} \\ \mathbf{E}_{2} \; & \mathbf{F}_{2} \; & \mathbf{G}_{2} \; & \mathbf{H}_{2} \\ \mathbf{E}_{3} \; & \mathbf{F}_{3} \; & \mathbf{G}_{3} \; & \mathbf{H}_{3} \\ \mathbf{E}_{4} \; & \mathbf{F}_{4} \; & \mathbf{G}_{4} \; & \mathbf{H}_{4} \end{bmatrix} & \begin{bmatrix} 1 \\ \mathbf{x} \\ \mathbf{x} \\ \mathbf{y} \\ \mathbf{y} \end{bmatrix} \\ \end{array} \\ \begin{array}{l} \text{where} \quad \mathbf{A} \;=\; \mathbf{u}_{1}\mathbf{A}_{1} \;+\; \mathbf{u}_{2}\mathbf{A}_{2} \;+\; \mathbf{u}_{3}\mathbf{A}_{3} \;+\; \mathbf{u}_{4}\mathbf{A}_{4} \;,\; \text{etc.} \;, \quad \text{and} \\ \\ \mathbf{E} \;=\; \mathbf{v}_{1}\mathbf{E}_{1} \;+\; \mathbf{v}_{2}\mathbf{E}_{2} \;+\; \mathbf{v}_{3}\mathbf{E}_{3} \;+\; \mathbf{v}_{4}\mathbf{E}_{4} \;,\; \text{etc.} \;. \end{array}$$

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(9)



Figure 5. Web Element Geometry and Nomenclature

The coefficients in any row of Equations 8 and 9 can now be evaluated by applying a unit displacement at the corresponding node. The first row of the square matrix in Equation 8 can be evaluated by taking

$$u_{1} = 1 \quad \text{and} \quad u_{2} = u_{3} = u_{4} = 0 , \quad (10)$$
$$u(x,y) = [A_{1} B_{1} C_{1} D_{1}] \{1 x xy y\}$$
$$= [1 x xy y] \{A_{1} B_{1} C_{1} D_{1}\} . \quad (11)$$

The corresponding boundary conditions are (Figure 5)

then

$$u(x_1, y_1) = 1$$
,  
 $u(x_2, y_2) = 0$ ,  
 $u(x_3, y_3) = 0$ , and  
 $u(x_4, y_4) = 0$ .

Substitution of Equations 12 into Equation 11 and rearrange-

$$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & x_2 & 0 & 0 \\ 1 & x_3 & x_3 y_3 & y_3 \\ 1 & x_4 & x_4 y_3 & y_3 \end{bmatrix} \begin{bmatrix} A_1 \\ B_1 \\ C_1 \\ D_1 \end{bmatrix}$$
(13)

since  $x_1 = y_1 = y_2 = 0$  and  $y_4 = y_3$ .

Equation 13 can be solved for the constants by premultiplying both sides by the inverse of the coordinate matrix with the

(12)

following result

$$\begin{bmatrix} A_{1} \\ B_{1} \\ C_{1} \\ D_{1} \end{bmatrix} = \frac{1}{x_{2}y_{3}} \begin{bmatrix} x_{2}y_{3} & 0 & 0 & 0 \\ -y_{3} & y_{3} & 0 & 0 \\ 1 & -1 & -\lambda & \lambda \\ -x_{2} & 0 & \lambda x_{4} & -\lambda x_{3} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \frac{1}{x_{2}y_{3}} \begin{bmatrix} x_{2}y_{3} \\ -y_{3} \\ 1 \\ -x_{2} \end{bmatrix}$$
(14)

where  $\lambda = x_2/(x_4 - x_3) = x_2/x_{43}$ 

if

$$x_{ij} = x_i - x_j$$
.

The remaining three rows of constants in Equation 8 can be readily determined from a consideration of the boundary conditions and Equations 11 through 14. For instance, if

$$u_2 = 1$$
 and  $u_1 = u_3 = u_4 = 0$  (15)

then 
$$u(x,y) = [1 x x y y] \{A_2 B_2 C_2 D_2\}$$
 (16)

where  $u(x_1, y_1) = 0$ ,

$$u(x_2, y_2) = 1$$
,  
 $u(x_3, y_3) = 0$ , and  
 $u(x_4, y_4) = 0$ .  
(17)

The equivalent of Equation 13 is then

$$\begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & x_2 & 0 & 0 \\ 1 & x_3 & x_3 y_3 & y_3 \\ 1 & x_4 & x_4 y_3 & y_3 \end{bmatrix} \begin{bmatrix} A_2 \\ B_2 \\ C_2 \\ D_2 \end{bmatrix}$$
(18)

It can be seen that only the two column vectors are different from those in Equation 13 so that the second row of constants in Equation 8 is equal to the second column of the coefficient matrix of Equation 14, i.e.,

$$\begin{bmatrix} A_{2} \\ B_{2} \\ C_{2} \\ D_{2} \end{bmatrix} = \frac{1}{x_{2}y_{3}} \begin{bmatrix} 0 \\ y_{3} \\ -1 \\ 0 \end{bmatrix}$$
(19)

The same approach can be used to determine the remaining two rows of constants in Equation 8 so that this equation can be written as

$$u(x,y) = \frac{1}{x_2 y_3} \begin{bmatrix} u_1 & u_2 & u_3 & u_4 \end{bmatrix} \begin{bmatrix} x_2 y_3 & -y_3 & 1 & -x_2 \\ 0 & y_3 & -1 & 0 \\ 0 & 0 & -\lambda & \lambda x_4 \\ 0 & 0 & -\lambda & -\lambda x_3 \end{bmatrix} \begin{bmatrix} 1 \\ x \\ y \\ y \end{bmatrix} (20)$$

Since all of the boundary conditions for evaluating the constants in Equation 9 are identical to those used to evaluate the constants in Equation 8, Equation 9 can be written as

$$\mathbf{v}(\mathbf{x},\mathbf{y}) = \frac{1}{\mathbf{x}_{2}\mathbf{y}_{3}} \begin{bmatrix} \mathbf{v}_{1} \ \mathbf{v}_{2} \ \mathbf{v}_{3} \ \mathbf{v}_{4} \end{bmatrix} \begin{bmatrix} \mathbf{x}_{2}\mathbf{y}_{3} \ -\mathbf{y}_{3} \ 1 \ -\mathbf{x}_{2} \\ 0 \ \mathbf{y}_{3} \ -\mathbf{1} \ 0 \\ 0 \ 0 \ -\lambda \ \lambda \mathbf{x}_{4} \\ 0 \ 0 \ \lambda \ -\lambda \mathbf{x}_{3} \end{bmatrix} \begin{bmatrix} 1 \\ \mathbf{x} \\ \mathbf{y} \\ \mathbf{y} \end{bmatrix}$$
(21)

In order to simplify future calculations the following definitions are introduced

$$u(x,y) = \frac{1}{x_2y_3} [u_1 \ u_2 \ u_3 \ u_4] [J] \{1 \ x \ xy \ y\}$$
(22)
$$v(x,y) = \frac{1}{x_2y_3} [v_2 \ v_2 \ v_3 \ v_4] [J] \{1 \ x \ xy \ y\}$$

$$v(x,y) = \frac{1}{x_2y_3} [v_1 v_2 v_3 v_4] [J] \{1 x xy y\}$$

where 
$$[J] = \begin{bmatrix} x_2 y_3 & -y_3 & 1 & -x_2 \\ 0 & y_3 & -1 & 0 \\ 0 & 0 & -\lambda & \lambda x_4 \\ 0 & 0 & \lambda & -\lambda x_3 \end{bmatrix}$$
 (23)

With these constants evaluated, it is now possible to determine stress and strain functions through the use of the equations of elasticity. For the two-dimensional case, the strain-displacement relations are

$$\varepsilon_{\mathbf{x}\mathbf{x}} = \frac{\partial \mathbf{u}}{\partial \mathbf{x}}$$
,  $\varepsilon_{\mathbf{y}\mathbf{y}} = \frac{\partial \mathbf{v}}{\partial \mathbf{y}}$ , and  $\varepsilon_{\mathbf{x}\mathbf{y}} = \frac{\partial \mathbf{u}}{\partial \mathbf{y}} + \frac{\partial \mathbf{v}}{\partial \mathbf{x}}$  (24)

Substitution of Equations 22 into these relations gives

$$\begin{aligned} \varepsilon_{xx}(x,y) &= \frac{1}{x_2 y_3} [u_1 \ u_2 \ u_3 \ u_4] [J] \{0 \ 1 \ y \ 0\} , \\ \varepsilon_{yy}(x,y) &= \frac{1}{x_2 y_3} [v_1 \ v_2 \ v_3 \ v_4] [J] \{0 \ 0 \ x \ 1\} , \text{ and} \end{aligned}$$
(25)  
$$\gamma_{xy}(x,y) &= \frac{1}{x_2 y_3} [u_1 \ u_2 \ u_3 \ u_4] [J] \{0 \ 0 \ x \ 1\} , \\ &+ \frac{1}{x_2 y_3} [v_1 \ v_2 \ v_3 \ v_4] [J] \{0 \ 1 \ y \ 0\} . \end{aligned}$$

The stresses can be determined from the strains and the equations of plane stress. These equations can be written as

$$\sigma_{xx} = E'(\varepsilon_{xx} + v \varepsilon_{yy}),$$

$$\sigma_{yy} = E'(\varepsilon_{yy} + v \varepsilon_{xx}), \text{ and} \qquad (26)$$

$$\tau_{xy} = \frac{(1 - v)E'}{2} \gamma_{xy}$$

where

$$E' = \frac{\Sigma}{1 - v^2}$$

\_!

 $\Sigma = Young's modulus$ 

v = Poisson's ratio.

Substitution of the strain equations into the plane stress equations yields

$$\sigma_{xx}(x,y) = \frac{E'}{x_2 Y_3} [u_1 \ u_2 \ u_3 \ u_4] [J] \{0 \ 1 \ y \ 0\} + \frac{\nu E'}{x_2 Y_3} [v_1 \ v_2 \ v_3 \ v_4] [J] \{0 \ 0 \ x \ 1\} \sigma_{yy}(x,y) = \frac{E'}{x_2 Y_3} [v_1 \ v_2 \ v_3 \ v_4] [J] \{0 \ 0 \ x \ 1\} + \frac{\nu E'}{x_2 Y_3} [u_1 \ u_2 \ u_3 \ u_4] [J] \{0 \ 1 \ y \ 0\} , and \tau_{xy} = \frac{(1 - \nu) E'}{2x_2 Y_3} [u_1 \ u_2 \ u_3 \ u_4] [J] \{0 \ 0 \ x \ 1\} + \frac{(1 - \nu) E'}{2x_2 Y_3} [v_1 \ v_2 \ v_3 \ v_4] [J] \{0 \ 1 \ y \ 0\} .$$

The stiffness coefficients can be determined from the stresses and strains by several methods. The method chosen here is the unit displacement method. The unit displacement equation is (Reference 1, p. 49)

$$l \times k_{ij} = \int (\sigma_{xxi} \varepsilon_{xxj} + \sigma_{yyi} \varepsilon_{yyj} + \tau_{xyi} \gamma_{xyj}) dV ,$$
(28)
$$V$$
(i,j = 1,8)

where  $k_{ij}$  is the force at i due to a unit displacement at j,  $\varepsilon_{xxj}$  is the strain due to a unit displacement at j, etc. The use of the equation will be demonstrated by evaluating  $k_{12}$ . The stresses are obtained from Equations 27 with  $u_1 = 1$  and all other nodal displacements equal to zero. The result is

$$\sigma_{xx} (x,y) = \frac{E}{x_2 y_3} (y - y_3) = -\frac{E}{x_2} (1 - \eta) ,$$
  

$$\sigma_{yy} (x,y) = \frac{E'}{x_2 y_3} (y - y_3) = -\frac{E'}{x_2} (1 - \eta) , \text{ and } (29)$$
  

$$\tau_{xy} (x,y) = \frac{(1 - v)E'}{2x_2 y_3} (x - x_2) = -\frac{(1 - v)E'}{2y_3} (1 - \xi)$$

where  $\xi = x/x_2$  and  $\eta = y/y_3$ .

The strains can be determined from Equations 25 with  $u_2 = 1$ and all other nodal displacements equal to zero, giving

$$\varepsilon_{xx}(x,y) = \frac{1}{x_2y_3}(y_3 - y) = \frac{1}{x_2}(1 - \eta)$$
,  
 $\varepsilon_{yy}(x,y) = 0$ , and (30)

$$\gamma_{xy}(x,y) = \frac{-x}{x_2y_3} = -\frac{1}{y_3} \xi$$
.

Equations 29 and 30 can now be used with Equation 28 to give

$$k_{12} = E' \int \left[ -\frac{1}{x_2^2} (1 - \eta)^2 + \frac{1 - \nu}{2y_3^2} (1 - \xi) \xi \right] dV \quad (31)$$

The differential volume can be expressed as

$$dV = t \, dx \, dy = t \, x_2 y_2 \, d\xi \, d\eta \tag{32}$$

and the limits of integration are, for y,

$$y = 0$$
 to  $y = y_3$  (33)  
 $n = 0$  to  $n = 1$ , and for x.

$$x = \frac{x_3}{y_3} y$$
 to  $x = x_2 + \frac{x_{42}}{y_3} y$  (34)

or 
$$\xi = \frac{x_3}{x_2} \eta = \rho \eta$$
 to  $\xi = 1 + \frac{x_{42}}{x_2} \eta = 1 + \beta \eta$ 

where  $\rho = \frac{x_3}{x_2}$  and  $\beta = \frac{x_{42}}{x_2}$ .

Equation 31 now becomes

or

$$k_{12} = E't \left\{ \frac{1-\nu}{2m} \left[ \frac{1}{2} (1+\beta + \frac{\beta^2 - \rho^3}{3}) - \frac{1}{3} (1+\frac{3\beta}{2} + \beta^2 + \frac{\beta^3 - \rho^3}{4}) \right] - m(\frac{1}{3} + \frac{\beta - \rho}{12}) \right\}$$
(35)

where  $m = y_3/x_2$ .

Since there are thirty-six independent stiffness coefficients, Equation 28 must be evaluated thirty-six times. Although this could be done in the direct manner just illustrated, there is an approach which is better suited to automatic computation. The stiffness relation for the plate element, Equation 1, may be partitioned and written as

where

$$\begin{bmatrix} \underline{p}_{x} \\ \overline{p}_{y} \end{bmatrix} = \mathbf{E} \cdot \mathbf{t} \begin{bmatrix} \frac{k_{xu} & k_{xv}}{k_{yu} & k_{yv}} \end{bmatrix} \begin{bmatrix} \underline{u} \\ \overline{v} \end{bmatrix}$$

$$\{ \mathbf{p}_{x} \} = \{ \mathbf{p}_{x1} & \mathbf{p}_{x2} & \mathbf{p}_{x3} & \mathbf{p}_{x4} \} ,$$

$$\{ \mathbf{p}_{y} \} = \{ \mathbf{p}_{y1} & \mathbf{p}_{y2} & \mathbf{p}_{y3} & \mathbf{p}_{y4} \} ,$$

$$\{ \mathbf{u} \} = \{ \mathbf{u}_{1} & \mathbf{u}_{2} & \mathbf{u}_{3} & \mathbf{u}_{4} \} , \text{ and}$$

$$\{ \mathbf{v} \} = \{ \mathbf{v}_{1} & \mathbf{v}_{2} & \mathbf{v}_{3} & \mathbf{v}_{4} \} .$$

The submatrices in Equation 36 each have a component due to the direct stresses,  $\sigma_{xx}$  and  $\sigma_{yy}$ , and a component due to the shear stress,  $\tau_{xy}$ . For instance, the upper left submatrix could be written as

$$\begin{bmatrix} k_{xu} \end{bmatrix}_{d} = \begin{bmatrix} k_{xu} \end{bmatrix}_{d} + \begin{bmatrix} k_{xu} \end{bmatrix}_{s}$$
(37)

It can be shown, however, that the shear components can be written in terms of the direct components. The resulting equations are

$$\begin{bmatrix} k_{xu} \end{bmatrix} = \begin{bmatrix} k_{xu} \end{bmatrix}_{d} + \frac{1 - \nu}{2} \begin{bmatrix} k_{yv} \end{bmatrix}_{d},$$

$$\begin{bmatrix} k_{yv} \end{bmatrix} = \begin{bmatrix} k_{yv} \end{bmatrix}_{d} + \frac{1 - \nu}{2} \begin{bmatrix} k_{xu} \end{bmatrix}_{d}, \text{ and } (38)$$

$$\begin{bmatrix} k_{xv} \end{bmatrix} = \begin{bmatrix} k_{yu} \end{bmatrix}^{T} = \begin{bmatrix} k_{xv} \end{bmatrix}_{d} + \frac{1 - \nu}{2\nu} \begin{bmatrix} k_{xv} \end{bmatrix}_{d}^{T}$$

The three four-by-four matrices in Equations 38 can be determined from the elements of a column matrix, {Z}, defined by

$$\{Z_{m}\} = [A_{mn}]\{C_{n}\}$$
 (m=1,21; n=1,6) (39)

The matrices  $[A_{mn}]$  and  $\{C_n\}$  are given as Equations 41 and 42.

The equations which define the firect stiffnesses are

$$\begin{bmatrix} k_{xu} \end{bmatrix}_{d} = \begin{bmatrix} z_{1} & -z_{1} & z_{2} & -z_{2} \\ & z_{1} & -z_{2} & z_{2} \\ & & z_{3} & -z_{3} \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & &$$

	m	2m	m	0	0	0
	0	$-\lambda m$	$-\lambda m$	0	0	0
	0	0	$\lambda^{2}m$	0	0	0
	V ·	ν	0	ν	ν	0
	0	0	0	-v .	- v	0
	-δλυ	-δλυ	0	-λυ	$-\lambda v$	. 0
	ρλν	ρλν	0	λν	λν	0
	0	-λυ	0	0	-λυ	0
	0	0	0	0	λν	0
• • •	0	$\delta \lambda^2 v$	0	0	$\lambda^2 v$	0
$[A_{mn}] =$	0	$-\rho \lambda^2 v$	0	0	$-\lambda^2 v$	0
	l/m	0	0	2/m	0	1/m
	0	0	0	-1/m	0	-1/m
	$-\delta \lambda /m$	0	0	-(1+δ)λ/m	0	-λ/m
	ρλ/m	0	0	(1+ρ)λ/m	0	λ/m
an an saidh a	0	0	0	0	0	l/m
	0	0	0	δλ/m	0	λ/m
	0	0	0	$-\rho \lambda /m$	0	λ/m
	$\delta^2 \lambda^2 / m$	0	0	$2\delta\lambda^2/m$	0	$\lambda^2/m$
	$-\delta\rho\lambda^2/m$	0	0	$-(\delta+\rho)\lambda^2/m$	0	$\lambda^2/m$
	$\rho^2 \lambda^2/m$	0	0	$2\rho\lambda^2/m$	0	$\lambda^2/m$
						(41)
$$C_{n} = \left\{ 1 - \frac{\beta - \rho}{2} - \frac{1}{2} - \frac{\beta - \rho}{3} - \frac{1}{2} - \frac{\beta}{3} - \frac{\rho}{3} - \frac{1}{2} - \frac{\beta}{3} - \frac{\beta^{2} - \rho^{2}}{6} - \frac{1}{4} - \frac{1}{2} - \frac{\beta}{2} - \frac{\beta^{2} - \rho^{2}}{6} - \frac{1}{4} - \frac{1}{2} - \frac{\beta}{3} - \frac{\beta^{2} - \rho^{2}}{6} - \frac{1}{4} - \frac{1}{3} - \frac{\beta^{2} - \rho^{2}}{6} - \frac{1}{4} - \frac{\beta^{2} - \rho^{2}}{6} - \frac{\beta^{2} - \rho^{2}}{6} - \frac{1}{4} - \frac{\beta^{2} - \rho^{2}}{6} - \frac{\beta^{2} -$$

A digital computer subprogram has been written to evaluate the stiffness coefficients as defined by Equations 38 through 42. This subprogram was used in both the stiffness analysis and the force analysis to calculate the stiffness matrices of the plate elements.

The details of the matrix displacement program are given in Appendix A along with a program listing and the tabulated results. The results of the displacement method and the force method are compared in Chapter V.

## CHAPTER III

#### THE MATRIX FORCE METHOD

Force methods of analysis are essentially the inverse of displacement methods. The force methods are based on the premise that of all the possible distributions of internal forces for which each element is in equilibrium, the correct distribution is the one which results in a geometrically compatible displacement configuration.

As in the case of the displacement method (Chapter II), the matrix force method is now an accepted method for analyzing complex structures. However, unlike the displacement method, there is only one basic matrix force method - the indirect method. A direct method is not possible because the forces acting on a structure are not completely independent. Both the applied loads and the reactions cannot be specified arbitrarily. Therefore, the constraints must be considered from the beginning. The matrix force equations used in this investigation were originally presented by Argyris and Kelsey in Reference 1; however, the nomenclature used is that of Pestel and Leckie (Reference 10).

The two basic equations of the matrix force method are

$$\{p\} = ([B_0] + [B_1][x]) \{f\}, and (43)$$

$$\{\mathbf{d}\} = \{[\mathbf{F}_{\mathbf{d}}] \{\mathbf{f}\}$$

where

- {p} = the column matrix of independent internal
  forces,
- {f} = the column matrix of external forces,
- [B<sub>0</sub>] = the matrix of statically equivalent internal forces due to unit values of the external forces,
- [B<sub>1</sub>] = the matrix of 'self-equilibrating' internal forces due to unit values of the redundants,
  - [x] = the matrix of unit redundants,
- {d} = the column matrix of the displacements at the external forces, and
- [F<sub>d</sub>] = the flexibility matrix of the assembled structure.

The equations used to determine [x] and  $[F_d]$  are given in Appendix B.

# The Mathematical Model

In the past, the mathematical model used in a force analysis has frequently differed from the model used in a displacement analysis, especially in the analysis of sheetstiffener type structures. For a displacement analysis the model is usually of the type described in the previous Chapter - stiffener elements and plate elements connected only at the nodes. On the other hand, the model for a force analysis has been obtained by assuming that the plate elements are in a state of pure shear while the stiffeners

(44)

carry the direct loads. In order to account for the fact that the plate elements actually carry some of the direct load, a part of the plate area is added to the adjacent stiffener areas and this 'effective' stiffener area is used in the analysis. Unless the stress distribution is very nearly uniform, it is difficult to accurately determine the plate area which should be assigned to each stiffener. An even more difficult problem arises when all of the nodal lines do not coincide with the stiffener centerlines, as is the case with Models 2 through 7 (Figure 2). It then becomes necessary to assume 'effective' stiffeners along these interior nodal lines. The purpose of this "lumped parameter" type of model is to reduce the number of redundants; however, the accuracy of the results is also reduced. Since the purpose of this investigation is to compare the computational accuracy of the force and displacement methods, this type of model is not used. The models used are identical to those used in the displacement analysis (Chapter II).

# Selection of Redundants

Another basic difference between the force and displacement method is that in order to use the force method the degree of redundancy of the structure is an important consideration. There is no equivalent consideration in the displacement method. As noted in the previous Chapter, the order of the matrix which must be inverted in a stiffness analysis is a function only of the number of nodes and the

number of degrees of freedom at each node. On the other hand, the order of the matrix which must be inverted in a force analysis is equal to the degree of redundancy of the structure.

The degree of redundancy of a structure can be determined from the equation

$$n = \ell - e + r \tag{45}$$

where n = the degree of redundancy,

l = the number of independent internal forces, e = the number of nodal equilibrium equations, and

r = the number of reactions.

The number of independent internal forces for a given type of member must be carefully determined. For instance, in Figure 4, four forces are shown on the leading edge and trailing edge stringers; however, only one of these forces is independent. That is, given any one of the forces, the other three can be calculated using the equations of equilibrium of the element. This is true for any axially loaded element. Each trapezoidal plate element has five independent forces, since there are a total of eight forces (Figure 4) and only three available equations of equilibrium.

The number of nodal equilibrium equations is equal to the number of degrees of freedom of the nodes which is equal to the order of the 'unreduced' stiffness matrix of the structure. The number of reactions for the panel under study here is three for all seven models. Table I shows the redundancy of each of the models along with some additional information which will be discussed below. It can be seen that Model 7 requires a larger matrix inversion for a force analysis (193 x 193) than for a displacement analysis (162 x 162). This is not true for all of the models, however. For Model 5, the matrices are approximately of equal size - 49 x 49 versus 50 x 50, and for Models 1 - 4, the flexibility matrix is smaller than the corresponding stiffness matrix.

Once the number of redundants has been determined, it is then necessary to select the internal forces which represent these redundants. For some structures, such as trusses, this is a relatively simple task. Selected elements in the structure are assumed to be 'cut' and the forces in these members are taken as the redundants. The matrix  $[B_1]$  in Equation 43 can then be easily formed since each column of this matrix consists of the internal forces due to a unit value of one of the redundants. In a structure such as the one being studied here, it is difficult to devise a stable, statically determinate structure for any of the models except Model 1. The four stiffeners of Model 1 could be 'cut' and the plate element would be both stable and statically determinate for the loads and reactions shown in Figure 3.

It is not necessary to actually devise a single stable, statically determinate structure for each model. It is only necessary to find n independent sets of internal forces which are themselves in equilibrium. This fact, although

М	N	l	n	NOA	NOB	NOC
2	2	. 9	4	4	0	0
3	2	16	7	6	1	0
3	3	28	13	8	4	1
5	3	52	25	12	10	3
5	5	96	49	16	, 24	9
9	5	184	97	24	52	21
9	9	352	193	32	112	49

DEGREE OF REDUNDANCY

			· · · · ·		
N	-	number	of columns	of	nodes

M = number of rows of nodes

- $\ell$  = number of independent internal forces
- n = number of redundants
- NOA = number of Type A redundants
- NOB = number of Type B redundants
- NOC = number of Type C redundants

n = NOA + NOB + NOC

TABLE I

previously known, was first used on sheet-stringer type structures by Argyris (Reference 1). Argyris derived a self-equilibrating force system for the type of analysis where the stringers carry the axial load and the sheet is in pure shear (Two other systems were also developed for box type structures). This self-equilibrating system could not be used for the panel being studied here. It was possible, however, to develop a series of three systems which uniquely define the redundants. These self-equilibrating systems called Types A, B, and C - are shown in Figures 6 and 7.

The Type A system was suggested by a similar application by Przemieniecki (Reference 11). A pair of equal and opposite unit loads are applied at the nodes of each stiffener element. These loads are reacted by unit loads at the same nodes on the adjacent web element. Since this system is in equilibrium no loads are transmitted to any of the adjoining elements.

The Type B system is equivalent to the Type A system at interior nodal lines where there are no stiffeners. Although the structure being studied here does not have any stiffeners at interior nodal lines, when there are interior stiffeners, two Type A systems are available for each stiffener element and a Type B system is not used.

The Type C system is similar to the system developed by Argyris. The major difference is that Argyris' system included interior stiffeners while the Type C system does not utilize interior stiffeners even if they are present. The

# (a) Type A Redundants



Figure 6. Type A and B Redundant Force Systems



Figure 7. Type C Redundant Force System

Type A systems account for all of the redundants due to the stiffeners.

The last three columns of Table I show the number of each of the systems used for the various models. It can be seen that the total is exactly equal to the number of redundants in every case.

The  $[B_0]$  matrix in Equation 43 must also be given special attention since a single stable, statically determinate structure is not used to determine  $[B_1]$ . Each column of  $[B_0]$  represents a set of internal forces due to a unit value of one of the external loads. Argyris has shown (Reference 1) that any set of internal forces that is 'statically equivalent' to, i.e., in equilibrium with, the applied load may be used.

Since there are five external loads (Figure 3), it was necessary to select five internal force distributions from among the large number of possible ones. The selection, made on the basis of ease of programming, is as follows:

> $F_1 = 1$  The load is transmitted as compression through the lower rib (Figure 3). None of the other elements are loaded.  $F_3 = 1$  The load is transmitted by the leading edge column and the lower row of web

> > elements (Figure 8). None of the stiffeners are loaded.

 $F_4 = 1$  The load is transmitted as tension by the upper rib to point 3 and then



Figure 8. Statically Equivalent Structure for a Horizontal Load at Point 3

transmitted to the supports the same as  $F_2$ .

- $F_7 = 1$  The load is resolved into two components, one along the leading edge stringer and one horizontal. The diagonal component is transmitted to the supports by the leading edge stringer and the lower rib and the horizontal component is transmitted the same as  $F_3$ .
- F<sub>8</sub> = 1 Again the load is resolved into components. One component is transmitted directly down the trailing edge stringer to the support. The other is transmitted by the upper rib to point 3 and then through the plate elements.

Subroutine subprograms have been written to generate the  $[B_1]$  and  $[B_0]$  matrices using the force systems described above and are listed in Appendix B. It should be noted that these subprograms are not at all general, i.e., they were developed for the specific structure being studied. The redundant force systems developed here are general, however, and should find application in future investigations.

The displacements and stresses that are calculated using the matrix force method are tabulated in Appendix B. These results are compared in Chapter V with those determined from the matrix displacement analysis.

### CHAPTER IV

#### THE EXPERIMENTAL PROGRAM

The three major segments of the experimental program are discussed in this Chapter. They are the design and construction of the test panel, the test fixture, and the instrumentation. The results of the experimental program are given in Appendix C.

## Test Panel

As outlined in the Introduction, the test panel was a single-bay, monolithic, tapered shear web bounded by four stiffener elements (Figure 1). After the basic configuration was selected, the primary decision necessary was the selection of the material. Aluminum alloy tool and jig plate was originally projected as a suitable material due to its dimensional stability during machining. However, the low strength of this material would have resulted in a larger web thickness and larger stiffener areas than those normally found in thin-wall aerospace structures. The material finally selected was aluminum alloy 6061-T6. This alloy has good machining qualities combined with medium strendth properties.

