

REFINEMENT OF A SINGLE FACILITY  
ELECTRONIC QUEUEING SIMULATOR  
AND THE DEVELOPMENT OF AN  
AUGMENTED QUEUEING  
SYSTEM SIMULATOR

By

CHARLES LOUIS BURFORD

Bachelor of Science  
Texas Technological College  
Lubbock, Texas  
1954

Master of Science  
Oklahoma State University  
Stillwater, Oklahoma  
1962

Submitted to the Faculty of the  
Graduate College of the  
Oklahoma State University  
in partial fulfillment of  
the requirements for  
the Degree of  
DOCTOR OF PHILOSOPHY  
July, 1966

OKLAHOMA  
STATE UNIVERSITY  
LIBRARY

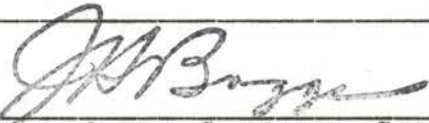
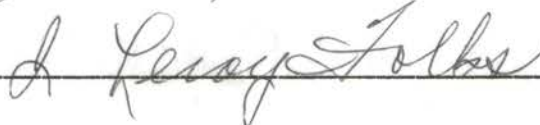
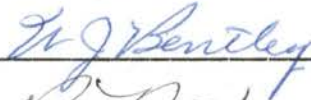
JAN 26 1967

REFINEMENT OF A SINGLE FACILITY  
ELECTRONIC QUEUEING SIMULATOR  
AND THE DEVELOPMENT OF AN  
AUGMENTED QUEUEING  
SYSTEM SIMULATOR

Thesis Approved:



Thesis Adviser



Dean of the Graduate College

627003

## PREFACE

This work was undertaken with the objective of developing an augmented queueing system simulator which would be useful as a classroom demonstration and teaching device and as a research tool. The system which has been designed, constructed, and tested is herein presented.

The system described is capable of generating electrical impulses at random time intervals with preset distributions and parameters, capable of using these impulses to simulate the operation of a complex queueing system, and is capable of providing both a visual and a permanent display of the data thus generated.

The author is deeply indebted to many individuals and organizations for their invaluable assistance. In particular, appreciation is expressed to Dr. Paul Torgersen, under whose direction this work was done, for his guidance, assistance, and patience during the entire course of this work. Appreciation is also expressed to Dr. George F. Schrader, Dr. Buck F. Brown, and Dr. P. M. Ghare for their assistance in the planning, design, and testing stages; to Mr. Roger Hale, Mr. John Staggs, Mr. Richard Carmon, and Mr. James Gibbs for their assistance in the construction stage; to Miss Velda Davis for her help and typing; and to

my family for "letting me do it."

Indebtedness to the following organizations is also acknowledged: Oklahoma State University for making this work possible, the National Science Foundation for providing funds for time and equipment, and Texas Technological College for permitting the use of various data recording devices.

## TABLE OF CONTENTS

Chapter	Page
I. INTRODUCTION . . . . .	1
II. CONSTRUCTION OF RANDOM TIME INTERVAL GENERATOR SECTIONS . . . . .	4
III. CONSTRUCTION OF QUEUEING SIMULATOR . . . . .	22
IV. OUTPUT AND USE . . . . .	32
V. DATA COLLECTION AND MODIFICATION . . . . .	34
VI. EVALUATION PROCEDURE AND DATA . . . . .	49
VII. EVALUATION OF DATA . . . . .	55
VIII. CONCLUSIONS . . . . .	66
BIBLIOGRAPHY . . . . .	70
APPENDIX A - SHOP MADE PARTS . . . . .	71
APPENDIX B - EVALUATION DATA . . . . .	75
APPENDIX C - CUMULATIVE DISTRIBUTION VALUES . . . . .	103

## LIST OF FIGURES

Figure	Page
1. Power Supply Section . . . . .	6
2. Constant Impulse Section . . . . .	9
3. Queue Display Section . . . . .	12
4. "RANDOM" Time Interval Section . . . . .	16
5. Queueing Simulator . . . . .	27
6. Completed Simulator Mounted in Cabinet . . . . .	30
7. Back View of Simulator Removed From Cabinet . . . . .	30
8. Front View of Simulator Removed From Cabinet . . . . .	30
9. Motion Picture Camera Film Strip From Eight Millimeter . . . . .	35
10. Film Strip From Sixteen Millimeter Motion Picture Camera . . . . .	37
11. "RANDOM" Time Interval Section . . . . .	40
12. Modified Queue Count Section . . . . .	43
13. A Typical Data Recording Session With the Oftner Dynagraph . . . . .	45
14. A Typical Two Channel Recording . . . . .	46
15. A Typical Three Channel Recording . . . . .	47
16. Resistance-Time Curves . . . . .	52
17. Cam Disk . . . . .	72
18. Motor Mount . . . . .	73
19. Potentiometer Mounting Bracket . . . . .	74
20. Support Bracket . . . . .	74

Figure	Page
21. Uniform Distribution Data - Arrival Up . . . . .	76
22. Uniform Distribution Data - Arrival Down . . . . .	78
23. Uniform Distribution Data - Service Down . . . . .	80
24. Uniform Distribution Data - Service Up . . . . .	82
25. Similar Distribution Data . . . . .	84
26. Exponential Distribution Data . . . . .	87
27. Queue Length . . . . .	94
28. Compiled Data - Number of Occurrences of Resistor Circuits . . . . .	99
29. Cumulative Distribution Values . . . . .	104

## CHAPTER I

### INTRODUCTION.

The purpose of this project has been to refine and improve a single station queueing simulator and to develop means by which several such units could be connected together in order to simulate a complex or augmented queueing system. The final queueing simulator was to be a refined model of a single station queueing simulator designed and constructed within the School of Industrial Engineering and Management, with the support of the Office of Engineering Research, Oklahoma State University.

A queue or waiting line is literally what the name suggests - a queue or line formed when moving units encounter an obstruction causing them to be delayed before they can proceed. It is an indication of the congestion that occurs when a flow system encounters a restriction or "bottleneck." A queue or waiting line is formed by the collection of individual units of the flow system being temporarily detained at the bottleneck. Lines formed by people waiting for seats at a motion picture theater or by automobiles waiting for traffic lights to change are familiar examples.



Queueing theory and the analysis of queues are needed in many industrial applications, such as communication and transportation networks as well as production scheduling. Telephone systems can be designed more economically when the required circuit capacity to carry traffic, with a predetermined maximum delay period is known. A similar situation exists in highway planning. The determination of the number of aircraft arrivals and departures a given airfield can accommodate per unit time is another example of the application of queueing theory. Many problems in operations research require a fundamental knowledge of the principles of queueing theory.

It was felt that, by providing a tool whereby queueing lines could be observed and studied without having to resort to the time consuming procedure of observing industrial situations or the laborious procedures involved in hand simulation, student interest in queueing theory could be increased within the classroom by the instructor and more students could learn to recognize situations in which queueing theory can be applied.

The simulator will permit the student to control various statistical parameters such as the arrival and service distributions as well as the mean service time and mean arrival time, in order to experience the effect of changing these parameters on the queue. By connecting two or more simulators together, complex queueing situations may be

demonstrated to show the effect of paralleled or series services with either similar or different parameters.

The queueing simulator is quite simple in concept. It has its nucleus, two "random" time interval generators. These "random" time interval generators are connected to an add and subtract stepping relay which displays the queue length.

Augumented or complex queues can be formed by combining either the individual "random" time interval generators or the simple queueing simulators according to the desired complexity of the queue.

## CHAPTER II

### CONSTRUCTION OF RANDOM TIME INTERVAL GENERATOR SECTIONS

The single station queueing simulator is constructed from five basic sections: (1) power supply section, (2) constant impulse section, (3) queue display section, (4) and (5) two "random" time interval generator sections. Although the power supply section and the constant impulse sections are required portions of the "random" time interval generator, they are listed as separate sections due to the fact that they are shared by the two "random" time interval generators.

The power supply section provides for the power requirements of the various other sections. It provides 110 volts alternating current, 6.3 volts alternating current, and 9 volts direct current (these voltages will vary according to the line voltage to the power supply) for the other sections. This section contains the parts listed in Parts List 1, and is wired according to Figure 1.

Leads A and B connect the power supply through the Power plug (P1-1) to an outside source of power (110 volts alternating current). Lead C provides the 110 volt

PARTS LIST 1  
Power Supply Section

<u>Part No.</u>	<u>Part Description</u>	<u>Specifications</u>	<u>Manufacturer</u>	<u>Mfg. Type</u>
C-1	Capacitor	.05mfd. 400VDC	Cornell-Dublier	PM455
C-2	Power Storage Capacitor	100mfd. 150VDC	Mallory	TC493
P1-1	Power Plug	2 wire polarized	Cinch Jones	P302-AB
S-1	Main Control Switch	DPDT	Cutter-Hammer	8373K8
SR-1	Silicon Rectifier	750ma 600PIV	Texas Instruments	IN547
TR-1	Transformer	6.3VAC 3A	Stancor	P6466

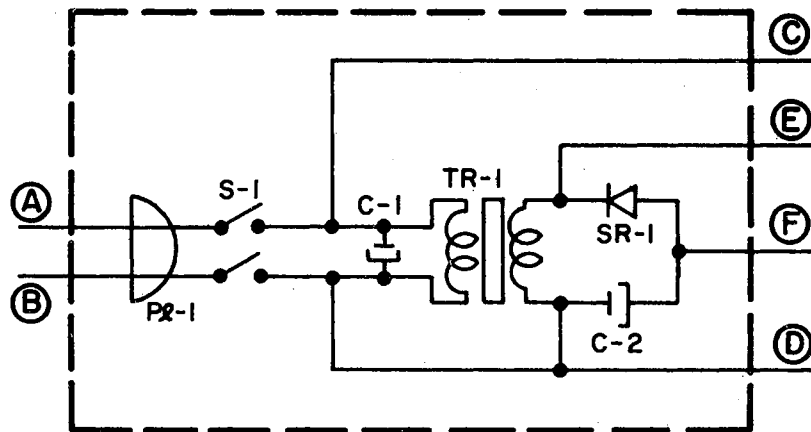


Figure 1. Power Supply Section

alternating current required by the outer sections. Lead D serves as a common return (ground) to the power supply for all circuits. Lead E provides alternating current stepped down by the transformer (TR-1) to about 6.3 volts. Lead F provides the stepped down voltage (about 9.3 volts direct current) after it has been rectified by the silicon rectifier (SR-1) and smoothed by the power storage capacitor (C-2). The main control switch (S-1) controls the flow of power to the entire unit. The capacitor (C-1) across the power input lines serves to filter undesirable stray current and to minimize arcing at various relay contact points.

The constant impulse section provides five impulses per second to step stepping relays in the "random" time interval generators. This section contains the parts listed in Parts List 2, and is wired according to Figure 2.

Lead C provides 110 volts alternating current from the power supply to drive the motor. Lead D provides a return path to the power supply for the alternating current. Lead G provides five impulses of 110 volt alternating current per second to the stepping relays in the "random" time interval generator. The cam disk (CD-1) is fitted on the shaft of the motor (M-1) so as to depress the arm of the microswitch (MS-1). The capacitor (C-3) smooths the current flow introduced by the stepping relays in the "random" time interval generator.

## PARTS LIST 2

## Constant Impulse Section

<u>Part No.</u>	<u>Part Description</u>	<u>Specifications</u>	<u>Manufacturer</u>	<u>Mfg. Type</u>
C-3	Capacitor	.47mfd. 600VDC	Mallory	PVC60+7
CD-1	Cam Disk	Shop made	Detail 1	
MT-1	Motor Mount	Shop made	Detail 2	
M-1	Motor	60RPM 115VAC 60 cycle	Hurst	SM-60RPM
MS-1	Microswitch	SPST	Micro Switch Corp.	6RL-2
S-5	Switch	SPST	Arrow-Hart and Hegeman	20994-BF

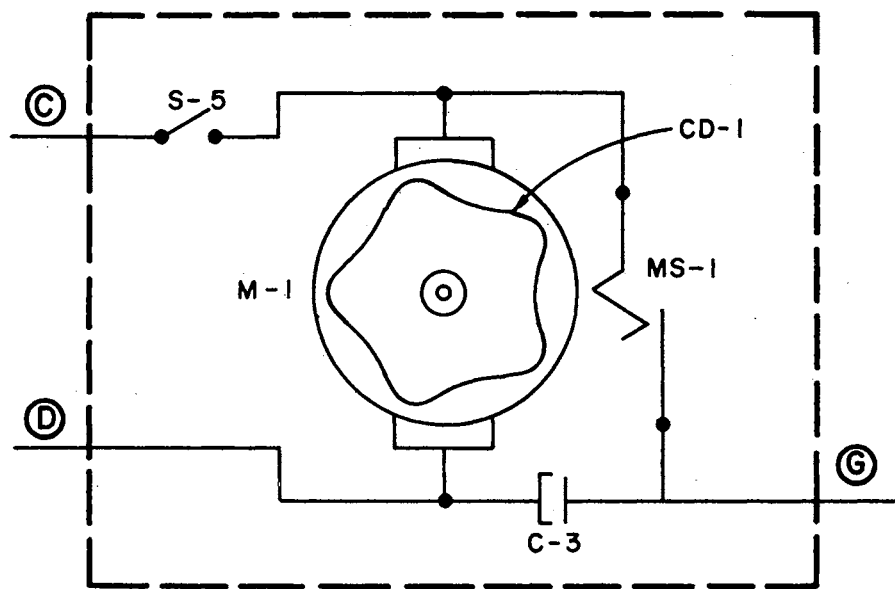


Figure 2. Constant Impulse Section



The queue display section provides a means of displaying the queue visually and a means of controlling the "random" time interval generator used to simulate services in the queueing system to prevent a service from occurring when there is no unit in the service facility. The queue display section consists of the parts listed in Parts List 3, and is wired according to Figure 3.

Lead C provides 110 volts alternating current from the power supply. Lead D provides a return path to the power supply to complete various portions of the circuit. Lead H is connected to the "random" time interval generator which simulates arrivals and causes one to be added to the queue count, whenever an impulse is generated by the arrival simulator. Lead I is connected to the "random" time interval generator which simulates services and causes one to be subtracted from the queue count whenever an impulse is generated by the service simulator. Lead J is connected to a control relay in the "random" time interval generator which simulates services to provide current to indicate by a light (L-21) that there is no unit in service, if no unit is in service. Lead K is connected to a control relay in the "random" time interval generator which simulates services to provide current to indicate by a light that a unit is in service, if a unit is in service. Lead L provides current from a contact point of the add and subtract relay (AS-R1-1) whenever the relay wippen arm is at position zero.

## PARTS LIST 3

## Queue Display Section

<u>Part No.</u>	<u>Part Description</u>	<u>Specifications</u>	<u>Manufacturer</u>	<u>Mfg. Type</u>
AS-R1-1	Add and Subtract Relay	4OPT 110VAC	Guardian	1R-RAS
C-4,C-5	Capacitors	.47mfd. 600VDC	Mallory	PVC 6047
L-1 to L-20	Neon Light Units	Clear	Dialco	5240 x H Type H995
L-21	Neon Light Unit	Green	Dialco	5240 x H Type 932
L-22	Neon Light Unit	Red	Dialco	5240 x H Type 991
S-2	Switch	SPST	Arrow-Hart and Hegeman	20994-BF

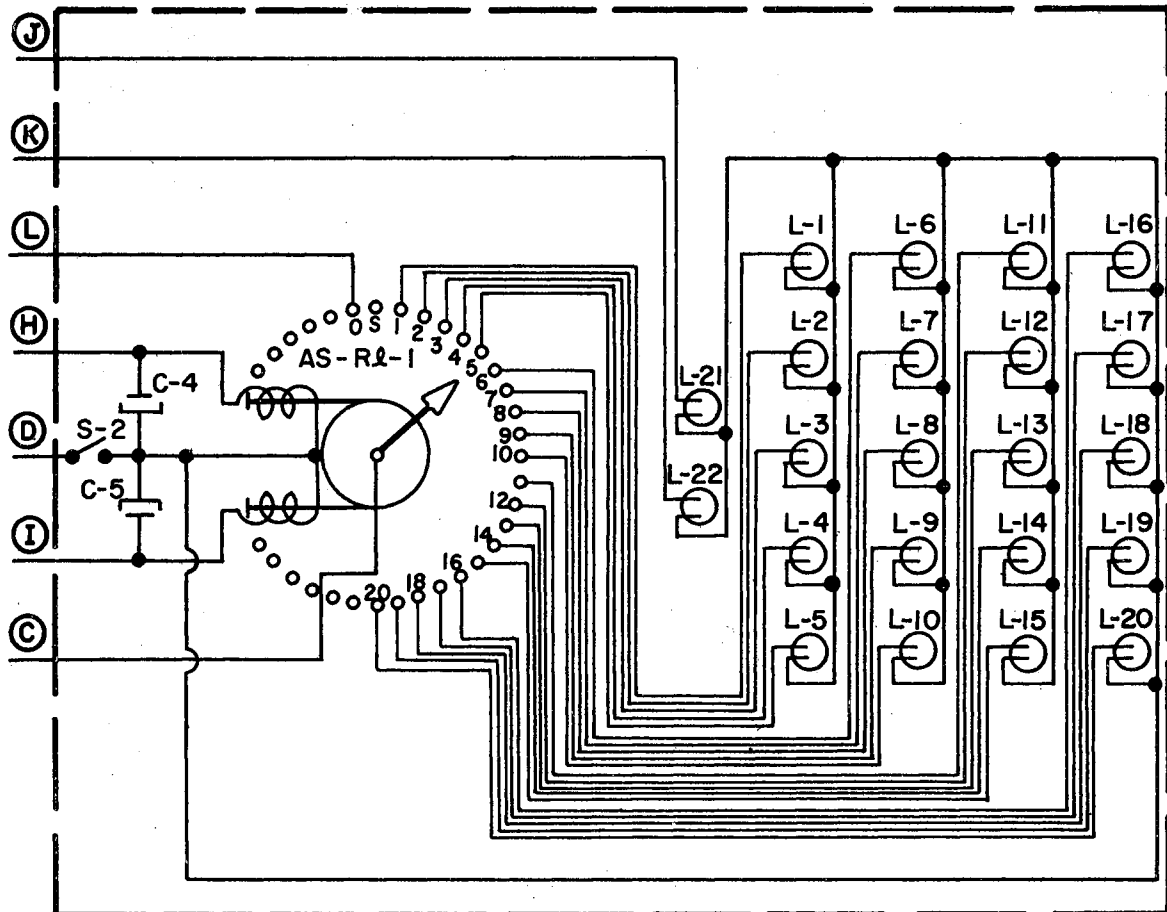


Figure 3. Queue Display Section

The two capacitors C-4 and C-5 smooth the current flow introduced by the add and subtract relay. One light (L-21) is lighted whenever there is no unit available to be serviced. A light (L-22) is lighted whenever there is a unit in service. The other twenty lights are wired so that as a queue forms from time-to-time the number of units in the queue will be indicated by a light being lighted in a position to correspond to the number in the queue. Thus, when the system is empty, only light No. 21 will be lighted, if there is only one unit in the system (in service) only light No. 22 will be lighted, if there is a queue of length  $x$ ,  $(x+1)$  in the system, light No. 22 and light No.  $x$  will be lighted. Switch (S-2) may be used to prevent the count from stepping and the lights from lighting when the simulator is used as part of an augmented system.