The web of the panel has an aspect ratio of approximately

1.8 and a taper ratio of 2.0. The aspect ratio was chosen as representative of the shear panels of aerospace structures. The taper is greater than that usually found in typical structures; however, a relatively large value was used so that taper effects on the stresses would be significant. The leading edge sweepback angle of 45° was chosen so that the leading edge of the tip rib would fall aft of the trailing edge of the root rib. Thus, vertical loads at either, or both, of the upper nodes produce significant bending as well as tension in the panel.

The web thickness and the stiffener areas were determined from a parameter study using the matrix force method of analysis. The programming for this study was performed by Mr. Charles Cole of The Boeing Company and the program was run on the Boeing 7094 computer. The original parameters were chosen as: web thickness = 0.125 in., stringer area = 1.0 sq. in., and rib area = 0.5 sq. in. These were later reduced to 0.096 in., 0.929 sq. in., and 0.462, respectively, on the final test panel.

Three panels, two aluminum and one steel, were actually constructed. The first aluminum panel was made in the Boeing experimental machine shop and was used for preliminary studies. Since this panel did not have loading lugs it was suspended in the test fixture with wires. The second aluminum panel was originally machined in the Oklahoma State University Mechanical Engineering machine shop. However, since a mill was not available which would allow machining of one

entire side without moving the panel, the required tolerances could not be maintained. Preliminary tests indicated that the eccentricities in the panel were too large for accurate testing; therefore, the panel was remachined in the engineering shop at Wichita State University. This remachining resulted in the final web thickness and areas given above. The steel panel was a one-inch thick plate which was milled to the proper shape and then ground flat. It was used to align the supporting structure and the loading mechanism prior to installing the final test panel.

# Test Fixture

The basic test fixture used to support the panel is described in Reference 2. The fixture was subsequently modified by welding one-inch steel plate to the mounting surfaces and then machining these surfaces flat and parallel. This improvement can be seen in Figure 9.

The original base support is also described in Reference 2. This support was designed with a ball bearing carriage for the roller support which could take either uploads or down-loads. In order to incorporate the four ball bearings, a built-up structure was necessary. As a result, the two supports could not be accurately aligned and lateral bending was induced in the test panel. The entire base support was redesigned as a two-piece structure with the movable support sliding on the fixed support (Figure 9). Although this support was much easier to align than the



Figure 9. Final Test Panel and Loading Fixture



Figure 10. Close-up of Test Panel

original one, the sliding friction between the two supports was appreciable. This friction was eliminated during the tests by vibrating the movable support with a plastic mallet just prior to recording load and strain data.

The loads were applied to the panel with a dual-cylinder hydraulic jack through a 10,000-1b universal load cell. Loads were indicated on a Budd P-350 portable strain indicator. The loads were applied in nominal 500-1b increments up to 5,000 pounds and then released in the same increments. However, no attempt was made to adjust the load to an exact value. The load was increased, or decreased, to approximately the desired value and then the movable support was vibrated until no change in load occurred. The load and strains were recorded.

#### Instrumentation

The final test panel was instrumented with twenty-four axial strain gages and eighteen strain rosettes (Figure 10). The gages were located along the centerlines and the quarterpoints of the panel. The axial gages were Budd Cl2-144B medium termperature gages and all but two of the rosettes were Budd Cl2-144D-R3Y medium temperature gages. The two outer rosettes on the horizontal centerline were Budd Cl2-1210-R3Y room temperature gages. In order to eliminate the effects of lateral bending of the panel, strain gages were mounted on both sides of the panel and the strain readings were averaged to obtain the strains in the median plane of

the panel.

The original gages were installed with Bean BAP-1 cement. However, during the installation of the terminal strips and the wires from the terminal strips to the gage tabs, the entire set of gages was destroyed by corrosion. It was suspected that this corrosion was due to either a flux that was used during the soldering of the lead wires or a corrosive atmosphere in the furnace used to cure the cement. However, all attempts to reproduce the corrosion on practice gages were unsuccessful. The replacement gages were installed with Eastman 910 cement and, therefore, did not require curing in the furnace.

Three strain indicating systems were used to record the strains:

- 20-Channel Budd Model A-110 System with automatic switching and balancing and printed output.
- 10-Channel Budd Model A-110 System with automatic balancing but manual switching and recording.
- 3. 50-Channel Budd Model P-350 System with manual switching, balancing and recording. Two P-350 Strain Indicators were used with 5 SB-1 Switch and Balance Units. Two channels of one of the SB-1 units were not used.

All circuits were three-wire quarter-bridge circuits. The internal dummy resistors in the strain indicators were used to complete the bridge circuit.

## CHAPTER V

#### COMPARISON OF RESULTS

The following discussion presents two independent comparisons of the results of this investigation:

- A comparison of the nodal displacements, stiffener stresses, and web stresses as calculated by the two analysis methods - the force method and the direct stiffness method.
- 2. A comparison of the calculated and the measured strains in the web and the stiffeners.

Comparison of the Analytical Results

Excellent agreement was obtained between both the displacements and the stresses calculated by the two analysis methods. Since there were a total of 105 displacements (Tables III and VIII) and 2,907 stresses (Tables IV through VI and IX through XI) calculated by each method, the only feasible way to compare these values was through the use of the digital computer. A program was written for the IBM 1620 which read and compared each value obtained from the analyses. The per cent variation was calculated by means of the following equation:

Per cent Variation =  $100[1 - \frac{Force Value}{Displacement Value}]$  (46)

The displacement value was arbitrarily chosen as the base. However, since the variations are small, no appreciable change in the magnitude of the variation would result if the second term of Equation 46 in the brackets were inverted.

The program was written so that variations which exceeded a specified per cent were punched into cards along with the actual values of the stresses or displacements. After a few trials, it was decided that only those variations equal to, or larger than, 0.5 per cent would be considered.

There was less than 0.5 per cent variation between all of the displacements. Only fourteen of the stresses differed by more than this variation, with a maximum variation of four per cent. Upon comparison of these fourteen stresses, it was discovered that their magnitudes were less than 0.02 psi per pound and that the maximum absolute variation was 0.0001 psi per pound. These stresses are identified by asterisks in the tables in Appendices A and B.

Comparison of the Analytical and Experimental Results

Since both the force and direct stiffness analyses give essentially the same analytical results, the direct stiffness method was used to calculate the strains for the comparison of analytical and experimental results. The decision to compare strains, rather than stresses, was based on two factors:

> The measured quantities in the experimental program were the strains, not the stresses.

The strains were recorded to the nearest

microstrain  $(1.0 \times 10^{-6} \text{ in./in.})$  with an uncertainty of plus or minus 5 microstrain. This could result in errors as large as 0.03 psi/lb in calculating the normal stresses and 0.02 psi/lb in calculating the shearing stresses from strain rosette data. It can be seen from Tables IV and IX that errors of this magnitude are significant.

2. The calculation of the stresses at a point from strain rosette data requires all three strains at the point. If one gage element is inactive, the strain gage is entirely inactive for stress calculations. However, if strains are compared, any active gage elements produce usable results.

Figures 11 through 22 present both the analytical and experimental results in graphical form. The first nine of these figures present the web strains for the three loading conditions ( $F_3$ ,  $F_8$ , and  $F_7 + F_8$ ). The last three figures present the stiffener strains for these same loading conditions. Each web strain figure compares the strains along one of the horizontal rows of strain rosettes (Lower, Center, and Upper rows).

Each graph (i.e.,  $\varepsilon_1$ ) in the web strain figures shows analytical curves for Models 1, 3, 5, and 7. The results for the even-numbered models were omitted to improve the clarity of the graphs. Since the strain gages did not, in general, lie along the lines where the strains were calculated, it was necessary to interpolate between element centroids in order to obtain the strains along the lines of rosettes. Linear interpolation was used for these calculations. The resulting strains were connected with straight

lines to form the curves in the graphs. The stiffener strains did not require interpolation; the calculated strain in each element was assumed to be the strain at the center of the element, and these strains were connected with straight lines from the curves shown in the last three figures.

It can be seen from the graphs that, in most cases, only the smallest element breakdown (Model No. 7) produced calculated strains that closely approximate the measured strains. For all three loading conditions, the calculated strains along the center row of strain rosettes are more accurate than those along the upper and lower rows. This is to be expected, since this row of rosettes is the most remote from the boundary constraints and the load points. It should also be noted that the calculated web strains are more accurate near the reentrant corners (upper right and lower left) than they are near the open corners (lower right and upper left). This is attributed to the fact that the shortest distance between the upper and lower ribs is along a line joining the open corners. This provides a direct load path from the loads to the most highly loaded support. Therefore the strain gradients in the vicinity of these corners are undoubtedly quite high and even the smallest element size used is too large to produce accurate strains in these areas.



Figure 11. Web Strains - Lower Row -  $F_3 = 1$ 



Figure 12. Web Strains - Center Row -  $F_3 = 1$ 



Figure 13. Web Strains - Upper Row -  $F_3 = 1$ 



Figure 14. Web Strains - Lower Row -  $F_8 = 1$ 



Figure 15. Web Strains - Center Row -  $F_8 = 1$ 



Figure 16. Web Strains - Upper Row -  $F_8 = 1$ 



Figure 17. Web Strains - Lower Row -  $F_7 + F_8 = 1$ 





Figure 19. Web Strains - Upper Row -  $F_7 + F_8 = 1$ 



Figure 20. Stiffener Strains -  $F_3 = 1$ 







Figure 22. Stiffener Strains -  $F_7 + F_8 = 1$ 

#### CHAPTER VI

## CONCLUSIONS AND RECOMMENDATIONS

The purpose and the objectives of the analytical and experimental investigation described in this dissertation are presented in the Introduction. The degree to which the objectives were attained can be summarized as follows:

1.	Ξt	t has been shown that the symmetrical
		monolithic shear panel is a valuable
	12	tool for obtaining accurate experi-
		mental results which can be used to
		verify new methods of analyses. The
		results of the study described herein,
		as well as the results obtained by
		Ayres (Reference 2) and Stone (Refer-
		ence 13) have demonstrated its value
	• •	in structural research.

- The validity of the trapezoidal plate stiffness matrix derived in Chapter II has been demonstrated by the excellent agreement between the analytical and experimental results.
- 3. It has been shown that, provided the same mathematical model is used, essentially identical results can be obtained with either the force or displacement method. This means that the structural analyst can concentrate on selecting the most accurate mathematical model of his structure. The analysis method can then be chosen on the basis of program availability; or, if programs are available for both methods, on the basis of the ease of preparation of the input data. Analyses by both methods could also be used to verify the input data.
  - The comparison of the analytical and experimental results has shown that only the smallest sub-element size resulted in calculated strains that

4.
are accurate enough for analysis and design. This is primarily a consequence of the small size of the test panel. Since all points in the panel are relatively close to either a load point or a free boundary, the strain gradients are large throughout the panel; therefore, small elements are required in order to obtain the desired accuracy.

5. The redundant force systems developed in Chapter III have provided a simple method for obtaining the elements of the unit redundant force matrix. The use of these force systems can be readily extended to structures with stiffeners along the interior nodal lines.

Although the results have extended the field of knowledge about the trapezoidal shear panel, much additional information needs to be made available. Some of the more immediate needs are:

- 1. The sub-element size effect on larger structures with multiple trapezoidal panels should be studied. The experimental results of Stone (Reference 13) could be used for experimental verification. In addition, the box-type structure should be investigated since it is more typical of actual construction and the boundary effects are minimized.
- 2. Additional trapezoidal plate stiffness matrices should be derived using other assumed displacement and stress distributions. The method used by Ayres (Reference 2) for the rectangular plate should be extended to include trapezoidal plates. The experimental results of this investigation could be used to evaluate these stiffnesses. It would also be desirable to simplify the final equations derived in Chapter II in order to reduce the computer time required to evaluate these equations.
- 3. The present work, and that of Ayres and Stone, should be extended to include thermal loading. Although analysis

methods are presently available there is no known experimental data.

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### APPENDIX A

### DEVELOPMENT OF THE MATRIX DISPLACEMENT PROGRAM

In addition to the generation and inversion of the panel stiffness matrix [K], see Equation 2, it is also necessary to utilize the elements of the resulting flexibility matrix to determine the nodal displacements and the element stresses. The digital computer program written to accomplish this result is described below. The program consists of three parts:

- 1. Generation of the Stiffness Matrix.
- 2. Inversion of the Stiffness Matrix.
- 3. Calculation of the Displacements and Stresses.

Parts 1 and 3 (Table II) were written by this author in Fortran II for the IBM 7094 Operating System. The major elements of these two programs will be described here. Part 2, written in the SOS language was available in the Boeing Wichita program library and is not described here.

Part 1 - Generation of the Stiffness Matrix

The basic input to the program consists of the following:

- 1. The panel material and section properties.
- 2. The coordinates of the corner nodes.
- 3. The constraint vectors.
- 4. The number of panel configurations.

#### 5. The number of rows and columns of nodes in each panel configuration, or model.

The constraint vectors are used to indicate which nodes are constrained. The vectors used for this analysis were

$$\{F_x\} = \{1 \in 0 \ 1 \ 1\} \text{ and } \{F_y\} = \{0 \ 0 \ 1 \ 1\}.$$
 (A-1)

A "one" indicates that the node is free to displace and a "zero" indicates that the node is constrained against displacement. Since the constraints are not taken into account until just prior to the matrix inversion, the use of these constraint vectors makes possible the investigation of any desired conditions of constraint.

The first two and the last basic inputs are written on the output tape for easy identification of the final results. Then several frequently used constants are calculated.

Since only the coordinates of the corner nodes are specified, it is necessary to calculate and store the coordinates of the interior nodes. These are stored in two arrays, a square array [X] for the X-coordinates and a column {Y} for the Y-coordinates.

The discussion of the generation of the 'unreduced' stiffness matrix of the panel in Chapter II implies that all of the element stiffness matrices must be developed and then combined. Although this approach is more straight-forward, it is impractical to store all of the element stiffnesses. In fact, it was necessary to store the panel stiffness matrix in a condensed form in order not to exceed the capacity of the available core storage. Therefore, as each element stiffness matrix is generated, its coefficients are added into the proper positions in the panel stiffness matrix.

The matrix equations derived in Chapter II for the stiffness of a trapezoidal plate were programmed and used to generate the plate element contributions to the panel stiffness. A relatively simple indexing system was developed to extract the nodal coordinates and to place the plate element stiffness coefficients in the panel stiffness matrix. Although this indexing system was developed for a plane structure, it could be extended for use with box-type structures. The axial element stiffness matrix derived in Reference 1 was used to calculate the stiffness coefficients of the stiffener elements.

As mentioned above, the panel stiffness matrix was stored in a condensed form in order to conserve core storage even though all computations to this point were in singleprecision arithmetic. Since the stiffness matrix is symmetric, only the diagonal and upper-right-hand coefficients were stored. The storage format is shown in Figure 23.



Figure 23. Storage Format for the Stiffness Matrix

Making the Stiffness Matrix Nonsingular - In order to obtain the flexibility matrix, it is necessary to make the 'unreduced' stiffness nonsingular. This can be accomplished by striking out the rows and columns corresponding to the external constraints. In the current case, this would reduce the size of the matrix by three rows and columns. It would then be necessary to expand the matrix after inversion if the indexing system previously mentioned were to be usable for determining the stresses and displacements. This approach was used in the first version of the program. However, due to the way in which the stiffness matrix is stored, the routines developed for this purpose were very lengthy. An alternate, and equally valid, procedure (suggested by Mr. Winder) was used in the later versions of the program. In this procedure all of the elements in the row and column corresponding to a constraint are set to zero except the diagonal element, which is set to one. After the inversion, the diagonal elements are set to zero.

The SOS matrix inversion program used to obtain the flexibility matrix required that the stiffness matrix be stored on magnetic tape by columns. Mr. Issacs wrote a subprogram to extract each column from the array stored as shown in Figure 23 and to write it on a scratch tape for subsequent inversion. Although the data was generated and stored as single-precision words, the actual inversion used double-precision words.

Part 3 - Calculation of the Displacements and Stresses

Due to the fact that each of the three parts of the total program are actually separate programs, the basic input data is reread for this part along with the flexibility matrix. Another subroutine, also written by Mr. Issacs, was used to enter the flexibility matrix in the format shown in Figure 23. The frequently used constants and the nodal coordinates were also recalculated.

The flexibility coefficients for the corner nodes were extracted from the panel flexibility matrix and placed in an 8x8 array. Since three rows and columns of this array are zero, this array was later reduced to a 5x5 array and only the nonzero elements are shown in the tabulated results. These results are shown in Table III.

The stresses at any point in a plate element can be determined from Equation 27. These equations relate the stresses at the point to the nodal displacements of the element, the nodal coordinates of the element, and the coordinates of the point in question. These equations can be combined into a matrix equation of the form

$$\{\sigma\} = [\Sigma] \{u\}$$
 (A-2)

The expansion of this equation is shown on the following page.

For the models with relatively large subelement sizes (Models 1 through 4), the web stresses are calculated at five points in each web element. These points are shown in

#### Web Stress Equation

$$\begin{bmatrix} \sigma & xx \\ E \\ \hline \\ g \\ Yy \\ E \\ \hline \\ \frac{\sigma}{yy} \\ E \\ \frac{\sigma}{y} \\ \frac{\sigma}{g} \\ \frac{$$

$$\frac{{}^{\mathsf{T}} \mathbf{x} \mathbf{y}}{\mathsf{G}} = \frac{2 {}^{\mathsf{T}} \mathbf{x} \mathbf{y}}{(1-\nu)\mathsf{E}} \qquad \xi = \frac{\mathbf{x}-\mathbf{x}_1}{\mathbf{x}_{21}} \qquad \rho = \frac{\mathbf{x}_{31}}{\mathbf{x}_{21}} \qquad \lambda = \frac{\mathbf{x}_{21}}{\mathbf{x}_{43}} = \frac{1}{\delta-\rho}$$

$$x_{ij} = x_i - x_j$$
  $n = \frac{y - y_1}{y_{31}}$   $\delta = \frac{x_{41}}{x_{21}}$ 

#### Stringer Stress Equation

 $\sigma = \frac{E}{L} \left[ -\cos\theta \quad \cos\theta \quad -\sin\theta \quad \sin\theta \right] \left\{ u_1 \quad u_2 \quad v_1 \quad v_2 \right\}$  $\theta = \alpha \quad \text{for Leading Edge Stringer} \quad \text{and}$ 

 $\theta$   $\beta$  for Trailing Edge Stringer

Rib Stress Equation

$$\sigma = \frac{E}{L} \begin{bmatrix} -1 & 1 \end{bmatrix} \{ u_1 & u_2 \}$$

(A-4)

(A-5)

v<sub>3</sub> v<sub>4</sub> Figure 24. For the other models, the web stresses were calculated only at the centroids of the elements. These stresses are given in Table IV.

The stiffener stresses were calculated from equations of the form of Equation A-2. Since the stress over the length of each stiffener element is assumed constant, the equations are much simpler than the corresponding web stress equation. The expanded stiffener stress equations are shown on page 73. The rib stresses are tabulated in Table V and the stringer stresses are shown in Table VI.





Explanation of Tables

Table II. Matrix Displacement Program Listing

This program is listed as it was executed with two exceptions:

- 1. The operating system control cards have been removed.
- 2. The "C" in column 1 of the comment cards has not been printed.

## Table III. Displacements of Corner Nodes

The displacements in this table are actually the flexibility matrices of the panel. In order to indicate the relative magnitude of these flexibilities, the computer output was multiplied by 10<sup>6</sup> and the results were printed with the decimal point in the proper position.

The first column in the table indicates the model number as identified in Figure 2. The second column and the last five column headings indicate the displacements and forces, respectively, as identified in Figure 3.

#### Table IV. Web Stresses

Since the web stresses are all of the order of one psi per pound, or less, it was only necessary to print them with the decimal point in the proper position in order to permit easy comparison.

The first column in the table indicates the model number (Figure 2). The second column identifies the element number by row and column (Figure 8). The third column indicates the points within each element at which the stresses were calculated. For Models 1 - 4, the stress points are as shown in Figure 24. For the remaining models, the stresses were determined only at the centroids of the elements. This is indicated by a "CG" in column 3. The fourth column identifies the type of stress, i.e.,  $SXX = \sigma_{XX}$ ,  $SYY = \sigma_{YY}$ , and  $SXY = \tau_{XY}$ . The remaining columns give the stresses due to unit loads as indicated by their column heading.

Table V. Rib Stresses and Table VI. Stringer Stresses

These stresses are presented in the same manner as the web stresses with the following exceptions:

 Since the stress is assumed constant over the length of each element, only one stress is given for each element.
 The rib and stringer elements are numbered as shown in Figure 25.



Figure 25. Rib and Stringer Numbering System

#### MATRIX DISPLACEMENT PROGRAM LISTING

ISOTHERMAL DIRECT STIFFNESS ANALYSIS OF A TRAPEZOIDAL PLATE WITH BOUNDARY STIFFENERS - PART 1

```
DIMENSION X(9.9) \cdot Y(9) \cdot A(21.6) \cdot C(6) \cdot Z(21) \cdot F(4.4) \cdot G(4.4) \cdot 1SM11(B1.82) \cdot SM12(B1.82) \cdot FX(4) \cdot FY(4) \cdot H(4.4)
COMMON SM11 · SM12
```

FORMAT STATEMENTS

```
200 FORMAT(6E12•4)
201 FORMAT(2I5)
202 FORMAT(1H •6E19•8)
```

KIN=2 KOT=3

BASIC INPUT/OUTPUT

```
CALL TESTXS(5)
REWIND 5
CALL ENDFIL(5)
CALL UNLOAD(5)
```

```
1 READ INPUT TAPE KIN.200.E.V.T.STA,RA.X1.X2.X3.X4.Y1.Y3
WRITE OUTPUT TAPE KOT.202.E.V.T.STA.RA
WRITE OUTPUT TAPE KOT.202.X1.X2.X3.X4.Y1.Y3
```

```
2 READ INPUT TAPE KIN.200.(FX(I).FY(I).I=1.4)
READ INPUT TAPE KIN.201.NOPAC
```

```
WRITE OUTPUT TAPE KOT . 201 . NOPAC
```

```
2000 READ INPUT TAPE KIN.201.M.N
WRITE OUTPUT TAPE KOT.201.M.N
```

CONSTANTS

```
EP=E/(1 •- (V**2))

EPT=EP*T

GS=E/(2 • *(1 • +V))

AM=M-1

AN=N-1

M1=M-1

N1=N-1

MN=M*N

MNN=MN-N

MN1=MN-N1

M2N1=N*(M-2)+1

MN4=MN-1

MN0=MN+1
```

```
NODAL COORDINATES
  X(1 \cdot 1) = X1
  X(1 + N) = X2
  X(M_{1}) = X3
  X(M \bullet N) = X4
  Y(1) = Y1
  Y(M) = Y3
  DELY=(Y3-Y1)/AM
  DO 4 I=2.M1
4 Y(I) = Y(I-1) + DELY
  DELXR=(X2-X1)/AN
  DELXT=(X4-X3)/AN
  DO 5 J=2+N1
  X(1 \bullet J) = X(1 \bullet J - 1) + DELXR
5 X(M,J)=X(M,J-1)+DELXT
  DO 6 I=2+M1
  DO 6 J=1+N
6 X(I+J)=X(1+J)+((X(M+J)-X(1+J))/(Y(M)-Y(1))*(Y(I)-Y(1)))
  PLATE STIFFNESS MATRIX
  DO 7 1=1.MN
  DO 7 J=1.MNO
  SM11(I+J)=0.0
7 SM12(I,J)=0.0
  DO 23 IA=1.M1
  DO 23 JA=1.N1
  XA=X(IA,JA)
  XB=X(IA \cdot JA+1)
  XC=X(IA+1+JA)
  XD=X(IA+1 \cdot JA+1)
  YA=Y(IA)
  YC=Y(IA+1)
  AR = (YC - YA) / (XB - XA)
  D=(XD-XA)/(XB-XA)
  P=(XC-XA)/(XB-XA)
  TR=1 \cdot / (D-P)
  B=D-1.
  DO 8 I=1+21
  DO 8 J=1+6
A(I_{\circ}J)=0_{\circ}O
  A(1 \cdot 1) = AR
  A(1.2)=2.*AR
  A(1.3)=AR
  A(2:2) = -TR*AR
  A(2,3)=A(2,2)
  A(3.3)=TR**2*AR
  A(4,1) = V
  A(4,2)=V
  A(4,4)=V
  A(4.5)=V
```

 $A(5 \circ 4) = -V$ A(5+5)=-V A(6.1)=-D\*TR\*V A(6,2) = A(6,1)A(6,4) = -TR \* VA(6,5) = A(6,4) $A(7 \circ 1) = P * T R * V$ A(7.2) = A(7.1)A(7.4)=-A(6.4) A(7,5) = -A(6,4)A(8,2) = A(6,4)A(8.5) = A(6.4)A(9,5) = -A(6,4)A(10.2)=D\*TR\*\*2\*V A(10+5)=TR#\*2\*V A(11.2) =-P\*TR\*\*2\*V A(11.5) = -A(10.5)A(12.1)=1./AR A(12.4) = 2.7A(12.6) = A(12.1)A(13,4) = -A(12,1)A(13.6) = -A(12.1) $A(14 \bullet 1) = -D \star TR / AR$ A(14+4) = -(1+D) \* TR / ARA(14.6) = -TR/ARA(15+1) = P + TR/ARA(15+4) = (1+P) + TR/ARA(15+6)=TR/AR  $A(16 \cdot 6) = A(12 \cdot 1)$ A(17,4) = -A(14,1)A(17+6) = TR/ARA(18+4) = -A(15+1)A(18+6) = -TR/ARA(19+1) = (D\*TR) \* \* 2/ARA(19,4)=2.\*D\*TR\*\*2/AR A(19+6)=TR\*\*2/AR A(20,1)=-D\*P\*TR\*\*2/AR A(20,4)=-(D+P)\*TR\*\*2/AR A(20,6) = -A(19,6) $A(21 \cdot 1) = (P \cdot TR) \cdot 2/AR$ A(21+4)=2+\*P\*TR\*\*2/AR A(21+6) = A(19+6)C(1) = 1 + 0 + 5 + (B - P)C(2)=-0.5-(B-P)/3.  $C(3) = (1 \cdot / 3 \cdot) + ((B-P) / 4 \cdot)$ C(4) = -0.5 - B/2.0 - (B + 2 - P + 2)/6.0C(5)=0.25+B/3.+(B\*\*2-P\*\*2)/8. C(6)=1./3.+B/2.+B\*\*2/3.+(B\*\*3-P\*\*3)/12. DO 10 I=1+21 10 Z(I) = 0.0

```
DO 11 1=1.21
  DO 11 J=1.6
11 Z(I)=Z(I)+A(I,J)*C(J)
   F(101)=Z(1)
   F(1,2) = -Z(1)
   F(1 \cdot 3) = Z(2)
   F(1,4) = -Z(2)
   F(2.2)=Z(1)
   F(2.3)=-Z(2)
   F(2+4)=Z(2)
   F(3.3)=Z(3)
   F(3,4) = -Z(3)
   F(4,4) = Z(3)
   G(1.1)=Z(12)
   G(1+2)=Z(13)
   G(1.3)=Z(14)
   G(1,4)=Z(15)
   G(2+2)=Z(16)
   G(2+3)=Z(17)
   G(2.4)=Z(18)
   G(3+3)=Z(19)
   G(3+4)=Z(20)
   G(4,4) = Z(21)
   DO 15 I=1.4
   DO 15 J=1.4
15 H(I.J)=EPT*(F(I.J)+(1.-V)*G(1.J)/2.)
   IB=JA+N*(IA-1)
   IC=IB+1
   ID=IB+N
   IE=1D+1
   IF=IC+1
   IG=IE+1
   SM11(IB.IC)=SM11(IB.IC)+H(1.1)
   SM11(IB.IF)=SM11(IB.IF)+H(1.2)
   SM11(IB.IE)=SM11(IB.IE)+H(1.3)
   SM11(IB.IG)=SM11(IB.IG)+H(1.4)
   SM11(IC+IF)=SM11(IC+IF)+H(2+2)
   SM11(IC.IE)=SM11(IC.IE)+H(2.3)
   SM11(IC+IG)=SM11(IC+IG)+H(2+4)
   SM11(ID.IE)=SM11(ID.IE)+H(3.3)
   SM11(ID+IG)=SM11(ID+IG)+H(3+4)
   SM11(IE+IG)=SM11(IE+IG)+H(4+4)
   DO 17 I=1.4
   DO 17 J=1.4
   H(1,J)=EPT*(G(1,J)+(1.-V)*F(1,J)/2.)
17 H(J.I)=H(I.J)
   SM11(IB.IB)=SM11(IB.IB)+H(1.1)
   SM11(IC.IB)=SM11(IC.IB)+H(2.1)
   SM11(IC+IC)=SM11(IC+IC)+H(2+2)
   SM11(ID.IB)=SM11(ID.IB)+H(3.1)
   SM11(ID.IC)=SM11(ID.IC)+H(3.2)
   SM11(ID,ID)=SM11(ID,ID)+H(3,3)
```

```
TABLE II (CONTINUED)
```

```
SM11(IE+IB)=SM11(IE+IB)+H(4+1)
   SM11(IE.IC)=SM11(IE.IC)+H(4.2)
   SM11(IE . ID)=SM11(IE . ID)+H(4.3)
   SM11(IE+IE)=SM11(IE+IE)+H(4+4)
   F(1 \circ 1) = Z(4)
   F(1,2)=Z(5)
   F(1,3) = Z(6)
   F(1.4)=Z(7)
   F(2 \circ 1) = -Z(4)
   F(2,2) = -Z(5)
   F(2+3)=-Z(6)
   F(2,4) = -Z(7)
   F(3.1)=Z(8)
   F(3,2)=Z(9)
   F(3.3)=Z(10)
   F(3,4)=Z(11)
   F(4.1)=-Z(8)
   F(4.2) = -Z(9)
   F(4,3) = -Z(10)
   F(4,4) = -Z(11)
   DO 20 1=1.4
   DO 20 J=1.4
20 G(I.J)=F(J.I)
   DO 22 1=1.4
   DO 22 J=1.4
22 H(1.J)=EPT*(F(1.J)+(1.-V)*G(1.J)/(2.*V))
   SM12(IB+IB)=SM12(IB+IB)+H(1+1)
   SM12(IB+IC)=SM12(IB+IC)+H(1+2)
   SM12(18+10)=SM12(18+10)+H(1+3)
   SM12(IB, IE)=SM12(IB, IE)+H(1.4)
   SM12(IC.IB)=SM12(IC.IB)+H(2.1)
   SM12(IC.IC)=SM12(IC.IC)+H(2.2)
   SM12(IC, ID)=SM12(IC, ID)+H(2,3)
   SM12(IC, IE)=SM12(IC, IE)+H(2.4)
   SM12(ID+1B)=SM12(ID+IB)+H(3+1)
   SM12(ID, IC)=SM12(ID, IC)+H(3,2)
   SM12(ID.ID)=SM12(ID.ID)+H(3.3)
   SM12(ID.IE)=SM12(ID.IE)+H(3.4)
   SM12(IE+IB)=SM12(IE+IB)+H(4+1)
   SM12(IE+IC)=SM12(IE+IC)+H(4+2)
   SM12(IE . ID)=SM12(IE . ID)+H(4.3)
23 SM12(IE, IE)=SM12(IE, IE)+H(4,4)
   STRINGER AND RIB STIFFNESS MATRIX
   LEADING EDGE STRINGER
   DELX=X(2+1)-X(1+1)
   SL=SQRTF(DELX**2+DELY**2)
   SLA=DELX/SL
   SMU=DELY/SL
   SLA2=SLA**2*STA*E/SL
```

```
SMU2=SMU**2*STA*E/SL
   SLAM=SLA*SMU*STA*E/SL
   DO 24 1A=1 . M2N1 . N
   IB=IA+1
   IC=IA+N
   ID=IC+1
   SM11(IA.IB)=SM11(IA.IB)+SLA2
   SM11(IA.ID)=SM11(IA.ID)-SLA2
   SM11(IC+ID)=SM11(IC+ID)+SLA2
   SM11(IA . IA)=SM11(IA . IA)+SMU2
   SM11(IC.IA)=SM11(IC.IA)-SMU2
   SM11(IC+IC)=SM11(IC+IC)+SMU2
   SM12(IA . IA) = SM12(IA . IA) + SLAM
   SM12(IA.IC)=SM12(IA.IC)-SLAM
   SM12(IC.IA)=SM12(IC.IA)-SLAM
24 SM12(IC.IC)=SM12(IC.IC)+SLAM
   TRAILING EDGE STRINGER
   DELX=X(2.N)-X(1.N)
   SL=SQRTF(DELX**2+DELY**2)
   SLA=DELX/SL
   SMU=DELY/SL
   SLA2=SLA**2*STA*E/SL
   SMU2=SMU**2*STA*E/SL
   SLAM=SLA*SMU*STA*E/SL
   DO 25 IA=N.MNN.N
   IB=IA+1
   IC=IA+N
   ID=IC+1
   SM11(IA.IB)=SM11(IA.IB)+SLA2
   SM11(IA.ID)=SM11(IA.ID)-SLA2
   SM11(IC+ID)=SM11(IC+ID)+SLA2
   SM11(IA, IA)=SM11(IA, IA)+SMU2
   SM11(IC.IA)=SM11(IC.IA)-SMU2
   SM11(IC, IC) = SM11(IC, IC) + SMU2
   SM12(IA, IA)=SM12(IA, IA)+SLAM
   SM12(IA+IC)=SM12(IA+IC)-SLAM
   SM12(IC+IA)=SM12(IC+IA)-SLAM
25 SM12(IC+IC)=SM12(IC+IC)+SLAM
   LOWER RIB
```

```
SA=RA*E/DELXR

DO 26 IA=1.N1

IB=IA+1

IC=IB+1

SM11(IA.IB)=SM11(IA.IB)+SA

SM11(IA.IC)=SM11(IA.IC)-SA

26 SM11(IB.IC)=SM11(IB.IC)+SA
```

```
UPPER RIB
```

```
SA=RA*E/DELXT
DO 27 IA=MN1.MN4
IB=IA+1
IC=IB+1
SM11(IA.IB)=SM11(IA.IB)+SA
SM11(IA.IC)=SM11(IA.IC)-SA
```

```
27 SM11(IB+IC)=SM11(IB+IC)+SA
```