The two "random" time interval generator sections serve as the source of electrical impulses which step the count. One of the "random" time generators is attached to the add side of the counter and is the arrival simulator. The other is attached to the subtract side and is the service simulator; as these units are nearly identical, they will be discussed as one, with their differences being identified when appropriate. A "random" time interval section consists of the parts listed in Parts List 4 and is wired according to Figure 4.

Lead C is connected to the power supply section and

## PARTS LIST 4

"Random" Time Interval Generator  
Section

<u>Part No.</u>	<u>Part Description</u>	<u>Specifications</u>	<u>Manufacturer</u>	<u>Mfg. Type</u>
C-6	Capacitor	80mfd. 350VDC	Mallory	PF 128
C-7	Timing Capacitor	50mfd. 25VDC	Mallory	TC 29
C-8	Capacitor	10mfd. 25VDC	Mallory	TC 22
C-9	Capacitor	.05mfd. 400VDC	Cornell-Dublier	PM 455
L-R1-1	Latching Relay	DPDT	Guardian	670G115
PMP	Potentiometer Mounting Panel	Shop made	Detail 4	
P-1 to P-80	Potentiometers	100K $\Omega$ Linear Taper	Mallory	SU 41
R-1	Resistor	10K $\Omega$ 1 watt		
R-2	Resistor	47K $\Omega$ 2 watts		
R-3	Resistor	330 $\Omega$ 2 watts		
R1-1	Relay	10,000 $\Omega$ Plate Current	Guardian	200MS 4PDT

## PARTS LIST 4 (Continued)

<u>Part No.</u>	<u>Part Description</u>	<u>Specifications</u>	<u>Manufacturer</u>	<u>Mfg. Type</u>
R1-2	Relay	115VAC	Guardian	500MS 4PDT
S-3,S-4	Switch	SPST	Arrow-Hart and Hegeman	20994-BF
S-R1-1 S-A1-2	Stepping Relay	40 Point	Guardian	IRPC
SR-2,SA-3	Silicon Rectifier	750ma 600VIC	Texas Instruments	IN 547
T-1	Electron Tube		RCA	2D21
TJ-1 to TJ-3	Tip Jack		G-E Electronics	Type 33-212
TS-1	Tube Socket	7 Pin	Elco	235PHSPDT

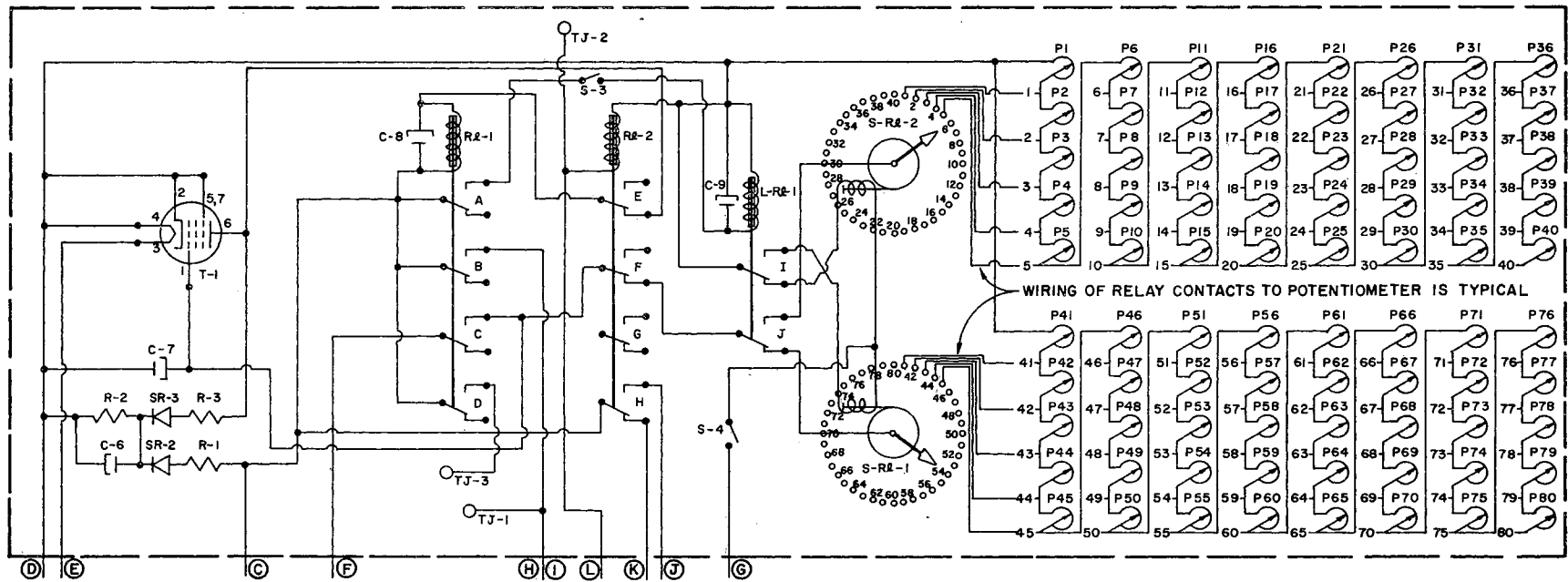


Figure 4. "RANDOM" Time Interval Section

provides 110 volt alternating current. Lead D is connected to the power supply section and serves as a common return (ground) for all circuits. Lead E is connected to the power supply section and furnishes 6.3 volts alternating current to the tube to heat its cathode. Lead F is connected to the power supply section and furnishes about 9.3 volts direct current to charge the timing capacitor (C-7) in the resistance-capacitance timing circuit. Lead G is connected to the output of the constant impulse section to provide five stepping impulses per second to the resistance stepping relays. The toggle switch (S-4) is provided to permit control of the resistance stepping relays so that a fixed resistance circuit can be used if desired. Lead H (in the arrival simulator) or Lead I (in the service simulator) provides impulses to the queue display section to step the count whenever a service or an arrival occurs. A means of controlling the output of the "random" time interval generator sections to prevent them from stepping the queue count is provided in the tip jacks (TJ-2S in the service simulator, and TJ-2A in the arrival generator).

This means can provide control either from another simulator (in an augmented queueing system) or any auxiliary device; the input must come from a source connected to the same power line as lead A in the power supply section. Lead L (in the service simulator only) is connected to the service facility empty contact of the queue display section



counting relay to prevent a service from occurring when no unit is in service. In the service simulator, current from lead L would close the service control relay (R1-2S). When this relay is closed, contact HS allows current to flow to lead J. Lead J is connected to the service facility empty light in the queue display sections. When the service control relay (R1-2S) is open, current flows through contact HS to lead K. Lead K is connected to the service facility occupied light (L-22) in the queue display section. Relay R1-1 provides an impulse source to other units or equipment through a tip jack (TJ-3). A means of externally stepping the queue count is provided through a tip jack (TJ-1).

The "random" time interval generator operates as follows. Whenever the voltage across the control capacitor (C-7) falls below a certain level, the control tube (T-1) will permit current to flow through contact E of the control relay (R1-2), if this relay is in its normally open position, to the coil of the impulse relay (R1-1). The capacitor (C-8) across the coil of this control relay (R1-1) smooths the current flow to insure reliable relay closure. When the impulse relay (R1-1) closes, it permits current to flow from lead F through contact C to recharge the control capacitor (C-7) and cut off the flow of current through the control tube (T-1); it permits current to flow from lead C through contact D to TJ-3, through

contact B to lead H or lead I to one of the stepping relays in the queue display section to step the queue count, and through contact A to step the latching relay (L-R1-1) to switch stepping relays and resistor circuits. When the control relay (R1-2) is open, as it normally is, current flows from the control capacitor (C-7) through its contact F to contact the latching relay (L-R1-1) to be directed to one of the banks of potentiometers to be dissipated as heat to discharge the control capacitor (C-7). The current to be dissipated, which flows through contact J of the latching relay (L-R1-1), will be directed by contact arm of whichever one of the two stepping relays (S-R1-1 or S-R1-2) that is stopped. This current will then flow through a number of the potentiometers (the number is determined by the location in which the stepping relay is stopped) to discharge the control capacitor (C-7). During the time that the current flows through one stepping relay and its corresponding potentiometers, the other stepping relay is being stepped by current from the constant impulse section which is directed to it through contact I of the latching relay (L-R1-1). Whenever the latching relay (L-R1-1) is energized, it switches the control capacitor discharge current to the stepping relay which has just previously been stepping and stops this relay from stepping. It also starts stepping the stepping relay which has just previously been controlling the capacitor

discharge current. This switching action permits the system to "randomly" select the number of potentiometers to be in series in the resistance-capacitance circuit at any given time. This in turn generates the random time intervals between impulses.

The distribution of time intervals is determined by the adjustment of the potentiometers. In the long run, either of the stepping switches will stop at each of its forty positions approximately the same number of times. This provides a rectangular distribution as far as the number of potentiometers in the circuit are involved. The number of potentiometers is, of course, a discrete number.

Forty positions provide enough points to approximate a continuous distribution for most purposes. One is able to adjust the distribution of time interval lengths by adjusting the various potentiometers. If potentiometer number one is adjusted to yield some desired time interval and all other potentiometers are adjusted to zero resistance, then all time intervals will be very nearly the same. Potentiometer number one should never be set to zero resistance as this will cause a direct short across the terminals of the control capacitor (C-7) and the direct current portion of the power supply. If all potentiometers are adjusted to the same resistance, then the difference between the time intervals generated by adjacent potentiometers will be equal. In adjusting the

potentiometers to generate a series of time intervals from different times, one must remember that the current flows through the potentiometers in series, and, therefore, that one is constructing a cumulative distribution of resistance and that the distribution of the stepping relay contacts is rectangular.

## CHAPTER III

### CONSTRUCTION OF QUEUEING SIMULATOR

The components described in Chapter II may be assembled into either of two different units. With one of the "random" time interval sections, a "random" time interval generator may be formed. This "random" time interval generator can be used to provide electrical impulses to trip a motion camera to make a filmed work sampling study or to indicate points for random sampling. The omission of the two sections mentioned is the only difference between the "random" time interval generator and the queueing simulator.

The queueing simulator utilizes all of the sections described in Chapter II and some additional hardware (see Parts List 5). It is wired as shown in Figure 5. It should be noted that the part number of each part in the service simulator section is followed by an S and that the part numbers of each part in the arrival simulator is followed by an A.

The lead (L) from the service facility empty contact (O) of the add and subtract relay (AS-R1-1) in the queue display section is connected to the service control relay

## PARTS LIST 5

## Queueing Simulator Parts List

<u>Part No.</u>	<u>Part Description</u>	<u>Specification</u>	<u>Mfg.</u>	<u>Mfg. No.</u>	<u>No. Req. for Simulator</u>
AS-R1-1	Add and Subtract Relay	40Pt. 115VAC	Guardian	12-RAS	1
C-1,C-9A C-9S	Capacitor	.05mfd. 400VDC	Cornell- Dublier	PM455	3
C-2	Capacitor Power Storage	100mfd. 150VDC	Mallory	TC493	1
C-3,C-4, C-5	Capacitor	.47mfd. 600VDC	Mallory	PVC6047	3
C-6A,C-6S	Capacitor	80mfd. 350VDC	Mallory	PF128	2
C-7A,C-7S	Timing Capacitor	50mfd. 25VDC	Mallory	TC29	2
C-8A,C-8S	Capacitor	10mfd. 25VDC	Mallory	TC22	2
CAB-1	Cabinet	12"H x 14 <sup>1</sup> / <sub>8</sub> "L x 18"D	Bud	WA-1544	1
CHA-1	Chassis	3H x 13L x 17D	Bud	AC-420	1
L-1 to L-20	Neon Lamps	Clear	Dialco	5240 x H Type H995	20

## PARTS LIST 5 (Continued)

<u>Part No.</u>	<u>Part Description</u>	<u>Specification</u>	<u>Mfg.</u>	<u>Mfg. No.</u>	<u>No. Req. for Simulator</u>
L-21	Neon Lamp	Green	Dialco	5240 x H Type 932	1
L-22	Neon Lamp	Red	Dialco	5240 x H Type 991	1
L-R1-1	Latching Relay	DPDT	Guardian	670 6115	1
M-1	Motor	60RPM 115 60Cy	Hurst	SM 60RPM	1
MS-1	Microswitch	SPS4	Micro Switch Corp	GRL-2	1
P-1A to P-80A P-1S to P-80S	Potentiometers	100K $\Omega$ linear taper	Mallory	SU-41	160
P1-1	Power Plug	2 wire Polarized	Cinch Jones	P302-AB	1
R-1A,R-1S	Resistor	10K $\Omega$ 1 Watt			2
R-2A,R-2S	Resistor	47K $\Omega$ 2 Watt			2
R-3A,R-3S	Resistor	330 $\Omega$ 2 Watt			2
R1-1A, R1-1S	Plate Relay	10,000 $\Omega$ , 4PDT	Guardian	200MS	2
R1-2A, R1-2S	Relay	115VAC, 4PDT	Guardian	500MS	2

## PARTS LIST 5 (Continued)

<u>Part No.</u>	<u>Description</u>	<u>Specification</u>	<u>Mfg.</u>	<u>Mfg. No.</u>	<u>No. Req. for Simulator</u>
S-1	Switch	2DPT	Cutter-Hammer	8373 K8	1
S-2,S-3A, S-3S,S-4A, S-4S,S-5	Switch	SPST	Arrow-Hart and Hegeman	20994-BF	6
SR-1,SR-2A SR-2S, SR-3A, SR-3S	Silicon Rectifier	750ma 600PIV	Texas Instruments	IN547	5
S-R1-1A S-R1-1S S-R1-2A S-R1-2S	Stepping Relay	40Pt. 115VAC	Guardian	IR-PC	4
T-U,T-1S	Tube	7 Pin	RCA	2D21	2
TJ-1A to TJ-3A TJ-1S to TJ-3S	Tip Jack		G-E Electronics	Type 33-212	6
TR-1	Transformer	6.3VAC3A	Stancor	P6466	1
TS-1A,TS-1S	Tube Socket	7 Pin	Elco	235 PHSPDT	2
CD-1	Cam Disk	See Figure 17	Shop made		1
MT-1	Motor Mount	See Figure 18	Shop made		1



## PARTS LIST 5 (Continued)

<u>Part No.</u>	<u>Description</u>	<u>Specification</u>	<u>Mfg.</u>	<u>Mfg. No.</u>	<u>No. Req. for Simulator</u>
SB-1	Support Bracket	See Figure 20	Shop made		2
PMP-1A PMP-1S	Potentiometer Mounting Panel	See Figure 19	Shop made		2

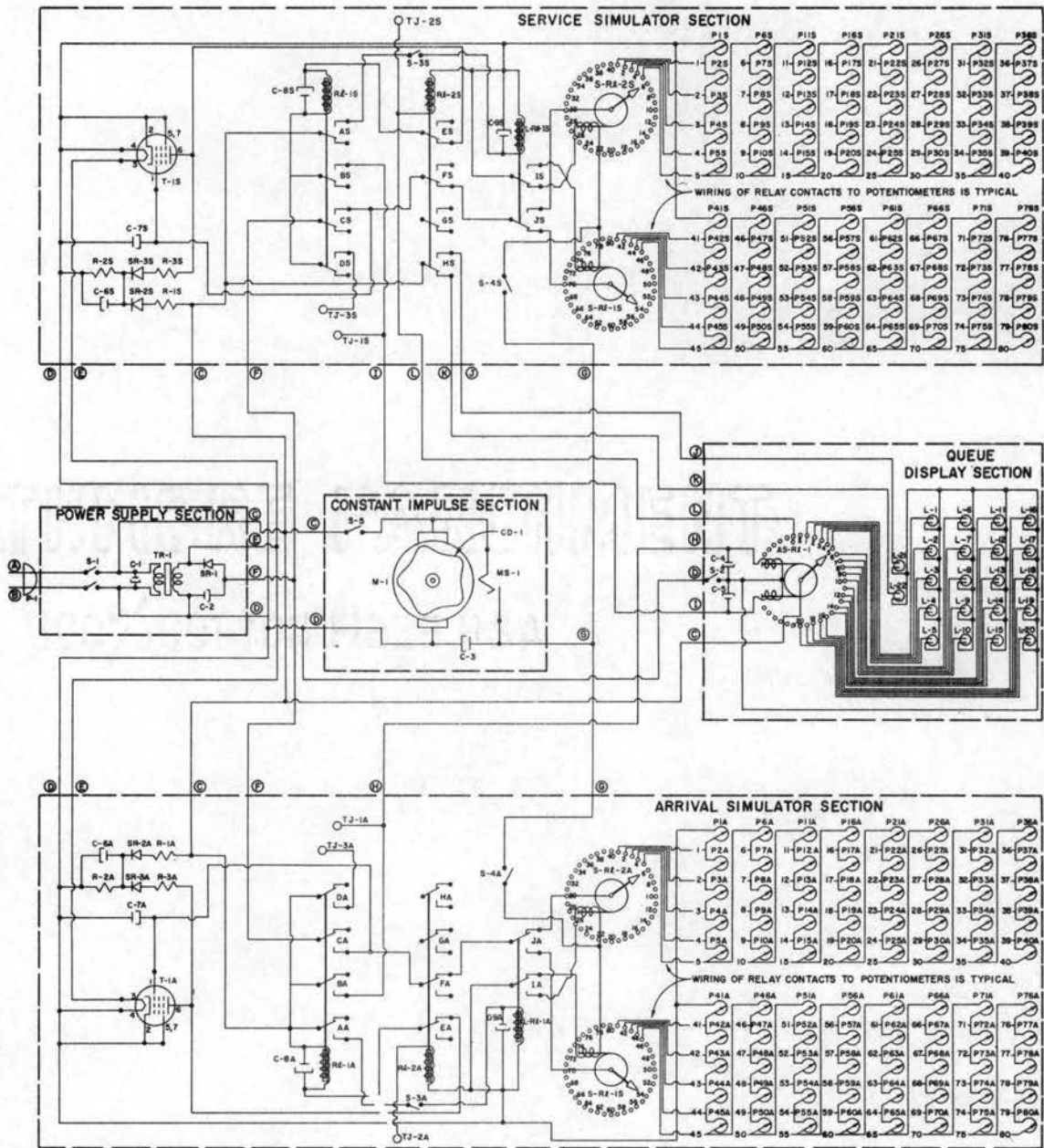


Figure 5. Queuing Simulator

(R1-2S) so that this relay will open and prevent a service impulse from occurring whenever no unit is present for servicing. This also provides current to flow through lead (J) to light (L-21) to indicate that the service facility is not occupied. When the service control relay (R1-2S) is not closed, current flows through lead (K) to light (L-22) to indicate that the service facility is occupied.