MAKING THE STIFFNESS MATRIX NONSINGULAR

```
IF(FX(1))30+28+30
28 DO 29 J=1+MN
SM11(1+J+1)=0+0
```

```
29 SM12(1.J)=0.0
```

```
SM11(1 \circ 2) = 1 \circ 0
```

```
30 IF(FX(2))35+31+35
```

```
31 DO 32 I=1.N
```

```
32 SM11(I • N+1)=0.0
DO 33 J=N.MN
```

```
33 SM11(N+J+1)=0.0
SM11(N+1)=1.0
D0 34 J=1+MN
```

```
34 SM12(N.J)=0.0
```

```
35 IF(FX(3))40+36+40
```

```
36 DO 37 I=1.MN1
```

```
37 SM11(I • MN1+1)=0.0
D0 38 J=MN1 • MN
```

```
38 SM11(MN1+J+1)=0+0
SM11(MN1+MN1+1)=1+0
D0 39 J=1+MN
```

```
39 SM12(MN1.J)=0.0
```

```
40 IF(FX(4))44.41.44
```

```
41 DO 42 I=1.MN
```

```
42 SM11(I•MN+1)=0.0
SM11(MN+MN+1)=1.0
D0 43 J=1.4MN
```

```
43 SM12(MN+J)=0.0
```

```
44 IF(FY(1))47.45.47
```

```
45 DO 46 I=1.MN
```

```
SM11(I+1)=0+0
46 SM12(I+1)=0+0
```

```
SMI1(1 \bullet 1) = 1 \bullet 0
```

```
47 IF(FY(2))52+48+52
```

```
48 DO 49 J=1+N
```

```
49 SM11(N•J)=0•0
D0 50 I=N•MN
50 SM11(I•N)=0•0
```

```
SM11(N•N)=1•0
D0 51 I=1•MN
```

```
51 SM12(I+N)=0.0
```

## TABLE II (CONTINUED)

```
52 IF(FY(3))57.53.57
53 D0 54 J=1.0NN1
54 SM11(MN1.0J)=0.0
D0 55 I=MN1.0NN
55 SM11(I.0NN1)=0.0
SM11(MN1.0NN1)=1.0
D0 56 I=1.0NN
56 SM12(I.0NN1)=0.0
57 IF(FY(4))61.58.61
58 D0 59 J=1.0NN
59 SM11(MN.0J)=0.0
SM11(MN.0N)=1.0
D0 60 I=1.0NN
60 SM12(I.0NN)=0.0
```

61 CALL MREAR(MN) NUM=NUM+1 IF(NUM-NOPAC) 2000,2000,1 END

```
SUBROUTINE MREAR(N2)
     DIMENSION A(81.82).B(81.82).TERM(170).COLSUM(170)
     COMMON A+B
1000 FORMAT(5X+6E18.8)
     ID=0
     N=N2+N2
     WRITE TAPE 5.N.N.ID
     L=N+1
     DO 10 K=1.N
  10 COLSUM(K)=0.0
     DO 210 I=1.N
     IF(I-N2) 20.20.110
  20 J=1
     M=1
     IC=J+1
     IR=1
     KS=0
  30 IF(IR+1-IC) 50,40,50
  40 KS=1
  50 TERM(M) = A(IR, IC)
                       .
     COLSUM(M)=COLSUM(M)+TERM(M)
     IF(KS) 60.60.70
  60 IR=IR+1
     GO TO 80
  70 IC=IC+1
  80 M=M+1
     IF(M-N2) 30+30+90
  90 IR=J
     DO 100 IC=1.N2
     TERM(M) = B(IR + IC)
     COLSUM(M)=COLSUM(M)+TERM(M)
```

1.1)

	100	M=M+1
		GO TO 190
	110	J=I-N2
	•	M=1
		IC=J
		DO 120 IR=1.N2
		TERM(M)=B(IR+IC)
		COLSUM(M)=COLSUM(M)+TERM(M)
÷	120	M=M+1
		IR=J
		KS=0
	n	IC=1
	130	IF(IR-IC) 150.140.150
	140	KS=1
	150	TERM(M)=A(IR.IC)
		COLSUM(M)=COLSUM(M)+TERM(M)
	<u>×</u>	IF(KS) 160+160-170
•	160	IC=IC+1
		GO TO 180
	170	IR=IR+1
	180	
		IF (M-N) 130+130+190
	190	
	200	
		WRITE TAPE STITERM(M) METOL
		WRITE OUTPUT TAPE 3010000 (TERM(M) 0M=10L)
	210	
	220	COESTIM(E) = COESTIM(E) + COESTIM(E)
	220	
		WRITE IMPE DIICULDUMIMIMEILL
	۰.	WRITE OUTPUT TAPE STITUTT COLSUMINTAME I
		KETUKN

END

#### TABLE II (CONTINUED)

```
ISOTHERMAL DIRECT STIFFNESS ANALYSIS OF A TRAPEZOIDAL PLATE WITH BOUNDARY STIFFENERS - PART 3
```

DIMENSION X(9.9).Y(9).SM11(81.81).SM12(81.81). 1SM22(81.81).STRES(3.8).DISP(8.8). 2XI(5).ETA(5).SIGMA(3.8).DELTA(8.8). DIMENSION FX(4).FY(4).NODE(8) COMMON SM11.SM12.SM22

#### FORMAT STATEMENTS

```
200 FORMAT(6E12.4)
201 FORMAT(215)
202 FORMAT(1X.6E18.8)
203 FORMAT(1H1)
204 FORMAT(12H BASIC INPUT //)
205 FORMAT(//)
206 FORMAT(30H DISPLACEMENTS OF CORNER NODES //)
207 FORMAT(30H DISPLACEMENTS OF CORNER NODES //)
208 FORMAT(13H WEB STRESSES //)
208 FORMAT(19H STIFFENER STRESSES //)
209 FORMAT(1X.E14.6.7E15.6)
```

KIN=2 KOT=3

BASIC INPUT/OUTPUT

CALL TESTXS(5) REWIND 5 CALL UNLOAD(5)

```
1 READ INPUT TAPE KIN+200+E+V+T+STA+RA

WRITE OUTPUT TAPE KOT+203

WRITE OUTPUT TAPE KOT+204

WRITE OUTPUT TAPE KOT+202+E+V+T+STA+RA

READ INPUT TAPE KIN+200+X1+X2+X3+X4+Y1+Y3

READ INPUT TAPE KIN+200+(FX(1)+FY(1)+I=1+4)

WRITE OUTPUT TAPE KOT+205

WRITE OUTPUT TAPE KOT+202+X1+X2+X3+X4+Y1+Y3

READ INPUT TAPE KIN+201+NOPAC

NUM=1
```

```
2 READ INPUT TAPE KIN+201+M+N
WRITE OUTPUT TAPE KOT+203
WRITE OUTPUT TAPE KOT+201+M+N
```

CONSTANTS

```
EP=E/(1 •- (V**2))
GS=E/(2 •* (1 •+V))
AM=M-1
AN=N-1
M1=M-1
N1=N-1
```

```
MN=M*N
   MNN=MN-N
   MN1=MN-N1
   M2N1=N*(M-2)+1
   MN4 = MN - 1
   NODE(1)=1
   NODE(2) = N
   NODE(3) = MN1
   NODE(4) = MN
   NODE (5) = MN+1
   NODE(6) = MN+N
   NODE(7) = MN + MN1
   NODE (8) = MN+MN
   NODAL COORDINATES
   X(1,1) = X1
   X(1 \circ N) = X2
   X(M \circ 1) = X3
   X(M_{0}N) = X4
   Y(1) = Y1
   Y(M)=Y3
   DELY=(Y3-Y1)/AM
   DO 4 1=2.M1
 4 Y(1)=Y(1-1)+DELY
   DELXR=(X2-X1)/AN
   DELXT=(X4-X3)/AN
   DO 5 J=2.N1
   X(1 \circ J) = X(1 \circ J - 1) + DELXR
 5 X(M,J)=X(M,J-1)+DELXT
   DO 6 1=2+M1
   DO 6 J=1.N
 S \times (I \circ J) = \times (I \circ J) + ((\times (M \circ J) - \times (I \circ J)) / (\vee (M) - \vee (I)) \times (\vee (I) - \vee (I)))
   DISPLACEMENTS OF CORNER NODES
   CALL REARR(MN)
   DO 8 1=1.4
    IF(FX(1)) 8,7,8
 7 J=NODE(I)
   SM11(J,J)=0.0
 8 CONTINUE
   DO 10 I=1.4
    IF(FY(I)) 10,9,10
 9 J=NODE(1+4)-MN
   SM22(J.J)=0.0
10 CONTINUE
   DISP(1,1) = SM11(1,1)
   DISP(1 \circ 2) = SMII(1 \circ N)
   DISP(1 \cdot 3) = SM11(1 \cdot MN1)
   DISP(1.4)=SM11(1.MN)
   DISP(1.5)=SM12(1.1)
```

DISP(1.6)=SM12(1.N) DISP(1.7)=SM12(1.MN1) DISP(1.8)=SM12(1.MN) DISP(2.2)=SM11(N.N) DISP(2.3)=SM11(N.MN1) DISP(2.4)=SM11(N.MN) DISP(2.5)=SM12(N.1) DISP(2.6)=SM12(N.N) DISP(2.7)=SM12(N.MN1) DISP(2.8)=SM12(N.MN) DISP(3,3)=SM11(MN1,MN1) DISP(3,4)=SM11(MN1,MN) DISP(3,5)=SM12(MN1,1) DISP(3.6)=SM12(MN1.N) DISP(3.7)=SM12(MN1.MN1) DISP(3.8)=5M12(MN1.MN) DISP(4,4) = SM11(MN,MN)DISP(4.5)=SM12(MN.1) DISP(4.6)=SM12(MN.N) DISP(4,7)=SM12(MN,MN1) DISP(4.8)=SM12(MN.MN) DISP(5+5)=SM22(1+1) DISP(5+6)=SM22(1+N) DISP(5,7)=SM22(1,MN1) DISP(5.8)=SM22(1.MN) DISP(6+6)=SM22(N+N) DISP(6.7)=SM22(N.MN1) DISP(6+8)=SM22(N+MN) DISP(7.7)=SM22(MN1.MN1) DISP(7.8)=SM22(MN1.MN) DISP(8.8)=SM22(MN.MN) DO 90 I=1.8 DO 90 J=1.8 90 DISP(J+1)=DISP(I+J) WRITE OUTPUT TAPE KOT. 205 WRITE OUTPUT TAPE KOT. 206 WRITE OUTPUT TAPE KOT . 209 . ((DISP(1.J) . J=1.8) . 1=1.8) WEB STRESSES

WRITE OUTPUT TAPE KOT.203 WRITE OUTPUT TAPE KOT.201.M.N WRITE OUTPUT TAPE KOT.205 WRITE OUTPUT TAPE KOT.207 IF (MN-15)91.91.100

WEB STRESSES FOR MN=15. OR LESS

91 D0 99 IA=1.M1 D0 99 JA=1.N1 XA=X(IA.JA) XB=X(IA.JA+1) XC=X(IA+1.JA)

#### TABLE II (CONTINUED)

XD=X(IA+1.JA+1) YA=Y(IA) YC=Y(IA+1) D=(XD-XA)/(XB-XA) P=(XC-XA)/(XB-XA) TR=1./(D-P) XBA=XB-XA YCA=YC-YA XI(1)=0.25\*(P+0.75+0.25/TR) XI(2)=0.25\*(P+2.25+0.75/TR) X1(3)=0.50\*(P+0.5+0.5/TR) X1(4)=0.25\*(3.\*P+0.25+0.75/TR) XI(5)=0.75\*(P+0.25+0.75/TR) ETA(1)=0.25 ETA(2)=0.25 ETA(3)=0.5 ETA(4)=0.75 ETA(5)=0.75 IB=JA+N\*(IA-1) IC=18+1 ID=IB+N IE=10+1 DELTA(1.1)=SM11(18.1) DELTA(1.2)=SM11(18.N) DELTA(1.3)=SM11(18.MN1) DELTA(1.4)=SM11(18.MN) DELTA(1.5)=SM12(18.1) DELTA(1.6) = SM12(18.N) DELTA(1.7)=SM12(18.MN1) DELTA(1.8)=SM12(18.MN) DELTA(2.1)=SM11(1C.1) DELTA(2.2)=SM11(1C.N) DELTA(2.3)=SM11(IC.MN1) DELTA(2.4) = SM11(1C.MN) DELTA(2.5)=SM12(1C.1) DELTA(2.6)=SM12(IC.N) DELTA(2.7)=SM12(IC.MN1) DELTA(2.8)=SM12(IC.MN) DELTA(3.1)=SM11(ID.1) DELTA(3.2)=SM11(ID.N) DELTA(3.3)=SM11(ID.MN1) DEL TA (3.4) = SM11 (10.MN) DELTA(3.5)=SM12(10.1) DELTA(3.6)=5M12(10.N) DELTA(3.7)=SM12(10.MN1) DELTA(3.8)=SM12(ID.MN) DELTA(4+1)=SM11(IE+1) DELTA(4+2)=SM11(IE+N) DELTA(4,3)=SM11(IE,MN1) DELTA(4+4) = SM11(IE+MN)DELTA(4.5)=SM12(IE.1) DELTA(4.6)=SM12(IE.N) DELTA(4.7)=SM12(IE.MN1)

DELTA(4.8)=SM12(IE.MN) DELTA(5.1)=SM12(1.18) DELTA(5+2)=SM12(N+1B) DELTA(5:3)=SM12(MN1:IB) DELTA(5.4)=SM12(MN.IB) DELTA(5:5)=SM22(18:1) DELTA(5.6)=SM22(18.N) DELTA(5.7)=SM22(18.MN1) DEL TA (5 . 8) = SM22(18 . MN) DELTA(6.1)=SM12(1.IC) DELTA(6+2)=SM12(N+IC) DELTA(6.3)=SM12(MN1.IC) DELTA(6.4) = SM12(MN.IC) DELTA(6,5)=SM22(IC.1) DELTA(6.6) = SM22(IC.N) DELTA(6.7)=SM22(IC.MN1) DELTA(6.8)=SM22(IC.MN) DELTA(7.1)=SM12(1.ID) DELTA(7.2)=SM12(N.ID) DELTA(7:3)=SM12(MN1:ID) DELTA(7.4)=SM12(MN.ID) DELTA(7.5)=SM22(ID.1) DELTA(7.6)=SM22(ID.N) DELTA(7,7)=SM22(ID,MN1)  $DELTA(7 \cdot 8) = SM22(ID \cdot MN)$ DELTA(8.1)=SM12(1.IE) DELTA(8,2)=SM12(N,IE) DELTA(8.3)=SM12(MN1.IE) DELTA(8.4)=SM12(MN.IE) DELTA(8.5)=SM22(IE.1) DELTA(8.6)=SM22(IE.N) DELTA(8.7)=SM22(IE.MN1) DELTA(8.8)=SM22(IE.MN) DO 99 1=1.5 SIGMA(1.1)=-(1.-ETA(1))/XBA SIGMA(1.2) =- SIGMA(1.1) SIGMA(1+3)=-TR\*ETA(1)/XBA SIGMA(1,4) = -SIGMA(1,3)SIGMA(1+5) =- V\*(1. - XI(I))/YCA SIGMA(1.6) =- V\*XI(I)/YCA SIGMA(1.7)=TR\*V\*(D-XI(I))/YCA SIGMA(1+8) =- TR\*V\*(P-XI(1))/YCA DO 93 J=1.4 SIGMA(2.J)=V\*SIGMA(1.J) 93 SIGMA(2+J+4)=SIGMA(1+J+4)/V DO 94 J=1.4 SIGMA(3,J)=SIGMA(2,J+4)94 SIGMA(3.J+4)=SIGMA(1.J) DO 95 J=1+2 DO 95 K=1+8 95 SIGMA(J.K)=EP\*SIGMA(J.K) DO 96 J=1.8

96 SIGMA(3+J)=GS\*SIGMA(3+J)

```
TABLE II (CONTINUED)
       DO 97 J=1+3
       DO 97 K=1+8
   97 STRES(J.K)=0.0
       DO 98 J=1.3
       DO 98 K=1.8
       DO 98 L=1.8
   98 STRES(J+K)=STRES(J+K)+SIGMA(J+L)*DELTA(L+K)
       WRITE OUTPUT TAPE KOT, 209, ((STRES(J,K),K=1,8), J=1,3)
   99 WRITE OUTPUT TAPE KOT. 205
       GO TO 109
       WEB STRESSES FOR MN GREATER THAN 15
  100 DO 108 IA=1.M1
       DO 108 JA=1.NI
       XA=X(IA+JA)
ι.
       XB=X(IA,JA+1)
       XC=X(IA+1,JA)
       XD=X(IA+1 \cdot JA+1)
       YA=Y(IA)
       YC=Y(IA+1)
       D=(XD-XA)/(XB-XA)
       P=(XC-XA)/(XB-XA)
       TR=1./(D-P)
       B=D-1.
       XBA=XB-XA
       YCA=YC-YA
       ETA(1) = (TR+2.)/(3.*(TR+1.))
       XI(1)=0.5*(1.+(P+B)*ETA(1))
       IB=JA+N*(IA-1)
       IC = IB + 1
       ID=IB+N
       IE = ID + 1
       DELTA(1 \cdot 1) = SM11(IB \cdot 1)
       DELTA(1 \circ 2) = SM11(IB \circ N)
       DELTA(1 \cdot 3) = SM11(IB \cdot MN1)
       DELTA(1 \cdot 4) = SM11(IB \cdot MN)
       DELTA(1.5)=SM12(18.1)
       DELTA(1 \cdot 6) = SM12(IB \cdot N)
       DELTA(1,7) = SM12(IB_{0}MN1)
       DELTA(1 \cdot 8) = SM12(IB \cdot MN)
       DELTA(2 \circ 1) = SM11(IC \circ 1)
       DELTA(2 \cdot 2) = SM11(IC \cdot N)
       DELTA(2 \cdot 3) = SM11(IC \cdot MN1)
       DELTA(2.4) = SM11(IC_0MN)
       DELTA(2.5) = SM12(IC.1)
       DELTA(2 \cdot 6) = SM12(IC \cdot N)
       DELTA(2.7) = SM12(IC.MN1)
       DELTA(2 \cdot 8) = SM12(IC \cdot MN)
       DELTA(3+1)=SM11(1D+1)
       DELTA(3 \cdot 2) = SM11(ID \cdot N)
```

 $DELTA(3 \cdot 3) = SM11(ID \cdot MN1)$  $DELTA(3 \cdot 4) = SM11(ID \cdot MN)$ 

DELTA(3.5)=SM12(1D.1) DELTA(3.6)=SM12(ID.N) DELTA(3,7)=SM12(10,MN1) DELTA(3.8)=SM12(ID;MN) DELTA(4.1)=SM11(IE.1) DELTA(4.2) = SM11(IE.N) DELTA(4.3) = SM11(IE.MN1) DELTA(4.4) = SM11(IE.MN)DELTA(4.5)=SM12(IE.1) DELTA(4.6)=SM12(IE.N) DELTA(4.7)=SM12(IE.MN1) DELTA(4.8)=SM12(IE.MN) DELTA(5.1)=SM12(1.1B) DELTA(5.2)=SM12(N.IB) DELTA(5.3)=SM12(MN1.IB) DELTA(5.4)=SM12(MN.1B) DELTA(5.5)=SM22(IB.1) DELTA(5.6)=SM22(IB.N) DELTA(5.7)=SM22(IB.MN1) DELTA(5.8) = SM22(18.MN) DEL TA(6.1) = SM12(1.IC) DELTA(6.2) = SM12(N.IC) DELTA(6.3)=SM12(MN1.IC) DELTA(6.4)=SM12(MN.IC) DELTA(6.5)=SM22(IC.1) DEL TA(6.6) = SM22(IC.N) DELTA(6.7)=SM22(IC.MN1) DELTA(6.8)=SM22(1C.MN) DELTA(7.1)=SM12(1.ID) DELTA(7.2)=SM12(N.ID) DELTA(7.3)=SM12(MN1.ID) DEL TA(7.4) = SM12(MN.ID) DELTA(7.5)=SM22(ID.1) DELTA(7.6)=SM22(10.N) DELTA(7,7)=SM22(ID,MN1) DELTA(7.8)=SM22(10.MN) DELTA(8+1)=SM12(1+1E) DELTA(8.2)=SM12(N.IE) DELTA(8.3)=SM12(MN1.IE) DELTA(8,4)=SM12(MN,IE) DELTA(8.5)=SM22(IE.1) DELTA(8.6)=SM22(IE.N) DELTA(8.7)=SM22(IE.MN1) DELTA(8.8)=SM22(IE.MN) SIGMA(1+1) =- (1 - ETA(1))/XBA SIGMA(1.2) =- SIGMA(1.1)  $SIGMA(1 \cdot 3) = -TR * ETA(1) / XBA$ SIGMA(1,4) =- SIGMA(1,3) SIGMA(1.5) =- V\*(1.-XI(1))/YCA SIGMA(1.6) = -V\*XI(1)/YCASIGMA(1.7)=TR\*V\*(D-XI(1))/YCA SIGMA(1+8) =- TR\*V\*(P-XI(1))/YCA

```
TABLE II (CONTINUED)
    DO 102 J=1.4
    SIGMA(2 \circ J) = V * SIGMA(1 \circ J)
102 SIGMA(2.J+4)=SIGMA(1.J+4)/V
    DO 103 J=1.4
    SIGMA(3 \circ J) = SIGMA(2 \circ J+4)
103 SIGMA(3 \cdot J + 4)=SIGMA(1 \cdot J)
    DO 104 J=1.2
    DO 104 K=1.8
104 SIGMA(JOK)=EP*SIGMA(JOK)
    DO 105 J=1.8
105 SIGMA(3 \cdot J)=GS*SIGMA(3 \cdot J)
    DO 106 J=1.3
    DO 106 K=1.8
106 STRES(J.K)=0.0
    DO 107 J=1.3
    DO 107 K=1.8
    DO 107 L=1.8
107 STRES(J.K)=STRES(J.K)+SIGMA(J.L)*DELTA(L.K)
    WRITE OUTPUT TAPE KOT . 209 . ((STRES(J.K) . K=1.8) . J=1.3)
108 WRITE OUTPUT TAPE KOT + 205
    STIFFENER STRESSES
109 WRITE OUTPUT TAPE KOT, 203
    WRITE OUTPUT TAPE KOT. 201. M.N.
    WRITE OUTPUT TAPE KOT 205
    WRITE OUTPUT TAPE KOT . 208
    STRESSES IN LEADING EDGE STRINGER
    DELX=X(2,1)-X(1,1)
    SL=SQRTF(DELX**2+DELY**2)
    SIGMA(1.1)=-E*DELX/SL**2
    SIGMA(1,2) = -SIGMA(1,1)
    SIGMA(1'03) =- E*DELY/SL**2
    SIGMA(1 \cdot 4) = -SIGMA(1 \cdot 3)
    DO 112 I=1.M2N1.N
    IPN=I+N
    DELTA(1 \bullet 1) = SM11(1 \bullet 1)
    DELTA(1 \cdot 2) = SM11(I \cdot N)
    DELTA(1.3)=SM11(1.MN1)
    DELTA(1 \circ 4) = SM11(I \circ MN)
    DELTA(1.5) = SM12(1.1)
    DELTA(1 \circ 6) = SM12(1 \circ N).
    DELTA(1+7)=SM12(1+MN1)
    DELTA(1.8)=SM12(1.MN)
    DELTA(2 \cdot 1) = SM11(IPN \cdot 1)
    DELTA(2.2) = SM11(IPN.N)
    DELTA(2.3) = SM11([PN.MN1)
    DELTA(2.4) = SM11(IPN.MN)
    DELTA(2,5) = SM12(IPN,1)
```

DELTA(2,6) = SM12(IPN,N)

```
DELTA(2.7)=SM12(IPN.MNI)
    DELTA(2 \cdot 8) = SM12(IPN, MN)
    DELTA(3,1)=SM12(1,1)
    DELTA(3,2) = SM12(N,I)
    DELTA(3.3)=SM12(MN1.1)
    DELTA(3,4) = SM12(MN,I)
    DELTA(3,5) = SM22(1,1)
    DELTA(3 \cdot 6) = SM22(I \cdot N)
    DELTA(3,7) = SM22(1,MN1)
    DELTA(3+8) = SM22(I+MN)
    DELTA(4 \cdot 1) = SM12(1 \cdot IPN)
    DELTA(4+2) = SM12(N+IPN)
    DELTA(4.3) = SM12(MN1.IPN)
    DELTA(4,4) = SM12(MN, IPN)
    DELTA(4,5) = SM22(IPN,1)
    DELTA(4.6) = SM22(IPN.N)
    DELTA(4,7) = SM22(IPN,MN1)
    DELTA(4,8) = SM22(IPN,MN)
    DO 110 K=1.8
110 STRES(1+K)=0.0
    DO 111 K=1.8
    DO 111 L=1.4
111 STRES(1 \circ K)=STRES(1 \circ K)+SIGMA(1 \circ L)*DELTA(L \circ K)
    WRITE OUTPUT TAPE KOT 209 (STRES(1.K), K=1.8)
112 WRITE OUTPUT TAPE KOT. 205
    WRITE OUTPUT TAPE KOT+205
    STRESSES IN TRAILING EDGE STRINGER
    DELX=X(2 \circ N)-X(1 \circ N)
    SL=SQRTF(DELX**2+DELY**2)
    SIGMA(1.1)=-E*DELX/SL**2
    SIGMA(1 \cdot 2) = -SIGMA(1 \cdot 1)
    SIGMA(1,3) = -E * DELY/SL * * 2
    SIGMA(1+4) = -SIGMA(1+3)
    DO 115 I=N, MNN, N
    IPN=I+N
    DELTA(1 \cdot 1) = SM11(I \cdot 1)
    DELTA(1 \cdot 2) = SM11(1 \cdot N)
    DELTA(1,3) = SM11(1, MN1)
    DELTA(1,4) = SM11(I,MN)
    DELTA(1.5)=SM12(1.1)
    DELTA(1 \cdot 6) = SM12(1 \cdot N)
    DELTA(1.7)=SM12(1.MN1)
    DELTA(1 \cdot 8) = SM12(1 \cdot MN)
    DELTA(2.1)=SM11(IPN:1)
    DELTA(2*2) = SM11(IPN*N)
    DELTA(2,3) = SM11(IPN,MN1)
    DELTA(2*4) = SMI1(IPN*MN)
    DELTA(2+5) = SM12(IPN+1)
    DELTA(2.6)=SM12(IPN.N)
    DELTA(2*7) = SM12(IPN*MN1)
```

```
DELTA(2+8)=SM12(IPN+MN)
DELTA(3 \cdot 1) = SM12(1 \cdot 1)
DELTA(3,2) = SM12(N,I)
DELTA(3\cdot3) = SM12(MN1\cdotI)
DELTA(3,4) = SM12(MN,I)
DELTA(3.5)=SM22(1.1)
DELTA(3.6) = SM22(I.N)
DELTA(3,7) = SM22(I,MN1)
DELTA(3 \cdot 8) = SM22(I \cdot MN)
DELTA(4 \cdot 1) = SM12(1 \cdot IPN)
DELTA(4.2) = SM12(N.IPN)
DELTA(4 \cdot 3) = SM12(MN1 \cdot IPN)
DELTA(4.4) = SM12(MN.IPN)
DELTA(4.5)=SM22(IPN.1)
DELTA(4.6) = SM22(IPN.N)
DELTA(4.7) = SM22(IPN.MN1)
DELTA(4 \cdot B) = SM22(IPN \cdot MN)
DO 113 K=1,8
```

```
113 STRES(1•K)=0.0
DO 114 K=1.8
```

```
DO 114 L=1,4
```