The power plug (P1-1) is of a polarized type to insure that inputs to the unit through the various tip jacks to either control the queue display section or either of the simulator sections matches the polarity of the current needed. It is intended that an external junction box will be constructed which would connect to a standard wall outlet (115AC) and provide as many leads as there are queueing simulators to be interconnected. One should note that the leads to the various tip jacks can all be followed to a common point (prong A of the power plug), and that any input to these jacks should come from the same line (or a line connected to it), or that any output from these jacks (TJ-3A or 3S) should go to a line of like nature.

The line switches can be used to vary the operation of the various components of the system. The power switch (S-1) is simply the main ON-OFF switch; in the OFF position it breaks both power lines to completely isolate the unit. Switch (S-2) controls the common power line to the

add and subtract relay (AS-R1-1) and the display lights in the queue display section to deactivate the queue display section when the unit is being used to supply impulses to either another unit or to some unit requiring randomly timed impulses. The two S-3 switches (S-3A and S-3S) may be used to prevent the latching relays (L-R1-1A and L-R1-1S) from acting, and hence to prevent the normal switching of the stepping relays (S-R1-1S, S-R1-2S, S-R1-1A, and S-R1-2A). This will permit either the service simulator section or the arrival simulator sections or both to operate as constant time interval sections. However, even with this switch open, the stepping switch not in circuit will continue to step. Switches (S-4A and S-4S) may be opened to break the common return line to prevent this stepping action. If no random impulses are needed, the constant impulse section can be turned off by opening switch S-5. The use of these various switches will permit a maximum flexibility and, at the same time, the operation of only the necessary section components.

Figure 6 shows a completed simulator mounted in its cabinet, with the queue display lights and some of the control switches on the front panel. Figure 7 shows the back of a completed simulator which has been removed from its cabinet, with its front panel removed. To be noted is the mounting of the stepping relays which are connected to the potentiometers (two are inverted and hung from one of

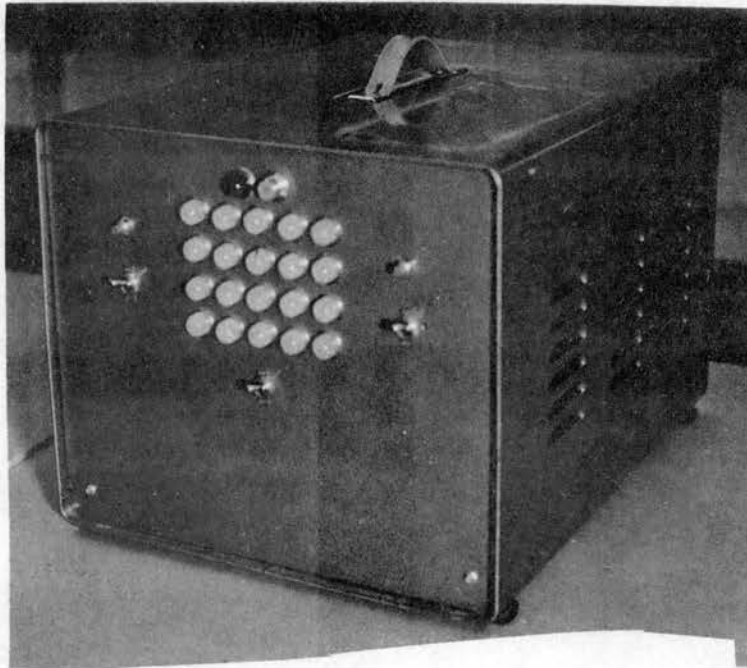


Figure 6. Complete Simulator  
Mounted in  
Cabinet

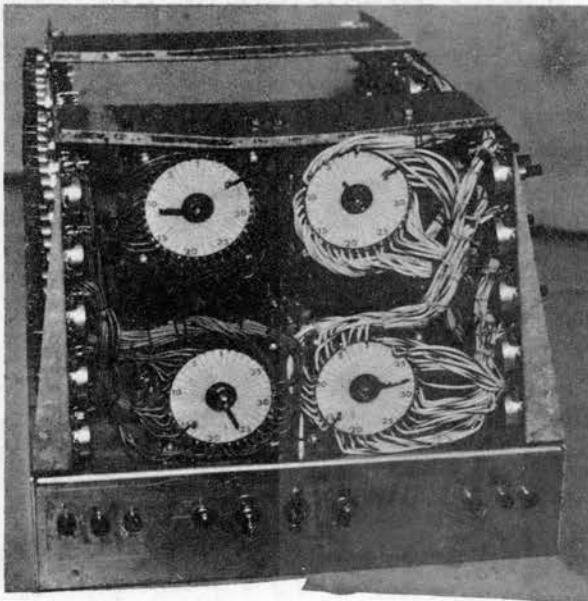


Figure 7. Back View of Simulator  
Removed From Cabinet

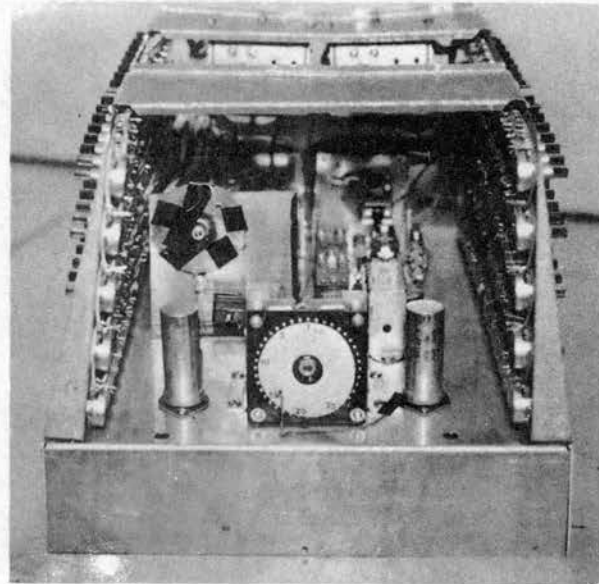


Figure 8. Front View of Simulator  
Removed From Cabinet

the support brackets), and switches, tip jacks, and power plug which are mounted on the chassis. Figure 8 shows the front of a completed simulator which has been removed from its cabinet, with its front panel removed. Note the add and subtract stepping relay which will have the leads to the queue display lights connected to it and the cam disk (with black tape on it) which is mounted on the motor shaft (motor hidden) and on the motor mount. Also, to be noted are the potentiometer mounting panels with the potentiometers mounted on them. No chassis layout is provided due to the fact that the layout is not critical. The detail drawings of the shop made parts are shown in Appendix A.

## CHAPTER IV

### OUTPUT AND USE

The primary output of the queueing simulator described previously is in the form of a visual display. This display provides a means for students to "observe" the queueing system and to acquaint themselves with it. By varying the potentiometers to alter the arrival and service parameters or by switching one random time interval generator to produce constant time intervals, the student can observe the effects on the system of various parameter changes.

Provision is made through the various tip jacks to interconnect more than one unit so that the student can observe the effects of multiple service channels or arrival channels.

An alternate form of output is provided by the tip jacks. This output is in the form of electrical impulses from the positive (+) side of the power supply (110 VAC). This output can be taken from either the arrival simulator or the service simulator and may be utilized in various ways. It can be used to provide the input to an inventory system simulator, used directly with a recorder to record

a series of random time intervals, or it can be used to trigger a camera for work sampling studies.

If an output other than 110 VAC is desired, a lead connected directly to a power source of the desired characteristics can be substituted for the lead connected to relay contact D of relay R1-1. The desired output will then be available through TJ-3. Both 6 VAC and 6 VDC are available from the power supply section (through leads E and F, respectively).



## CHAPTER V

### DATA COLLECTION AND MODIFICATIONS

Data used to evaluate the performance characteristics of the queueing simulator has been collected and recorded in several different ways, two of which have been rejected as being inadequate for this purpose.

Initially, an eight millimeter home motion picture camera was used to photograph a clock whenever an electrical impulse was generated by the random time interval generator section being studied.

This arrangement was made possible by the use of a solenoid to activate the camera. Positive film was used and specially processed without splitting so that a standard motion and time study analysis projector could be used to analyze the film. Figure 9 illustrates the film which resulted from this procedure. The figures shows a strip of film (actual size) and a section of "blown-up" film.

It should be noted that only one random time interval generator can be studied at a time. Also, this type of clock is quite difficult to read with any degree of accuracy.



These inadequacies were partially overcome by the use of a sixteen millimeter motion picture camera and by mounting a stopwatch so that it could be photographed along with the resistance circuit selection stepping relays.

The sixteen millimeter motion picture camera resulted in larger, clearer negatives, information concerning both random time interval generators, and more accurate time interval data. Furthermore, it provided information as to the identity of the resistor circuit which was responsible for each time interval. Figure 10 illustrates film exposed using this system. A camera was found to be capable of operating independently, and, thus, could be used to collect data while unattended.

This system was found to have some undesirable features along with its desirable ones. One disadvantage was that it was quite difficult to identify which section of a random time interval generator was in operation. Another was that a considerable delay was experienced in the processing of the film. Still another was that even with the best of equipment, taking data from film is a slow and laborious process; the time intervals could not be found directly, but had to be calculated from the film data. In addition to these disadvantages, this system did not permit the collection of data concerning the condition of the queue which was generated.

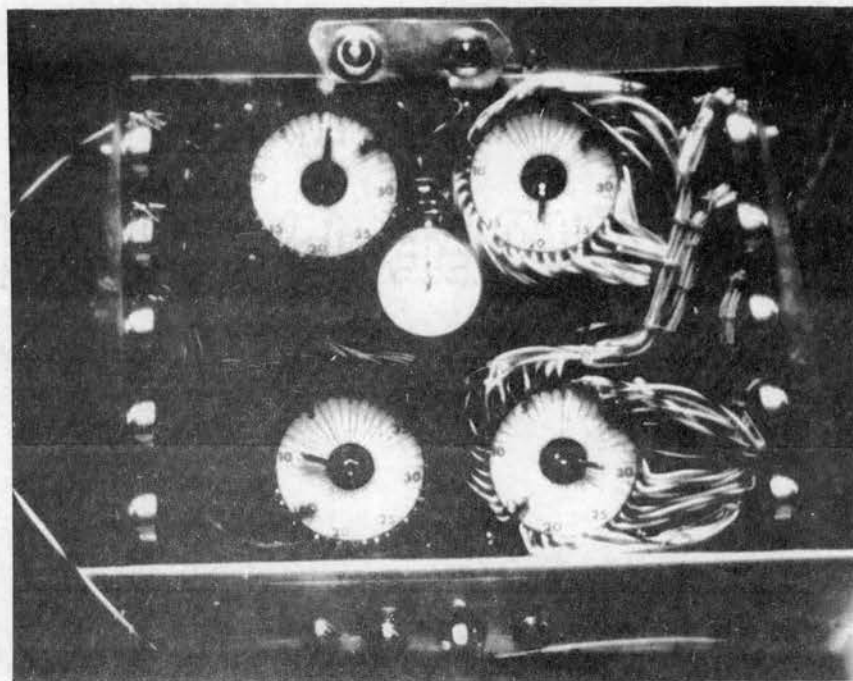


Figure 10. Film Strip From Sixteen  
Millimeter Motion  
Picture Camera

The use of photographs to collect data to be used to study the performance characteristics was eventually rejected due to the above limitations and disadvantages.

It was eventually determined that the only data collection system which was available to the author and which would overcome the above limitations and disadvantages while providing a permanent record of the desired data was a system which would utilize a recording dynagraph. This system would provide for the determination of time interval length quite accurately, and it would provide for immediate feedback of information. The only disadvantage of this system was that it did not provide for a means for the recording of information concerning the identity of the resistor circuit which was responsible for the various time intervals. However, this information could be recorded manually directly onto the dynagraph recording paper as the time interval lengths were being recorded.

Two dynagraphs were available for use: (1) A two channel recording dynagraph - A Brush Development Company Type BL 202 - which was used for the first two tests performed when information concerning time interval lengths and their corresponding resistor circuits was required, and (2) an eight channel recording dynagraph - Offner Type R - which was used for the third test performed, when information concerning queue lengths was desired in addition to the above information.

Two modifications of the queueing simulator were required before the dynagraphs could be utilized. The random time interval generator sections had to be modified so that the voltage across the timing capacitor could be recorded by the dynagraph to measure the time interval length. This modification and the parts required for it are shown in Figure 11. It should be noted that both random time interval sections were modified identically, and that this modification simply required the addition of an external plug so that the dynagraph could be attached to the system.

The second modification was made to facilitate the recording of the queue count, or rather a count of the total number in the system - in service and waiting - and was considerably more extensive than the first modification. In fact, it required removing the original queue count section and installing a new section. The new or modified queue count section is shown in Figure 12. The materials required for the modified queue count section are listed in Parts List 6.

Two persons were required to collect data concerning the identities of the resistance circuits responsible for the various time intervals - one to read the resistance circuit identity directly from the simulator and one to record this information onto the recording paper adjacent to the time interval data recorded by the dynagraph.

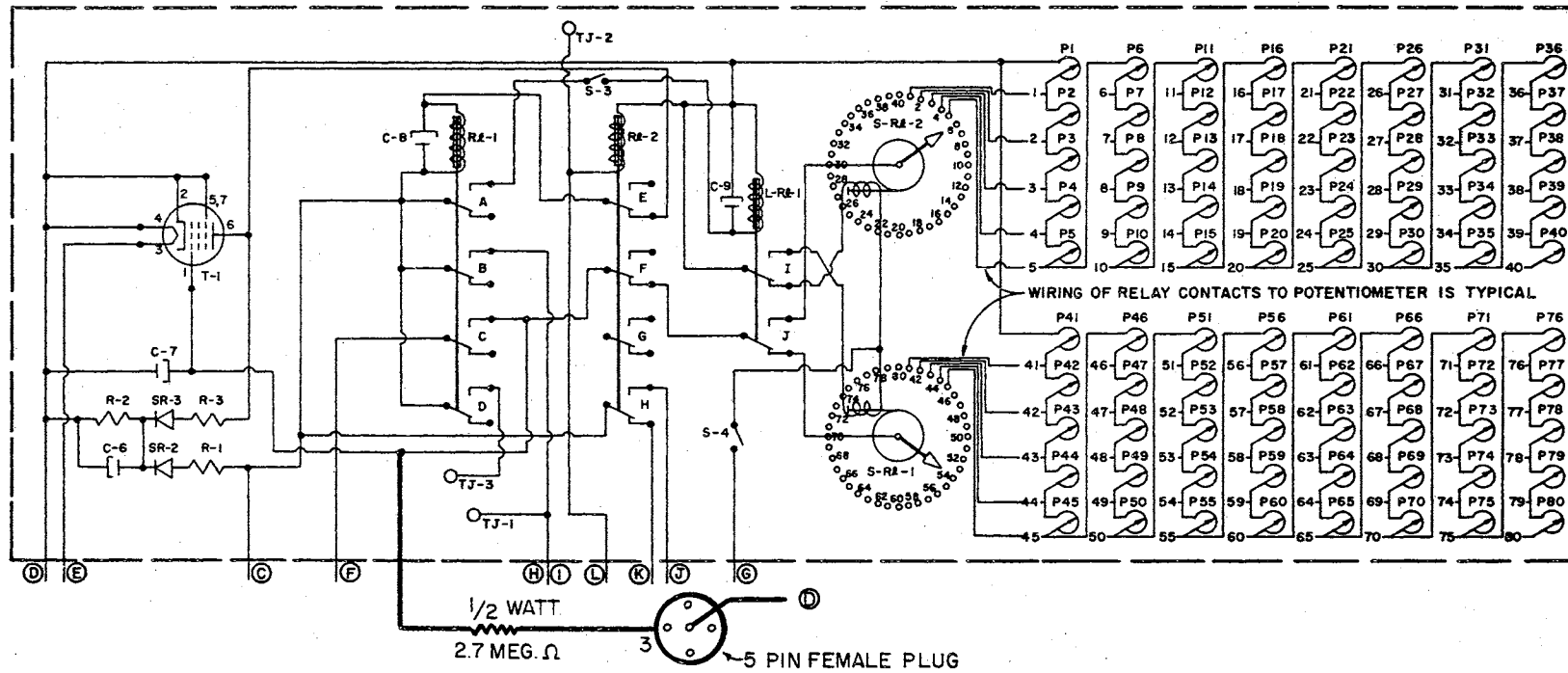


Figure 11. "RANDOM" Time Interval Section

## PARTS LIST 6

## Modified Queue Count Section

<u>Part No.</u>	<u>Part Description</u>	<u>Specifications</u>	<u>Manufacturer</u>	<u>Mfg. Type</u>
AS-R1-1	Add and Subtract Relay	40 PT 110VAC	Guardian	IR-RAS
S-2,S-6	Switch	SPST	Arrow-Hart and Hegeman	20994-BF
C-4,C-5	Capacitor	.47mfd 600VDC	Mallory	PVC 6047
C-10,C-11	Capacitor	.100mfd 150VDC	Sprague	TVA-1420
C-12	Capacitor	100vtd 150v.	Sprague	TVA-1420
C-13	Capacitor	.1mfd 200VDC	Sprague	2TM-PIO
C-14	Capacitor	2mfd 200VDC	Sprague	118P-2059252
C-15	Capacitor	100mfd 25 VDC	Sprague	TVA-1207
SR-4, SR-5, SR-6	Silicon Rectifier	750ma 600 PIV	Texas Instruments	IM547
P-81	Potentiometer	500 k $\Omega$ linear taper	Mallory	SU-50
R-4	Resistor	1k $\Omega$ 2 watt	IRC Carbon	SR-2