- 114 STRES(1.K)=STRES(1.K)+SIGMA(1.L)\*DELTA(L.K)
- WRITE OUTPUT TAPE KOT 209 (STRES (1 .K) .K=1.8)
- 115 WRITE OUTPUT TAPE KOT.205 WRITE OUTPUT TAPE KOT.205

STRESSES IN LOWER RIB

```
SIGMA(1.1) =-E/DELXR
    SIGMA(1+2)=+E/DELXR
    DO 118 I=1.N1
    DELTA(1 + 1) = SM11(1 + 1)
    DELTA(1+2) = SM11(I+N)
    DELTA(1+3) = SM11(I+MN1)
    DELTA(1.4) = SM11(I.MN)
    DELTA(1+5)=SM12(1+1)
    DELTA(1+6)=SM12(1+N)
    DELTA(1,7) = SM12(I,MN1)
    DELTA(1 \circ B) = SM12(1 \circ MN)
    DELTA(2+1) = SM11(1+1+1)
    DELTA(2,2) = SM11(I+1,N)
    DELTA(2+3) = SM11(I+1+MN1)
    DELTA(2 \cdot 4) = SM11(1+1 \cdot MN)
    DELTA(2.5)=SM12(I+1.1)
    DELTA(2+6) = SM12(I+1+N)
    DELTA(2.7)=SM12(1+1.MN1)
    DELTA(2.8) = SM12(1+1.0MN)
    DO 116 K=1.8
116 STRES(1+K)=0.0
```

```
DO 117 K=1.8
DO 117 L=1.2
```

117 STRES(1.K)=STRES(1.K)+SIGMA(1.L)\*DELTA(L.K)

TABLE II (CONTINUED)

```
WRITE OUTPUT TAPE KOT+209+(STRES(1+K)+K=1+8)
118 WRITE OUTPUT TAPE KOT. 205
    WRITE OUTPUT TAPE KOT. 205
    STRESSES IN UPPER RIB
    SIGMA(1 \cdot 1) = -E/DELXT
    SIGMA(1+2)=+E/DELXT
    DO 121 I=MN1.MN4
    DELTA(1,1) = SM11(1,1)
    DELTA(1 \cdot 2) = SM11(I \cdot N)
    DELTA(1+3) = SM11(I+MNI)
    DELTA(1 \cdot 4) = SM11(1 \cdot MN)
    DELTA(1+5)=SM12(1+1)
    DELTA(1+6) = SM12(I+N)
    DELTA(1+7)=SM12(1+MN1)
    DELTA(1+8) = SM12(1+MN)
    DELTA(2+1) = SM11(I+1+1)
    DELTA(2+2)=SM11(I+1+N)
    DELTA(2.3)=SM11(I+1.MN1)
    DELTA(2.4) = SMI1(I+1.MN)
    DELTA(2+5)=SM12(1+1+1)
    DELTA(2+6)=SM12(1+1+N)
    DELTA(2.7) = SM12(1+1.MN1)
    DELTA(2.8) = SM12(I+1.0MN)
    DO 119 K=1.8
119 STRES(1.K)=0.0
    DO 120 K=1.8
    DO 120 L=1.2
120 STRES(1 .K)=STRES(1 .K)+SIGMA(1 .L)*DELTA(L .K)
    WRITE OUTPUT TAPE KOT, 209, (STRES(1,K),K=1,8)
121 WRITE OUTPUT TAPE KOT.205
    NUM=NUM+1
    IF (NUM-NOPAC) 2.2.1
```

```
END
```

```
SUBROUTINE REARR(N2)

DIMENSION A(81+81)+B(81+81)+C(81+81)+TERM(170)

COMMON A+B+C

N=N2+N2

DO 60 I=1+N

READ TAPE 5+NR+NC+NTYPE

IF(I=N2) 10+10+40

READ TAPE 5+(TERM(L)+L=1+N)

IR=I

10 M=1

DO 20 IC=1+N2

A(IR+IC)=TERM(M)
```

```
20 M=M+1
```

```
DO 30 IC=1.N2
30 M=M+1
B(IR.IC)=TERM(M)
GO TO 60
```

- 40 IR=I-N2 D0 50 IC=1+N2
- M=N2+1 50 M=M+1
- C(IR.IC)=TERM(M) 60 CONTINUE
  - RETURN

# TABLE III

# DISPLACEMENTS OF CORNER NODES

# INCHES PER MILLION POUNDS

MOD NO	FORCE	F1	F3	F4	F7	F8
1	F1	1.3888	.9985	1.2154	0291	6057
	F3	• 9985	5.1240	5.7372	-1.7008	-3.8586
	F4	1.2154	5.7372	6.9983	-2.0822	-4.5743
	F7	0291	-1.7008	-2.0822	1.5412	2.2442
	F8	-•6057	-3.8586	-4.5743	2.2442	4.7349
2	F1	1.5600	1.4853	1.4821	2945	7983
	F3	1.4853	7.2103	7.2773	-2.7163	-5.1704
	F4	1.4821	7.2773	8.2304	-2.8358	-5.6905
	F7	2945	-2.7163	-2.8358	2.2354	2.6965
	F8	7983	-5.1704	-5.6905	2.6965	5.8838
3	F1	1.7331	1.8883	1.8811	3418	-1.0720
	F3	1.8883	8.2236	8.3337	-2.8418	-5.9655
	F4	1.8811	8.3337	9.3799	-2.9734	-6.6155
	F7	3418	-2.8418	-2.9734	2.2746	2.8307
	F8	-1.0720	-5.9655	-6.6155	2.8307	6.7343
4	F1	1.8779	2.1979	2.1999	4404	-1.2753
	F3	2.1979	9.5203	9.4757	-3.4357	-6.8437
	F4	2.1999	9.4757	10.5412	-3.4387	-7.5119
	F7	4404	-3.4357	-3.4387	2.7682	3.1022
	F8	-1.2753	-6.8437	-7.5119	3.1022	7.5498
5	F1	2.0157	2.5335	2.5317	5183	-1.4970
	F3	2.5335	10.4360	10.3870	-3.7124	-7.5003
	F4	2.5317	10.3870	11.4827	-3.7034	-8.2200
	F7	5183	-3.7124	-3.7034	2.9390	3.3108
	F8	-1.4970	-7.5003	-8.2200	3.3108	8.1383
6	F1	2.1086	2.7236	2.7246	5621	-1.6134
	F3	2.7236	11.1107	10.9870	-4.0108	-7.9209
	F4	2.7246	10.9870	12.0984	-3.9433	-8.6647
	F7	5621	-4.0108	-3.9433	3.2064	3.4587
	F8	-1.6134	-7.9209	-8.6647	3.4587	8.5124
7	F1	2.1873	2.9076	2.9083	6101	-1.7345
	F3	2.9076	11.6113	11.4814	-4.1944	-8.2718
	F4	2.9083	11.4814	12.6035	-4.1182	-9.0340
	F7	6101	-4.1944	-4.1182	3.3345	3.5968
	F8	-1.7345	-8.2718	-9.0340	3.5968	8.8053

# TABLE IV

# WEB STRESSES

# PSI PER POUND

MOD	ELEM NO	PT	STR	F1	F3	F4	F7	F8
1	1-1	1	SXX	6264	1466	0201	.0034	-01141
			SYY	.2410	•6321	•7056	.3783	6488
			SXY	0619	.6025	.4811	1809	2790
		2	SXX	7272	5241	4560	.1264	.3215
			SYY	0780	5623	6738	.7674	•7298
			SXY	.1205	.8203	.8436	2561	4761
		3	SXX	3621	1055	.2535	0185	0513
			SYY	.0183	5009	5314	.7447	+6939
			SXY	.0565	.5501	.5389	1684 .	1607
		4	SXX	0102	.2638	.9062	1475	3672
			SYY	.0730	5956	5693	.7728	.8380
			SXY	.0163	.3083	.2816	0904	.1289
		5	SXX	0847	0150	.5842	0566	0453
			SYY	1626	-1.4780	-1.5884	1.0603	1.8566
			SXY	.1512	.4692	.5494	1460	-+0167#
2	1-1	1	SXX	7320	1091	1388	1022	0443
-		1.2	SYY	4165	1.4827	1.4656	2121	-1-1400
			SXY	1137	- 3465	. 3663	0551	- 1582
		2	SXX	9277	9103	9276	.2675	6577
		-	SVY	2026	-1.0525	-1.0304	- 9581	1.0818
			SYV	.2364			- 2516	- 4840
200	F	3	SXX	5471	1320	- 1819	1025	1817
		-	SVY	.0482	2718		- 5042	. 4627
			SXY	.0851	-5360	- 5364	- 1512	- 1592
		4	SXX	1784	.5971	-5154		
		-	SVY	.2612	.3535	- 3409	- 3021	0202
			SYV	0446	-1456	1558	.0308	-1455
		5	SXX	- 3501	1057	-1766	- 1255	- 3649
		5	cvv	- 2021	-1.8709	-1.8400	1.3200	1.0202
	ć.		evv	- 2625	-1.0709	-1.0490	- 3290	109292
	2-1		CVV	02025	60076	10/00	- 2408	
	2-1	*	SAA	- 0136	- 3160	- 1405		
			CVV	0136	3100	1495	102094	-02616
		-	SXY	0026	01324	•5294	2240	-02709
		2	SXA	.0308	.6004	. 1602	3903	2116
			SYT	.0052	5870	8067	• 7965	.9390
		2	SXY	0071	•5298	.6194	0848	3201
		3	SXX	.0175	• 3565	.9050	1919	3800
			SYY	0014	6280	6/33	.9222	01499
			SXY	0028	.5196	.5088	1/54	1418
		4	SXX	.0046	.1056	1.0329	0056	405/
			SYY	0066	6910	5934	1.0096	•6551
		-	SXY	.0005	.4930	.4054	2548	.0328
		5	SXX	.0096	.0339	.8590	1307	1586
			SYY	.0091	9179	-1.1438	.6135	1.6269
			SXY	0076	.3233	•4808	1382	0032
MOD	ELEM NO	PT	STR	F1	F3	F4	F7	F8
-----	------------	-----	-----	--------	---------	---------	--------	---------
3	1-1	1	Sxx	7611	0494	1004	0957	•0156
			SYY	• 5759	1.9918	1.8979	3829	-1.3816
			SXY	0746	•4908	.5314	0291	3079
		2	SXX	9457	6135	6369	.0680	+406B
			SYY	0080	.2065	.2000	.1355	1438
			SXY	.1320	.8591	.8718	1725	5027
		3	SXX	5677	.0383	0358	1908	.0706
		10	SYY	.0627	.2638	.2484	.0968	1469
			SXY	.0205	.4940	.5236	0698	2439
		4	SXX	2010	•6557	•5323	4398	2415
			SYY	.0977	.2116	1928	.0900	0741
			SXY	0782	.1514	.1963	.0239	.0028
		5	SXX	3630	.1607	•0616	2960	1015
		-	SYY	4147	-1.3547	-1.2968	.5449	1.0119
			SXY	.1030	. 4746	. 4949	1018	1680
	1-2	1	SXX	8579	7321	7627	.0873	. 3957
			SYY	.1727	.2491	. 3293	- 4530	2234
			SXY	0523	.3782	. 3913	- 2510	- 1830
		2	SXX	9662	-1-1888	-1.2254	.3156	
		-	SYY	1701	-1.1961	-1.1349	1.1757	1,1909
			SXY	.1668	.7831	. 7730	4221	3849
		3	SXX	5439	4010	4817		
		-	SYY	0274	9081		1.0506	1.0264
			SVV	.0835	- 09001	- 00005	1.0508	1.0284
			SAL	- 1281	-4477	.4341	2554	0825
		4	SXA	1201	.3588	•2335	3382	•0713
			STT	0942	/086	6/55	.9699	.9487
		-	SXT	.0137	.1372	•1186	0991	•2474
		Э	SXA	- 2232	0419	1/24	1378	•4635
			CVV	2065	-1.9767	-1.9602	1.6039	2.1897
	2.1		SAT	.2080	•4924	•4535	2492	.0703
	2-1	1	SXX	0793	.8974	1.1044	1755	7031
			STT	.0326	2986	2364	1.3669	0903
		-	SXY	.0464	.9580	• 7493	2847	5110
		4	SXX	•0842	• 7626	•9222	2210	-•4699
	1.05		SYY	0785	7254	8130	1.2230	•6475
		-	SXY	.0400	.8567	.8028	2375	5641
		3	SXX	.0581	•4676	1.0057	1145	5380
			SYY	1152	9281	9345	1.2198	•8154
		- 1	SXY	.0053	.7014	•6472	2667	3606
		4	SXX	.0290	•1617	1.0745	0118	5872
			SYY	1611	-1.1655	-1.1029	1.2048	1.0431
		-	SXY	0299	.5378	•4960	2921	1615
		5	SXX	0003	.0487	.9219	0499	3919
			SYY	2541	-1.5230	-1.5858	1.0843	1.6612
			SXY	0352	•4530	.5408	2526	2060

MOD	ELEM NO	PT	STR	F1	F3	FĄ	F7	F8
3	2-2	1	SXX	.1082	.8149	1.0956	4389	6540
			SYY	-01104	4633	2285	.9034	0964
			SXY	0844	.3098	.2787	0814	0298
		2	SXX	.1590	.8416	1.0075	5330	4217
3			SYY	.0502	3788	5073	• 6055	•6386
			SXY	1178	.1702	.3067	.0127	0508
		3	SXX	.0806	•4913	1.0678	3060	4462
			SYY	.0432	4801	5190	.6444	.7120
			SXY	0743	.1781	.2276	0640	01644
		4	SXX	.0063	.1432	1.1208	0866	-04519
			SYY	.0492	5746	5534	.6590	.8452
			SXY	0335	.1747	.1507	1330	.3779
		5	SXX	.0489	•1656	1.0470	1655	2573
			SYY	.1839	5038	7870	.4095	1.4609
			SXY	0615	.0578	.1742	0541	• 3604
4	1-1	1	SXX	8721	3535	3546	.0661	.2179
			SYY	.8434	2.2713	2.2674	4130	-1.4985
			SXY	1475	.4243	.4256	0810	2470
		2	SXX	-1.1940	-1.1125	-1.1130	.1975	.6947
			SYY	1752	1305	1324	.0029	.0103
			SXY	.1709	.8861	.8883	1816	4933
		з	SXX	8302	5228	5227	.0763	• 3650
			SYY	•1346	•5153	•5131	1149	3825
			SXY	0072	•5274	• 5296	1151	2772
		4	SXX	4760	.0443	.0449	0409	.0494
			SYY	.4141	1.0897	1.0874	2204	7305
			SXY	1759	.1824	.1847	0515	0685
		5	SXX	7787	6695	6682	.0827	.4978
			SYY	5439	-1.1693	-1.1697	.1708	.6886
			SXY	.1235	•6168	•6198	1461	3002
	1-2	1	SXX	-1.0327	-1.1210	-1.1224	.1997	•6137
			SYY	•1695	.4007	.4079	.2130	2478
			SXY	0970	.1362	.1368	1874	.0035
		2	SXX	-1.1973	-1.7846	-1.7870	.5861	1.2192
			SYY	3512	-1.6991	-1.6951	1.4355	1.6681
			SXY	.2789	.8287	.8278	4806	3745
		3	SXX	8038	9619	9653	.2090	.7038
		-	SYY	0993	9250	9205	1.0170	1.0361
			SXY	.1201	•4125	•4117	2682	0638
		4	SXX	4152	1588	1633	1564	.2064
			SYY	.1370	2133	2085	•6349	.4611
			SXY	0274	.0170*	.0161	0646	.2355
	S	5	SXX	5699	7829	7884	.2068	.7758
			SYY	3528	-2.1883	-2.1866	1.7847	2.2632
			SXY	.3262	•6682	.6660	3403	1200

		t y t t						
utsunt Martin u				TABLE	IV (CONT	INUED)		
MOD	ELEM	PT	STR	F1	F3	F4	F7	F8
NO	NO	· · · ·						
•	2-1		SYY	- 1340	7605	7690	0700	
, 11 T	<u> </u>		SVV	- 1349	1-2246	0/002	2702	
			SXY		• 60 60	1.5010		-1.0715
		2	SXX	3050	•1534	1587	0206	
		-	SYY	- 2577				- 4019
			SXY	1161	-8860	.8030	•0529	+4710
		ંગ	Sxx	-1450	•5552	•5637	- 2548	
	1	7	SYY	-1230				- 1561
			SXY	0283	.5973	•6071	- 1530	•1301
		4	SXX	•0092	•9362	•0071		
			SYY	-0064	•1726	.1671	2845	
			SXY	~ 0552	• 3180	. 3298	0303	-1061
		5	SXX	-1493	•3616	• 3798	- 2477	■•0527
		· •	SYY	- 5082	-1.6455	-1.6313	1.0213	1.3311
		· ·	SXY	• 0602	•5791	.5948	- 1993	2859
	2-2	1	SXX	1311	•5522	•5297	4785	- \$2710
		. 1 × 11	SYY	0334	1812	1564	•6524	.1163
			SXY	1119	0857	.1042	0489	.1118
		2	Sxx	0990	.3237	.3032	3665	.0497
5			SYY	.0682	9042	8732	1.0068	1.1315
	1 A. A. A. A.		SXY	0866	•2152	•2095	1363	•0561
· · .	ang si ta ta	3	SXX	0801	•5152	4687	- 4855	0861
			SYY	.0521	6867	-•6653	.8922	.8681
			SXY	0802	•0949	0959	0716	.1946
- 10 A		4	SXX	0601	<b>₀699</b> 0	•6266	60.07	2113
			SYY	.0394	4936	4815	<b>•</b> 7897	•6389
	1 		SXY	0729	0209	<b>-</b> •0141*	0098	• 3311
		5	SXX	0301	•4859	•4153	4963	•0878
· · ·			SYY	•1343	-1.1678	-1.1500	1.1201	1.5856
			SXY	0493	•0998	•0839	0913	¢2792
	3-1	<u> </u>	SXX	·1054	1.3728	1.3357	6830	8677
			SYY	0075	•5089	• 3511	•4932	4948
			SXY	•0136	• 5363	• 5760	0023	-•3522
		2	SXX	e <sup>0</sup> 845	1.0454	1.0482	5691	5474
			SYY	0737	5270	5586	•8534	•5185
1.1			SXY	0053	•5957	•6309	0905	4027
		3	SXX	.0640	1.1578	1.1504	6904	~•6482
			SYY	0729	-•3769	4258	•7753	•3747
			SXY	0124	•4409	o 4947	0284	2522
		4	SXX	•0427	1.2574	1.2414	8073	7364
			SYY	0746	2674	3284	.7112	•2704
			SXY	0202	•2884	• 3605	0302	1037
		5	SXX	.0234	•9556	•9763	7024	4412
			SYY	1356	-1.2225	-1.1672	1.0433	1.2047
• •			SXY	-00377	• 3431	.4112	0510	1503

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MOD NO	ELEM NO	РТ	STR	F1	F3	F4	F7	F8
4	3-2	1	Sxx	0517	•6562	•6675	4397	2972
			SYY	0387	8374	-•5760	1.3022	.3783
			SXY	0575	•3435	• 3364	1882	0062
		2	sxx	0321	•6376	•5867	5577	0858
			SYY	•0235		8318	.9289	1.0472
			SXY	0492	.2915	.3100	1136	•0.386
		з	SXX	- 0259	•5781	.5708	- 44.31	0736
		-	SYY	0142	- 9042	- 7906	1.0326	.9301
			SXY	- 0420	.2936	• 2789	1817	1248
		4	SXX	0190	.5178	•5517	3332	0531
		•	SYY	.0073		- 7594	1,1217	.8392
			SXY	0345	2936	.2467	- 2469	.2128
		5	SXX	0008	.5007	.4772	- 4419	.1417
		-	SYY	0647	- 9688	- 9952	.7775	1.4559
			SXY	0268	•2457	.2224	1781	2542
	4-1	· 1	SXX	0322	6008	1.0269	0582	6989
	• •	-	SYY	0104	-1-3302	-1.1535	2.4807	.5955
			SXY	.0051		.6801	3777	
		2	SXX	0302	,7309	1.0709	3921	6141
			SYY		- 9185	-1.0143	1.4240	.8639
			SXY	0025	•6814	.6694	-1570	- 4635
		З	SXX	.0193	.2954	1.0531		
		0	SVV		-1.0757	-1-0266	1,5806	-8462
			SYV	- 0031	.7666	. 6934	3470	4178
		4	SXX	.0082	1340	1.0373	.2644	
		•	SYY	0233	-1.2140	-1.0324	1.6883	.8409
	15		SXY	0041	.8381	•7169	5267	3724
		5	SXX	.0065	0159	1.0772	0385	5641
		-	SYY	0289	- 8403	~ 9061	.7293	1.0845
			SXY	0111	•5684	.7072		- 3793
	4-2		SXX	0113	•4422	.9873	- 2469	- 5370
		•	SYY	- 0066	3901	.0412	6769	3182
			SXY	0152	.4101	•3937	-1913	0122
		2	SXX	0072	.4517	.7672	3414	1639
		-	SYY	,0060	3600	- 6553	3777	.8622
			SXY	0129	2681	.5567	0795	1411
		з	SXX	0045	2455	1.0342	- 1665	4041
		-	SYY	0052	4291	-,4797	.4722	.6317
			SXY		.2938	.4154	1462	.0767
		4	SXX	0015	.0397	1.2910	.0039	6270
		. v	SYY	0050	- 4969	- 3364	5528	4558
			SXY	0091	.3130	.2818	2078	.2886
		5	SXX	.0021	.0483	1.0912	0818	2885
		2	SYY	.0166	4695	-•9685	.2812	1.5271
			SXY	0070	.1841	.4296	1064	.1716

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				IABLE	IV (CONT	INUED)		· · ·
MOD	ELEM NO	PT	STR	F1	F3	F4	F7	F8
5	1-1	ÇG	SXX	-•8236	3859		•0474	•2787
1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 - 1997 -			SYY	•2073	•6390	•6385	1143	4286
			SXY	0223	•6088	•6099	-•1109	3579
-	1-2	CG	SXX	8938	-•8293	-•8165	•1518	•5649
			SYY	•0268	•1734	•1773	•0466	1382
			SXY	0642	•2819	•2761	-•0978	0934
	-1-3	ÇG	SXX	8693		9477	•1293	•6577
			SYY		-02347	-•2403	• 3008	•2197
	1-0	CC	SVV	- 7669	•2746	• 2781	1958	0370
	1-4		SVV	- 1607	- 1 4324		• 1630	1 5500
			SYV	-1682	-104324	-104205	- 4241	100090
	2-1	CG	SXX	0295	•8195	•8491	2341	~ 4431
	•		SYY	0964	0815	.0918	• 2087	-1369
			SXY	•0271	•6699	.6637	1369	3910
	2-2	CG	SXX	1190	.6201	• 5996	3575	2333
			SYY	-•1678	3110	3470	•4734	• 2554
			SXY	0327	• 3469	• 3785	0916	-•1552
	2-3	CG	SXX	1031	•5135	• 4652	4136	0803
			SYY	1458	9369	9179	. 1•0464	•9090
	۰.		SXY	0755	•2190	•2439	1734	0116
	2-4	CG	SXX	.0178	•6806	•6202	-•6224	-•1753
	ta ang Ang		SYY	.1457	7865	7265	•9829	1.0408
			SXY	-•1515	1043	1211	0179	• 3966
	3-1	CG	SXX	•1176	1.4127	1.3537	~.7793	
			SYY				•5268	•1279
	2-2	cc	SXT	0094	1 0500	.05279	.0536	3187
· · · · ·	3-2	CG	577		<b>1</b> 0,300	1:0507	1,1735	
			SXY	-0558	-4008	4505		2115
	3-3	CG	SXX	0353	.8139	.8098	5578	- 2852
			SYY	0353	8383	- 7026	1.0751	•7765
			SXY	0876	•2633	,2848	1515	•0284
	3-4	CG	SXX	0683	•4346	• 3505	3783	•1423
			SYY	.0166		7449	•8611	۰96 <b>3</b> 6
			SXY	0225	·2340	•1978	1639	.2727
	4-1	CG	SXX	•0562	•4377	1•1268	0862	7274
			SYY	0277	-1.2913	-1.2358	1.9850	•9542
			SXY	0093	•8807	•7415	-•3960	-•5086
	4-2	CG	SXX	.0199	•3556	1.1371	1504	6795
			SYY	•C022	8044	7171	1.1363	.6234
			SXY	0164	•6359	•6474	3209	3476
	4-3	CG	SXX	0271	•2291	1.0308	-•1295 6447	- 4992
			211	-0013	-00400	-6403/	•044/	• 5666
	0-0	<u>د</u> م	SYY	- 001Z	• <del>•</del> • • • • • • • •	1.0075	- 1903	
	<b>4 4</b>		SYY	0015	3469	- 4340	• 3262	•6364
			SXY	0035	.1923	•3382	0975	•2339
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MOD	ELEM NO	PT	STR	F1	F3	F4	F7	F8
6	1-1	CG	SXX	-1.0783	8047	8046	.1553	•5161
			SYY	.2634	•6806	.6806	1354	4357
			SXY	0621	• 5550	• 5553	1022	3314
	1-2	CG	SXX	-1.1774	-1.3072	-1.3072	.2543	.8364
			SYY	.0378	.1924	.1919	0404	1548
			SXY	1479	.0667	.0679	0254	.0288
	1-3	CG	SXX	-1.1463	-1.4548	-1.4561	.2942	.9220
			SYY	0645	0177	0179*	.0265	0476
			SXY	0032	•1800	• 1820	1701	.0173
	1-4	CG	SXX	-1.0159	-1.5011	-1.5044	.4218	1.0214
		Set.	SYY	3150	-1.7174	-1.7134	1.5788	1.7454
		\$	SXY	•2868	•7582	•7567	6030	3351
	2-1	CG	SXX	4068	.2804	.2813	0550	1191
			SYY	•0548	•4162	• 4152	0728	3230
			SXY	0159	.6109	•6115	1201	3567
	2-2	CG	SXX	5596	2621	2613	.0391	.2692
			SYY	1277	0600	0615	.1233	0326
			SXY	0717	.2717	.2744	1259	0942
	2-3	CG	SXX	5203	4363	4386	.0493	•4518
			SYY	2625	8339	8313	•7634	•7099
			SXY	0100	.3334	.3369	3155	1197
	2-4	CG	SXX	2054	.0953	.0859	3473	.1042
			SYY	.0756	9101	9020	1.0938	1.1958
			SXY	0841	0231*	0249	1205	•2548
	3-1	CG	SXX	0792	•7734	•7761	2135	3838
			SYY	0804	.2047	.2015	.0787	2307
			SXY	.0171	•6638	•6652	1441	3996
	3-2	CG	SXX	1616	•4299	• 4326	2107	1050
			SYY	2148	4140	4164	•4992	.2802
			SXY	0572	•3749	.3812	1733	1856
	3-3	CG	SXX	1188	•4207	•4143	3786	0725
			SYY	1114	7414	7339	.8581	.7465
			SXY	1272	.1012	.1102	1286	.0668
	3-4	CG	SXX	1244	•2779	•2575	3942	•0637
			SYY	.0852	8605	8417	1.0130	1.1240
			SXY	1086	0900	0935	0251	• 3732
	4-1	CG	SXX	.0844	1.0691	1.0767	4039	5735
			SYY	1472	0373	0456	• 3481	0478
			SXY	.0115	•6402	•6441	1232	4006
	4-2	CG	SXX	.0243	.8637	.8699	4797	3960
			SYY	1439	4661	4706	.6940	.3877
			SXY	0808	.3131	• 3295	0871	1376
	4-3	CG	SXX	0356	•6710	•6588	5263	2167
			SYY	0396	7367	7154	•9380	.7737
			SXY	1117	•1017	•1229	-,0605	.1094
	4-4	CG	SXX	0649	•4936	• 4441	5102	0111
			SYY	.0572	9075	8634	.9995	1.1117
			SXY	0695	.0190	.0115	0597	.3543

MOD	ELEM NO	PT	STR	F1	F3	F4	F7	F8
6	5-1	CG	SXX	•1141	1.1986	1.2188	5662	7052
			SYY	1179	1619	1848	•5780	.0885
			SXY	0031	•5656	• 5765	0553	3603
	5-2	CG	SXX	•0442	•9869	1.0116	6056	5082
			SYY	0773	5276	5327	.8674	.4761
			SXY	0604	• 3056	• 3463	0321	1270
	5-3	CG	SXX	0091	.8605	.8256	6739	3137
			SYY	0108	8012	7487	1.0256	.8054
			SXY	0668	.1688	.2204	0577	.0809
	5-4	CG	SXX	0309	•6572	.5708	5928	0501
			SYY	.0298	9905	8873	1.0192	1.1038
			SXY	0355	.1703	•1504	1523	.2963
	6-1	CG	SXX	.0736	1.1618	1.2349	6190	7558
			SYY	0662	2690	3270	.7988	.2227
			SXY	0050	•4914	.5219	.0192	3261
	6-2	CG	SXX	.0288	1.1442	1.1660	8029	6322
			SYY	0341	6305	6392	1.0385	•5722
			SXY	0331	.2944	• 3987	.0017*	1531
	6-3	CG	SXX	0022	•8546	.8602	6281	3109
			SYY	0019	-1.0080	8421	1.2087	.8589
			SXY	0316	.3550	• 4177	2158	0434
	6-4	CG	SXX	0131	•6325	•5751	5018	.0074
		Present.	SYY	.0132	9159	7642	.8661	.9781
			SXY	0153	.2962	.2668	2318	.2482
	7-1	CG	SXX	.0354	1.3731	1.4513	9409	9509
			SYY	0292	3749	5501	1.0224	.4077
			SXY	0033	•4017	• 4858	.0905	3112
	7-2	CG	SXX	.0122	•7887	1.0655	4688	5693
			SYY	0131	-1.1807	9964	1.6046	.8321
			SXY	0138	.6482	.7096	3875	3939
	7-3	CG	SXX	0009	•5145	.8085	3044	2522
			SYY	.0007	8752	6372	.9542	•6584
			SXY	0124	.5427	.6186	3787	1955
	7-4	CG	SXX	0048	• 3947	•5173	2615	.1254
			SYY	.0051	5562	4533	• 4571	.6847
			SXY	0057	.2910	• 3193	1956	.2463
	8-1	CG	SXX	.0108	.0983	1.0286	.1432	6928
			SYY	0121	-1.8523	-1.6592	2.6803	1.2448
			SXY	0003	1.1391	.9266	7135	6526
	8-2	CG	SXX	.0039	.1027	1.1808	.0036	7377
			SYY	0022	6916	5452	.8638	•4573
			SXY	0053	•7838	•8155	5225	4922
	8-3	CG	SXX	0000	•1157	1.2223	0470	6609
			SYY	.0009	2893	2088	•2762	.2566
			SXY	0045	•4281	•6488	2587	2444
	8-4	CG	SXX	0011	.1224	1.1058	0671	3807
			SYY	.0011	1383	2949	.0882	.4890
			SXY	0018	.1535	.4120	0778	.1986

MOD	ELEM NO	PT	STR	F1	F3	F4	F7	F8
7	1-1	CG	SXX	-1.0205	6065	6065	•1154	• 3891
			SYY	.3103	.7822	.7822	1491	4960
			SXY	0491	•6646	.6647	1242	4105
	1-2	CG	SXX	-1.1566	-1.0652	-1.0649	.2014	.6816
			SYY	•1099	•3403	• 3402	0636	2279
			SXY	1959	.1775	.1776	0328	0885
	1-3	CG	SXX	-1.1982	-1.2956	-1.2959	.2432	.8290
			SYY	.0186	.1345	.1341	0174	1062
			SXY	2082	.0010	.0016	0083	.0493
	1-4	CG	SXX	-1.1973	-1.4184	-1.4180	•2718	.9059
			SYY	0282	.0205	•0203	0208	0382
			SXY	1569	0168*	0159	0331	.0946
	1-5	CG	SXX	-1.1750	-1.4785	-1.4790	.2913	.9431
			SYY	0600	0699	0703	.0684	•0241
			SXY	0690	•0686	.0701	1070	.0744
	1-6	CG	SXX	-1.1333	-1.4963	-1.4978	•3110	•9563
			SYY	0949	2062	2059	• 1698	.1409
			SXY	.0496	•2626	•2642	2542	0273
	1-7	CG	SXX	-1.0537	-1.4464	-1.4487	.3155	.9330
			SYY	1615	5754	5738	.4915	.5112
			SXY	.2043	.6071	.6074	5174	2591
	1-8	CG	SXX	9041	-1.3256	-1.3286	.3309	.9083
			SYY	3965	-2.2740	-2.2701	2.0746	2.3348
			SXY	• 3811	1.0466	1.0444	8458	5730
	2-1	CG	SXX	2375	•6987	•6993	1401	3946
			SYY	.0621	•4308	•4304	0709	3164
9		-	SXY	0117	.6877	•6878	1299	4207
	2-2	CG	SXX	4160	•2187	•2187	0568	0733
			SYY	0477	•1610	•1598	0087	1620
			SXY	1012	•3608	• 3615	0797	1901
	2-3	CG	SXX	5137	1037	1017	,0026	.1513
			SYY	1172	0390	0395	.1001	0377
20-	110		SXY	1130	.2208	•2216	0856	0729
	2-4	CG	SXX	5513	2961	2960	•0267	.3011
			SYY	1672	2207	2227	•2140	•0996
	-		SXY	0848	.1915	• 1944	1339	0299
	2-5	CG	SXX	5346	3863	3876	.0279	.3920
			SYY	2094	4584	4579	•4054	•3152
	221 2		SXY	0413	•2417	.2451	2310	0487
	2-6	CG	SXX	4573	3540	3568	0186	•4068
			SYY	-02440	8214	8178	.7380	.7034
			SXY	0087	.3164	.3190	3492	0980
	2-7	CG	SXX	3029	1358	1417	1704	•2886
			SYY	2259	-1.3550	-1.3487	1.2973	1.3788
			SXY	0318	•2672	.2679	3748	0533
	2-8	CG	SXX	0269	•4968	•4871	6313	1953
			SYY	•2211	8226	8155	101117	1.2651
			DXY	-01/34	-06012	2900	00463	04/98

MOD NO	ELEM NO	PT	STR	F1	F3	F4	F7	F8
7	3-1	CG	Sxx	.0024	1.0032	1.0040	2527	5455
		-	SYY	0427	.3084	.3063	.0263	2912
			SXY	.0266	.7270	.7273	1381	4506
	3-2	CG	SXX	0845	.7246	.7295	2139	3417
			SYY	1371	•0174	•0157	1686	1010
			SXY	0300	•5135	.5140	1258	2926
	3-3	CG	SXX	1342	.5444	.5445	2223	1933
			SYY	1955	2269	2328	.3219	.0933
			SXY	0576	.3764	.3817	1354	1874
	3-4	CG	SXX	1480	.4212	• 4224	2358	0838
			SYY	2232	4919	4917	-5388	. 3395
			SXY	0757	.2997	. 3055	1784	1223
	3-5	CG	SXX	1295	.3835	.3834	2928	0355
			SYY	2120	7463	7424	.7813	•6382
			SXY	1011	.2176	.2248	- 2042	
	3-6	CG	SXX	0899	.4335	.4259	4080	0602
			SYY	1302	9321	9237	1.0099	.9499
			SXY	1440	.0687	.0772	= 1592	.0895
	3-7	CG	SXX	0615	.5084	.4897	5463	1276
			SYY	.0748	7925	- 7771	.9881	1.0176
			SXY	1822	1638	- 1592	0037	. 3530
	3-8	CG	SXX	1626	.1771	1501	3621	1415
	50		SYY	.1246	9200.	8993	1.0574	1.2491
			SXY	0833	1216	1290	•0053*	.4560
	4-1	CG	SVV	.1247	1.1727	1 1909	- 2072	- 6000
			SVV	1202	.1178	.1130		
			SXY	.0285	.7072	.7072	- 1224	- 4515
	4-2	CG	SXX	.0787	1.0467	1.0460	4298	
			SYY	1703	1402	1534	. 3974	0307
			SXY	0202	.5263	.5342	1031	- 3188
	4-3	CG	SXX	0478	.8970	.9094	4225	4165
			SYY	1824	4114	- 4123	.6216	.2784
			SXY	0615	.4038	.4103	1243	2160
	4-4	CG	SXX	.0270	.8200	.8311	4762	3463
18			SYY	1553	5867	5896	.7767	+5017
15-			SYY	0993	.2601	. 2764	1043	0948
•	4-5	CG	SYY	.0062	.7813	.7762	5574	3009
	4.5		SYY	0864	7074	7026	.9053	\$7047
			SYY	1294	.1128	1397	0612	.0491
	4-6	CG	SVY	0287	.7099	6818	6015	2301
	40	~~	SVV	.0083	7590	7330	.9657	.8477
			SYV.	1329	.0071	.0334	0242	.2007
	4-7	CG	SXX	0855	•5218	.4721	5272	0532
			SYY	.0412	9101	8619	1.0459	1.0607
			SXY	0832	.0270	.0364	0575	.2897
	4-8	CG	SXX	0594	.4785	.4145	5144	.0248
			SYY	0755	9734	9181	1.0162	1.2157
			SXY	0469	.0164*	0047	0666	.4185

MOD NO	ELEM NO	PT	STR	F1	F3	F4	F7	F8
7	5-1	CG	SXX	.1435	1.2944	1.2074	5741	7610
			SYY	1270	0404	0645	-4693	
			SXY	.0136	.6299	-6354	0580	- 4168
	5-2	CG	SYX	.1100	1.0953	1.1419	- 5017	- 6247
	5 -		SVY	- 1281	3154	1.1419	5017	0247
		1 23	SXY	0274	-5163	- 5176		3121
	5-3	CG	SXX	.0776	1.0636	1.0964	6087	
	55		SVY	1034	4105	1.0904	- 7579	-05121
			SXY	0601	. 3275	. 3639	0103	- 1690
	5-4	CG	SXX	.0427	1.0295	1.0320	- 6057	
	2.4		SVY	0614	5793	5921	- 0020	
			SXY	0793	.2000	- 2636	.0102	- 0503
	5-5	CG	SXX	.0049	.9408	.0120	7091	
	55		SYY	0185	7602	- 7201	1.0359	- 7402
			SXY	0787	1570	.2236	0300	0404
	5-6	CG	SXX	0266	.8080	.7509	6579	2423
			SYY	.0030	- 9270	- 8351	1.1101	.0170
			SXY	0588	.1768	. 2220	- 1027	1153
	5-7	CG	SYX	0:247	.7240	. 6415	6210	- 1211
	51		SVV	.0290	- 0853	0415	1.0677	1 0292
			SVV	0434		-1808	1.0037	1.0303
	5-8	CG	SVV		.6034	. 1005	- 14.35	•2309
	5-0	00	SVV	-0331	-1.0055			1.1607
			SYV	0205	-1703	1256	- 1658	2640
	6-1	CG	SXX	.0949	1.1117	1.2168	1030	- 7520
	• •		SVV	0784	2286	- 2628	7806	
			SXY	.0018	.5859	.5782	0225	3860
	6-2	CG	SXX	.0696	1.2814	1.3202	8067	7999
	0 -		SYY	0619	2058	3284	. 7079	2456
			SXY	0217*	-3163	- 3072	.1409	- 2200
	6-3	CG	SYX	.0428	1.2314	1.2485	8470	7135
	0.0		SVY	0410	5705	1.6158	1.0509	-67133
			SYY	0345	.2777	. 3889	.0539	- 1729
	6-4	CG	SYY	.0179	1.0864	1.0089	7711	5624
	0 4		SYY	0220	- 8689	7940	1.2496	.7194
			SXY	0367	. 3249	.4306	0958	1526
	6-5	CG	SXX	.0008	.9232	.9304		- 3886
	0.0		SYY	0083	-1.0014	8440	1.2506	.8240
			SXY	0318	. 3713	.4518	2126	- 1060
	6-6	CG	SXX	0045	.7903	.7807	5795	2238
			SYY	.0072	9966	- 8003	1.1120	.8639
			SYY	0267	- 3696	. 4137	2583	0013
	6-7	CG	SYY	0133	-5644	6235	- 5053	0507
	0-1		SVV	.0112	- 9416	- 7554	.9300	- 0154
			SYV	0160	- 3335	. 3322	- 2527	1501
	6-8	CG	SXX	0115	-5855	· 5046	4697	.0893
	00		SYY	.0129	- 8498	7329	.7342	1.0083
			SXY	0080	.2569	.2023	2068	.3508

MOD	ELEM NO	PT	STR	F1	F3	F4	F7	F8
7	7-1	CG	Sxx	.0415	1.6300	1.6180	-1.1781	-1.0974
			SYY	0310	.0073*	2985	.6724	. 1944
			SXY	0011	•2564	• 3677	• 3098	2422
	7-2	CG	SXX	.0269	1.2159	1.3482	8073	8551
			SYY	0234	9537	9530	1.6270	.7318
			SXY	0088	•5198	•5987	1248	3792
	7-3	CG	SXX	•0147	•9179	1.1515	5678	6612
			SYY	0151	-1.1596	-1.0053	1.6496	.8157
			SXY	0123	.6515	.7172	3657	4261
	7-4	CG	SXX	.0066	•7111	1.0006	4199	4936
			SYY	0074	-1.0759	8529	1.3650	•7445
			SXY	0131	•6683	•7356	4474	3890
	7-5	CG	SXX	.0018	.5726	.8711	3351	3327
			SYY	.0002	9084	6652	1.0344	.6481
			SXY	0122	•6027	•6787	4226	-•2821
	7-6	CG	SXX	0036	•4741	.7317	2855	1525
			SYY	.0023	7515	5223	.7572	• 5943
			SXY	0083	.4939	•5741	3449	1215
	7-7	CG	SXX	0035	•4183	•5807	2673	.0485
			SYY	.0043	6136	4378	.5392	•6056
			SXY	0055	•3591	• 4224	2447	.0986
	7-8	CG	SXX	0040	• 3799	.3926	2611	.2850
			SYY	.0040	4970	4419	.3722	.7256
			SXY	0026	.2216	• 2254	1483	.3851
	8-1	CG	SXX	.0107	•1783	1.0351	.1028	7177
			SYY	0121	-2.2405	-2.0236	3.2921	1.5014
			SXY	.0007	1.2325	.9621	7712	6960
	8-2	CG	SXX	.0070	.1309	1.1107	.0518	7457
			SYY	0067	-1.3368	-1.1513	1.8699	.8761
			SXY	0025	1.0951	•9560	7500	6599
	8-3	CG	SXX	.0043	•1146	1.1702	.0121	7568
			SYY	0029	8127	6531	1.0596	•5228
			SXY	0043	.9097	.8878	6310	5718
	8-4	CG	SXX	.0021	•1141	1.2130	0192	7476
			SYY	0004	5124	3749	.6062	.3318
			SXY	0045	.7140	.7999	4812	4606
	8-5	CG	SXX	0004	•1176	1.2325	0413	7093
			SYY	.0002	3423	2280	• 3560	.2426
			SXY	0035	.5282	.7133	3366	3377
	8-6	CG	SXX	0001	.1273	1.2286	0605	6370
			SYY	.0009	2411	1629	.2147	.2267
			SXY	0027	.3593	•6279	2121	1949
	8-7	CG	SXX	0010	.1298	1.1742	0707	5020
			SYY	.0009	1771	1785	.1319	.3016
			SXY	0015	.2150	•5285	1160	0031
	8-8	CG	SXX	0008	.1281	1.0387	0754	2648
			SYY	.0007	1298	3424	.0792	.5677
			SXY	0006	.0971	.3495	0487	.3299

# TABLE V

### RIB STRESSES

PSI PER POUND

MOD	ELEM	F1	F3	F4	F7	F8
NO	NO					
1	1	-1.0372	7456	-•9077	•0217	•4523
	2	•3012	•8513	1.7507	- 5295	9934
2	1.1	-1.1650	-1.1092	-1.1068	•2199	•5962
	2	0043	•0930	1.3231	-•1659	7220
A <b>3</b>	1	-1.2988	-1.3127	-1.2859	•2720	•7874
	2	-1•2898	-1.5077	-1.5237	•2385	•8137
	3	• 0654	. 2991	1•5449	2850	-1.0381
	4	0853	•0066 <del>*</del>	1•3597	0802	-•7667
4	1	-1.4045	-1.4568	-1.4574	•2806	<b>.</b> 8971
	2	-1.4003	-1.8258	-1.8283	•3772	1.0077
	3	•0057	1361	1.3497	.0174	-•9167
	4	0001	•0123	1.6088	0256	9384
5	1	-1.5724	-1.6827	-1.6813	•320 <b>6</b>	1.0487
	2	-1.5040	-1.8490	-1.8530	•3371	1.1396
	3	-1.4554	-1.9434	-1.9389	• 38 <b>7</b> 8	1.1407
	4	-1.4895	-2.0929	-2.0893	•5027	1.1428
	5	-•0058	2490	1.2596	.1001	-,9048
	6	-•0102	-•0953	1.4414	•0203	-•9970
	· 7	۰0 <sup>0</sup> 87	•0369	1.6425	0426	-1.0722
	8	0028	0351	1.7409	0280	-1.0228
6	1	-1.6603	-1.8449	-1.8449	•3476	1.1505
	. 2	-1.5790	-2.0249	-2.0252	•3808	1.2468
	3	-1.5052	-2.0514	-2.0525	•4080	1.2108
· · ·	4	-1.5542	-2.2146	-2.2164	•5427	1.2114
	5	.0035	4438	1•1981	•2567	8646
	6	.0018	1879	1.04586	0955	-1.0273
· ·	· /	•0005	0520	1.6721	.0215	-1.1210
	8	•0000	0027	1.8431	.0009	-1.1174
	1	-1.8003	-2.0448	-2.0448	• 3854	1.2776
	2	-1.7447	-2.1532	-2.1533	•4052	1.3442
	`د ۱	-1.005/	-2.1581	-2.1580	•4052	1.3405
	4	-1.5937	-2.1304	-2.1307	•4006	1.3074
	5	-1+5437	-2.1102	-2.1106	• 4059	1.2072
		-105262	-2.1253	-2.1262	•4355	1.2375
		-1.5029	-2.2145	-2.2159	•5165	1.0240.7
	8	-1.6406	-2.4347	-2.4360	•6905	1+3411
	10	0028	~•5/95	1.0936	03//3	
	10	.0022		102034	• • <u>•</u> <u>-</u>	-1 0008
	12	-0013	- 1414	1.4071	0601	
	13	-0005		1.60019	02071	-1.1354
	10	+0005		1.00447	• · · · · · · · · · · · · · · · · · · ·	
	14 .	•0000		1.8442		-101/0/
	16	-0000		1.0202		-1.1661
	10		e0000	107673	0020	-161001

# TABLE VI

# STRINGER STRESSES

# PSI PER POUND

MOD	ELEM	F1	F3	F4	F7	F8
NO	NO		<b>、</b>			
	•					
1.	1	-•1271	•7347	•7392	0395	-,3056
	2	•0671	-•1189	•0873	•4108	<b>•</b> 8176
2	1	-•2295	•8753	•8818	-•1590	-•5254
	2	•0057	•9481	•9116	.0461	4900
	3	•1143	-•3989	4093	•5719	1.1012
	4	0028	1433	0669	°5335	•9272
з	1	1542	1.0527	1.0587	1660	6294
	2	• 0411	1.0645	1.0499	0294	6207
	3	•0874	4928	5204	•6082	1.2320
	4	•0029	1669	1359	<u>،</u> 2392	1.0338
4	1	2092	1.1506	1.1510	2179	7153
	2	·0220	1.4017	1.4017	-•2458	8924
	3	•0332	1.2204	1.2228	0527	7999
	4	• 0079	•9383	<b>.</b> 8753	.2412	5814
	5	₀140B	6707	6727	<b>•7662</b>	1.3847
	6	0262	5969	6087	₀5733	1.3441
	7	o060	2871	-•3269	•2647	1.1972
	8	•0004	0514	0016	•05 <b>7</b> 0	1.0506
5	1	1324	1:3386	1.3387	2508	-•8345
	2	•0727	1.5219	1.5217	-,2562	<del>~</del> 。9685
	3	•0508	1.2754	1.2798	~•0593	8485
	4	.0081	e9427	.8921	• 2571	6117
	5	•1152	7878	7885	.8442	1.4991
	6	•0284	-•6106	-•6284	• 5684	1.3792
	7	•0048	2992	3553	•2636	1.2384
	8	0000	0601	0465	₀0604	1.1143

MOD	ELEM NO	F1	F3	F4	F7	F8	
6	1	-•1552	1.3999	1.3999	2639	8741	
	2	•0232	1.6038	1.6038	3033	-1.0059	
· · · ·	3	.0837	1.6233	1.6230	3024	-1.0351	
	4	•0827	1.5436	1.5425	2543	-1.0116	
	5	•0538	1.3929	1.3895	1436	-•9376	
	6	.0262	1.2087	1.1988	•0191	-•8282	
	7	.0102	1.0029	<b>₀9777</b>	•2293	-•6882	
	8	.0033	•8336	•7348	•4320	5251	
	9	• 1604	8259	-•8272	<b>9228</b>	1.5593	
	10	•0773	8204	8234	.8113	1.5304	
	11	•0423	7216	-•7286	•6665	1.4621	
	12	0199	-•5883	-+6045	•5115	1.3884	
	13	•0082	4126	-•4483	<b>•3</b> 353	1.3041	
	14	•0029	2222	-•2838	•1643	1.2271	
,	15	.0007	0754	1436	.0490	1.1849	
	16	• <b>0</b> 000	0082	.0132	.0052	1.1409	
7	1	0916	1.5463	1.5463	2914	-•9662	
	2	•0661	1.7040	1.7040	3207	-1.0694	
	3	•1027	1.6686	1.6684	3059	-1.0632	
	· 4	•0919	1.5646	1.5636	2523	-1.0240	
	5	• 0586	1.4069	1.4039	1439	-•9487	
	6	•0271	1.2187	1.2087	.0171	8395	
	7	•0093	1.0060	•9808	•2330	-•6957	
	8	•0026	•81 <u>59</u>	•7234	•4586	5215	
	9	•1362	9235	-•9244	•9981	1.6504	
	10	•0804	8388	8413	•8278	1.5561	
	11 _	•0436	7312	<b>~•</b> 7378	•6704	1.4759	
	12	•0192	-•5936	6111	<b>∗</b> 5094 -	1.3981	
	13	.0074	4150	4543	• 332 <b>7</b>	1.3133	
	14	.0023	2270	-,2936	.1672	1.2400	
	15	0005	-•0808	1585	•0536	1.2046	
	16	•0000	0108	0121	·0069	1.1755	
	•						

### APPENDIX B

### DEVELOPMENT OF THE MATRIX FORCE PROGRAM

The matrix force analysis used here is based on the formulation of Pestel and Leckie (Reference 10, Chapter 9). Therefore, the basic equations of the method will not be developed here but will be taken directly from Reference 10. The basic equations are

$$[D_{11}] = [B_1]^T [F_v] [B_1]$$
(B-1)

$$[D_{10}] = [B_1]^T [F_v] [B_0]$$
(B-2)

$$[X] = -[D_{11}]^{-1}[D_{10}]$$
(B-3)

$$[B] = [B_0] + [B_1] [X]$$
(B-4)

$$\{p\} = [B] \{f\}$$
 (B-5)

$$[\mathbf{F}_{d}] = [\mathbf{B}]^{T} [\mathbf{F}_{v}] [\mathbf{B}]$$
(B-6)

$$[d] = [F_{d}] \{f\}$$
 (B-7)

### where

 $[B_1]$  = the matrix of internal forces due to unit values of the redundants  $(1 \times n)$ ,

[F<sub>v</sub>] = the flexibility matrix of the unassembled structure. This matrix is a diagonally partioned matrix with the flexibilities of the individual structural elements as its diagonal subelements (l x l), [D<sub>11</sub>] = the matrix defined by Equation B-1

$$[D_{10}] =$$
 the matrix defined by Equation B-2  
( $n \ge m$ ),

(n x n),

[X] = the matrix of unit redundants. Each column of this matrix gives the values of the redundants due to a unit value of one of the external forces (n x m),

 $\{p\}$  = the column matrix of internal forces ( $\ell \times 1$ ),

[F<sub>d</sub>] = the flexibility matrix of the assembled structure. The elements of this matrix are the deflection influence coefficients of the structure (m x m),

{d} = the column matrix of displacements
 (m x l),

k = the number of elements in the structure
(the number of submatrices in the unassembled structure flexibility matrix is

equal to k),

 $\ell$  = the number of independent internal forces  $(\ell \leq k)$ ,

m = the number of external forces, and n = the number of redundants

The development of a program to solve Equations B-1 through B-7 is relatively straight forward; however, for large structures; all of the matrices in these equations cannot be simultaneously stored in the main memory of even the largest computer available today. The simplest method of handling this problem is to store all of the large matrices on magnetic tape and to read them into main memory, usually a row or a column at a time, as they are needed. The method used here does this, in part; but two other techniques are used to minimize the number of matrices that must be stored on tape, i.e.,

1. the "Recurrence Method for Highly Redundant Systems" of Pestel and Leckie (Reference 10, Section 9-6) is used to reduce the size of the matrix [D<sub>11</sub>] which must be inverted, and 2. the large matrix [F<sub>V</sub>] is stored as an l x 5 array instead of an l x l array.

sectors where The Recurrence Method

Pestel and Leckie have shown that a highly redundant system can be analyzed by subdividing the redundants and considering each subset of redundants separately. To illustrate, let us assume that the n redundants are subdivided into three sets - a, b, and c - with  $\alpha$ ,  $\beta$ , and  $\gamma$  redundants, respectively, such that

$$\alpha + \beta + \gamma = n \quad . \tag{B-8}$$

We can now proceed as though there were only  $\alpha$  redundants and that there are  $\beta + \gamma + m$  external forces and calculate the first  $\alpha$  redundants in terms of these 'assumed' external forces. The first  $\alpha$  redundants are then eliminated from further consideration. We next consider the b-set with  $\beta$ redundants and calculate these redundants as a linear combination of the  $\gamma + m$  'assumed' external forces. Finally, the c-set of redundants are considered. Since this is the last set, the 'assumed' external forces are the 'actual' external forces and all of the redundants have been eliminated.

The primary advantage of the recurrence method lies in the fact that several smaller matrices,  $[D_{11}^{i}]$ , are inverted instead of one, usually large,  $n \ge n$  matrix. However, in attempting to write a program using this method, two difficulties were encountered, i.e.,

- extensive programming would be required to accommodate unequal size subsets of redundants, and
- the storage required could become greater than that required by the direct method if the number and size of the subsets was not chosen properly.

It was discovered that not only is the programming greatly simplified, but the storage requirements are minimized if

the redundants are subdivided into n sets with one redundant in each set. It is also advantageous to store and manipulate  $[B_1]$  and  $[B_0]$  as a single matrix  $[B_{10}]$  and  $[D_{11}]$  and  $[D_{10}]$ as a single matrix, also called  $[D_{10}]$ . The recursion equations can then be written as

$$\begin{bmatrix} D_{10}^{i} \end{bmatrix} = \{B_{1}^{i}\}^{T} [F_{v}] [B_{10}^{i}]$$
  

$$\begin{bmatrix} X^{i} \end{bmatrix} = -\begin{bmatrix} D_{10}^{i} \end{bmatrix} / D_{11}^{i} \qquad (i = 1, n) \qquad (B-9)$$
  

$$\begin{bmatrix} B_{10}^{i+1} \end{bmatrix} = \begin{bmatrix} B_{0}^{i} \end{bmatrix} + \{B_{1}^{i}\} [X_{i}]$$

where  $\{B_{1}^{i}\}$  is the first column of  $[B_{10}^{i}]$  and  $D_{11}^{i}$  is the first element of  $[D_{10}^{i}]$ . Each recursion reduces the number of columns in  $[B_{10}^{i}]$ , until after the nth recursion,  $[B_{10}^{n+1}]$  is an  $\ell$  x m matrix and is the unit internal force matirx [B]. Equations B-5 through B-7 can then be used to determine the internal forces and the displacements.

Equations B-9 show clearly that both storage and programming are minimized since  $[D_{10}^{i}]$ ,  $[X^{i}]$ , and the matrix product  $\{B_{1}^{i}\}^{T}[F_{v}]$  are all row matrices. Also, since  $D_{11}^{i}$  is a scalar, all requirements for matrix inversion are eliminated.

# Storage of the Matrix $[F_v]$

Since the flexibility matrix for the unassembled structure can be very large, it is uneconomical to store it, either in main storage or on tape, as an  $\ell \propto \ell$  array. After it was decided to program the recurrence method for *n*  recurrsions with a single redundant per recurrion, it was also noticed that it would be relatively simple to obtain the product  $\{B_1^i\}^T[F_v]$  if  $[F_v]$  were stored as an  $\ell \ge 5$  array. The necessity for five columns is dictated by the fact that the largest element stiffness matrix is the 5  $\ge 5$  array required by a plate element.

In order to be able to obtain the product  $\{B_1^i\}^T [F_v]$  for any combination and arrangement of elements in the structure, each element stiffness matrix must be right-justified in the array. For an axially loaded element, the flexibility must be entered as one row consisting of four zeros followed by the element flexibility. A beam element would require two rows each with three zeros followed by two flexibility coefficients. A rectangular or trapezoidal plate requires five rows for the twenty-five coefficients. It should be noted that the routine used to form this product in the program which follows has been simplified since the structure under study here has only two types of elements, axially loaded elements and plate elements. A general routine can be found in Reference 8.

### The Matrix Force Program

A program listing is given in Table VII. The program is written in Fortran IV using the format specified for the IBM 7044/7094 Operating System. It is written as a main program with three subroutines which are used to generate the matrices  $[F_v]$ ,  $[B_1]$ , and  $[B_0]$ . Since each subroutine is called only once, the subroutines could have been incorporated into the main program; however, this would have exceeded the maximum number (200) of statements allowed in this operating system.

The input to the program is identical to that required by the displacement program (Appendix A). The constant and nodal coordinate routines are essentially the same as in the displacement program except for some rearrangement and the addition of several constants.