## PARTS LIST 6 (Continued)

<u>Part No.</u>	<u>Part Description</u>	<u>Specifications</u>	<u>Manufacturer</u>	<u>Mfg. Type</u>
R-5	Resistor	270 $\Omega$ 1 watt	IRC Carbon	GBT-1
R-6	Resistor	3.3M $\Omega$ $\frac{1}{4}$ watt	IRC Carbon	SR- $\frac{1}{4}$
R-7 to R-45	Resistors	9.1k $\Omega$ $\frac{1}{4}$ watt	IRC Carbon	SR- $\frac{1}{4}$
R1-3	Relay, Plate	10,000 $\Omega$	Guardian	200MS, 4PDT
T-2	Electron Tube		G.E.	2D21
Female Plug	To fit recording device			

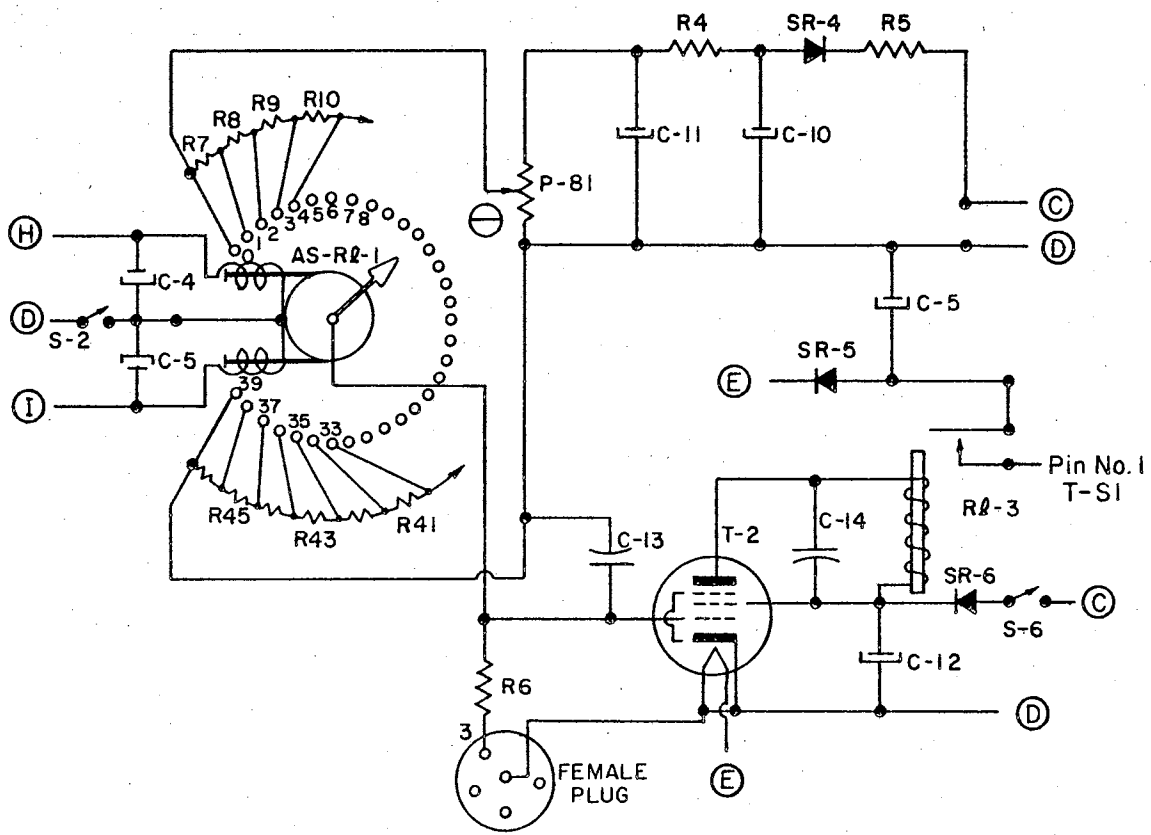


Figure 12. Modified Queue Count Section

Figure 13 provides a view of the queueing simulator, Offner Dynagraph, the author and his wife prepared to make a data run. Figure 14 shows a portion of a recording made with the two channel recorder. The numbers which read from the bottom of the page identify the particular resistor circuit which was responsible for that particular time interval. The U or D reveals whether the Up or Down section was involved. The numbers, which read from the sides, are the lengths of the various time intervals in centimeters. This recorder was adjusted to have the recording paper pass the recording pens at a rate of one centimeter per second, so these numbers also give the lengths of the time interval in seconds. The left portion corresponds to the service section of the queueing simulator, the right to the arrival. Figure 15 shows a portion of a recording made with the Offner Dynagraph. This recorder was operated at the rate of .5 centimeters per second; therefore, the lengths in centimeters represent a time interval of twice the corresponding magnitude. The righthand channel records the number in the system, which will be called queue length. Each step, it will be noted, corresponds to the end of a time interval and indicates the occurrence of either a service or an arrival. It will also be noted that when the queue count is zero, the voltage recorded for the service channel does not change. This is due to the fact that the service facility

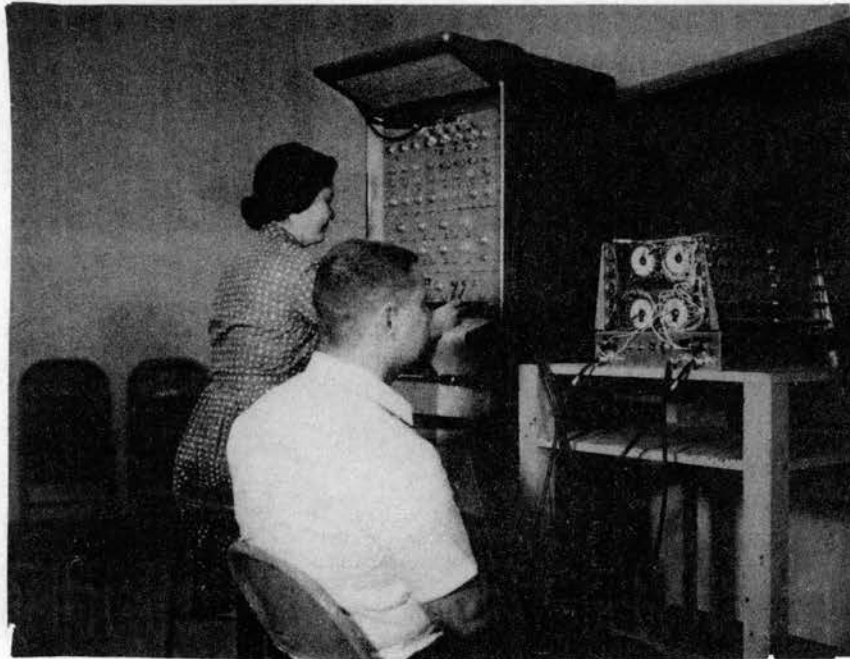


Figure 13. A Typical Data Recording  
Session With the Offner  
Dynagraph

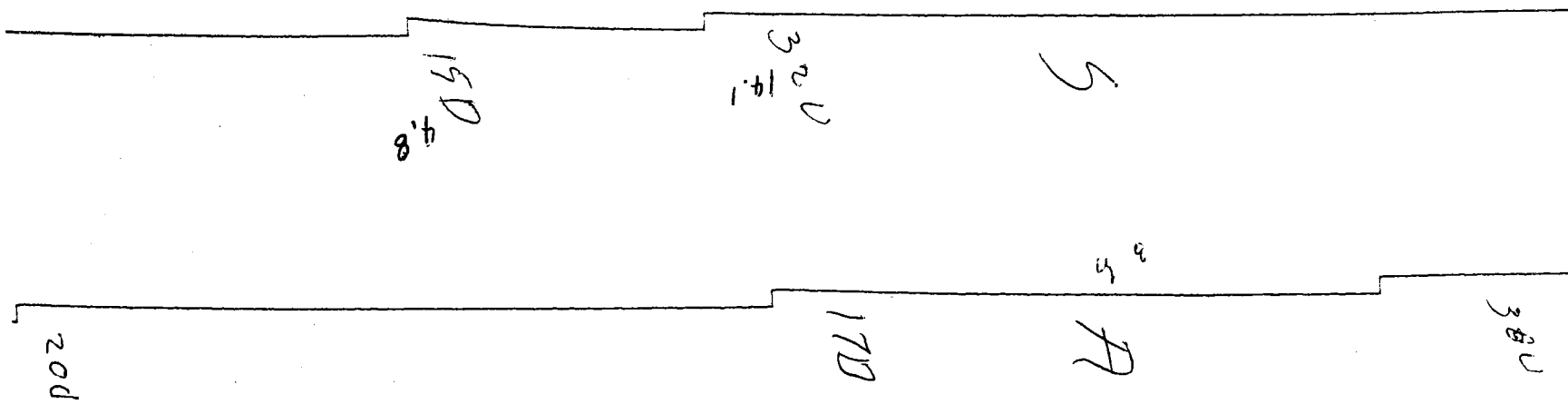


Figure 14. A Typical Two Channel Recording

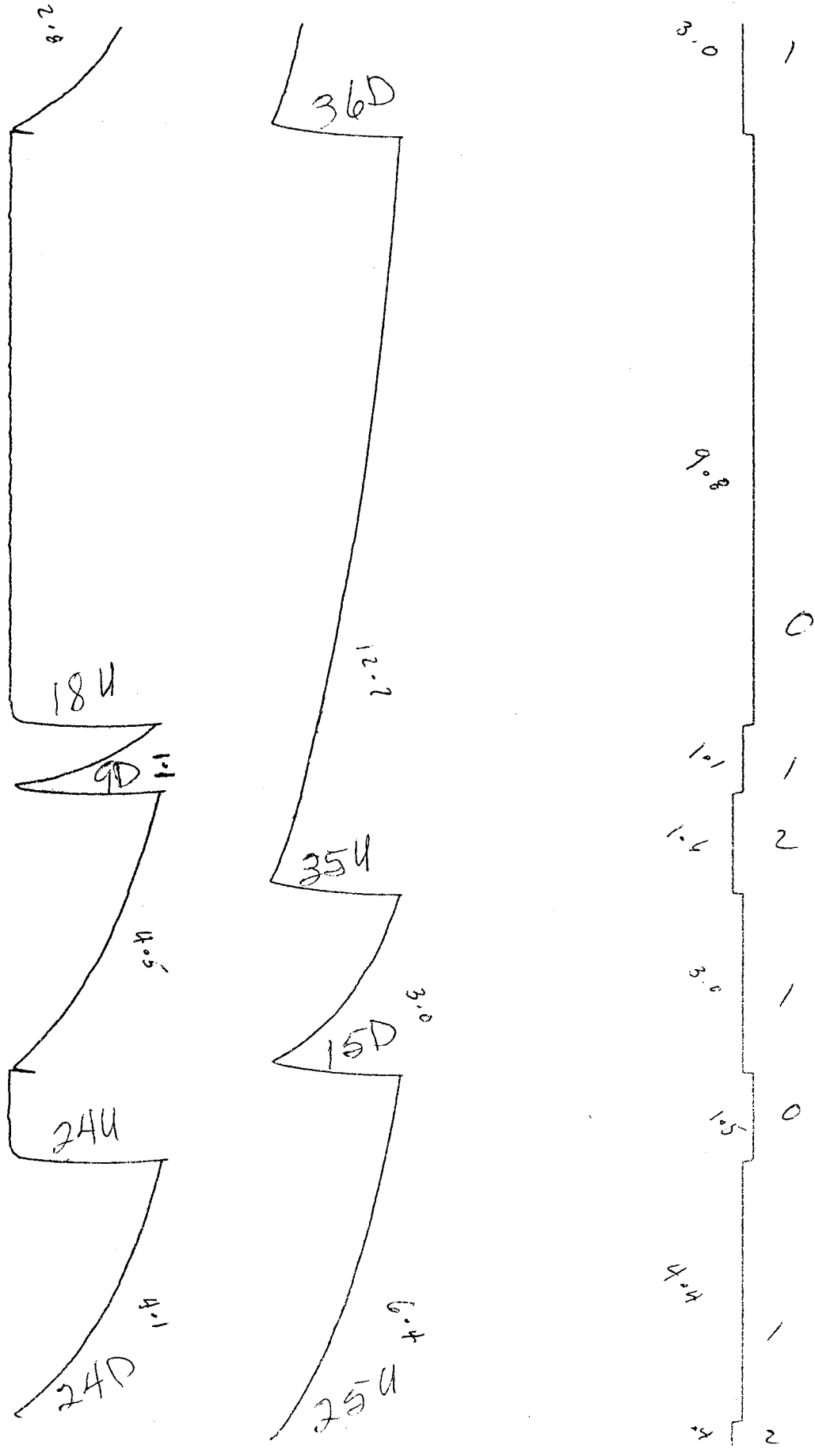


Figure 15. A Typical Three Channel Recording

is empty and no unit is being serviced.

The numbers adjacent to the queue count recording are the queue count and the length of duration of this condition (centimeters).

## CHAPTER VI

### EVALUATION PROCEDURE AND DATA

The evaluation of the adequacy of the queueing system simulator which has been developed was divided into three phases. The first was to determine if the number of times each resistor circuit is called upon to generate a time interval is uniformly distributed (each resistor has an equal probability of being called upon for each time interval), and to determine if a rectangular time interval distribution can be generated by adjusting each resistor to the same value.

The resistance required to yield a time interval one centimeter long on the Brush Dynagraph was determined for both the arrival section and the service section. These two values were different. Then, each resistor was adjusted to the value determined for its section using a Simpson Model 260 Volt-Ohm meter. The results are shown in Figures 21, 22, 23, and 24 (Appendix B).

The purpose of the second phase was to determine if the two portions of a single section could be adjusted to produce similar distributions, and, thus, demonstrate that the distribution generated could be controlled. This phase was



performed by adjusting a set of values into the upper set of resistors in the arrival section. These resistors were set by a trial and error procedure to produce a desirable distribution. After setting a resistor circuit, the generator would be adjusted to produce a series of constant time intervals from this circuit. Then, the intervals would be measured and if necessary the resistors set again. After the upper set of resistors had been adjusted thusly, the lower set was adjusted using the volt-ohm meter.

After the resistances of the lower set of resistors were adjusted as closely as possible to the upper set, the Brush Dynagraph was used to record the time interval lengths generated. Figure 25 (Appendix B) shows this set of data.

The purpose of the third phase was to determine whether predetermined distributions could be simulated and to evaluate the operation of the queue count section. This phase was designed to evaluate the entire queueing system simulator. Exponential distributions with mean times of 13.3 seconds and 10 seconds were selected for simulation. Using these mean times, times corresponding to each 1.25 per cent increment of cumulative probability were calculated. These values were determined as follows:

1.  $f(x) = \mu e^{-\mu x}$
2.  $f(x)$  was integrated to yield  $F(t)$

$$F(t) = \int_0^t f(x) dx$$

$$\begin{aligned}
 &= \int_0^t \mu e^{-\mu x} dx \\
 &= \left. \frac{\mu e^{-\mu x}}{-\mu} \right|_0^t \\
 &= 1 - e^{-\mu t}.
 \end{aligned}$$

3.  $F(t)$  was set equal to 0, .0125, .0250, .0375, ..., .9875, 1.0000.

4. Defining  $\bar{x} = \frac{1}{\mu}$  and using the value  $\mu_a = .075$  and  $\mu_s = .10$ , the various values of  $t$  were calculated. For example,  $F(t) = .0125$ ,

$$\mu = .10$$

$$1 - e^{-\mu t} = .9875$$

$$e^{\mu t} = 1.0126582$$

$$\mu t \approx .0126$$

$$t \approx .126.$$

The time for resistor circuit numbers 1 and 2 was selected as the time corresponding to  $F(t) = .025$  or the time corresponding to the mid-point of the first five per cent of the cumulative distribution curve. Thereafter, the time interval for each resistor circuit was selected as the sequential mid-points of sections 2.5 per cent wide taken from the cumulative distribution curve. Figure 29 (Appendix C) shows these mid-point times and the times which correspond to the edges of the sections. The resistance required to produce each of the desired times was then determined using resistance-time curves (Figure 16). Data from the previous phases, as well as supplementary data, was used to

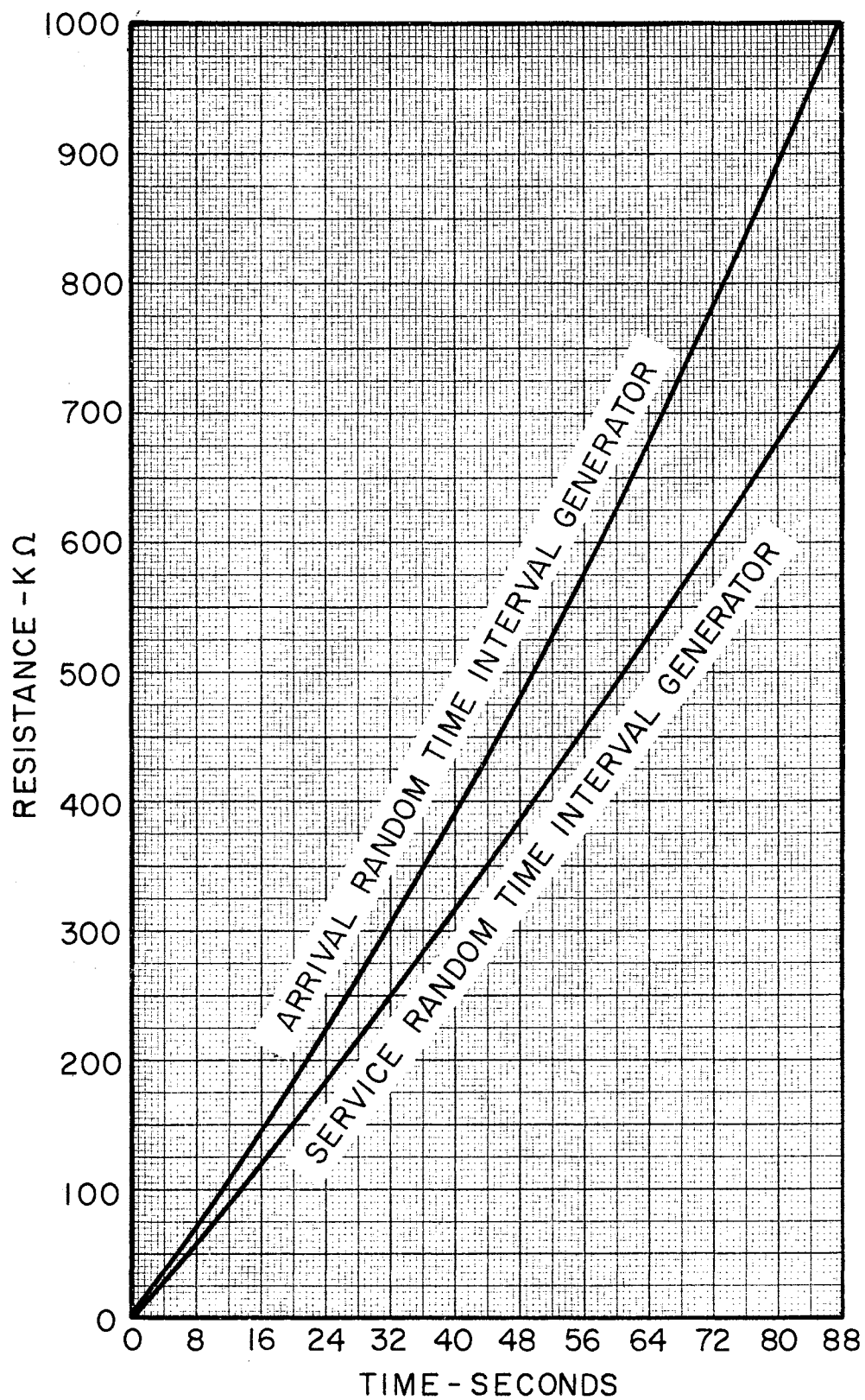


Figure 16. Resistance-Time Curves

plot the resistance-time curves. It should be noted that the curves for the two sections differ. It is expected that the curves for all random time interval generators will differ due to manufacturing tolerances of the component parts. After the required resistance was determined for each resistance circuit, the resistors were adjusted using the ohm meter. Difficulty was experienced at this point due to the fact that the resistors were rather coarse and did not lend themselves to fine adjustments; also, some had a tendency to move slightly after they were set.

Upon completion of "setting the distributions," the queue count section was added to the circuit and the Offner dynagraph was attached. The data thus collected and analyzed is shown in Figures 26, 27, and 28. Figure 26 (Appendix B) shows data concerning the individual parts of the random time interval sections, giving the resistor circuit numbers and the time interval lengths from the corresponding resistor circuits. Figure 27 (Appendix B) shows the queue count data providing a log of the various time intervals that the queue (total number in the system) was of various lengths and the total length of time that the various lengths occurred. Figure 28 (Appendix B) shows data compiled to test the hypothesis that the number of occurrences of each resistor circuit is rectangular. It contains data concerning the number of occurrences which was collected in an extended run.

During the progress of the third phase, some effects of wear were noted in the operation of the simulator. At times, the resistance circuit stepping relays failed to step properly, the relay to switch from one stepping switch to the other failed to operate properly, and the queue count would either fail to add with the occurrence of an arrival or else would subtract two when a service occurred. Thus, it was expected that the variance of the time distributions would be large and that the mean queue length would be low.

## CHAPTER VII

### EVALUATION OF DATA

The data for the first phase of evaluation was used to test the hypothesis that each resistor circuit would be called upon to generate time intervals the same number of times as any other, and to examine the lengths of the time intervals thus generated to determine if the author had been able to generate the desired rectangular distribution.

The data of Figures 21 to 24 was used to calculate  $\chi^2$  (chi-square) values which were used as test statistics.

The chi-square critical value was determined by interpolation of values given by Snedecor (3).

Degrees of Freedom	$\chi^2$ (df, .05)
30	43.77
39	
40	55.76

$$\chi^2_{39,.05} = 43.77 + \frac{9}{10} (55.76 - 43.77)$$
$$\chi^2_{39,.05} = 54.56.$$

The hypothesis will be accepted if the test statistics are less than this chi-square value.

Calculation of the test statistics reveal them to be:

	$\chi^2$
Arrival Up	40.16
Arrival Down	53.88
Arrival (Combined) Section	40.56
Service Up	47.57
Service Down	31.08
Service (Combined) Section	36.56

Thus, one is able to accept the hypothesis that the number of times that each resistor circuit is called upon is uniformly distributed. The time interval lengths were examined visually. It is obvious that the lengths do not agree with the circuit numbers, but it is also obvious from Figures 21 to 24 that all values which resulted from a given circuit do agree rather closely. In consideration of this visual examination, it was felt that the time interval lengths could be controlled and, thus, a desired distribution be generated, but the setup could not be performed by the method used in this phase of evaluation.

The second phase of evaluation was performed to confirm that a desired distribution could be generated, as explained earlier (p. 49), only one random time interval generator section was used for this phase.

The hypothesis that two identical distributions could be generated using the two parts of a random time interval section was evaluated by comparing the means and variances of

the time intervals generated.

Calculation of the means and variances of the data of Figure 25 reveals them to be:

	Mean	Variance
Upper Part	31.35	156.85
Lower Part	31.67	155.88

No test was performed to compare these values, as they are from an unknown distribution. However, it is felt that the closeness of these values does indicate that this hypothesis is correct. At least, it reassured the author to the degree that the third phase of evaluation was performed.

In the third phase of evaluation, the author attempted to test the hypotheses accepted in the first phase, as well as evaluate a method of pre-establishing a desired distribution and simultaneously evaluate the complete system.

The first hypothesis tested in the third phase of evaluation was the hypothesis accepted in the first phase "each resistor circuit would be called upon to generate time intervals the same number of times as all other resistance circuits." Calculation of the chi-square test statistic for each of the individual parts and the two sections from the pertinent data shown in Figure 28 reveals the statistics to be:

	$\chi^2$
Arrival Up	48.78
Arrival Down	47.53
Arrival (Combined)	48.05



	$\chi^2$
Service Up	22.63
Service Down	29.87
Service (Combined)	25.12

Comparison of these values with the critical value of chi square  $[\chi^2(39, .05) = 54.56]$  determined in the first test again permits the acceptance of this hypothesis.

The second hypothesis tested in this phase of evaluation was the hypothesis that it was possible to generate distributions determined in advance. As previously stated, the distributions selected were exponential ( $f(t, x) = \frac{e^{-t/x}}{x}$ ) with event rates of  $1/x = .075$  and  $.10$ .

This hypothesis was tested by using maximum-likelihood estimators as suggested by Mood (1).

The Maximum-likelihood estimators ( $\hat{\theta}_1, \hat{\theta}_2, \dots, \hat{\theta}_k$ ) for parameters of a density function  $f(x; \theta_1, \theta_2, \dots, \theta_k)$  from samples of size  $n$  are for large samples approximately distributed by the multi-variate normal distribution with means  $\theta_1, \theta_2, \dots, \theta_k$  and with coefficient  $\|\sigma^{ij}\|$  in the quadratic form when

$$\sigma^{ij} = -E\left[\frac{d^2}{d\theta_1 d\theta_2}\right] \log f(x_j, \theta_1, \theta_2, \dots, \theta_k).$$

The variances and covariances of the estimators are  $\|\frac{1}{n}\sigma_{ij}\|$  where  $\|\sigma_{ij}\| = \|\sigma^{ij}\|^{-1}$ .

In this case,  $f(t, x) = \frac{1}{x}e^{-t/x}$

$$\log f(t, x) = \log \frac{1}{x} - \frac{t}{x}$$

$$\frac{d}{dx} \log f(t, x) = -\frac{1}{x} + \frac{t}{x^2}$$

$$\frac{d^2}{dx^2} \log f(t, x) = \frac{1}{x^2} - \frac{2t}{x^3}$$

$$\begin{aligned}
\sigma'' &= -E\left[\frac{d^2}{dx^2} \log f(t,x)\right] \\
&= -E\left(\frac{1}{x^2} - \frac{2t}{x^3}\right) \\
&= -\frac{1}{x^2} + \frac{2}{x^3} E_{(T)} \text{ where } E_{(T)} = X \\
&= \frac{1}{x^2}.
\end{aligned}$$

Now  $\|\sigma_{11}\| = \|\sigma^{11}\|^{-1}$

so  $\|\sigma_{11}\| = x^2$

and  $\|\frac{\sigma_{11}}{n}\| = \frac{x^2}{n}$  which is the variance.

So, the standard deviation of the maximum likelihood estimate  $\sigma_{\bar{x}}$  is  $\frac{x}{\sqrt{n}}$ . Also from Mood (1):

If  $f(x_1, x_2, \dots, x_n, \theta)$  is the density function for a random sample of size  $n$  drawn from a population with an unknown parameter  $\theta$ , then the maximum likelihood estimator of  $\theta$  is the number  $\hat{\theta}$ , if it exists such that  $f(x_1, x_2, \dots, x_n; \hat{\theta}) > f(x_1, x_2, \dots, x_n, \theta')$  where  $\theta'$  is any other possible value of  $\theta$ .

To find  $x$ , the likelihood estimator,  $(\log \prod_{i=1}^n f(t_i, x))$  will be maximized.

$$\begin{aligned}
L &= \log \prod_{i=1}^n f(t_i, x) = \sum_{i=1}^n \log f(t_i, x) \\
&= \sum_{i=1}^n \log \left(\frac{1}{x} e^{-t/x}\right) \\
&= n \log \frac{1}{x} - \frac{\sum_{i=1}^n t_i}{x} \\
\frac{dL}{dx} &= -\frac{n}{x} + \frac{\sum t}{x^2}
\end{aligned}$$

Setting

$$\frac{dL}{dx} = 0$$

$$\frac{\sum t_i}{\hat{x}} = n$$

$$\hat{x} = \frac{\sum t_i}{n}$$

Referring to Figure 26 for the various values of  $n$ , confidence limits can be found to use in evaluating the data.

	$n$	$\frac{1}{x}$	$\sigma_{\bar{x}} = \frac{x}{\sqrt{n}}$	$x - 3\sigma_{\bar{x}}$	$x + 3\sigma_{\bar{x}}$
Arrival Up	446	.075	.6313	11.44	15.28
Arrival Down	447	.075	.6307	11.44	15.28
Arrival Combined	893	.075	.4462	11.99	14.67
Service Up	457	.10	.4677	8.59	11.40
Service Down	450	.10	.4715	8.58	11.41
Service Combined	907	.10	.3320	9.00	11.00

Calculation of  $\frac{\sum t_i}{n}$  for the relevant data of Figure 26 yields the following values for  $\hat{x}$ :

	$\hat{x}$
Arrival Up	12.350
Arrival Down	14.118
Arrival Combined	13.263
Service Up	10.076
Service Down	10.036
Service Combined	10.056.

Thus, one may accept the hypothesis that it is possible to generate time interval distributions with predetermined distributions and parameters.

In passing, one also notes that the standard deviations, which for the exponential distribution should equal the mean, (shown below) of this data also falls within the above limits:

	Standard Deviation $\sigma$
Arrival Up	12.06
Arrival Down	13.28
Arrival Combined	12.80
Service Up	8.84
Service Down	10.00
Service Combined	9.94.

Thus, there is an indication that the standard deviations are not significantly different from the desired means, and that the researcher has succeeded in generating exponential distributions with mean times of 10 and 13.33 seconds.

Further calculations show the two sigma limits for the maximum likelihood estimator to be

	$\bar{x} - 2\sigma_{\bar{x}}$	$\bar{x} + 2\sigma_{\bar{x}}$
Arrival Up	12.07	14.60
Arrival Down	12.07	14.60
Arrival Combined	12.44	14.22
Service Up	9.06	10.94

	$x - 2\sigma_{\bar{x}}$	$x + 2\sigma_{\bar{x}}$
Service Down	9.06	10.94
Service Combined	9.34	10.66

When the means and standard deviations are compared to these tighter limits that of the twelve values listed above only two fall beyond them.

The final portion of the third phase of evaluation involves examining the queue which was generated. The probability of a simple queue with exponential arrivals and services such as the one simulated being in any state  $n$  is given by Morse (2) to be

$$P_n = \rho^n P_0 \text{ where } \rho = \frac{X_S}{X_P}$$

$$X_S, X_A = \text{means}$$

so

$$f(n) = (1 - \rho)^{\rho^n} \quad P_0 = 1 - \rho$$

The maximum likelihood estimator will be found as before:

$$\begin{aligned}
 L &= \log \prod_{i=1}^n f(x_i, \rho) & x_i &= \text{Number in system} \\
 &= \log \prod_{i=1}^n (1 - \rho)^{\rho^{x_i}} \\
 &= \sum_{i=1}^n \log(1 - \rho) \rho^{x_i} \\
 &= n \log(1 - \rho) + \sum x_i \log \rho
 \end{aligned}$$

$$\frac{dL}{d\rho} = -\frac{n}{1-\rho} + \frac{\sum x_i}{\rho} \quad n = \text{Total number time of unit time periods.}$$

$$\frac{n}{1-\rho} = \frac{\sum x_i}{\rho}$$

$$\hat{\rho} = \frac{\sum x_i}{n + \sum x_i}$$

This researcher proceeds in a manner similar to his previous procedure to determine the distribution of this statistic:

$$\sigma^{ij} = -E\left[\frac{d^2}{d\theta_i d\theta_j} \log f(x, \theta_1, \theta_2, \dots)\right]$$

$$\sigma'' = -E\left[\frac{d^2}{d\rho^2} \log (1-\rho)\rho^x\right]$$

$$= -E\left[\frac{d}{d\rho} \left(\frac{x}{\rho} - \frac{n}{1-\rho}\right)\right]$$

$$= -E\left[\frac{x}{\rho^2} - \frac{1}{(1-\rho)^2}\right]$$

$$= \frac{E(x)}{\rho^2} + \frac{1}{(1-\rho)^2}$$

where

$$E(x) = \sum_{i=1}^{\infty} x_i (1-\rho)\rho^{x_i}$$

$$= (1-\rho)(\rho + 2\rho^2 + 3\rho^3 + \dots + n\rho^n + \dots)$$

$$E(x)\left(\frac{1}{1-\rho}\right) = \rho + 2\rho^2 + 3\rho^3 + \dots + n\rho^n + \dots$$

$$E(x)\left(\frac{\rho}{1-\rho}\right) = \rho^2 + 2\rho^3 + 3\rho^4 + \dots (n-1)\rho^n + \dots$$

$$E(x) = \rho + \rho^2 + \rho^3 + \dots + \rho^n + \dots$$

$$\rho E(x) = \rho^2 + \rho^3 + \rho^4 + \dots + \rho^{n+1} + \dots$$

$$E(x) = \frac{\rho}{1-\rho}$$

Thus

$$\begin{aligned}\sigma'' &= \frac{\rho}{\rho^2(1-\rho)} + \frac{1}{(1-\rho)^2} \\ &= \frac{1}{\rho(1-\rho)^2}\end{aligned}$$

and

$$\|\sigma_{11}\| = \|\sigma''\|^{-1}$$

so

$$\sigma_{11} = \rho(1-\rho)^2$$

$$\text{so } \sigma \text{ (standard deviation)} = \sqrt{\frac{\rho(1-\rho)^2}{n}}$$

where  $n$  = number of observations of unit length, or

$$\sigma = (1-\rho)\sqrt{\frac{\rho}{n}}$$

For this distribution

$$\rho = \frac{.075}{.100} \text{ or } \frac{10.00}{13.333} = .75$$

$$\begin{aligned}\sigma_p &= (1-.75)\sqrt{\frac{.75}{5950.75}} \text{ n from Figure 27} \\ &= .00282.\end{aligned}$$

The  $3\sigma$  confidence limits ( $\rho \pm 3\sigma_\rho$ ) are now found to be  $.75 \pm .00846$  or  $.74154$  and  $.75846$ , while

$$\begin{aligned}\hat{\rho} &= \frac{\sum x_i}{n + \sum x_i} = \frac{17055.8}{17055.8 + 5950.78} \\ &= .74134.\end{aligned}$$

Thus, it is found that the hypothesis in this last test must be rejected. It must be noted, however, that this low value was expected due to the occasional malfunction of the worn add and subtract relay in the queue count section which was mentioned on page 54.



## CHAPTER VIII

### CONCLUSIONS

It is concluded from the results of the foregoing tests, that the random time interval sections do utilize each resistor circuit approximately the same number of times in generating a set of time intervals. Furthermore, it is concluded that the lengths of the time intervals resulting from these resistor circuits can be controlled. Hence, it is concluded that this system can be used to generate time intervals from any desired distribution. This ability was demonstrated for three distributions.

Even though the attempt to simulate a queue of predictable characteristics failed, it is felt that this failure was due to the failure, due to wear, of a particular part rather than a failure of the total system. Therefore, it is felt that the total system has been demonstrated to be capable of simulating simple queues in its present form.

The device makes available a means of examining queues with "exodit" (other than exponential based) queues without the necessity of using digital computers as simulation devices; additionally, it can be used to simulate

many types of "Monte Carlo" problems, inventory problems, production control problems, manufacturing lines, and materials handling problems.

It has, in another study, proved useful in examining the spacing of the empty service facility occurrences due to its data printout form.

This device makes available to the classroom a means of simulating and observing and studying Monte Carlo situations without having to resort to the time consuming procedure of observing industrial situations or the laborious procedures involved in hand simulation.

The simulator will permit the student to control various statistical parameters such as the arrival and service distributions of queues, in order to experience the effects of these changes. By connecting two or more units, complex situations may be demonstrated and studied to show or study the effects of parallel or series systems.