The element stiffener flexibilities are generated directly, i.e.,

$$F_{g} = L_{g} / A_{g} E_{g}$$
(B-10)

and entered into the  $[F_v]$  array. The web flexibilities are obtained by first generating the stiffness matrix for the element using the routine described in Chapter II and Appendix A: This matrix is then reduced from a 8 x 8 singular matrix to a 5 x 5 nonsingular matrix by striking out rows and columns 2, 5, and 6. This corresponds to the restraints shown in Figure 26. This matrix is then inverted and placed in  $[F_v]$ .

The  $B_1$  and  $B_0$  subroutines are used to generate the elements of  $[B_{10}]$  and to write these elements on a magnetic tape. Each column of  $[B_{10}]$  consists of the internal forces due to a unit value of either a redundant or an external force. The methods of calculating these internal forces are given in Chapter II.



Figure 26. Plate Element Constraints

Subsequent to the generation of  $[\mathbf{F}_v]$  (in core) and  $[\mathbf{B}_{10}]$ (on magnetic tape), the recurrence method, as described previously, is used to calculate the unit internal force matrix [B]. Since only one column of  $[\mathbf{B}_{10}]$  is in core at any one time, it is necessary to read the entire array twice during each recurrsion, once to calculate  $[\mathbf{D}_{10}^i]$  and again to 10calculate  $[\mathbf{B}_{10}^{i+1}]$ . It is also necessary to use two tapes in order to generate  $[\mathbf{B}_{10}^{i+1}]$  since each new  $[\mathbf{B}_{10}^{i}]$  has one less column (or tape record) than the previous one.

The flexibility matrix, the deflections due to unit external forces, is calculated using Equation B-6. It should be noted that Pestel and Leckie (Reference 10, page 255) do not present the equation for the flexibility matrix in this form. They present the equation

$$[F_{d}] = [B_{0}]^{T}[F_{v}][B]$$
 (B-11)

It can be shown that Equations B-6 and B-11 give exactly the same results. The reason that Equation B-6 must be used here is that  $[B_0]$  is destroyed in the recurrence analysis. The flexibilities are tabulated in Table VIII.

The web stresses are calculated at the same points as in the displacement analysis, i.e., for Models 1 through 4, the stresses are calculated at five points within each plate element; but for Models 5 through 7, only the stresses at the centroid are obtained. The equation for calculating the stress, however, is a modification of the stress equation used in the displacement analysis. This modification is necessary because the displacement analysis is formulated in terms of the absolute displacements of the element nodes, while the force analysis uses relative displacements, or deformations, in its formulation (See Figure 26). The modification consists of striking out columns 2, 5, and 6 in the  $[\Sigma]$  matrix of Equation A-2 and replacing the displacement matrix  $\{u\}$  with the deformation matrix  $\{v\}$  giving

$$\{S\} = [\Sigma^{\perp}] \{v\}$$
 (B-12)

The web stresses are given in Table IX. The format is identical to that used in Appendix A for the displacement method web stresses.

The stiffener stresses can also be readily determined. Since the deformation is the relative displacement of the ends, measured along the length of the member, the stress is given by this equation,

$$s = (E/L)v, \qquad (B-13)$$

where both the stress s and the deformation v are scalars. The rib stresses are given in Table X and the stringer stresses are given in Table XI.

### Explanation of Tables

Tables VII through XI are identical in format to Tables II through VI in Appendix A in order that the results of the force and displacement analyses can be compared.

#### TABLE VII

#### MATRIX FORCE PROGRAM LISTING

ISOTHERMAL MATRIX FORCE ANALYSIS OF A TRAPEZOIDAL PANEL

TYPE DECLARATION STATEMENTS

DOUBLE PRECISION B10(352) +FV(352+5)+B1TFV(352) DOUBLE PRECISION D10(198)+FVB(352+5)+FD(5+5) DOUBLE PRECISION XI(5)+ETA(5)+SIGMA(3+5)+STRES(3+5) DOUBLE PRECISION B(352+5)

DIMENSION AND COMMON STATEMENTS

COMMON /PARAM/E.V.T.STA.RA.EP.EPT.GS COMMON /PACON/M.N.M1.N1.M2.N2.AM.AN.AM2 COMMON /REDUN/KI.LI.MI.NI.NOA.NOB.NOC COMMON /DELTA/DELXR.DELXT.DELY.DELLE.DELTE COMMON /ARRAY/X(9.9).Y(9).B10.FV

#### FORMAT STATEMENTS

- 300 FORMAT(215)
- 301 FORMAT(6E12.6)
- 351 FORMAT(29X 11H PARAMETERS/)

352 FORMAT(8X+16H YOUNG\*S MODULUS+E10.3+ 13X+16H POISSON\*S RATIO+F6.3/)

- 353 FORMAT(3X+14H WEB THICKNESS+6+3+2X+14H STRINGER AREA+ 1F8+5+2X+9H RIB AREA+F8+5/)
- 354 FORMAT(5X+3H XA+F8+3+5X+3H XB+F8+3+5X+3H XC+F8+3+ 15X+3H XD+F8+3/)
- 355 FORMAT(5X+3H YA+F8+3+21X+3H YC+F8+3/)
- 356 FORMAT(5X+14H ROWS OF NODES+13+15X+
  - 117H COLUMNS OF NODES . 13//)
- 357 FORMAT(25X.19H FLEXIBILITY MATRIX/)
- 358 FORMAT(5E14.6)
- 359 FORMAT(28x,13H WEB STRESSES/)
- 360 FORMAT(25X, 19H STIFFENER STRESSES/)

NUMBER OF PANEL CONFIGURATIONS READ(5:300)NOPAC

PANEL PARAMETERS

1 READ(5.301)E.V.T.STA.RA READ(5.301)X1.X2.X3.X4.Y1.Y3

2 READ(5.300)M.N WRITE(7.351) WRITE(7.352)E.V WRITE(7.353) T.STA.RA WRITE(7.354)X1.X2.X3.X4 WRITE(7.355)Y1.Y3 WRITE(7.356)M.N

```
CONSTANTS
```

```
EP=E/(1.-(V**2))
EPT=EP*T
GS=E/(2 • * (1 • + V))
AM = M - 1
AN=N-1
M1 = M - 1
N1 = N - 1
MN=M*N
AM2=M-2
M2=M-2
N2=N-2
DELXR=(X2-X1)/AN
DELXT=(X4-X3)/AN
DELY=(Y3-Y1)/AM
DELLE=SQRT((X3-X1)**2+(Y3-Y1)**2)/AM
DELTE=SQRT((X4-X2)**2+(Y3-Y1)**2)/AM
KI = MN + M + N - 3
LI=5*MN-3*M-3*N+1
MI = 5
NI=3*MN-3*M-3*N+4
NOA = 2*(M1+N1)
NOB=M2*N1+N2*M1
NOC=M2*N2
```

NODAL COORDINATES

```
X(1.1)=X1
X(1.0)=X2
X(M.1)=X3
X(M.0)=X4
Y(1)=Y1
Y(M)=Y3
D0 3 I=2.01
```

```
3 Y(I)=Y(I-1)+DELY
DO 4 J=2.N1
X(1.J)=X(1.J-1)+DELXR
4 X(M.J)=X(M.J-1)+DELXT
```

```
D0 5 I=2.M1
D0 5 J=1.N
```

5 X(I,J)=X(1,J)+((X(M,J)-X(1,J))/(Y(M)-Y(1))\*(Y(I)-Y(1)))

GENERATE THE ELEMENT FLEXIBILITY MATRIX FV CALL FLEX

GENERATE THE UNIT REDUNDANT MATRIX BI CALL BI

GENERATE THE UNIT EXTERNAL FORCE MATRIX BO CALL BO

```
RECURSION ANALYSIS
  MINI=MI+NI
  DO 16 IR=1.NI
  REWIND 1
  READ B10(IR)
  READ(1)B10
  B1 TRANSPOSE TIMES FV.
  DO 6 I=1+LI
 6 B1TFV(I)=0.0
   DO 7 I=1.NOA
 7 B1TEV(I)=B10(I)*EV(I+5)
  K=KI-NOA
   J=NOA+1
   J4=J+4
   DO 9 I=1•K
   DO 8 1A=1.5
   IAJ=IA+J-1
   DO 8 JA=J+J4
8 B1TFV(IAJ)=B1TFV(IAJ)+B10(JA)*FV(JA+IA)
   J=J+5
 9 J4=J+4
   CALCULATION OF DIO(FIRST ELEMENT IS DII)
   DO 10 I=1.MINI
10 D10(1)=0.0
  DO 11 I=1+LI
11 D10(1)=D10(1)+B1TFV(I)*B10(I)
   DO 12 J=2.MINI
   READ(1)B10
   DO 12 I=1.LI
12 D10(J)=D10(J)+B1TFV(I)*B10(I)
  REWIND 1
   REWIND 8
   CALCULATION OF REDUNDANTS (STORED IN D10)
   DO 13 I=2.MINI
13 D10(I) = -D10(I)/D10(1)
   CALCULATION OF NEW B10
   READ(1)B1TFV
   DO 15 J=2.MINI
   READ(1)B10
   DO 14 I=1.LI
14 B10(I)=B10(I)+B1TFV(I)*D10(J)
15 WRITE(8)B10
  REWIND 8
  REWIND 1
```

```
DO 85 KK=2.MINI
   READ (8) B10
85 WRITE (1) B10
   MINI=MINI-1
16 CONTINUE
   REWIND 1
   DEFORMATIONS
   DO 17 I=1.LI
   DO 17 J=1+MI
17 FVB(I+J)=0.0
   DO 21 IR=1.MI
   READ(1)B10
   DO 18 I=1.LI
18 B(I \cdot IR) = B10(I)
   DO 19 I=1.NOA
19 FVB(I.IR)=FV(I.5)*B10(I)
   K=KI-NOA
   I=NOA+1
   14 = 1 + 4
   D0 21 J=1+K
   DO 20 IA=I.I4
   DO 20 JA=1.5
   JAI = JA + I + I
20 FVB(IA.IR)=FVB(IA.IR)+FV(IA.JA)*B10(JAI)
   1=1+5
21 I4=I+4
   DISPLACEMENTS
   DO 22 I=1.MI
   DO 22 J=1.MI
22 FD(I \cdot J) = 0 \cdot 0
   DO 23 I=1.MI
   DO 23 J=1+MI
   DO 23 K=1.LI
23 FD(I+J)=FD(I+J)+B(K+I)*FVB(K+J)
   WRITE(7+357)
   WRITE(7+358)(FD(I+1)+FD(I+2)+FD(I+3)+FD(I+4)+
  1FD(I+5)+I=1+5)
   WEB STRESSES
   WRITE(7+359)
   JJ=NOA
   DO 36 IA=1.M1
   DO 36 JA=1.N1
   COORDINATES OF NODES
   XA=X(IA,JA)
  XB=X(IA+JA+1)
```

```
XC=X(IA+1+JA)
   XD=X(IA+1)JA+1
   YA=Y(IA).
   YC=Y(IA+1)
   D=(XD-XA)/(XB-XA)
   P=(XC-XA)/(XB-XA)
   TR=1 \cdot / (D-P)
   BX=D-1.
   XBA=XB-XA
   YCA=YC-YA
   IF (MN-15)24.24.25
   COORDINATES OF STRESS POINTS (MN=15, OR LESS).
24 NO=5
   XI(1)=0.25*(P+0.75+0.25/TR)
   XI(2)=0.25*(P+2.25+0.75/TR)
   X1(3)=0.50*(P+0.5+0.5/TR)
   XI(4)=0.25*(3.*P+0.25+0.75/TR)
   X1(5)=0.75*(P+0.25+0.75/TR)
   ETA(1)=0.25
   ETA(2) = 0.25
   ETA(3)=0.5
   ETA(4)=0.75
   ETA(5)=0.75
   GO TO 26
   COORDINATES OF STRESS POINTS(MN GREATER THAN 15)
25 NO=1
   ETA(1) = (TR+2)/(3 + (TR+1))
   XI(1)=0.5*(1.+(P+BX)*ETA(1))
   SIGMA MATRIX
26 DO 35 I=1.NO
   SIGMA(1+1) = -(1 - ETA(1)) / XBA
   SIGMA(1,2) = -TR \times ETA(1) / XBA
   SIGMA(1,3) = -SIGMA(1,2)
   SIGMA(1+4)=TR*V*(D-XI(I))/YCA
   SIGMA(1+5) = TR*V*(P-XI(I))/YCA
   DO 27 J=1.3
27 SIGMA(2+J)=V*SIGMA(1+J)
   DO 28 J=4.5
28 \text{ SIGMA}(2 \cdot J) = \text{SIGMA}(1 \cdot J) / V
   SIGMA(3 \cdot 1) = -(1 \cdot - XI(1))/YCA
   DO 29 J=2.3
29 SIGMA(3,J)=SIGMA(2,J+2)
   DO 30 J=4.5
30 SIGMA(3+J)=SIGMA(1+J-2)
   DO 31 J=1+2
   DO 31 K=1+5
31 SIGMA(J+K)=EP*SIGMA(J+K)
   DO 32 J=1.5
```

32 SIGMA(3) = GS\*SIGMA(3)

STRESSES D0 33 J=1.3 D0 33 K=1.5 33 STRES(J.K)=0.0 D0 34 J=1.3 D0 34 K=1.5 D0 34 L=1.5

LL=L+JJ

34 STRES(J+K)=STRES(J+K)+SIGMA(J+L)\*FVB(LL+K)

```
35 WRITE(7+358)(STRES(J+1)+STRES(J+2)+STRES(J+3)+
1STRES(J+4)+STRES(J+5)+J=1+3)
JJ=JJ+5
```

```
36 CONTINUE
```

STIFFENER STRESSES

D0 37 I=1+N1 J=I+N1 D0 37 K=1+5 FVB(I+K)=FVB(I+K)\*E/DELXR 37 FVB(J+K)=FVB(J+K)\*E/DELXT

DO 38 I=1.0M1 J=I+2\*N1 K=I+2\*N1+M1 DO 38 L=1.5 FVB(J.L)=FVB(J.L)\*E/DELLE

```
38 FVB(K+L)=FVB(K+L)*E/DELTE
wRITE(7+360)
wRITE(7+358)(FVB(I+1)+FVB(I+2)+FVB(I+3)+FVB(I+4)+
1FVB(I+5)+I=1+NOA)
```

NOPAC=NOPAC-1 IF(NOPAC)39+39+2 39 STOP

END

SUBROUTINE FLEX

ISOTHERMAL MATRIX FORCE ANALYSIS OF A TRAPEZOIDAL PANEL SUBROUTINE TO GENERATE THE ELEMENT FLEXIBILITY MATRIX

TYPE DECLARATION STATEMENTS

DOUBLE PRECISION B10(352) + FV(352+5)

DIMENSION AND COMMON STATEMENTS

COMMON /PARAM/E.V.T.STA.RA.EP.EPT.GS COMMON /PACON/M.N.M1.N1.M2.N2.AM.AN.AM2 COMMON /REDUN/KI.LI.MI.NI.NOA.NOB.NOC

```
COMMON /DELTA/DELXR+DELXT+DELY+DELLE+DELTE
  COMMON /ARRAY/X(9,9),Y(9),B10,FV
  DIMENSION A(21.6) . C(6) . Z(21) . F(4.4) . G(4.4) . H(8.8)
  STIFFENER FLEXIBILITIES
1 DO 2 1=1.NOA
  DO 2 J=1.5
2 FV(1.J)=0.0
  RIBS
  RFL=DELXR/(RA*E)
  RFU=DELXT/(RA*E)
  DO 3 I=1.N1
  J=N1+I
  FV(1,5)=RFL
3 FV(J.5)=RFU
  STRINGERS
  STFLE=DELLE/(STA*E)
  STFTE=DELTE/(STA*E)
  K=2*N1+1
  L=2*N1+M1
  DO 4 1=K+L
  J=M1+I
  FV(1.5)=STFLE
4 FV(J+5)=STFTE
  WEB FLEXIBILITIES
  KA=NOA
  DO 26 IA=1.M1
  DO 26 JA=1.N1
  XA=X(IA \cdot JA)
  XB=X(IA \cdot JA+1)
  XC=X(IA+I,JA)
  XD=X(IA+1 \cdot JA+1)
  YA=Y(IA)
  YC=Y(IA+1)
  AR = (YC - YA) / (XB - XA)
  D=(XD-XA)/(XB-XA)
  P = (XC - XA) / (XB - XA)
  TR=1./(D-P)
  B=D-1.
  DO 5 1=1.21
  DO 5 J=1+6
5 A(I_{,J})=0.0
  A(1 \circ 1) = AR
  A(1+2)=2+*AR
  A(1,3) = AR
  A(2\cdot 2) = -TR * AR
  A(2,3) = A(2,2)
```

A(3.3)=TR\*\*2\*AR A(4,1) = VA(4,2) = VA(4,4) = VA(4,5)=V A(5,4)=-V A(5,5) = -VA(6.1)=-D\*TR\*V A(6.2) = A(6.1)A(6,4) = -TR + VA(6,5) = A(6,4) $A(7 \bullet 1) = P * T R * V$ A(7+2)=A(7+1)A(7,4) = -A(6,4)A(7,5) = -A(6,4)A(8,2) = A(6,4)A(8,5) = A(6,4)A(9,5) = -A(6,4)A(10+2)=D\*TR\*\*2\*V A(10:5)=TR\*\*2\*V A(11+2) = -P\*TR\*\*2\*VA(11,5) = -A(10,5)A(12,1)=1.7A(12.4)=2./AR A(12.6) = A(12.1)A(13\*4) = -A(12\*1)A(13,6) = -A(12,1) $A(14,1) = -D \times TR/AR$ A(14+4) = -(1+D) \* TR / AR $A(14 \cdot 6) = -TR/AR$ A(15.1)=P\*TR/AR A(15+4)=(1+P)\*TR/AR $A(15_{6})=TR/AR$ A(16.6) = A(12.1)A(17,4) = -A(14,1)A(17,6) = TR/ARA(18,4) = -A(15,1)A(18+6) = -TR/ARA(19.1)=(D\*TR)\*\*2/AR A(19,4)=2.\*D\*TR\*\*2/AR A(19+6)=TR\*\*2/AR A(20+1) =- D\*P\*TR\*\*2/AR A(20+4) = -(D+P) \* TR \* \* 2/ARA(20.6) = -A(19.6) $A(21 \cdot 1) = (P * TR) * * 2/AR$ A(21.4)=2.\*P\*TR\*\*2/AR A(21.6) = A(19.6)C(1) = 1 + 0 + 5 + (B - P)C(2) = -0.5 - (B - P)/3. $C(3) = (1 \circ / 3 \circ) + ((B-P) / 4 \circ)$ C(4) = -0.5 - B/2 - (B + 2 - P + 2)/6C(5)=0.25+B/3.+(B\*\*2-P\*\*2)/8.

```
C(6)=1./3.+B/2.+B**2/3.+(B**3-P**3)/12.
   DO 6 I=1+21
6 Z(1)=0.0
   DO 7 I=1.21
   DO 7 J=1.6
7 Z(1)=Z(1)+A(1+J)*C(J)
   F(1 + 1) = Z(1)
   F(1+2) = -Z(1)
   F(1,3)=Z(2)
   F(1,4) = -Z(2)
   F(2,2)=Z(1)
   F(2,3) = -Z(2)
   F(2,4)=Z(2)
   F(3,3)=Z(3)
   F(3,4) = -Z(3)
   F(4,4)=Z(3)
   G(1,1)=Z(12)
   G(1,2)=Z(13)
   G(1 \cdot 3) = Z(14)
   G(1,4)=Z(15)
   G(2,2)=Z(16)
   G(2,3)=Z(17)
   G(2,4)=Z(18)
   G(3,3)=Z(19)
   G(3,4)=Z(20)
   G(4+4)=Z(21)
   DO 8 I=1.4
   DO 8 J=1.4
B H(1.J)=EPT*(F(1.J)+(1.-V)*G(1.J)/2.)
   DO 9 I=1+4
   DO 9 J=1.4
9 H(I+4+J+4)=EPT*(G(I+J)+(1+-V)*F(I+J)/2+)
   F(1,1)=Z(4)
   F(1,2)=Z(5)
  F(1,3)=Z(6)
   F(1,4)=Z(7)
   F(2,1) = -Z(4)
   F(2,2) = -Z(5)
   F(2,3) = -Z(6)
   F(2,4) = -Z(7)
   F(3,1)=Z(8)
   F(3,2)=Z(9)
   F(3,3)=Z(10)
   F(3,4)=Z(11)
   F(4+1) = -Z(8)
   F(4,2) = -Z(9)
   F(4,3) = -Z(10)
   F(4 \cdot 4) = -Z(11)
   DO 10 I=1+4
   DO 10 J=1.4
10 G(I,J) = F(J,I)
```

```
DO 11 I=1+4
   DO 11 J=1+4
11 H(I.J+4)=EPT*(F(I.J)+(1.-V)*G(I.J)/(2.*V))
   DO 12 I=1+8
   DO 12 J=I+B
12 H(J_{0}I) = H(I_{0}J)
   MAKING THE WEB STIFFNESS MATRIX NONSINGULAR
   DO 13 I=1.8
   DO 13 J=3.8
13 H(I + J - 1) = H(I + J)
   DO 14 I=1.8
   DO 14 J=6+7
14 H(I \cdot J - 2) = H(I \cdot J)
   DO 15 1=3.8
   DO 15 J=1+5
15 H(I-1,J)=H(I,J)
   DO 16 I=6,7
   DO 16 J=1+5
16 H(I-2,J)=H(I,J)
   INVERTING THE WEB STIFFNESS MATRIX
   H(1,6)=1,0
   DO 17 I=1.5
17 H(1+1.6)=0.0
   DO 24 K=1.5
   DO 18 J=1+5
18 H(6,J)=H(1,J+1)/H(1,1)
   DO 23 1=2.5
   IF(5-K-1+2)19.19,20
19 CONST=H(I+1)
   GO TO 21
20 CONST = -H(1,1)
21 JCOL=I-1
   DO 22 J=JCOL.5
22 H(I-1,J)=H(I,J+1)+CONST*H(6,J)
   DO 23 J=1.JCOL
23 H(I + J) = H(J + I)
24 H(5,5)=H(6,5)
   TRANSMITTING THE WEB FLEXIBILITY TO FV
   DO 25 I=1.5
   KA=KA+1
   DO 25 J=1.5
25 FV(KA+J)=H(1+J)
26 CONTINUE
   RETURN
   END
```

SUBROUTINE B1

ISOTHERMAL MATRIX FORCE ANALYSIS OF A TRAPEZOIDAL PANEL SUBROUTINE TO GENERATE THE UNIT REDUNDANT MATRIX

TYPE DECLARATION STATEMENTS

DOUBLE PRECISION B10(352) + FV(352+5)

DIMENSION AND COMMON STATEMENTS

```
COMMON /PACON/M.N.MI.NI.M2.N2.AM.AN.AM2
COMMON /REDUN/KI.LI.MI.NI.NOA.NOB.NOC
COMMON /DELTA/DELXR.DELXT.DELY.DELLE.DELTE
COMMON /ARRAY/X(9.9).Y(9).B10.FV
```

REWIND 1

#### TYPE A REDUNDANTS

```
LOWER RIB

1 DO 3 I=1.N1

DO 2 IJ=1.LI

2 B10(IJ)=0.0

K=I

B10(K)=1.0

K=NOA+5*(I-1)+1

B10(K)=1.0

3 WRITE(1)B10
```

```
UPPER RIB
DO 5 I=1.N1
DO 4 IJ=1.LI
```

```
4 B10(IJ)=0.0

K=N1+I

B10(K)=1.0

K=N0A+5*(N1*M2)+5*(I-1)+2

B10(K)=1.0

B10(K+1)=-1.0
```

```
5 WRITE(1)B10
```

```
LEADING EDGE STRINGER

ALPHA=ATAN((Y(M)-Y(1))/(X(M.1)-X(1.1)))

DO 7 I=1.M1

DO 6 IJ=1.LI

6 B10(IJ)=0.0

K=2*N1+I

B10(K)=1.0
```

```
K=NOA+5*N1*(I-1)+1
B10(K)=COS(ALPHA)
B10(K+1)=-B10(K)
```

```
B10(K+3)=-SIN(ALPHA)
7 WRITE(1)B10
```

```
TRAILING EDGE STRINGER
BETA=ATAN((Y(M)-Y(1))/(X(M•N)-X(1•N)))
DO 9 I=1•M1
DO 8 IJ=1•LI
8 B10(IJ)=0•0
K=2*N1+M1+I
B10(K)=1•0
K=NOA+5*N1*I-2
```

```
B10(K)=-COS(BETA)
B10(K+2)=-SIN(BETA)
```

```
9. WRITE(1)B10
```

```
TYPE B REDUNDANTS
```

```
IF (NOB) 22+22+10
```

HORIZONTAL

```
10 IF(M2)14.14.11
```

```
11 J=N1*M2
DO 13 I=1+J
DO 12 IJ=1+LI
```

```
12 B10(IJ)=0.0

K=NOA+5*(I-1)+2

B10(K)=-1.0

B10(K+1)=1.0

K=NOA+5*N1+5*(I-1)+1

B10(K)=1.0
```

```
13 WRITE(1)B10
```

DIAGONAL

```
14 IF(N2)18.18.15
```

```
15 DO 17 I=1•N2
DO 17 J=1•M1
GAMMA=ATAN((Y(M)-Y(1))/(X(M•I+1)-X(1•I+1)))
DO 16 IJ=1•LI
```

```
16 B10(IJ)=0.0

K=NOA+5*(I-1)+5*N1*(J-1)+3

B10(K)=COS(GAMMA)

B10(K+2)=SIN(GAMMA)

B10(K+3)=B10(K)

B10(K+4)=-B10(K)
```

```
B10(K+6)=-810(K+2)
```

```
17 WRITE(1)810
```
```
TYPE C REDUNDANTS
```

```
18 IF(NOC)22+22+19
```

- 19 D0 21 I=1.N2 D0 21 J=1.M2 D0L=(X(J+1.2)-X(J+1.1))/DELY D0 20 IJ=1.LI
- 20 B10(IJ)=0.0 K=NOA+5\*(I-1)+5\*N1\*(J-1)+3 B10(K)=-DOL B10(K+1)=1.0 B10(K+2)=-1.0 B10(K+3)=-DOL B10(K+4)=DOL B10(K+6)=-1.0 B10(K+7)=1.0 K=NOA+5\*(I-1)+5\*N1\*J+3 B10(K)=DOL B10(K+3)=DOL B10(K+4)=-DOL
- 21 WRITE(1)B10
- 22 RETURN END

SUBROUTINE BO

ISOTHERMAL MATRIX FORCE ANALYSIS OF A TRAPEZOIDAL PANEL SUBROUTINE TO GENERATE THE UNIT EXTERNAL FORCE MATRIX

TYPE DECLARATION STATEMENTS DOUBLE PRECISION B10(352)+FV(352+5)

DIMENSION AND COMMON STATEMENTS

COMMON /PACON/M+N+M1+N1+M2+N2+AM+AN+AM2 COMMON /REDUN/KI+LI+MI+NI+NOA+NOB+NOC COMMON /DELTA/DELXR+DELXT+DELY+DELLE+DELTE COMMON /ARRAY/X(9+9)+Y(9)+B10+FV

F1=1

- 1 DO 2 1J=1.LI
- 2 B10(IJ)=0.0 D0 3 K=1.N1
- 3 B10(K)=-1.0 WRITE(1)B10

```
F3=1
   NUMB=0
   CONST=1.0
   DO 4 IJ=1+LI
 4 B10(IJ)=0.0
 5 IF(M+N-5)12,11,6
 6 IF (M+N-6)9.9.7
   LEADING EDGE COLUMN OF WEB ELEMENTS
 7 DO 8 1=2.M2
   K = NOA + 5 \times N1 \times (I - 1) + 3
   B10(K)=1.0*CONST
   AMI = M1 - I
   B10(K+1)=((AMI*DELY)/(X(I+1+2)-X(I+1+1)))*CONST
 8 B10(K+2)=-B10(K+1)
   LOWER ROW OF WEB ELEMENTS
 9 DO 10 J=2.N1
   K=NOA+5*(J-1)+1
   ANJ=N-J
   B10(K)=(1.0-(ANJ*AM/AN))*CONST
   B10(K+1)=(ANJ*AM/AN)*CONST
   ANJ1 = ANJ - 1.0
10 B10(K+2)=-(ANJ1*AM/AN)*CONST
   WEB ELEMENT 1.1
11 K=NOA+3
   B10(K) = -(AM2 - (AM/AN)) + CONST
   B10(K+1)=(AM2*DELY)/(X(2+2)-X(2+1))*CONST
   B10(K+2) = -B10(K+1)
   ELEMENT M-1+1
12 K=NOA+5*M2*N1+2
   B10(K)=1.0*CONST
   WRITE(1)B10
   NUMB=NUMB+1
   GO TO(13+16+20+24)+NUMB
   F4=1
13 CONST=1.0
   DO 14 IJ=1.LI
14 B10(IJ)=0.0
   UPPER RIB
   DO 15 I=1.N1
   K=N1+I
15 Blo(K)=1.0
   GO TO 5
```

F7=1

```
16 ALPHA=ATAN((Y(M)-Y(1))/(X(M,1)-X(1.1)))
CONST=-COS(ALPHA)/SIN(ALPHA)
D0 17 IJ=1.LI
```

17 B10(IJ)=0.0

LOWER RIB DO 18 K=1.N1

18 B10(K)=CONST

LEADING EDGE STRINGER DO 19 I=1.M1 K=2\*N1+I 19 B10(K)=1.0/SIN(ALPHA)