The random time interval units alone can be used individually to serve as the timing unit for motion pictures to be used for work sampling studies. They may also be used to time quality control samples. For that matter, they can be used whenever a series of random time intervals are desired. The only limits on the time intervals and distributions are limits imposed by the sizes of the resistors and number of resistor circuits. These limits can be overcome if necessary by the design of a special unit.

The existing units can be improved in several ways it is felt. Likely, the most drastic improvement would be to redesign the entire system to use solid state components rather than tubes and relays. This would overcome the component reliability problem which was encountered near the end of the testing as well as greatly reducing the noise level. A much less drastic change, which it is felt would be of considerable benefit, would be to replace relay R1-1 with a single pole single throw relay of the same size and type, and use this new relay to control a 110 volt a.c. relay which would control the circuits which R1-1 now controls. This change would insure the positive action of the various circuits controlled at the present by R1-1. Several advantages could also be gained by constructing three separate units, two random time interval generator units and a queue count unit, rather than a single system such as was constructed and is shown in the present design. This would provide the advantages of remote operation of the random time interval generators, and would also permit the operation of only those components needed at a particular time.

The process of setting up a distribution and adjusting the potentiometer to the desired values is at the present time a very laborious and time consuming procedure. It is felt that this difficulty can be partially overcome by the use of logarithmically tapered potentiometers in the resistance circuits rather than the presently used

uniformly tapered ones and then by the use of a wheatstone bridge rather than a standard ohm meter to determine the resistance. The process will still be slow and time consuming, but not as slow as with the present system.

This research and development should be continued to devise means of utilizing the present system to simulate more complex systems and to use it as a tool to investigate systems and system phenomena which cannot be readily investigated by other means.

## BIBLIOGRAPHY

- (1) Mood, Alexander M. Introduction to the Theory of Statistics. New York: McGraw-Hill Book Co., Inc., 1950.
- (2) Morse, Philip M. Queues, Inventories, and Maintenance. New York: John Wiley and Sons, Inc., 1958.
- (3) Snedecor, George W. Statistical Methods, 5th ed. Ames, Iowa: The Iowa State College Press, 1956.

APPENDIX A

SHOP MADE PARTS

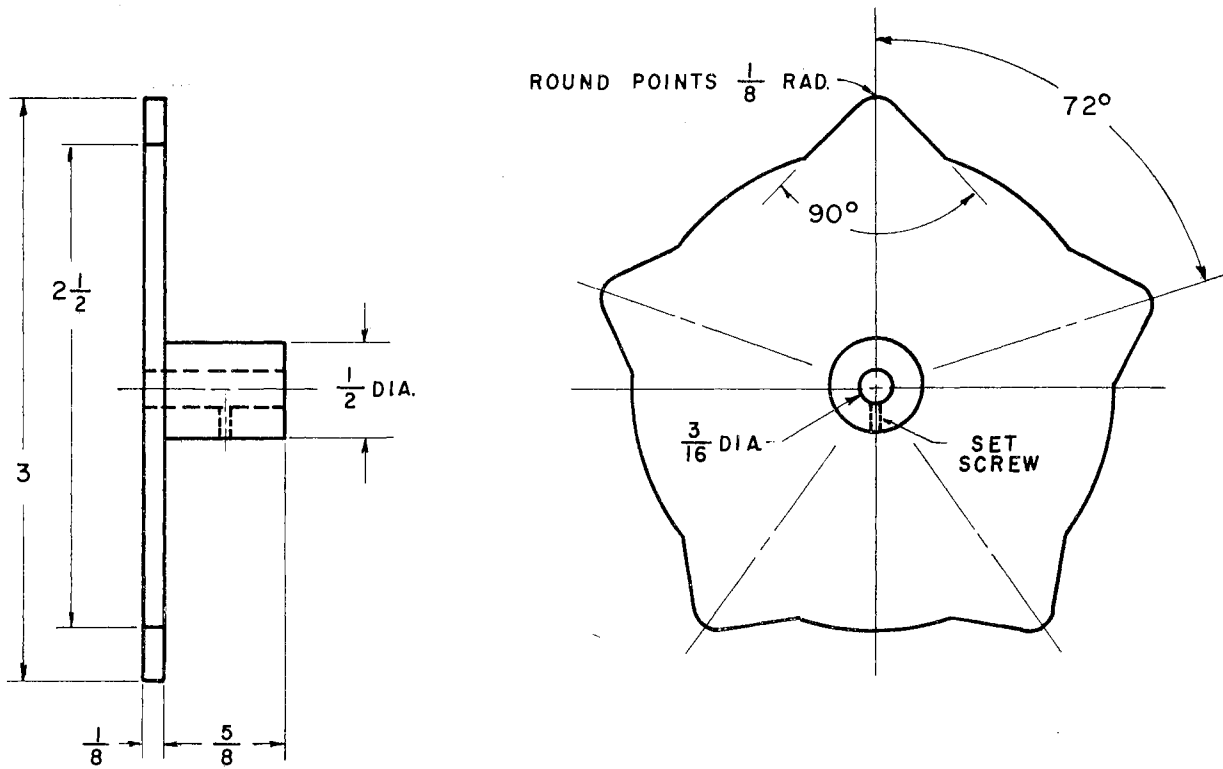


Figure 17. Cam Disk





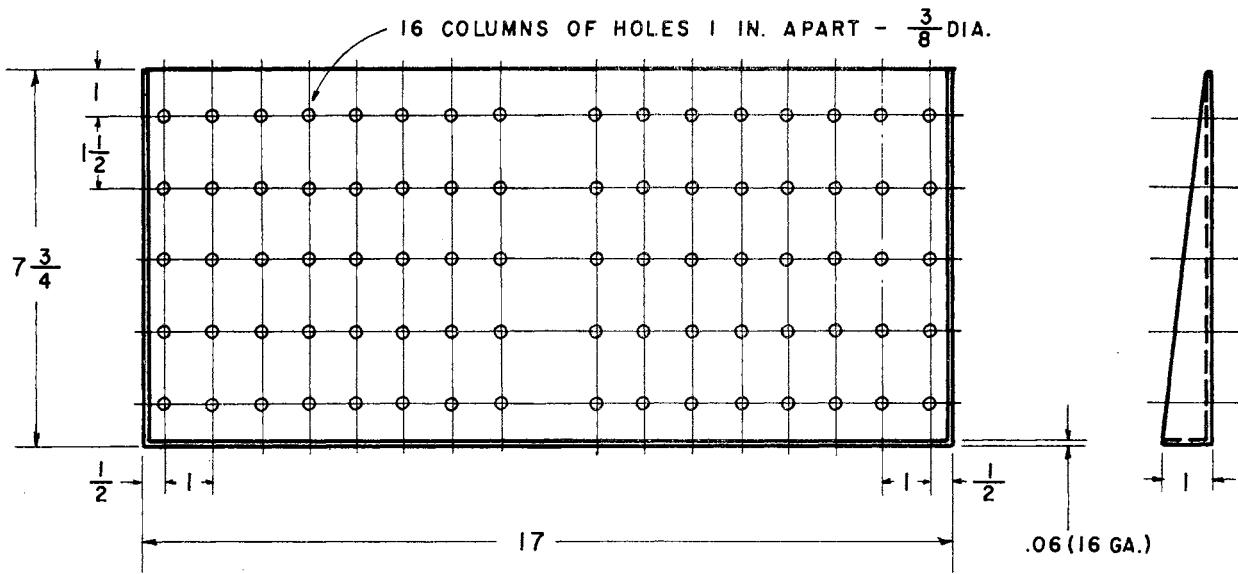


Figure 19. Potentiometer Mounting Bracket

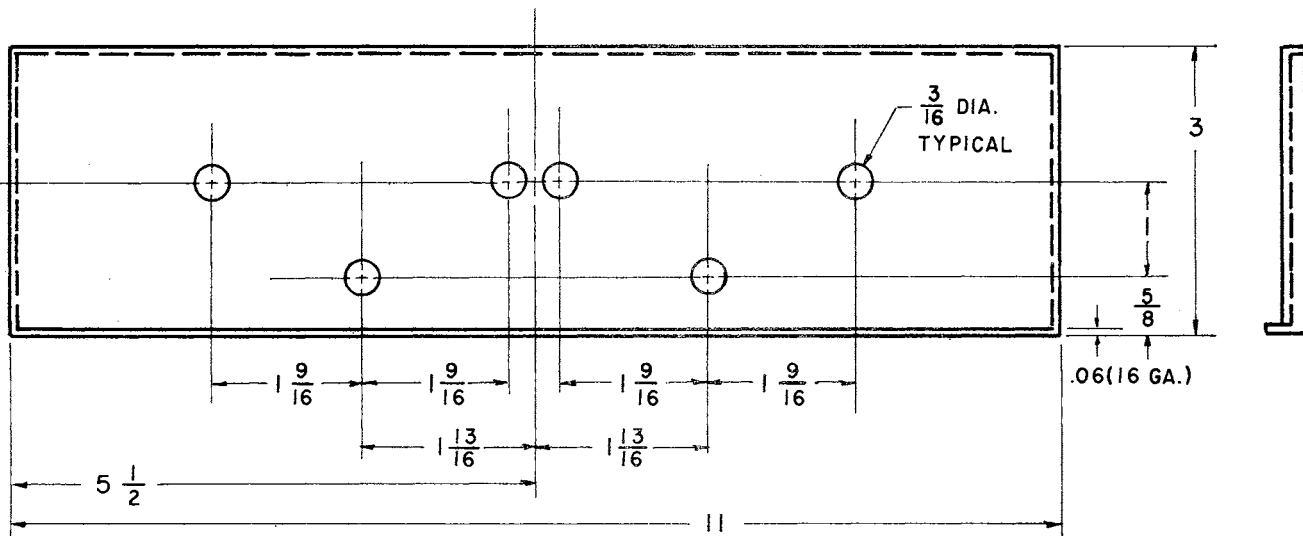


Figure 20. Support Bracket

APPENDIX B  
EVALUATION DATA

Resistor Circuit Number	Time Intervals (Sec)	Mean Time
1	1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1	1.0
2	2, 2, 2, 2, 2, 2, 2, 2, 2	2.0
3	3, 3, 3, 3,	3.0
4	4, 4, 4, 4, 4, 4, 4, 4, 4, 4, 4	4.0
5	5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5	5.0
6	6, 6, 6, 6, 6, 6	6.0
7	7, 7, 7, 7, 7, 7, 7, 7, 7, 7, 7	7.0
8	8, 8, 8, 8, 8, 8, 8, 8, 8, 8	8.0
9	9, 9, 9, 9, 9, $9\frac{1}{2}$ , 9, $9\frac{1}{2}$	9.2
10	10, 10, 10, 10, 10, 10, 10, 10, 10	10.0
11	11, 11, 11, 11, 11, 11, 11, 11, 11, 11, 11, 11,	
	11, 11, 11	11.0
12	12, 12, 12, 12, 12, 12, 12, 12, 12, 12, 12,	
	12	12.0
13	13, 13, 13, 13, 13, 13	13.0
14	14, 14, 14, 14, 14, $15\frac{1}{2}$	14.2
15	15, 15, 15	15.0
16	15, $15\frac{1}{2}$ , 16, 16, 16, 16, 16, 16, 15, 16, 15,	
	16, 16	15.7
17	$16\frac{1}{2}$ , 18, 17, 16, 16	16.7
18	17, $17\frac{1}{2}$ , 18, 17, $18\frac{1}{2}$ , 17, 18, 17, 18, 18,	
	18, 18, 18	17.8
19	18, 18, 19, 18, 19	18.4
20	$19\frac{1}{2}$ , 19, 18, 20, 20, 19, 19, 19	19.3
21	$20\frac{1}{2}$ , 20, 19, 20, 21, $20\frac{1}{2}$ , 20, 20, $20\frac{1}{2}$ ,	
	20, 20, 20, 20, 20, 21	20.0
22	21, 21, 21, 22, 21, $21\frac{1}{2}$ , 21, 21, 21, 21,	
	21, 21, 21, 21	21.1
23	22, 22, 22, 22, $21\frac{1}{2}$ , 22, 22, 22, 22, $21\frac{1}{2}$ ,	
	22	21.9
24	23, 21, 22, 23, 23, 24, 22, 23, 23, $22\frac{1}{2}$	22.7
25	24, 23, 24, 24, 24, $24\frac{1}{2}$ , 23, 24, 23, 24,	
	24	23.7
26	25, 24, 24, 23, 25, 24, 25, 24, 25	24.3
27	25, $25\frac{1}{2}$ , 25, $25\frac{1}{2}$ , 26, 25, $25\frac{1}{2}$ , 26, 25,	
	25, 25	25.3
28	26, 26, 27, $26\frac{1}{2}$ , 26, 26	26.2
29	27, 27, $26\frac{1}{2}$ , 25, 26, 27, 27, 27, 26, 27	26.7
30	28, 28, 28, 29, 28, 28	28.1
31	$28\frac{1}{2}$ , 28, $28\frac{1}{2}$ , 29, 29, 30, 28, 29, 29	28.8
32	$29\frac{1}{2}$ , 29, 29, 29, 30, 30, 30	29.5
33	30, 31, $30\frac{1}{2}$ , 30, 30, $30\frac{1}{2}$ , 30, $30\frac{1}{2}$ , 30,	
	31, 20	30.3
34	30, 31, 31, 31, $31\frac{1}{2}$	

Figure 21. Uniform Distribution Data - Arrival Up

Resistor Circuit Number	Time Intervals	Mean Time
35	31, 31, 32, 32, 33, 30, 33, 33, 32, 32, 31, 32	31.8
36	32, 32 $\frac{1}{2}$ , 31, 32 $\frac{1}{2}$ , 32 $\frac{1}{2}$	32.1
37	33 $\frac{1}{2}$ , 34, 32, 34, 34, 33, 33, 32 $\frac{1}{2}$ , 33, 33	33.2
38	34 $\frac{1}{2}$ , 33, 35, 33 $\frac{1}{2}$ , 34, 33	33.8
39	35, 34, 35, 35, 34 $\frac{1}{2}$ , 35, 35, 35	34.8
40	36, 35, 35, 35, 35, 35 $\frac{1}{2}$ , 36, 37, 37 $\frac{1}{2}$ , 35 $\frac{1}{2}$ , 36, 36, 35	35.7

Figure 21. (Continued)

Resistor Circuit Number	Time Intervals (Sec.)	Mean Time
1	1, 1, 1, 1, 1, 1, 1, 1, 1	1.0
2	2, 2, 2, 2, 2, 2, 2, 2, 2	2.0
3	3, 3, 3, 3, 3, 3, 3, 3, 3, 3, 3	3.0
4	4, 4, 4, 4, 4, 4, 4, 4, 4	4.0
5	5, 5, 5, 5, 5, 5, 5, 5, 5, 5	5.0
6	6, 6, 6, 6, 6, 6, 6, 6, 6, 6	6.0
7	7, 7, 7, 7, 7, 7, 7, 7, 7, 7	7.0
8	8, 8, 8, 8, 8, 8, 8, 8, 8, 8	8.0
9	9, 9, 9, 9, 9, 9, 9	9.0
10	10, 10, 10	10.0
11	11, 11, 11, 11, 11, 11, 11, 11, 11, 11, 11, 11, 11, 11	11.0
12	12 $\frac{1}{2}$ , 12, 12, 12, 12, 11, 12	12.0
13	13, 13, 13, 13, 13, 13, 13, 13	13.0
14	13 $\frac{1}{2}$ , 13 $\frac{1}{2}$ , 13 $\frac{1}{2}$ , 14, 14	13.7
15	15, 15, 15, 15, 15, 15, 15, 14 $\frac{1}{2}$ , 15, 15, 15	15.0
16	16, 16, 16, 15 $\frac{1}{2}$ , 16, 16, 16, 16, 16, 17, 16, 16, 16, 15 $\frac{1}{2}$ , 16, 16	16.0
17	17, 16, 16, 17, 17, 17, 17, 17, 17, 16 $\frac{1}{2}$ , 16 $\frac{1}{2}$ , 17	16.7
18	18, 17, 18, 17, 17, 18	17.5
19	18, 18, 18, 19, 20, 18, 18 $\frac{1}{2}$ , 19, 18, 18, 19, 18, 18	18.4
20	19, 19, 19, 19, 19	19.0
21	20, 20, 21, 20	20.3
22	21, 21, 20 $\frac{1}{2}$ , 22, 21, 20, 21, 21	20.9
23	21 $\frac{1}{2}$ , 22, 21, 22, 22, 22, 22, 23, 21 $\frac{1}{2}$ , 22, 22	21.9
24	22, 22 $\frac{1}{2}$ , 23, 22, 24, 23 $\frac{1}{2}$ , 22, 23, 23, 22 $\frac{1}{2}$ , 23, 22, 22	22.5
25	23, 24, 23, 24, 23 $\frac{1}{2}$ , 24, 24, 24, 24, 23, 24, 23 $\frac{1}{2}$ , 23	23.6
26	24, 24, 24 $\frac{1}{2}$ , 24, 24, 24, 25, 24 $\frac{1}{2}$	24.3
27	25, 26, 25 $\frac{1}{2}$ , 25, 25, 27, 24, 26	25.4
28	26, 25, 26, 26, 26, 26 $\frac{1}{2}$ , 26, 26, 26, 26	26.0
29	26, 27, 25, 27, 26, 27, 27, 27, 26 $\frac{1}{2}$ , 27 $\frac{1}{2}$ , 27, 26 $\frac{1}{2}$	26.6
30	28, 27, 27, 27, 28, 28, 28, 28 $\frac{1}{2}$ , 28, 28	27.8
31	28, 28 $\frac{1}{2}$ , 28 $\frac{1}{2}$ , 28, 28	28.2
32	29, 29 $\frac{1}{2}$ , 29 $\frac{1}{2}$ , 29, 30, 29	29.3
33	30, 30, 30, 30, 30, 30, 31	30.1
34	31 $\frac{1}{2}$ , 30, 31, 30 $\frac{1}{2}$ , 31, 31, 31, 31, 31, 30	30.8
35	31, 31, 31, 31, 31	31.0

Figure 22. Uniform Distribution Data - Arrival Down

Resistor Circuit Number	Time Intervals (Sec.)	Mean Time
36	31, 32, 32, 32, 36, 33, 33, 32, 34, 32	32.7
37	$29\frac{1}{2}$ , 33, 34, 35, 33, 33, 33, 33	32.9
38	34, 34, 34, 35, $34\frac{1}{2}$ , 34, 34, 35, 32	34.1
39	35, 34, 35, 35, 35, 34, 35, $34\frac{1}{2}$ , $34\frac{1}{2}$	34.7
40	$34\frac{1}{2}$ , 35, $35\frac{1}{2}$ , 36, 35, 37, 36, 35, 35, 36	35.5

Figure 22. (Continued)

Resistor Circuit Number	Time Intervals (Sec)	Mean Time
1	1, 1, 1, 1, 1, 1	1.0
2	2, 2, 2, 3, 2, 2, 2, 2, 2, 2, 2, 2	2.0
3	3, 3, 3, 3, 3, 3	3.0
4	4, 4, 4, 4, 4, 4, 4, 4	4.0
5	5, 5, 5, 5, 5 $\frac{1}{2}$ , 4 $\frac{1}{2}$ , 5, 5	5.0
6	5, 5, 6, 6, 6, 6	5.7
7	7, 7, 7, 7, 7	7.0
8	8, 7 $\frac{1}{2}$ , 8, 8, 7, 8, 8, 8, 8, 8, 8, 8, 8, 8 $\frac{1}{2}$ , 8	7.9
9	8 $\frac{1}{2}$ , 9, 10, 8 $\frac{1}{2}$ , 9, 9, 9, 9, 8 $\frac{1}{2}$ , 8 $\frac{1}{2}$ , 10, 9	9.0
10	9, 9 $\frac{1}{2}$ , 9, 9 $\frac{1}{2}$ , 9, 10	9.3
11	10, 10, 10 $\frac{1}{2}$	10.2
12	11 $\frac{1}{2}$ , 11, 11, 11, 11, 11, 11, 11, 11, 11, 12	11.2
13	12, 12, 12, 11, 13, 12, 12, 12, 12, 12, 12, 12	12.0
14	13, 13, 13, 13, 14 $\frac{1}{2}$ , 13, 13, 13, 13, 13, 13 $\frac{1}{2}$	13.2
15	13 $\frac{1}{2}$ , 14, 14, 14, 14, 15, 14, 14	14.1
16	15, 16, 14 $\frac{1}{2}$ , 15, 15, 16, 15, 15, 15 $\frac{1}{2}$	15.2
17	16, 16, 15, 15 $\frac{1}{2}$	15.6
18	16, 16, 16, 17	16.2
19	17, 17 $\frac{1}{2}$ , 18, 17, 17, 18, 17, 17, 17	17.3
20	18, 18 $\frac{1}{2}$ , 18, 19, 18, 18, 16 $\frac{1}{2}$ , 18 $\frac{1}{2}$ , 18, 18, 19	18.1
21	20 $\frac{1}{2}$ , 21, 19, 20, 19	19.9
22	21, 19, 19 $\frac{1}{2}$ , 20, 19 $\frac{1}{2}$ , 21, 20, 20, 20, 21 $\frac{1}{2}$	20.2
23	21 $\frac{1}{2}$ , 20, 21, 21, 20, 20 $\frac{1}{2}$ , 20 $\frac{1}{2}$ , 20, 21, 20 $\frac{1}{2}$ , 22	20.6
24	21 $\frac{1}{2}$ , 21, 22, 21, 21, 22, 22, 21	21.4
25	22, 22, 22 $\frac{1}{2}$ , 21 $\frac{1}{2}$ , 22, 23, 22, 22 $\frac{1}{2}$ , 23	22.3
26	23, 23, 23, 23 $\frac{1}{2}$ , 23 $\frac{1}{2}$ , 23	23.2
27	24, 24, 24, 27, 26, 24, 24	24.7
28	24 $\frac{1}{2}$ , 25, 27, 24 $\frac{1}{2}$ , 25, 25, 25, 25, 24 $\frac{1}{2}$	25.1
29	25, 26, 26, 25, 25, 25, 25 $\frac{1}{2}$ , 25 $\frac{1}{2}$ , 26, 26	25.5
30	26, 27, 26, 29, 26 $\frac{1}{2}$ , 26	26.8
31	27, 27, 27, 27, 26, 28, 27, 27, 26, 26	26.8
32	25 $\frac{1}{2}$ , 28, 28, 28, 30, 28, 29, 27 $\frac{1}{2}$ , 28	28.0
33	29, 27, 30, 31, 31, 29, 28, 28, 29, 29, 28, 29, 28	28.9
34	29, 30, 29, 30, 30, 29 $\frac{1}{2}$ , 29, 29 $\frac{1}{2}$ , 29	29.4
35	31, 29 $\frac{1}{2}$ , 30, 30, 31, 30 $\frac{1}{2}$ , 33, 30, 30, 30, 30, 30, 30 $\frac{1}{2}$	30.4
36	31, 30, 30, 31, 31, 30 $\frac{1}{2}$ , 32, 34, 34, 31, 30, 31, 31 $\frac{1}{2}$ , 31, 29	31.1
37	32 $\frac{1}{2}$ , 32, 31, 31, 32, 31 $\frac{1}{2}$ , 31 $\frac{1}{2}$ , 32, 32	31.7
38	32, 32, 32, 32, 36, 33, 32, 32, 33	32.7

Figure 23. Uniform Distribution Data - Service Down

Resistor Circuit Number	Service Down	Mean Time
39	33, 33 $\frac{1}{2}$ , 33, 33, 33, 33	33.1
40	34, 34, 34, 34, 34, 33, 33, 33 $\frac{1}{2}$ , 33, 33, 34, 34, 34, 34	33.7

Figure 23. (Continued)



Resistor Circuit Number	Time Intervals (Sec)	Mean Time
1	1, 1, 1, 1, 1, 1, 1, 1	1.0
2	2, 2, 2, 2, 2, 2, 2, 2	2.0
3	3, 3, 3, 3, 3	3.0
4	4, 4, 4, 4, 4, 4, 4, 4	4.0
5	5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5, 5	5.0
6	6, 6, 6, $5\frac{1}{2}$ , 6, 6, 6, 6, 6	5.9
7	7, 6, 8, 7, 7, 7, 7, 7, 7, 7	7.0
8	8, 8, 8, 8, 8, 8, $7\frac{1}{2}$ , 7, 8	7.8
9	9, 9, 9, 8, 8, 9, 9, $8\frac{1}{2}$ , 9, 9, $8\frac{1}{2}$ , $8\frac{1}{2}$	8.7
10	10, 9, 9, 9, 9, 9, $9\frac{1}{2}$ , $9\frac{1}{2}$ , 10, 10, 9, $9\frac{1}{2}$ , 10, 10, $9\frac{1}{2}$	9.38
11	11, $10\frac{1}{2}$	10.7
12	11, 13, 11, 11, $11\frac{1}{2}$ , 11	11.4
13	12, 12, 12, 12, 13, 12, 12, 12, $12\frac{1}{2}$	12.2
14	$13\frac{1}{2}$ , 13, 13, 13, 13, 14, 13, 13	13.2
15	14, 14, 14	14.0
16	15, 15, 15	15.0
17	16, 16, 16, 16, 18, 18, 16	16.6
18	16, $16\frac{1}{2}$ , 17, 15, 17, 16, $16\frac{1}{2}$ , 17, 17	16.4
19	18, 18, 17, 18, 19, 17, 17, 18	17.7
20	$18\frac{1}{2}$ , 18, 18, 19, $18\frac{1}{2}$ , $18\frac{1}{2}$ , 19, 19, 20, 18, $18\frac{1}{2}$ , 18	18.6
21	20, 19, 19, $19\frac{1}{2}$ , 19, 19, 19	19.2
22	20, 21, 21, $19\frac{1}{2}$ , 20	20.3
23	21, 21, 21, 20, $21\frac{1}{2}$ , 21, 21, 21, 21	20.9
24	23, 22, 22, 21, 22, 25, 22, 22, 22, 22, 22, 22, 22	22.2
25	$23\frac{1}{2}$ , 23, 23, 25, 22, $23\frac{1}{2}$ , 23, 23, 23, 23	23.2
26	23, 24, 23, 24, 26, 26, 24, 24, 24, 24, 23, 24	24.1
27	$24\frac{1}{2}$ , 24, 25, 25, 25, 24, 28, 25, 24, 25	25.0
28	25, 25, 25, 26, 25, $25\frac{1}{2}$ , 25, 28, $25\frac{1}{2}$ , 25, 26, 25	25.53
29	25, 25, $25\frac{1}{2}$ , 26, 26, 25, 26, 25, 27	25.81
30	27, 27, $26\frac{1}{2}$ , $27\frac{1}{2}$ , $26\frac{1}{2}$ , 28, 27, 26, $26\frac{1}{2}$ , 27, 27, 27, 27, 27, 27, 26	26.9
31	28, 28, 28, 28, 28, $27\frac{1}{2}$ , 28, 27	27.8
32	29, 28, 28, 29, 28, 28, 29	28.4
33	29, 29, $28\frac{1}{2}$ , 29, 29, 29, 30, 30, 29	29.2
34	29, 30, 30, 30, 29, 30, $30\frac{1}{2}$ , 30	29.8
35	$30\frac{1}{2}$ , 31, 30, 31, 31, $31\frac{1}{2}$	30.8

Figure 24. Uniform Distribution Data - Service Up

Resistor Circuit Number	Time Intervals (Sec)	Mean Time
36	31, 30, 31, 32, 32, 31	31.2
37	32, 31, 31 $\frac{1}{2}$ , 32, 32, 33, 33	32.1
38	33, 33 $\frac{1}{2}$ , 34, 32 $\frac{1}{2}$ , 32, 33, 33, 33, 33, 33 $\frac{1}{2}$ , 33, 34, 33, 33, 33	33.1
39	33, 34, 33, 34, 33, 34, 34	33.6
40	34, 33 $\frac{1}{2}$ , 35, 35, 37, 34, 34	34.6

Figure 24. (Continued)

Resistor Circuit No.	Upper Section	
	Time Intervals	
1	1.2, 1.2, 1.2, 1.2, 1.6, 1.6	
2	8, 8, 8, 8, 8, 8, 8	
3	12.8, 12.8, 12.8, 12.8, 12.8, 12.8, 12.4, 12.8, 12.4, 12, 12.8, 12.4	
4	12.8, 12.8, 12.8, 12.8, 12.8, 12.8, 12.4, 12.8, 12.8, 12.8, 12.4, 12.8, 12.4, 12.8, 12.8	
5	17.2, 16.8, 16.8, 16.8, 16.8, 16.8	
6	16.8, 16.8, 16.8, 16.8, 16.8, 17.2, 16.8	
7	20, 20.4, 20.8, 21.2, 20.8, 21.6, 20.8, 20.8, 20.8, 20.8, 20, 20	
8	20.8, 20.4, 20.8, 19.6, 20.8, 20.8, 20.8	
9	20.8, 21.6, 20.8, 20.8, 20, 20.8, 21.2, 20.8, 20.8, 21.6, 20.8, 20.8	
10	21.6, 20.8, 20.8, 20.8, 20.8, 20.8, 20.4	
11	24.4, 24.8, 24.8, 25.2, 25.6, 24.8, 25.6, 24.4, 24.8, 24.8, 25.2, 24, 25, 24.8	
12	25.6, 25.2, 26, 25.6, 29.2, 24.4, 25.2, 24	
13	25.6, 24.8, 25.6, 25.2, 24.8, 24.4, 24.4, 25.2, 25.2, 24	
14	25.2, 24.8	
15	28.8, 30, 29.2, 29.6, 29.6, 29.6, 28.8, 28.8, 28.4, 28.4, 28.8, 28, 28.8, 28, 28	
16	29.6, 28.8, 28.8, 28.8, 28	
17	28.8	
18	29.6, 29.6, 28.4, 28.8, 28.8, 28, 28.4, 28.8	
19	32.8, 32, 32, 32, 32, 31.2, 32, 32.8, 31.6, 32.4	
20	32.8, 32.4, 33.2, 32, 34.4, 31.6, 32, 32, 30.8	
21	32.8, 32.8, 32.8, 31.2, 30.4, 32, 30	
22	32, 30.8, 32.4, 31.6, 31.2	
23	35.2, 35.6, 36, 34.4, 34	
24	36, 34, 42, 34.4, 34, 34.8, 34.8, 34, 35.6, 34.8, 35.2	
25	36, 36, 34.4, 35.2, 34.8, 34	
26	36, 35.2, 35.6, 34, 34.8, 35.2, 34	
27	39.2, 39.2, 39.2, 38, 39.2	
28	37.6, 40, 39.2, 38.8, 37.6, 38.4, 37.6, 38, 38	
29	40, 38.4, 38.4, 38.8, 38, 38.8	
30	39.2, 39.6, 40, 38.8, 38.4, 38.4, 38.4, 38.4, 38, 37.6, 37.2	
31	40.8, 42, 43.2, 41.6, 42.8, 42.8	
32	43.6, 43.6, 44, 43.6, 40.8, 43.6, 42, 40.4, 40.4	
33	42.8, 44, 42, 42, 41.6, 42, 41.2, 43.2, 43.2	
34	44, 44, 43.6, 42, 41.6, 42, 42, 42.8, 42, 41.6, 42.8, 42.8, 42.8	
35	44.8, 48, 47.6, 47.2, 46.4, 46.4, 46, 46.4, 45.6, 43.6, 46, 47.2	
36	48, 48, 46, 46.4, 46, 46.4, 46.4, 44.8, 47.2, 45.6, 46, 46.8, 47.2, 46, 45	

Figure 25. Similar Distribution Data

## Upper Section (Continued)

Resistor Circuit No.	Time Intervals
37	52, 49.6, 50.4, 50.4, 50.8
38	50.8, 52, 50.8, 50, 50, 48.8, 49.2, 48, 50, 54.4
39	54.4, 54, 52, 52, 52, 52.8, 52
40	57.6, 59.6, 57.2, 56.8, 56, 57.6

## Lower Section

1	1.6, 1.2, 1.2, 1.6, 1.6
2	8, 8, 8, 8, 8, 8, 8, 8, 8, 8, 7.6, 8
3	12.8, 12.8, 13.2, 12.8, 12.8, 12.8, 12.8, 12.8, 12.8, 12.8
4	12.8, 12.8, 12.8
5	17.2, 17.2, 17.2, 16.4, 16.8, 16.8, 17.2, 16.8, 16.8, 16.8, 16.8, 16
6	16.8, 17.2, 16.8, 16.8, 16.8, 16.8
7	20.4, 20.4, 21.2, 20.8, 20.4, 22, 20.4, 20
8	20.8, 21.2, 21.2, 20, 20.4, 20.4, 20.8, 21.2, 20
9	20, 21.6, 21.2, 20.4, 20.8, 20.4, 20.8, 20.8, 20.8, 20.8, 20, 20.8, 20.4
10	20.8, 21.2, 20.4, 21.2, 20.4, 20.8, 21.2, 21.2, 19.6, 21.2, 20.8
11	25.6, 25.2, 24.8, 25.6, 24.8, 24.8, 24.8
12	25.2, 25.6, 25.6, 25.2, 25.6, 24.8, 24.8, 25.6, 25.2, 26
13	25.2, 25.6, 26, 25.2, 25.6, 26, 24.8, 25.2, 25.2, 25.6, 25.6, 26
14	25.6, 26, 25.6, 25.6, 25.6, 25.2
15	29.6, 28.8, 28.8, 28, 28.8, 28.8, 28.8, 29.8, 28
16	29.6, 29.6, 28.8, 27.6, 28, 28.8, 28.8, 28.8, 28, 28
17	29.6, 29.2, 29.6, 29.2, 28.8, 28.4, 28, 27.6, 27.6, 29.6, 29.2, 28
18	28.8, 29.2, 28.4, 28.8, 28, 28
19	32, 32.4, 32, 32.4, 32, 30.8, 32, 32.4, 32.4, 32
20	32.8, 32.8, 32, 32, 32, 32.4, 30.8, 30
21	32, 31.6, 31.6, 32, 31
22	31.6, 32, 30.8, 31.2, 32.4, 30.8
23	35.6, 36, 36, 35.6, 35.2, 34.4, 34.4, 36, 35.6
24	35.2, 34, 36.4, 36.4, 36, 35.2, 34, 34.4, 36, 35.6, 36, 34, 34.4
25	36, 34.8, 36, 34.8, 34.8, 34, 34, 34.4, 35.6, 35.2
26	35.2, 34.8, 35.6, 35.6
27	38.4, 38, 39.2, 39.2
28	40, 39.2, 38.8
29	40, 40, 40, 39.6, 40, 38, 38, 38

Figure 25. (Continued)

Resistor Circuit No.	Down Section									
	Time Intervals									
30	39.6,	39.6,	39.6,	40,	40,	38.8,	39.2,	38.4,	38.8,	
	38.8,	38.4,	38.4,	37.6						
31	43.2,	43.6,	42,	41.6,	42.4,	41.2				
32	43.6,	44,	42,	42,	41.6,	42,	42.8,	41		
33	43.6,	43.6,	43.6,	42,	42.8,	42,	42,	42,	40.4,	
	43.2									
34	41.6,	42.8,	42,	42,	43.2,	42.4				
35	47.6,	47.6,	46,	46.8,	51.2,	46,	46,	45.2,	46,	
	44.8,	45.2,	47.2,	45.2,	45					
36	48.8,	46,	46,	46.4,	47.2,	46.8,	46.8,	45.6		
37	51.2,	49.6,	48.8,	48.8,	50,	50,	54.8,	48.4		
38	50.4,	48.8,	49.2,	50,	48.4,	50,	50,	52,	48	
39	52,	52.4,	54.8,	54.4,	54,	54,	54.4,	54,	52	
40	60.8,	58,	59.6,	58.8,	58,	57.2,	58,	57.2,	60	

Figure 25. (Continued)

Service Channel  
 Section Up  
 Date 9-25-65  
 Time P. M.