GO TO 5

F8=1

```
20 BETA=ATAN((Y(M)-Y(1))/(X(M+N)-X(1+N)))
CONST=-COS(BETA)/SIN(BETA)
DO 21 IJ=1+LI
```

21 B10(IJ)=0.0

UPPER RIB DO 22 I=1•N1 K=N1+I

```
22 B10(K)=CONST
```

TRAILING EDGE STRINGER DO 23 I=1•M1 K=M1+2\*N1+I 23 B10(K)=1•0/SIN(BETA)

```
GO TO 5
```

24 RETURN END

### TABLE VIII

DISPLACEMENTS OF CORNER NODES

## INCHES PER MILLION POUNDS

MOD NO	FORCE	F1	F3	F4	F7	F8
1	F1	1•3888	•9984	1.2154	0291	-•6057
	F3	•9984	5.1241	5.7374	-1.7009	-3.8589
	F4	1•2154	5.7374	6.9985	-2.0824	-4.5745
	F7	-•0291	-1.7009	-2.0824	1.5413	2.2443
	F8	-•6057	-3.8589	-4.5745	2.2443	4.7353
2	F1	1 • 5600	1•4853	1•4821	2945	-•7984
	F3	1•4853	7.2106	7.2776	-2.7165	-5.1708
	F4	1 • 4821	7.2776	8.2307	-2.8361	-5.6909
	F7	2945	-2.7165	-2.8361	2.2355	2.6967
	F8	-•7984	-5.1708	-5.6909	2.6967	5.8844
3	F1	1.7330	1.8883	1.8811	3418	-1.0720
	F3	1•8883	8.2240	8.3341	-2.8421	-5.9660
	F4	1.8811	8.3341	9.3802	-2.9737	-6.6161
	F7	-•3418	-2.8421	-2.9737	2.2747	2.8310
•	F8	-1.0720	-5.9660	-6•6161	2.8310	6.7349
4	F1	1.8778	2.1979	2.1999	4405	-1.2754
	F3	2.1979	9.5208	9.4762	-3.4361	-6.8444
	F4	2.1999	9.4762	10.5417	-3.4391	-7.5126
	F7	4405	-3.4361	-3.4391	2.7684	3.1026
	F8	-1.2754	-6.8444	-7.5126	3.1026	7.5506
5	F1	2.0156	2+5335	2.5317	5184	-1.4971
	F3	2.5335	10.4365	10.3875	-3.7128	-7.5009
	F4	2+5317	10.3875	11•4832	-3:7038	-8.2207
	F7	-•5184	-3.7128	-3.7038	2.9392	3.3113
	F8	-1•4971	-7.5009	-8.2207	3.3113	8 • 1 3 9 1
6	F1	2.1085	2.7236	2•7246	5622	-1.6134
	F3	2•7236	11.1111	10.9875	-4.0112	-7.9217
	F4	2.7246	10.9875	12.0989	-3,9437	-8,6655
	F7	-•5622	-4.0112	-3.9437	3.2066	3.4592
	F8	-1.6134	-7.9217	-8.6655	3.4592	8.5133
7	F1	2.1872	2.9076	2.9083	6102	-1.7345
	F3	2.9076	11.6118	11.4819	-4.1948	-8.2725
	F4	2.9083	11.4819	12.6040	-4.1187	-9.0348
	F7	6102	-4.1948	-4.1187	3.3348	3.5972
	F8	-1.7345	-8.2725	-9.0348	3.5972	8.8062

### TABLE IX

## WEB STRESSES

PSI PER POU	JND
-------------	-----

NO	ELEM NO	PT	STR	F1	F3	F4	F7	F8
1	1-1	1	SXX	6264	1466	0201	.0034	1141
			SYY	.2410	.6321	.7056	.3783	6489
			SXY	0619	.6025	.4811	1809	2790
		2	SXX	7272	5241	4560	.1264	.3215
			SYY	0780	5623	6738	.7674	.7298
			SXY	.1205	.8203	.8436	2561	4762
		3	SXX	3621	1055	.2535	0185	0513
			SYY	.0183	5010	5315	.7447	•6939
			SXY	.0565	.5501	• 5389	1684	1607
		4	SXX	0102	.2638	.9062	1475	3672
			SYY	.0730	5956	5693	.7729	.8381
			SXY	.0163	.3083	.2816	0904	.1289
		5	SXX	0847	0150	.5842	0566	0453
			SYY	1626	-1.4781	-1.5885	1.0604	1.8567
			SXY	.1512	.4692	.5494	1460	0166*
2	1-1	1	SXX	7320	1091	1388	1022	0443
			SYY	•4165	1.4828	1.4657	2122	-1.1401
			SXY	1137	.3465	.3663	0551	1582
		2	SXX	9277	9103	9276	.2675	.6577
			SYY	2026	-1.0526	-1.0304	.9581	1.0819
			SXY	.2364	.9642	.9530	3516	4841
		3	SXX	5471	1320	1819	1026	.1817
			SYY	.0482	2718	2682	.5943	.4627
			SXY	.0851	.5360	.5364	1513	1592
		4	SXX	1784	• 5971	.5154	4500	2512
			SYY	.2612	•3535	.3409	.3021	0202
			SXY	0446	.1456	•1558	.0308	•1455
		5	SXX	3501	1057	1766	1255	• 3648
			SYY	2821	-1.8710	-1.8491	1.3291	1.9294
			SXY	.2625	.6876	.6706	2293	1403
	2-1	1	SXX	.0248	•6861	.9679	2409	6443
			SYY	0136	3161	1495	1.2694	2212
			SXY	.0026	.7324	.5294	2240	2770
		2	SXX	.0308	•6005	.7603	3903	2777
			SYY	.0052	5870	8067	.7965	.9390
			SXY	0071	.5298	.6194	0848	3201
		3	SXX	.0175	.3565	.9050	1919	3866
		-	SYY	0014	6280	6734	.9223	.7500
			SXY	0028	.5196	.5087	1754	1418
		4	SXX	.0046	.1056	1.0329	0056	4658
			SYY	0066	6910	- 5934	1.0096	•6551
			SXY	.0005	.4930	.4054	2548	.0328
		5	SXX	.0096	.0339	.8590	1307	1587
		-	SYY	.0091	9180	-1.1438	6135	1.6270
			SXY	0076	.3233	4808	1382	0032
								L

MOD NO	ELEM NO	PT	STR	F1	F3	F4	F7	FB
3	1-1	1	SXX	7611	0494	1003	0957	.0156
			SYY	•5759	1.9918	1.8980	3830	-1.3817
			SXY	0746	•4908	.5314	0291	3079
		2	SXX	9457	6135	6369	.0681	.4068
			SYY	0080	.2066	.2000	.1355	1438
			SXY	•1319	.8591	.8718	1725	5027
		3	SXX	5677	.0383	0358	1908	.0706
			SYY	.0627	.2638	.2484	.0968	1468
			SXY	.0205	.4940	• 5236	0698	2439
		4	SXX	2010	.6557	.5324	4398	2416
			SYY	.0976	.2115	.1928	.0900	0740
			SXY	0782	.1514	.1963	.0239	.0028
		5	SXX	3630	.1607	.0616	2960	.1015
			SYY	4147	-1.3548	-1.2969	.5450	1.0120
			SXY	.1030	.4746	.4949	1018	1680
	1-2	1	SXX	8579	7321	7627	.0873	.3957
			SYY	.1727	.2492	.3294	• 4530	2234
			SXY	0523	.3782	• 3913	2510	1830
		2	SXX	9662	-1.1888	-1.2254	.3156	.8427
		17	SYY	1701	-1.1961	-1.1349	1.1757	1.1909
			SXY	1668	.7831	.7730	- 4221	3849
		3	SXX	5439	4010	- 4817	0182	.4433
		-	SYY	0274	9081	8603	1.0507	1.0265
			SXY	.0835	.4477	. 4341	2554	0625
		4	SXX	1281	.3588	.2335	3382	.0713
			SYY	.0942	7087	- 6755	.9699	.9488
			SXY	.0137	.1372	.1186	0991	.2474
		5	SXX	2232	0419	1724	1378	.4635
		-	SYY	2065	-1.9769	-1.9604	1.6040	2.1898
			SXY	2060	. 4924	. 4535	2492	.0703
	2-1	1	SXX	.1193	.8975	1.1045	1756	7032
		1	SYY	.0326	2986	2364	1.3669	0903
			SXY	.0464	.9580	.7493	2847	5110
		2	SXX	.0842	.7626	.9223	2210	4700
		-	SYV	.0400	.8567		2375	5642
			SVV	0785	7254	- 8130	1.2231	-6476
		3	SVY	-0681	- 1234	1.0058	1146	5381
		5	SVV	1152	9281	9346	1.2198	
			SVV	.0053	7014		- 2667	- 3607
			CVV	.0390	. 1617	1.07/5	2007	5873
		4	SXA	.0290	1 1655	1.0745		
			STT	1611	-1.1055	-1.1030	1.2048	1.0432
		5	SVV	0299	.0487	.4960	2921	1015
		5	SYY	- 2541	-1.5230	-1.5850	1.0844	1.6614
			SYY	0352	. 4530	-5408	- 2526	2060

MOD NO	ELEM NO	PT	STR	F1	F3	F4	F7	F8
3	2-2	1	SXX	.1082	•8149	1.0957	4389	6540
			SYY	1104	4634	2285	.9034	0964
			SXY	0844	.3098	.2787	0814	0298
		2	SXX	.1590	.8416	1.0076	5330	4217
			SYY	.0502	3788	5073	.6055	•6386
			SXY	1178	.1702	.3067	.0127	0508
		3	SXX	.0806	.4913	1.0678	3060	4462
			SYY	.0432	4802	5191	.6444	.7121
			SXY	0743	.1781	.2276	0639	•1644
		4	SXX	.0063	.1432	1.1208	0866	4519
			SYY	.0492	5746	5535	.6590	.8452
			SXY	0335	.1747	.1507	1330	.3779
		5	SXX	.0489	.1656	1.0470	1655	2573
			SYY	•1839	5038	7870	• 4095	1.4610
			SXY	0615	.0578	.1741	0541	• 3604
4	1-1	1	SXX	8721	3535	3546	.0661	.2179
			SYY	.8434	2.2714	2.2676	4131	-1.4987
			SXY	1475	.4243	.4256	0810	2470
		2	SXX	-1.1940	-1.1125	-1.1131	. 1976	.6948
		3	SYY	1751	1305	1324	.0029	.0103
			SXY	.1709	.8862	.8883	1816	4933
		3	SXX	8302	5228	5227	.0764	• 3650
			SYY	.1346	.5153	.5131	1149	3825
			SXY	0072	.5274	.5296	1151	2773
		4	SXX	4760	.0443	.0450	0409	.0493
			SYY	• 4141	1.0897	1.0874	2204	7305
			SXY	1759	.1824	.1847	0515	0685
		5	SXX	7787	- 6695	- 6683	.0827	.4979
		-	SYY	5439	-1.1694	-1.1698	.1708	.6888
			SXY	1235	•6168	46198	-+1461	3002
	1-2	1	SXX	-1.0327	-1-1211	-1-1224	.1998	•6137
	• -	•	SVY	.1695	.4008	.4079	.2130	2479
			SVV	0970	1362	1368	1874	-0035
		2	SXX	-1.1973	-1.7847	-1.7871	.5861	1.2192
		-	SVY	3512	-1.6992	-1.6952	1.4356	1.6682
			SYV	.2789	.8287	.8278	-4806	- 3746
		3	SXX	8038	9619	9653	.2091	.7038
		5	SVV	0993	9250	- 9206	1.0171	1.0362
			SYV	.1201	.4125	. 4117	2682	0638
		~	SVV	- 4151	- 1589	- 1633	- 1564	- 2064
		**	SVV	4151	- 2122	- 2085		. 4611
			SYV	=.0374	-0160*	- 2005	0645	2366
		5	SYV	- 5690	- 7820	- 7884	2068	.7750
		5	SVY	- 3529	-2.1985	-2.1867	1.7848	2.2634
			SXV	. 3262	-6682	.6660	3403	1200
					<b>B</b> 1 1 1 1 1 7		- 1 - 1 - C - 3	

MOD	ELEM	PT	STR	F1	F3	F4	F7	F8
4	2-1	1	Sxx	1349	•7696	•7683	2703	4467
			SYY	.2804	1.3246	1.3018	1371	-1.0716
			SXY	0077	.6060	.6098	1005	3589
		2	SXX	3049	.1534	.1588	0206	.0473
			SYY	2576	6252	6269	.6530	.4919
			SXY	•1161	.8860	.8940	2818	5516
		3	SXX	1450	• 5552	.5638	2548	2413
			SYY	1230	1934	1973	.4554	.1562
			SXY	.0283	.5973	.6071	1530	3256
		4	SXX	.0092	.9362	.9482	4806	5134
			SYY	0064	.1726	.1670	.2845	1267
			SXY	0552	.3180	• 3298	0303	1061
		5	SXX	1493	•3617	.3798	2478	0527
			SYY	5082	-1.6456	-1.6314	1.0214	1.3312
			SXY	.0602	•5791	•5948	1993	2859
	2-2	1	SXX	1311	.5522	.5298	4785	2710
			SYY	0334	1812	1564	.6524	.1163
			SXY	1119	.0857	.1042	0489	.1118
		2	SXX	0989	.3237	.3033	3665	.0497
			SYY	.0683	9042	8732	1.0068	1.1315
			SXY	0866	.2152	.2095	1363	.0562
		3	SXX	0801	•5152	• 4688	4855	0862
			SYY	.0521	6867	6653	.8923	.8681
			SXY	0802	.0949	.0959	0716	.1946
		4	SXX	0601	•6990	•6266	6007	2113
			SYY	.0394	4936	4816	.7897	•6390
			SXY	0729	0209	0142*	0098	.3312
		5	SXX	0301	•4860	•4154	4963	.0877
			SYY	.1343	-1.1679	-1.1500	1.1201	1.5857
			SXY	0493	.0998	.0839	0913	.2793
	3-1	1	SXX	.1054	1.3729	1.3358	6830	8677
			SYY	0075	.5090	• 3511	•4932	4948
			SXY	.0136	•5364	.5760	0023	3522
		2	SXX	.0845	1.0455	1.0483	5692	5475
			SYY	0737	5270	5586	.8535	.5186
			SXY	0053	•5957	.6309	0905	4027
		з	SXX	.0640	1.1579	1.1505	6905	6482
			SYY	0729	3770	4258	•7753	• 3747
			SXY	0124	•4409	• 4947	0284	2522
		4	SXX	.0427	1.2575	1.2414	8073	7365
			SYY	0746	2674	3285	.7112	•2705
			SXY	0202	•2884	• 3605	.0302	1037
		5	SXX.	.0234	•9556	.9763	7024	4412
			SYY	1356	-1.2226	-1.1673	1.0434	1.2048
			SXY	0377	.3431	.4112	0510	1503

NO	ELEM NO	PT	STR	F1	F3	F4	F7	F8
4	3-2	1	Sxx	0517	•6562	.6676	4398	2972
			SYY	0387	8374	5760	1.3022	.3783
			SXY	0575	.3435	.3364	1882	0062
		2	SXX	0321	.6377	.5867	5577	0858
			SYY	.0235	8960	8319	.9289	1.0472
			SXY	0492	.2915	.3100	1135	.0386
		3	SXX	0259	•5781	.5708	4432	0736
			SYY	.0142	9043	7906	1.0326	.9302
			SXY	0420	.2936	.2789	1817	.1248
		4	SXX	0190	.5178	.5518	3332	0531
			SYY	.0073	9148	7594	1.1217	.8392
			SXY	0345	.2936	.2467	2469	.2128
		5	Sxx	0008	.5008	.4772	4420	.1417
			SYY	.0647	9688	9953	.7775	1.4560
			SXY	0268	.2457	.2224	1781	.2542
	4-1	1	SXX	.0322	.6008	1.0269	0582	6989
			SYY	0104	-1.3302	-1.1535	2.4807	.5955
			SXY	.0051	.9786	.6801	3777	- 4559
		2	SXX	.0302	.7309	1.0709	3922	6141
		-	SYY	0166	9185	-1.0144	1.4240	.8640
			SXY	0025	.6814	.6694	1570	4635
		3	SXX	.0193	.2954	1.0531	0561	- 6296
		-	SYY	0198	-1.0758	-1.0266	1.5806	.8463
			SXY	0031	.7666	.6934	3470	4178
		4	SYX	.0082	1340	1.0373	.2644	6411
		-	SVY	0233	-1-2140	-1.0325	1.6883	.8410
			SVV	0041	.8381	.7169	- 5267	- 3724
		5	SVV	.0065	-0159	1.0772	0386	5641
		5	SVV	0289	- 8403	9062	.7293	1.0846
			SYV	0111	- 5684	. 7072	- 3264	- 3793
	1-2		SVV	0117	+000+	0873	- 2469	5370
	4-2	•	SVV	0066	3901	- 0412	-6769	3182
			CVV	0153		- 2037	- 1012	0122
		2	SVV	0072	•4101	. 7672	3414	
		-	SVV	-0060	3600	- 6553	. 3777	8622
			SVV	0120			0795	- 1011
		3	SVV		.2455	1.0342		
		3	SAA		- 4201	- 4708	-•1005	-6317
			CVV	- 0110	4291	4/90	- 1462	0767
			SAT	0110	02930	1 2010	1402	- 6271
		4	SAA		- 4960	1.2364		
			STT	.0050	4969	3364	• 5548	.4558
3		-	SAT	0091	.3130	•2017	2078	.2000
		5	SXX	.0021	.0483	1.0912	0818	2005
			SYY	.0166	4096	9680	.2812	1.52/1
			SXY	0070	•1841	.4290	1064	.1/1/

MOD	ELEM NO	PT	STR	F1	F3	F4	F7	F8
	de la s							
5	1-1	CG	SXX	8236	3859	3927	.0474	•2788
			SYY	.2073	•6390	•6385	1143	4286
			SXY	0223	.6088	.6099	1109	3580
	1-2	CG	SXX	8938	8293	8165	•1518	•5649
			SYY	.0268	.1734	.1773	.0466	1382
			SXY	0642	•2820	•2761	0978	0934
	1-3	ĊG	SXX	8693	9436	9477	•1294	•6578
			SYY	0769	2347	2403	.3008	.2198
			SXY	.0182	.2746	.2781	1958	0370
	1-4	CG	SXX	7668	9602	9779	.1630	.7173
			SYY	1697	-1.4325	-1.4286	1.4165	1.5591
			SXY	•1682	•5133	•5154	4241	1389
	2-1	CG	SXX	0294	.8195	.8491	2342	4432
			SYY	0964	.0815	.0917	.2087	1369
			SXY	.0271	.6700	•6637	1369	3910
	2-2	CG	SXX	1190	•6201	• 5996	3575	2333
			SYY	1678	3110	3470	.4735	•2555
			SXY	0327	• 3469	.3785	0916	1553
	2-3	CG	SXX	1031	•5135	• 4653	4136	0804
			SYY	1458	9369	9180	1.0465	.9090
			SXY	0755	.2189	.2439	1734	0116
	2-4	CG	Sxx	.0178	•6806	.6202	6224	1754
			SYY	.1457	7865	7265	.9829	1.0408
			SXY	1515	1043	1212	0179	• 3966
	3-1	CG	SXX	•1176	1.4127	1.3537	7794	- 8045
			SYY	1354	1120	2376	.5269	.1280
			SXY	.0094	•4546	.5279	.0536	3187
	3-2	CG	SXX	.0764	1.0500	1.0507	6135	5177
			SYY	0793	8184	7693	1.1736	.6768
			SXY	0558	.4008	.4505	1357	2115
	3-3	CG	SXX	.0353	.8139	.8098	5579	2852
			SYY	.0353	8383	7027	1.0751	.7766
			SXY	0876	.2633	.2848	1515	.0284
	3-4	CG	SXX	0683	•4346	• 3505	3783	.1423
			SYY	.0166	8667	7449	.8611	.9637
			SXY	0225	.2340	.1978	1638	.2727
	4-1	CG	SXX	.0562	.4377	1.1268	0863	7275
			SYY	0277	-1.2913	-1.2358	1.9851	.9542
			SXY	0093	.8807	.7415	3960	5086
	4-2	CG	SXX	.0199	.3556	1.1372	1504	6795
			SYY	.0022	8044	7171	1.1363	•6235
			SXY	0164	.6359	.6474	3209	3476
	4-3	CG	SXX	0271	.2291	1.0308	1295	4993
			SYY	0043	5459	4838	.6447	.5222
			SXY	.0012	.4331	.5537	2235	1447
	4-4	CG	SXX	.0069	.2755	1.0075	1903	3209
			SYY	.0015	3469	4340	.3262	.6364
			SXY	0035	.1923	. 3381	0975	.2339

MOD	ELEM NO	PT	STR	F1	F3	F4	F7	F8
6	1-1	CG	Sxx	-1.0783	8048	8046	•1554	•5162
			SYY	•2634	.6807	•6806	1354	4358
			SXY	0621	•5551	.5553	1022	3314
	1-2	CG	SXX	-1.1774	-1.3073	-1.3073	.2544	.8365
			SYY	.0378	•1924	.1919	0404	1548
			SXY	1479	.0667	.0679	0254	.0288
	1-3	CG	SXX	-1.1463	-1.4548	-1.4562	.2942	.9220
			SYY	0645	0177	0180*	•0265	0476
			SXY	0032	.1800	.1820	1701	.0173
	1-4	CG	SXX	-1.0158	-1.5012	-1.5044	•4219	1.0215
			SYY	3150	-1.7174	-1.7135	1.5788	1.7455
			SXY	.2868	•7582	•7567	6030	3351
	2-1	CG	SXX	4067	•2805	•2813	0551	1191
			SYY	•0548	•4162	•4152	0728	3230
			SXY	0159	•6109	.6115	1202	3567
	2-2	CG	SXX	5596	2621	2613	•0391	.2692
			SYY	1277	0600	0616	.1233	0326
			SXY	0717	•2717	•2744	1259	0943
	2-3	CG	SXX	5202	4363	4386	•0493	•4518
			SYY	2624	8339	8313	•7634	•7100
			SXY	0100	•3334	• 3369	3155	1197
	2-4	CG	SXX	2054	.0953	• 0859	3473	•1042
			SYY	•0756	9101	9020	1.0938	1.1958
			SXY	0841	0232*	0249	1205	•2548
	3-1	CG	SXX	0792	•7735	•7762	2135	3838
			SYY	0804	•2047	.2015	•0787	2306
			SXY	•0171	•6638	•6652	1441	3996
	3-2	CG	SXX	1616	•4300	•4326	2107	1050
			SYY	2148	4141	4164	•4993	.2803
		~~	SXY	0572	.3749	.3812	1733	1856
	3-3	CG	SXX	1188	•4207	•4144	3786	0726
			SYY	1114	/414	/339	•8581	• 7466
		~~	SXY	12/2	.1012	•1102	1285	.0668
	3-4	CG	SXX	1244	.2780	•25/5	3942	.0637
			SYY	.0852	8605	8417	1.0130	101241
			SXT	1086	0900	0935	0251	• 3733
	4-1	CG	SXX	.0844	1.0691	1.0768	4039	5/36
			SYY	1472	0373	0456	• 3482	0478
		~~	SXY	.0115	•6402	•6441	- 1233	4006
	4-2	CG	SXA	.0243	•0038	.0099	4797	
			STT		4001	4706	- 0971	- 1376
		~~	SXT	0808	.3131	• 3295	08/1	1376
	4-3	CG	SVV	0356	7368	- 7154		
			SYV		-1017	.1229	- 0605	-1095
	0-0	co	SYY	0640	.4936	. 4441	5102	0111
			SYY	.0572	- 9075	- 8634	.9995	1.1117
			SXY	0695	.0190	.0115	0596	.3544

NOD	ELEM NO	PT	STR	F1	F3	F4	F7	F8
6	5-1	CG	SXX	•1141	1.1987	1.2189	5663	7052
			SYY	1179	1619	1848	.5780	.0885
			SXY	0031	.5656	.5765	0553	3603
	5-2	CG	SXX	•0442	•9870	1.0116	6056	5082
			SYY	0773	5276	5327	.8674	.4762
			SXY	0604	.3056	• 3463	0321	1270
	5-3	CG	SXX	0091	.8605	.8256	6739	3138
			SYY	0108	8012	7488	1.0256	.8055
			SXY	0667	.1688	.2204	0577	.0809
	5-4	CG	SXX	0308	.6572	.5709	5928	0501
	35 14		SYY	.0298	9906	8873	1.0192	1.1038
			SXY	0355	.1703	.1504	1522	.2964
	6-1	CG	SXX	.0736	1.1618	1.2350	6191	7559
			SYY	0662	2690	3270	.7989	.2227
			SXY	0050	.4914	.5219	.0192	3261
	6-2	CG	SXX	.0288	1.1442	1.1660	8030	6323
		100	SYY	0341	6305	6392	1.0385	•5723
			SXY	0331	.2944	• 3987	.0018*	1531
	6-3	CG	SXX	0022	.8547	.8602	6282	3109
	1999 - 1991 - 1991 - 1991 - 1991 - 1991 - 1991 - 1991 - 1991 - 1991 - 1991 - 1991 - 1991 - 1991 - 1991 - 1991 -	12020	SYY	0019	-1.0081	8421	1.2087	.8589
			SXY	0316	.3550	.4177	2158	0434
	6-4	CG	SXX	0131	•6325	.5751	5018	.0074
			SYY	.0132	- 9159	7642	.8662	.9782
			SXY	0153	.2962	2667	-+2318	2482
	7-1	CG	SXX	.0354	1.3732	1.4513	9410	9509
	• •		SYY	0292	3749	5501	1.0224	.4077
			SXY	0033	.4017	4858	.0905	3112
	7-2	CG	SXX	.0122	.7887	1.0655	- 4689	5694
			SYY	0131	-1.1807	9964	1.6046	.8321
			SXY	0138	.6482	.7096	3875	3939
	7-3	CG	SXX	0009	.5145	.8085	3044	2522
			SYY	.0007	8752	6373	.9543	•6585
			SYY	0124	-5426	+6186	3787	- 1955
	7-4	CG	SYY	0048	. 3947	-5173	2615	.1254
	,	00	SVY	.0051	5563	- 4533	.4571	.6847
			SYV	0057	.2910	.3192	1956	.2463
	8-1	CG	SYY	.0108	.0983	1.0286	1432	6928
	• •		SYY	0121	-1.8523	-1.6592	2.6804	1.2449
			SVV	0003	1.1391	. 9266	7136	6527
	8-2	cc	SVV	-0039	1027	1.1808	.0036	7377
	0-2	co	SAA	- 0039	- 6016	- 5452	0638	. 4573
			SVV		- 7838		- 5225	- 4923
	0-2	ce	SAT	0000	.1157	1.2223	0470	
	0-3	0	SVV	.0000	-,2803	- 2088	2762	2566
			SVV	- 0045	. (28)	6488	- 2587	2444
	9-4	cc	SVV		.1224	1.1058	0672	3807
	0-4		SVV	-0011	-1383	- 2049	.0882	. 4890
			SVV	- 0019	-1535	. 4120	0778	- 1986

MOD	ELEM	PT	STR	F1	F3	F4	F7	F8
NO	NO							
7	1-1	CG	SXX	-1.0205	-•6065	-•6065	•1154	• 3892
			SYY	•3103	•7822	•7822	-•1492	<b>~•496</b> 0
	- 19 - 19 -		\$XY	0491	•6647	•6647	1242	4105
•	1-2	CĢ	SXX	-1.1565	-1.0652	-1.0649	•2014	•681 <b>6</b>
			SYY	•1099	•3403	• 3402	0637	2280
. *			SXY	-•1959	<ul><li>1775</li></ul>	•1776	<del>~</del> •0328	0886
	1-3	CG	SXX	-1.1982	-1.2956	-1.2959	•2433	•8290
			SYY	•0186	•1345	•1341	0174	1062
			SXY	2082	•0010	•0016	0083	•0493
	1-4	CG	SXX	-1.1973	-1.4185	-1.4180	•2718	•9059
			SYY	0282	•0205	•0203	•0208	0382
			SXY	-•1569	<b>~</b> •0167 <b>*</b>	-•0159	0331	•0946
	1-5	ÇG	SXX	-1.1750	-1.4785	-1.4790	.2914	·9432
			SYY	0600	0699	0703	• 0684	0241
			SXY	0690	•0686	•0701	1070	•0744
. ,	1-6	CG	SXX	-1.1333	-1.4964	-1.4979	•3111	•9563
	ć		SYY	0949	2062	-•2059	•1699	•1409
			SXY	•0496	•2626	•2642	-•2542	<del>-</del> •0273
	1-7	CG	SXX	-1.0536	-1.4465	-1.4488	•3155	•9331
			SYY	-•1615	-•5754	-•5739	•4916	•5112
			SXY	•2043	•6071	•6074	-•5174	2592
	1-8	CG	SXX	-•9041	-1.3256	-1.3286	• 3310	<del>،</del> 9084
		5	SYY	3965	-2.2741	-2.2702	2.0747	2.3349
			SXY	•3811	1.0465	1.0444	8458	-•5730
	2-1	CG	SXX	2375	•6988	•6993	1402	-•3946
			SYY	• <sup>0</sup> 621	•4308	•4304	0709	-•3165
N	÷		SXY	0117	•6877	•6878	1299	4208
N.	2-2	CG	SXX	-•4160	·2187	•2187	0568	0733
			SYY	-•0477	•1610	•1598	.0087	1620
	•		SXY	1012	•3608	•3615	0797	1901
	2-3	CG	SXX	5137	-•1037	- • 1017	•0026	•1513
*			SYY	1172	0390	0395	• 100 <b>1</b>	0377
			SXY	<b>-</b> •1130	•2208	•2216	0856	0729
	2-4	CG	SXX	-•5513	-•2961	2960	•0267	•3011
			SYY	1672	2207	2227	•2141	•0996
•			SXY	0848	•1915	• 1944	1339	0300
	2-5	CG	SXX	5346	3863	3876	•0279	• 3920
			SYY	2094	4585	4579	•4054	•3152
			SXY	0413	,2417	•2451	2310	
	2-6	CG	SXX	4572	3540	-•3568	-0186	•4069
			SYY	2440	8215		•7381	•7035
		<u> </u>	SXY.	0087	•3163	•3190		
	2-7	ĊĠ	SXX	3029	-•1358	-•1417	1704	•2886
			SYY	-•2259	-1.3550	-1.3488	1.2973	1.3788
	~ ~		SXY	0318	•2671	•2679	3748	0532
3. N	2-8	CG	SXX	0269	•4968	• 48 / 1		1953
			SYY	• 2211				4700
			SXY	1734	28/3	2901	<u>₀0424</u>	04/98

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MOD	ELEM	РТ	STR	F1	F3	F4	F7	F8
NO	NO				· .			
	3-1	CG	SXX	.0024	1.0032	1.0041	- 2527	-•5456
			SYY	0427	• 3084	.3063	0263	2912
			SXY	•0266	•7270	•7274	1381	4506
	3-2	CG	SXX	0845	•7246	•7296	2140	-•3417
			SYY	1371	•0174	•0157	•1686	1010
			SXY	0300	•5135	•5140	1258	2926
	3-3	CG	SXX	-•1342	•5444	•5445	2224	1933
			SYY	1955	-•2270	2328	• 3220	•0934
			SXY	0576	.3764	•3817	1354	1874
	3-4	CG	SXX	1480	•4212	•4225	2358	0839
			SYY	2232	4919	-•4918	•5388	• 3396
			SXY	-•0757	•2997	• 3055	1784	-•1223
	3-5	CG	SXX	1295	•3835	• 3835	2929	0356
			SYY	2120	7464	7424	•7813	•6382
			SXY	1011	. 2175	.2248	2042	0511
	3-6	CG	SXX	0899	•4335	•4259	4080	0602
			SYY	1302	-•9321	9237	1.0099	●9499
			SXY	1440	•0687	•0771	-•1592	•0895
	3-7	CG	Sxx	<b>-</b> •0ó15	•5084	<b>∙</b> 4897	-•5463	-•1276
			SYY	•0748	7925	7771	•9881	1.0176
			SXY	-•1822	1638	1592	0037	•3531
	3-8	CG	SXX	1626	•1771	•1501	3621	•1415
		-	SYY	•1246	9201	8994	1.0575	1.2491
			SXY	0832	1216	1290	•0054 <b>*</b>	•4561
	4-1	CG	SXX	•1247	1.1728	1.1809	3873	6485
			SYY	1202	•1178	•1130	•2330	1857
			SXY	.0285	.7072	•7072	1224	4515
	4-2	CG	sxx	•0787	1.0467	1.0460	-•4299	-•5337
			SYY	1703	1402	1534	.3975	•0308
			SXY	0202	•5263	•5342	1031	3188
	4-3	CG	SXX	•0478	•8971	•9095	-•4225	-•4166
			SYY	1824	4114	4124	•6216	•2784
			SXY	-• <sup>0</sup> 615	•4039	•4103	1243	2160
	4-4	CG	SXX	•0270	.8200	•8312	4763	-•3464
			SYY	1552	-•5867	-•5896	•7767	•5018
			SXY	-•099 <b>3</b>	•2601	•2764	1043	0948
,	4-5	CG	SXX	.0062	•7814	•7762	5574	3009
			SYY	0863	7074	7027	•9054	•7047
			SXY	1294	.1128	•1397	0611	•0491
	4-6	CG	SXX	0287	•7100	•6818	6015	2302
			SYY	•0083	7590	-•7331	•9657	•8478
			SXY	-•1329	•0071	•0334	0241	•2008
	4-7	CG	SXX	0855	•5218	•4721	-•5272	0532
			SYY	•0412	<b>~</b> •9102	8619	1.0459	1.0608
N.			SXY	0832	o270 ،	•0364	0575	•2898
	4-8	CG	SXX	0594	•4785	•4145	5145	•0248
			SYY	•0755	9735	-•9181	1.0162	1.2158
			SXY	0469	•0163 <b>*</b>	0047	<del>~</del> •0666	•4186

TABLE IX (CONTINUED) MOD ELEM PT STR F1 -FЗ F4 F7 F8 NO NO 5-1 CG SXX .1435 1.2944 1.2974 -- 5742 -.7611 SYY -.1270 -.0404 -.0646 •4693 -.0406 SXY .0136 .6299 .6354 -.0580 -.4169 5-2 CG SXX •1100 1.0953 1.1419 -.5018 -.6248 SYY -.1281 -.3154 -.3219 •7019 .2014 SXY •5163 -.0274 •5177 -.0822 -.3122 5-3 CG SXX .0776 1.0636 1.0964 -.6087 -.5728 SYY -.1034 -.4105 -.4445 •7579 .3638 SXY -.0601 •3275 • 3639 -.0103 -.1690 5-4 CG SXX •0427 1.0295 1.0320 -.6958 -•5075 SYY -.0614 -•5793 -•5921 •9024 •5576 SXY -.0793 .2000 2636 .0102 -.0503 5-5 CG SXX .0049 •9408 •9120 -.7091 -.3962 SYY -.0185 -.7602 -.7201 1.0359 .7403 SXY -.0787 •1570 •2236 -.0299 .0404 5-6 CG SXX -.0266 •8080 •7510 -.6579 -.2423 SYY .0030 -.9271 - • 8352 1.1102 •9179 SXY -.0588 .1768 .2220 -.1027 .1153 5-7 CG SXX -.0247 •7241 .6415 -.6210 -.1212 SYY .0290 -.9854 -.8671 . 1.0637 1.0384 SXY -.0434 1753 1808 -.1434 .2310 5-8 CG SXX -.0322 •6034 •4985 -.5558 .0253 -1.0056 SYY .0331 -.9015 •9582 1.1698 SXY -.0205 .1703 •1255 -.1658 • 3649 6-1 CG SXX .0949 1.1117 1.2168 -.4924 -.7529 SYY -.0784 -.2286 •1400 -.2628 •7806 SXY .0018 •5859 •5782 -.0225 -.3869 .0696 6-2 CG SXX 1.2814 1.3202 -.8000 -- 8067 SYY -.0619 -.2058 -.3284 •7079 •2456 SXY .3163 •3972 -.0216\* .1409 -.2200 6-3 CG SXX .0428 1.2314 1.2485 -.8474 -.7136 SYY -.0410 -.5795 -•6158 1.0509 •5223 SXY -.0345 •2777 •3889 •0539 6-4 CG SXX .0179 1.0864 1.0989 -.7711 --- 5625 SYY -.0220 -.8689 -.7940 1.2496 •7194 SXY -.0366 •3248 •4306 -.0958 -.1526 6-5 CG SXX .0008 .9232 .9304 -.6648 -.3886 SYY -.0083 -1.0014 -.8441 1.2506 .8241 SXY -.0318 .3713 •4518 -.2125 -.1060 6-6 CG SXX -.0045 •7808 -.5795 •7903 -.2238 SYY .0072 - - • 9967 -•8004 1.1121 •8640 SXY -.0267 .4136 -.2583 -.0013 **a**3695 6-7 CG SXX -.5054 -.0507 -.0133 •6644 .6235 SYY -.9416 .0112 -.7554 .9300 •9154 SXY -.0160 •3335 • 3322 -.2526 •1501 6-8 CG SXX -.0115 •5855 •5046 -.4697 •0893 SYY .0129 -.8498 .7342 1.0084 -.7329 SXY -.2068 •3508 -,0080 •2569 2023

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MOD NO	ELEM NO	PT	STR	F1	F3	F4	F7	F8
	7-1	CG	SXX	•0415	1 6300	1.6180	-1.1781	-1.0974
	·		SYY	0310	•0072*	- 2985	.6724	1945
			SXY	0011	•2564	•3677	• 3098	- 2422
	7-2	CG	sxx	• 0269	1.2159	1.3482	- 8074	- 8551
			SYY	0234	- 9537	- 9530	1.6270	•7318
			SXY	0088	•5198	•5987	1248	- 3792
	7-3	CG	sxx	•0147	•9179	1.1515	- 5679	
	•		SYY	0151	-1.1596	-1.0053	1.6497	•8158
			SXY	0123	•6515	•7172	3657	- 4261
	7-4	CG	sxx	•0066	•7111	1.0006	- 4199	- 4936
			SYY	0074	-1.0759	8530	1.3650	•7445
			SXY	0131	•6683	•7356	4474	3890
	7-5	CG	SXX	•0018	•5726	•8711	3352	3327
			SYY	• 0002	9084	6652	1.0345	•6481
			SXY	0122	•6026	•6787	4226	2821
	7-6	CG	SXX	0036	•4741	•7317	-•2855	
			SYY	.0023	-•7515	5223	•7572	•5943
			SXY	0083	•4938	•5741	3449	1215
	7-7	CG	SXX	0035	•4183	•5808	2673	.0485
			SYY	.0043	-•6136	4378	•5392	•6056
			SXY	0055	•3591	•4224	2447	•0986
	7-8	CG	SXX	0040	•3799	• 3926	-•2611	.2850
			SYY	•0040	- • 4970	4419	• 3723	•7256
			SXY	0026	•2216	•2254	1483	•3851
	8-1	CG	SXX	•0107	•1783	1.0351	•1027	7178
			SYY	0121	-2.2405	-2.0236	3.2921	1.5014
			SXY	•000 <b>7</b>	1.2325	•9621	7712	6960
	8-2	CG	SXX	.0070	•1309	1.1107	•0518	7457
			SYY	0067	-1.3368	-1.1513	1.8699	•8761
			SXY	0025	1.0951	•9560	7500	-•6599
	8-3	CG	SXX	•0043	•1146	1.1703	•0121	7568
			SYY	0029	-•8127	6531	1.0596	•5228
			SXY	0043	•909 <b>7</b>	•887 <b>8</b>	6310	-•5718
	8-4	CG	SXX	.0021	•1142	1.2130	0192	7477
			SYY	0004	-•5124	-•3749	•6062	•3318
			SXY	0045	•7140	•7999	-•4811	4606
	8-5	CG	Sxx	0004	•1176	1.2325	-•0413	7094
			SYY	•0002	3423	2280	• 3560	•2426
			SXY	0035	•5282	•7133	3366	-•3377
	8-6	CG	sxx	0001	.1274	1.2286	0605	6371
			SYY	•0009	2411	-•1629	•2147	•2267
			SXY	0027	•3593	•6279	2121	1949
	8-7	CG	Sxx	0010	•1298	1.1742	0707	5020
			SYY	• 0009	1771	1785	•1319	•3017
			SXY	0015	•2150	•5285	1160	0031
	8-8	CG	SXX	0008	•1281	1.0387	0754	2648
			SYY	•000 <b>7</b>	1298	3424	•0792	•5677
			SXY	0006	0971	•3495	0487	• 3300

## TABLE X

RIB STRESSES

PSI PER POUND

MOD	ELEM	F1	F3	F4	F7	F8
NO	NO					
	_					
1	1	-1.0371	7456	9077	.0217	• 4523
•	2	•3012		1.7508	5295	9935
2	1	-1.1650	-1.1092	-1.1069	•2199	•5962
	2	-++0043	•0930	1.3231	1659	7220
5		-1+2988	-1.3127	-1+2859	•2720	•7875
	. 2	-1.2898	-1.5077	~1.5237	•2386	.8137
	. 3		•2991	1.5449	2850	-1.0381
4	4	-1-0046	•0065 <del>*</del>	1.3597	0802	7668
	1	-1+4046	-1 8050	-1.4575	•2806	•8972
	2	-1:4003	-100209	-1.0283	•3//3	1.0078
		•0057		1.3497	•0174	
5		-1.5724	0123	1.60.88	0256	9385
5	· · ·		-1.0027	-1.0014	0.3207	1.0488
	2	-1.05540	-1.0490	-10201	e 3372	101397
		-1.4994	-2.0930	-2 0804	e 3078	1.1408
	5	-104099	-2:0930	-200094	• 5028	101429
	6	-+0102		1.0010	•1001	- 0071
	7	•0087	- 0369	1.6425	- 0426	- 1 - 0722
	, А		.0351	1.7409	- 0380	-1 0220
6	1	-10020	-1-8450			-1:0229
Ŭ	2	-1.5790	-2.0250	· 1•0+50	• 3808	1.2069
		-1.5052	-2.0510	-2,0525	* 4080	1.2109
	Δ	-1.5542	-2.2147	-2.2165	- 5429	1.2115
	· 5	.0035	4438	1.1981	.2567	
	6	•0018	- 1879	1.4586	.0955	-1.0274
	7	• 0005	0520	1.6721	0215	-1.1211
	8	• 0000	0027	1.8431	.0009	-1.1174
7	1	-1.8003	-2.0448	-2.0448	.3854	1.2776
	2	-1.7447	-2.1533	-2.1533	4053	1.3443
	3	-1.6657	-2.1581	-2.1581	.4053	1.3406
	4	-1.5937	-2.1305	-2.1308	• 4006	1.3075
	5	-1.5437	-2.1102	-2.1106	4059	1.2673
	6	-1.5262	-2.1254	-2.1262	4356	1.2376
	7	-1.5529	-2.2146	-2.2159	•5166	1.2468
	8	-1.6405	-2.4347	-2.4360	.6905	1.3412
	9	.0028	5794	1.0936	.3773	7992
	10	•0022	3878	1.2634	• 2333	9171
	11	•0013	2449	1.4071	•1341	-1.0098
	12	•0007	1414	1.5319	•0690	-1.0814
	13	0005	0692	1.6447	•0287	-1.1354
	14	• 0000	0248	1.7475	.0076	-1.1708
	15	• 0000	0009	1.8442	0014	-1.1855
	16	-•0000	•0060	1.9293	0026	-1.1661

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TABLE X	l
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### STRINGER STRESSES

PSI PER POUND

		· .				
MOD NO	ELEM NO	F1	F3	F4	F7	F8
1	1	1271	•7347	•7392	0395	3056
	2	.0671	1189	0872	.4108	•8176
2	1.	2295	•8753	.8818	1590	5254
	2	.0057	•9481	.9117	•0460	4900
	3	•1143	3989	4093	•5719	1.1012
•	4	0028	1433	0669	• 2335	ø9272
3	1	1542	1.0527	1.0587	1660	-•6295
	2	•0410	1.0645	1.0499	o294	6207
	3	• 0874	4928	5204	•6082	1.2320
	4	.0029	1669	1359	• 2392	1.0338
4	1	2092	1.1507	1.1510	2179	7154
	2	• 0220	1.4017	1.4018	2459	8925
	3	•0332	1.2204	1.2229	0527	8000
	4	.0079	•9383	•8753	.2412	5814
	5	• 1408	6707	6728	•7662	1.3847
	6	• 0262	-•5969	6087	•5733	1.3441
	7	•0060	2871	3269	•2647	1.1973
	8	•0004	0514	0016	.0570	1.0506
5	1	1324	1.3387	1.3388	2508	8345
	2	.0727	1.5219	1.5218	-,2562	9686
	3	• 0508	1.2755	1.2798	0593	-•8486
	4	.0081	•9428	.8921	.2571	-•6118
	5	•1152	-,7879	7885	.8442	1.4991
•	6	•0284	6106	-•6284	• 5684	1,3793
	7	.0048	2992	3553	•2636	1•2384
	8	.0000	-+0601	0465	.0604	1.1143

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MOD	ELEM	F1	F3	F4	F7	F8
NO	NO			• .		
,	•					07.40
0	1		1+3999	1.4000	2640	8742
	2	•0232	1.6038	1.6038	3034	-1.0060
	3	0837	1.6233	1.6230	3024	-1.0352
	4	• 0827	1.5437	1.5425	2544	-1.0116
	5	• 0538	1 • 3929	1.3895	-•1436	-•9377
	6	•02 <b>62</b>	1.2087	1•1988	•0191	8282
	7	•0102	1.0029	<del>،</del> 9777	•2293	6883
	8	e0033	•8336	•7348	•4320	5251
	9	• 1604	-•8260	8272	•9229	1 • 5594
	10	•0773	8204	8234	•8113	1.5304
	11	•0423	7216	-,7287	•6665	1.4621
1	12	•0199		-•6046	•5115	1.3884
	13	.0082	4126	4483	• 335 <b>3</b>	1.3042
	14	•0029	2222	2838	.1643	1.2271
	15	.0007	0754	1436	.0490	1.1849
	16	• 0000	0082	.0132	.0052	1.1409
7	1	0916	1.5464	1.5464	2914	9663
	2	0661	1.7041	1.7040	3207	-1.0695
	3	.1027	1.6687	1.6684	3059	-1.0633
	4	.0919	1.5646	1.5636	- 2523	-1.0240
	5	0586	1.4069	1.40.39	1440	9488
	. 6	0271	1.2187	1.2087	.0171	
	7	.0093	1.0061	.9808	2329	- 6957
	8	•0026	.8159	.7234	4586	
	Q.	1362	- 9235	- 9244	•9981	1.6504
	10	0804	8388	8413	.8278	1.5562
	11	0436	- 7312	-,7379	6705	1.4760
	12	- 0102	- 5036		.5090	1,3982
	13	00172			- 3327	1.3133
	14	- 0023			- 1673	1.2400
	14	002J	- # 22 / 0	- # 2 7 30	0072	1.20%4
	15	.0005	0808		•0536	102040
	16	•0000	-•0108	0121	•0069	101/55

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#### APPENDIX C

#### EXPERIMENTAL RESULTS

The experimental results of this investigation consist of the strain per unit load at the seventy-eight strain gages for the three loading conditions  $F_3 = 1$ ,  $F_8 = 1$ , and  $F_7 + F_8$ = 1 (Figure 3). The average strain per unit load for the back-to-back strain gages was also calculated.

As indicated in Chapter V, the loads and strains were recorded at load increments of approximately 500 pounds up to a maximum load of 5,000 pounds. The strain per unit load was calculated for each gage by determining the slope of the least-square straight line through a plot of strain versus load. The slopes were determined analytically using a program written for the IBM 1620. The average strain per unit load for the back-to-back gages was calculated using the individual gage readings rather than averaging the back-toback strain readings or averaging the slopes of the lines for the back-to-back gages.

The strains per unit load are tabulated in Tables XII through XIV. The strain gage numbering system is shown in Figure 27. All even-numbered gages are on one side of the panel while all odd numbered gages are on the opposite side, It can be seen from the data, that although lateral bending

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## Figure 27. Strain Gage Numbering System

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was present, the strains could be reproduced on subsequent runs, with a few exceptions. In Table XIV, the data for the last three rosettes is missing for Run 5-22 because these three rosettes had not been installed at the time of the run. In Table XII, the data for Gages 66-67 is missing because Gage 67 had been damaged beyond repair prior to these runs. Due to the lateral bending, only the average strain per unit load can be compared with the analytical results; therefore, the data for Gage 66 is not included. STRAIN PER UNIT LOAD - F3

GAGE	RUN NO	RUN NO	GAGE	RUN NO	RUN NO
NUMBER	6-25	6-26	NUMBER	6-25	6-26
0	-0.218	-0.218	20	-0.075	-0.074
1	-0.218	-0.217	21	-0.075	
•	-0.218	-0.217	<b>~ -</b>	-0.075	
		U LI		00075	00075
2	-0.213	-0.213	22	0.156	0•116
3	-0.209	-0.212	23	0.147	0 • 147
	-0.211	-0.213		0.152	0.132
4	-0.212	-0.211	34	0.110	0.111
	-0.212	-0.207	24	0.110	0.111
5	-0.207	-0.207	25	0.115	0.114
	-0+209	-0.209		0.113	0.112
6	0.178	0.178	26	0.129	0.129
7	0•161	0.161	27	0.131	0.131
•	0.170	0.170		0.130	0.130
. 8	0.036	0.036	28	-0.002	-0.001
9	0.036	0.037	29	-0.002	-0.002
	0.036	0.036	27	-0.002	-0.002
10	0.034	0.034	30	-0.076	-0.076
11	0.033	0.033	31	-0.079	-0.078
•	0.033	0.033		-0.077	-0.077
12	-0.046	-0.046	32	0.093	0.093
1.3	-0.048	-0.048	33	0,092	0,092
10	-0.047	-0.047		0.093	0.093
14	0.061	0.056	34	-0.020	-0.020
15	0.058	0.058	35	-0.018	-0.018
	0.060	0.057		-0.019	-0.019
16	-0.065	-0.064	36	-0-106	-0.105
17	-0.067	-0.067	37	-0.110	-0.111
<b>1</b> /	-0.066	-0.065	3,	-0.108	-0.108
•	•.				
18	-0.067	-0.067	38	-0.012	-0.012
19	-0.066	-0.067	39	-0.013	-0.014
	-0.067	-0.067		-0.013	-0.013

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а 1997 — Алар			TABLE XII	(CONTINUED)		
· · · · ·	GAGE	RUN NO	RUN NO	GAGE	RUN NO	RUN NO
	NUMBER	6-25	6-26	NUMBER	6-25	6-26
	40	-0.050	-0.050	60	0.120	0.121
	41	-0.051	-0.052	61	0.121	0.121
		-0.051	-0.051		0 • 121	0.121
	42	-0.034	-0.034	62	-0.021	-0.021
	43	-0.035	-0.035	63	-0.019	-0.019
· ;		-0•034	-0.034		-0.020	-0.020
	44	-0.008	-0.008	64	-0.104	-0.104
·	45	-0.011	-0.011	65	-0•111	-0.111
	an a	-0.010	-0.010		-0.107	-0.108
	46	0.002	0.002	66		
	47	-0.002	-0.003	67		
		0.000	-0.001			
	48	0.031	0.032	68	0.022	0.022
	49	0.032	0.032	69	0.020	0.020
		0.032	0.032		0.021	0.021
	50	-0.003	-0.003	70	-0.069	-0.066
	51	-0.006	-0.006	71	-0.064	-0.064
		-0.004	-0.005		-0.067	-0:065
	52	-0.065	-0.065	72	0.095	0.095
	53	-0.071	-0.071	73	0.097	0.097
		-0•068	-0.068		0.096	0.096
	54	0.105	0.105	74	-0.045	-0.045
	55	0.107	0.107	75	-0.048	-0.048
		0.106	0.106		-0.047	-0.047
	56	-0.025	-0.025	76	-0.063	-0.063
	57	-0.025	-0.025	77	-0.061	-0.061
		-0.025	-0.025		-0.062	-0.062
	58	-0.061	-0.061		· · ·	
	59	-0.061	-0.062			
		-0.061	-0.062			
		÷ .				
	•					
		•	· ·			

## TABLE XIII

STRAIN PER UNIT LOAD - F8

	GAGE	RUN NO	RUN NO	GAGE	RUN NO	RUN NO
*	NUMBER	6-11	6-12	NUMBER	6-11	6-12
			. – – – – – – – – – – – – – – – – – – –		•••	
	0	0.128	0.129	20	0.142	0.142
•	1	0.134	0.133	21	0.151	0.151
	· · · ·	0.131	0.131	ñ.e 4	0.147	0.146
			00101		00147	0-1-0
	2	0.124	0.123	22	-0-102	-0.102
	3	0.123	0.123	23	-0.097	-0.096
	-	0.123	0.123	20	-0.000	
		~~. <u>.</u>	00125		-0:099	-0.099
	Δ	0.116	0.115	24	-0.078	-0.078
	5	0.111	0.111	24		-0.076
		0.117	0.117	25	-0.077	-0.078
		00113	00113		-0.078	-0.077
	6	-0.105	-0.105	26	-0.085	-0.085
	7	-0.101	-0+101	27	-0.085	-0.085
		-0.103	-0.103		-0.085	-0.085
	8	-0.006	-0.006	28	0.014	0.014
	9	-0.006	-0.006	29	0.014	0.014
		-0.006	-0.006		0.014	0.014
	10	-0.021	-0.021	30	0.059	0.059
	11	-0.020	-0.021	31	0.060	0.059
		-0.020	-0.021		0.059	0.059
					_	
	12	0.018	0.017	32	-0.034	-0.034
	13	0.017	0.017	33	-0.033	-0.033
		0.018	0.017		-0.033	-0.033
	14	-0.028	-0.028	34	0.060	0.060
	15	-0.029	-0.028	35	0.057	0.057
		-0.028	-0.028	•	0.059	0.059
	16	0•084	0.084	36	0.054	0.054
	17	0.085	0.085	37	0,056	0.056
		0.085	0.084		0.055	0.055
				an a		
	18	0.052	0.051	38	0.119	0.118
	19	0.057	0.051	39	0.118	0 • 117
		0.055	0.051		0.118	0.118

GAGE	RUN NO	RUN NO	GAGE	RUN NO	RUN NO	
NUMBER	6-11	6-12	NUMBER	6-11	6-12	
40	0.133	0.133	60	-0.066	-0.066	
41	0.137	0.137	61	-0.066	-0.066	
	0.135	0.135		-0.066	-0.066	
42	-0.094	-0.094	62	0.035	0.035	
43	-0.091	-0.091	63	0.034	0.034	
3	-0.092	-0.093		0.034	0.034	
<i>7</i>	and the second sec					
44	-0.108	-0.105	64	0.071	0.071	
45	-0.106	-0.103	65	0.073	0.073	
	-0.107	-0.104		0.072	0.072	
					<del>-</del>	
46	-0.110	-0.110	66	-0.060	-0.060	
47	-0.109	-0.109	67	-0.059	-0.059	
	-0.110	-0.109		-0.060	-0.060	
						t
48	-0.003	-0.003	68	-0.007	-0.007	
49	-0.003	-0.003	69	-0.006	-0.006	
	-0.003	-0.003		-0.007	-0.007	
		· · .				
50	0.013	0.013	70	0.041	0.041	
51	0.015	0.015	71	0.039	0.039	
	0.014	0.014		0.040	0.040	
52	0.036	0.036	72	-0.047	-0.049	
53	0.039	0.038	73	-0.045	-0.046	
-	0.038	0.037		-0.046	-0.048	
54	-0.056	-0.056	74	0.089	0.089	
55	-0.055	-0.055	75	0.091	0.091	
	-0.055	-0.055		0.090	0.090	
56	0.046	0.046	76	0.040	0.037	
57	0.047	0.046	77	0.034	0.034	
	0.046	0.046		0.037	0.036	
	-					
58	0.040	0.040				
59	0.040	0.040				
-,	0.040	0.040	<b>^</b> .			

# TABLE XIV

STRAIN PER UNIT LOAD - F7 + F8

	GAGE	RUN NO	RUN NO	GAGE	RUN NO	RUN NO
	NUMBER	5-22	6-04	NUMBER	5-22	6-04
	0	0.085	0.083	20	0.113	0.110
	1	0.094	0.091	21	0.110	0•107
		0.090	0.087		0.112	0.109
	2	0.086	0.083	22	-0.062	-0.061
	, <sup>1</sup> 3	0.083	0.082	23	-0.051	-0.063
		0.085	0.082	• •	-0.055	-0.062
	4	0•089	0.083	24	-0.033	-0.033
	5	0.073	0.073	25	-0.036	-0.034
		0.081	0.078		-0.034	-0.034
	6	-0.069	-0.067	26	-0.098	-0.098
	7	-0.073	-0.070	27	-0.099	-0.099
		-0.071	-0.069		-0.099	-0.098
	8	-0.010	-0.009	28	0.051	0.050
	9	-0.010	-0.009	29	0.049	0.049
ر		-0.010	-0.009		0.050	0.050
	10	-0.011	-0.011	30	0.063	0.062
	11	-0.011	-0.011	31	0.065	0.065
		-0.011	-0.011		0.064	0.064
	12	0.018	0.019	32	-0.054	-0.053
	13	0.021	0.021	33	-0.053	-0.053
		0.020	0.020	• •	-0.053	-0.053
•	14	-0.047	-0.047	34	0.047	0.047
	15	-0.049	-0.049	35	0.045	0.044
		-0.048	-0.048		0.046	0.045
	16	0.067	0.067	36	0.079	0.079
	17	0.068	0.068	37	0.080	0.000
		0.067	0.068	· · ·	0.080	0.080
• •	18	0.069	0.069	38	0.061	0.061
	19	0.068	0.067	39	0.066	0.066
		0.069	0.068	н Н	0.063	0.062
,						

GAGE	RUN NO	RUN NO	GAGE	RUN NO	RUN NO
NUMBER	5-22	6-04	NUMBER	5-22	6-04
<b>AO</b>	0.080	0.000	<b>FO</b>		0.001
40	0.089	0.088	60		-0.086
41	0.089	0.088	61		-0.087
, 1	0.089	0.088			-0.087
42	-0.035	-0.035	62	· ·	0.051
43	-0.042	-0+041	63		0.050
	-0.039	-0.038	· .		0.050
44	-0.052	-0.052	64		0.090
45	-0.057	-0.055	65		0.093
-	-0.055	-0.054			0.092
a se	•				
46	-0.054	-0.055	66		-0.068
47	-0.060	-0.058	67		-0.066
	-0.057	-0.057	•		-0.067
48	-0.017	-0.017	68		0.015
49	-0.018	-0.017	69		0.015
	-0.017	-0.017			0.015
50	0.012	0.011	70		0.044
51	0.012	0.010	70		0.043
5.	0.012	0.011	• •		0.043
	00012	00011			
52	0.047	0.047	72		-0.070
53	0.050	0.050	73		-0.071
. · .	0.049	0.048			-0.070
54	-0.071	-0.071	74		0.077
55	-0.073	-0.073	75		0.078
	-0.072	-0.072			0.077
56	0.052	0.053	76		0.056
57	0.053	0.053	77		0.052
~	0.052	0.053	••		0.054
58	0.052	0.051			
59	0.052	0.052			
	0.052	0.052			

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#### VITA

#### Everett L. Cook

#### Candidate for the Degree of

#### Doctor of Philosophy

#### Thesis: AN ANALYTICAL AND EXPERIMENTAL INVESTIGATION OF A MONOLITHIC TRAPEZOIDAL SHEAR PANEL SUBJECTED TO MECHANICAL LOADING

Major Field: Mechanical Engineering

Biographical:

- Personal Data: Born at Mounds, Oklahoma, September 9, 1927, the son of Peter Everett and Nona Mae Cook.
- Education: Attended grade schools in Skiatook, Tulsa, Drumright, and Miami, Oklahoma and Baxter Springs, Kansas; graduated from Miami High School in 1945; received Associate in Arts degree from Spartan College in June, 1950; received Bachelor of Science in Aeronautical Engineering from Wichita State University in May, 1954; received Master of Science in Aeronautical Engineering from Wichita State University in May, 1958; completed requirements for the Doctor of Philosophy degree in May, 1967.
- Professional Experience: Designer, Technical Training Aids, Inc., Tulsa, Oklahoma, 1950; Instructor in Aeronautical Engineering, Spartan College, 1951; Stress Analyst, Beech Aircraft Corporation, 1951 to 1953; Associate Professor of Aeronautical Engineering, Wichita State University, 1953 to present; Director of Digital Computing, Wichita State University, 1964 to present.
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