Resistor Circuit No.	Time Intervals
1.	.18, .18, .20, .20, .22, .20, .18, .20, .18, .16
2.	15.7, 16.2, 16.5, 16.5, 16.9, 16.65, 16.2, 16.72, 17.15, 16.38, 16.35
3.	.32, .30, .32, .40, .34, .22, .32, .30, .32
4.	11.7, 12.0, 12.55, 12.0, 12.20, 12.15, 11.9, 12.20, 12.15, 12.71, 12.6, 11.72, 11.6, 12.35
5.	.70, .65, .60, .60, .62, .70, .62, .70, .65, .65, .60, .65
6.	9.4, 10.3, 9.25, 9.38, 9.6, 10.0, 10.15, 9.25, 9.5, 9.78, 9.9, 9.95, 9.6, 9.76, 9.85, 9.65, 9.62, 9.45
7.	.90, .90, 1.0, .90, .95, .90, .92, 1.0
8.	7.75, 8.0, 8.4, 7.62, 8.0, 8.05, 8.4, 8.1, 8.15, 7.89
9.	1.15, 1.22, 1.3, 1.25, 1.23, 1.18, 1.25, 1.2, 1.3, 1.25, 1.2, 1.1, 1.2, 1.1
10.	6.7, 6.82, 6.75, 6.83, 6.9, 6.9, 6.9, 6.95, 6.99, 6.64, 7.15, 6.5, 6.9, 6.8, 7.0
11.	1.55, 1.55, 1.55, 1.41, 1.47, 1.6, 1.6, 1.55, 1.65, 1.6, 1.45, 1.62, 1.6, 1.55, 1.52, 1.6, 1.6, 1.55, 1.62, 1.6
12.	6.05, 5.9, 6.3, 6.0, 6.0, 6.25, 5.82, 5.8, 5.9, 6.4, 5.95
13.	1.8, 1.95, 1.85, 1.85, 1.8, 1.82, 1.9, 1.68, 1.95, 1.78, 1.78, 1.95
14.	5.3, 4.95, 5.35, 5.4, 5.27, 5.32, 5.1, 5.35, 5.6, 4.55, 5.05, 5.12, 5.25, 5.4, 5.1, 5.5, 5.2
15.	2.15, 2.12, 2.26, 2.21, 2.55, 2.12, 2.5, 2.35, 2.3, 2.3, 2.2, 2.3, 2.3, 2.2, 2.4
16.	4.42, 4.62, 4.68, 4.7, 4.68, 4.35, 4.72, 4.3, 4.3, 4.65, 4.45
17.	2.55, 2.52, 2.65, 2.69, 2.7, 2.64, 2.68
18.	3.8, 4.1, 4.05, 4.07, 4.15, 4.1, 3.96, 4.12, 3.82, 3.9, 4.1
19.	3.1, 3.23, 3.1, 3.1, 3.28, 3.23, 3.3, 3.3
20.	2.92, 3.0, 2.8, 2.95, 2.95, 3.1, 3.2, 2.9, 3.1, 3.05, 3.0, 2.86, 2.92, 3.1, 3.0, 3.0
21.	3.42, 3.22, 3.72, 3.45, 3.41, 3.4, 3.4, 3.6, 3.34, 3.5

Figure 26. Exponential Distribution Data

Resistor  
Circuit  
No.

Time Intervals

---

22.	3.65, 3.65, 3.42, 3.62, 3.65, 3.75, 4.6, 4.8, 3.65
23.	2.75, 2.8, 2.9, 2.82, 2.9, 2.7, 2.8, 2.7, 2.85, 2.85, 2.72
24.	4.35, 4.12, 4.4, 4.15, 4.18, 4.32, 4.25, 4.4, 4.42, 4.4, 4.4, 4.2
25.	2.4, 2.3, 2.32, 2.45, 2.55, 2.5, 2.38, 2.5, 2.5
26.	5.1, 4.65, 4.92, 4.92, 4.8, 4.8, 4.8, 4.92, 5.2, 5.15, 3.72, 4.82, 5.35
27.	2.05, 2.1, 1.95, 2.05, 2.05, 2.05, 2.0, 1.97, 2.12, 2.1, 2.0, 2.1, 2.0, 1.85, 2.0, 2.05
28.	5.33, 5.6, 5.95, 5.7, 5.82, 5.8, 5.7
29.	1.64, 1.75, 1.68, 1.77, 1.72, 1.62, 1.75, 1.62, 1.68, 1.68, 1.65, 1.7, 1.65, 1.75
30.	6.4, 6.42, 6.75, 6.7, 7.0, 6.5, 6.2, 6.7, 6.65, 6.58, 6.42, 6.62
31.	1.5, 1.4, 1.5, 1.4, 1.35, 1.45, 1.48, 1.5, 1.31
32.	8.0, 7.52, 7.85, 7.8, 7.5, 7.5, 7.5
33.	1.1, 1.12, 1.1, 1.12, 1.1, 1.08
34.	8.75, 8.86, 8.95, 8.85, 8.68, 8.92, 9.0, 9.07, 8.78, 9.4
35.	.72, .70, .78, .72, .72, .82, .80, .85, .78, .80, .72, .80, .75
36.	10.6, 10.0, 10.71, 10.9, 11.0, 10.36, 10.34, 10.85
37.	.48, .50, .50, .50, .50, .50, .45, .40
38.	13.55, 14.2, 14.07, 13.25, 14.32, 13.63, 13.45, 13.35
39.	.18, .20, .22, .20, .20, .22, .20, .20, .20, .22
40.	22.05, 23.35, 22.4, 22.6, 23.0, 21.9, 21.92, 23.35, 21.85, 22.4, 24.1, 21.97, 23.15, 21.42, 21.9

Service Channel  
Section Down

1.	.20, .19, .20, .20, .20, .20, .18, .20, .20, .20, .20, .20, .20, .18
2.	15.58, 15.95, 15.82, 16.82, 17.14, 16.4, 11.7, 16.8, 16.5, 16.4, 17.02, 17.3, 17.6
3.	.32, .30, .30, .30, .30, .30, .30, .30, .32, .30, .35, .35, .30
4.	12.1, 10.95, 12.3, 11.85, 12.2, 12.12, 12.3, 12.3, 12.7, 12.9, 12.32, 11.76, 12.0, 11.85, 12.0, 12.0

---

Figure 26. (Continued)

Resistor Circuit No.	Time Intervals
5.	.60, .60, .60, .60, .63, .70, .70
6.	10.3, 9.85, 9.83, 10.1, 10.1, 9.62, 10.2, 9.35
7.	.85, .92, .90, 1.05, 1.05, .85, .80, .92, 1.0, .9
8.	7.8, 8.5, 8.2, 8.8, 7.97, 8.0, 8.1, 8.42, 8.05, 8.02, 8.1, 8.3, 7.8
9.	1.2, 1.2, 1.2, 1.2, 1.2, 1.22, 1.2
10.	7.0, 7.32, 7.2, 6.6, 7.4, 7.07, 6.85, 6.9
11.	1.62, 1.55, 1.52, 1.55, 1.58, 1.62, 1.45, 1.51, 1.5, 1.55, 1.55
12.	5.85, 6.3, 6.35, 5.72, 5.95, 5.78, 5.9, 6.2, 5.92, 5.85, 6.45, 6.3, 5.85
13.	1.8, 1.67, 1.8, 1.75, 1.8, 1.58, 1.9, 1.8, 1.8, 1.8, 1.75, 1.85, 1.9, 1.85, 1.7, 1.82
14.	5.1, 5.15, 5.25, 5.1, 5.05, 5.4, 5.1, 5.3, 5.6, 5.32, 5.2, 5.4, 5.65, 5.62
15.	2.18, 2.25, 2.15, 2.18, 2.2, 2.2
16.	4.35, 4.8, 4.88, 4.61, 4.7, 4.55, 4.45, 4.2, 4.5, 4.6, 4.62, 4.25
17.	2.52, 2.62, 2.45, 2.6, 2.6, 2.65, 2.8, 2.7, 2.5, 2.8
18.	3.8, 4.02, 3.78, 3.85, 4.0, 4.12, 3.7, 4.05, 4.05, 4.1, 3.72
19.	3.15, 3.1, 3.05, 3.1, 2.98, 3.05, 2.35, 3.08, 3.04, 3.12, 3.0, 3.12, 3.08, 3.0, 3.05, 3.1, 3.1
20.	3.52, 3.28, 3.35, 3.4, 3.5, 3.6, 3.2, 3.32, 3.55, 3.3, 3.5, 3.6
21.	3.1, 3.3, 3.0, 3.3, 3.33, 3.32, 3.2, 3.35, 3.18, 3.3, 3.2, 3.25, 3.28, 3.25, 3.0, 3.2, 3.1
22.	3.64, 3.85, 3.87, 3.42, 4.0, 3.82, 3.8
23.	2.78, 2.55, 2.7, 2.78, 2.9, 2.7, 2.85, 2.72
24.	4.5, 4.35, 4.2, 4.1, 4.35, 4.42, 4.3, 4.5, 4.24, 4.35, 4.25, 4.3, 4.3, 4.35
25.	2.23, 2.4, 2.4, 2.42, 2.42, 2.5, 4.42, 2.4, 2.45, 2.4, 2.5, 2.41, 2.45, 2.25
26.	4.95, 5.02, 4.82, 4.78, 5.0, 5.25, 5.2, 4.85, 5.1, 5.2, 4.98
27.	2.0, 2.15, 2.1, 2.05, 1.95, 2.12, 1.95, 2.05, 2.0, 1.9, 2.05
28.	5.22, 6.0, 5.35, 5.38, 5.71, 5.78, 5.6, 5.37, 5.8, 5.54, 5.42
29.	1.7, 1.7, 1.57, 1.6, 1.72, 1.72, 1.65, 1.58, 1.7, 1.74, 1.62, 1.6, 1.72
30.	6.9, 6.8, 6.38, 6.7, 6.4, 6.5, 6.55, 6.5, 6.3, 7.05, 6.6, 6.7, 6.25, 6.62, 6.4, 6.05, 5.9, 6.55

Figure 26. (Continued)



Resistor  
Circuit  
No.

Time Intervals

---

31.	1.45, 1.42, 1.35, 1.42, 1.42, 1.45, 1.3, 1.5, 1.4, 1.42, 1.35, 1.35
32.	7.5, 7.58, 7.22, 7.8
33.	1.02, 1.1, 1.05, 1.15, 1.05, 1.05, 1.08, 1.1
34.	8.3, 8.47, 8.61, 8.82, 8.2
35.	.80, .75, 1.15, .75, .72, .72, .80, .80, .78, .75, .72
36.	10.5, 10.62, 11.15, 10.78, 10.44, 11.02, 10.92
37.	.45, .40, .42, .45, .45, .50, .45, .42, .50, .45, .45, .45, .45
38.	13.0, 13.28, 13.65, 14.8, 13.72, 14.42, 14.35, 13.9, 13.8, 14.28, 13.3, 14.35
39.	.18, .20, .20, .18, .20, .19, .20, .15, .15, .20, .20, .20, .20, .20, .15
40.	21.25, 21.05, 22.1, 21.0, 22.2, 22.3, 21.05, 22.2, 21.0, 23.32, 21.55, 21.1, 21.3, 22.8, 21.6

Arrival Channel  
Section Up  
Date 9-25-65  
Time 9-12 p.m.

1.	.20, .20, .19, .18, .19, .20, .19, .18, .20, .20, .18
2.	21.3, 21.7, 19.74, 21.4, 21.35, 21.15, 21.5, 21.3
3.	.40, .40, .45, .40, .38, .40, .38, .40, .40, .40, .40, .40
4.	15.5, 15.7, 16.05, 15.65, 15.52, 15.62, 15.64, 15.45, 15.67, 15.62, 15.9
5.	.80, .72, .70, .75, .75, .75, .72, .70, .74, .80
6.	12.4, 12.35, 12.42, 12.32, 12.52, 12.3, 12.28, 12.61, 12.5, 12.55
7.	1.2, 1.1, 1.1, 1.1, 1.08, 1.1, 1.08, 1.1, 1.11, 1.12, 1.08, 1.08, 1.12, 1.16, 1.15, 1.1, 1.15
8.	10.2, 10.58, 12.6, 10.45, 10.33, 10.6, 10.5, 10.45, 10.5, 10.42, 10.5, 10.36, 10.5
9.	1.55, 1.57, 1.51, 1.58, 1.5, 1.52, 1.35, 1.55, 1.5, 1.51, 1.57, 1.5
10.	9.18, 9.35, 9.15, 9.06, 9.0, 9.0, 9.75, 9.1, 9.15, 9.11
11.	1.51, 2.0, 2.05, 1.95, 2.07, 1.95, 2.0, 1.8, 2.0, 2.0, 2.05, 2.0, 1.98, 1.85, 2.0, 2.0
12.	8.0, 7.85, 7.9, 8.0, 7.9, 7.82, 7.95, 7.85, 7.96, 7.88, 7.92, 8.02

Figure 26. (Continued)

Resistor Circuit No.	Time Intervals
13.	2.41, 2.38, 2.4, 2.44, 1.82, 2.38, 2.41, 2.4, 2.38, 2.32, 2.42
14.	6.9, 6.9, 7.05, 6.9, 7.0, 7.01, 7.08, 6.98, 6.92, 6.96, 7.0, 7.0, 6.95
15.	2.85, 2.81, 2.9
16.	6.14, 6.1, 6.1, 6.4, 6.05, 6.05, 5.95
17.	3.41, 3.45, 3.41, 3.4, 3.4, 3.45, 3.45, 3.4, 3.45, 3.48, 3.5
18.	5.3, 5.3, 5.24, 5.35, 5.5, 5.48, 5.21, 5.35, 5.28, 5.24, 5.4
19.	4.05, 4.0, 3.9, 4.08, 4.0, 3.97, 4.02, 4.05, 4.01, 4.0, 4.05, 4.0, 4.05, 4.1
20.	4.71, 4.6, 4.72, 4.62, 4.65, 4.65, 4.55, 4.62, 4.68, 4.74, 4.72
21.	4.4, 4.4, 4.25, 4.4, 4.25, 4.3, 4.34, 4.28, 4.3 4.3, 4.32, 4.4, 4.32
22.	5.0, 5.09, 4.9, 4.82, 5.0, 5.08, 4.91, 5.01, 5.0, 5.0, 5.0, 5.1
23.	3.69, 3.74, 3.61, 3.7, 3.69, 3.61, 3.7
24.	5.7, 5.72, 5.85, 5.7, 5.71, 5.7, 5.75, 5.75, 5.65, 5.7, 5.7, 5.7, 5.7, 5.8
25.	3.17, 3.25, 3.2, 3.15, 3.12, 3.1, 3.18, 3.04, 3.15, 3.2, 3.15, 3.1
26.	6.38, 6.55, 6.4, 6.58, 6.56, 6.6, 6.55, 6.53, 6.38, 6.31, 6.53, 6.5
27.	2.65, 2.61, 2.58, 2.62, 2.65, 2.62, 2.54, 2.6, 2.6, 2.6, 2.55
28.	7.25, 7.65, 7.4, 7.41, 7.4, 7.5, 7.43, 7.48, 7.22, 7.48
29.	2.21, 2.15, 2.2, 2.11, 2.2, 2.17, 2.2, 2.2, 2.16, 2.15, 2.2, 2.18, 2.18, 2.21, 2.2
30.	8.67, 8.41, 8.35, 8.35, 8.45, 8.4, 8.4, 8.55, 8.45, 8.22, 8.5, 8.5, 8.55
31.	1.7, 1.7, 1.75, 1.7, 1.77, 1.7, 1.72, 1.74, 1.69, 1.75, 1.65, 1.75, 1.65, 1.68, 1.74
32.	9.58, 9.52, 9.83, 9.55, 9.4, 9.78, 9.6
33.	1.3, 1.28, 1.3, 1.37, 1.3, 1.3, 1.37, 1.35, 1.3, 1.28, 1.31
34.	11.3, 11.4, 11.42, 11.45, 11.4, 11.31, 11.32, 11.45, 11.4
35.	.91, .92, .90, .91, .95, .90, .91, .90, .92, .92, .95
36.	13.35, 13.85, 14.0, 14.05, 13.81, 14.25, 14.5, 13.85
37.	.55, .55, .60, .55, .50, .55, .55, .40, .52

Figure 26. (Continued)

Resistor  
Circuit  
No.

Time Intervals

---

38.	17.72, 17.6, 17.81, 17.8, 17.75, 17.6, 17.9, 17.75, 17.5, 18.0, 17.42, 17.8
39.	.20, .20, .19, .19, .19, .19, .18, .20, .20, .20
40.	27.4, 27.3, 28.0, 28.2, 30.0, 27.4, 27.4, 27.8, 28.08, 27.85, 27.02, 28.4, 27.5, 28.35

Arrival Channel  
Section Down

1.	.19, .18, .20, .20, .20, .17, .18, .18, .20, .19, .20
2.	22.0, 22.05, 22.52, 22.0, 21.91, 21.91, 21.95, 21.95, 21.95, 22.05, 22.08, 21.91, 22.2, 22.42
3.	.40, .40, .40, .38, .42, .42, .41, .41, .40, .38, .41
4.	15.95, 16.25, 16.12, 16.0, 16.2, 16.12, 16.12, 16.16, 16.0, 16.0, 16.35
5.	.71, .76, .75, .75, .71, .75, .72, .71, .75
6.	12.7, 13.0, 12.95, 13.0, 12.97, 13.52, 12.8, 12.75, 13.0, 12.95
7.	1.09, 1.07, 1.1, 1.05, 1.07, 1.1, 1.1, 1.1, 1.1, 1.1, 1.06
8.	10.8, 10.7, 10.95, 10.78, 10.92, 10.81, 11.0, 10.92, 10.97
9.	1.85, 1.5, 1.51, 1.5, 1.45, 1.5, 1.45, 1.5, 1.42
10.	9.4, 9.7, 8.8, 9.2, 9.5, 9.2, 9.21, 9.3, 9.36, 8.45, 9.45, 9.3
11.	1.98, 1.95, 1.95, 1.91, 1.91, 1.97, 2.0, 2.0, 1.95, 1.97, 2.0
12.	8.07, 8.0, 8.1, 8.0, 8.1, 8.07, 8.0, 8.06, 8.15, 8.0, 7.95, 8.0, 8.0, 8.02, 8.05, 8.1, 7.9, 8.01, 8.1
13.	2.31, 2.42, 2.31, 2.4, 2.37, 2.35, 2.38, 2.4, 2.35, 2.32, 2.31, 2.38
14.	7.1, 6.9, 7.1, 7.1, 6.81, 7.01, 6.95, 7.1, 6.9, 7.05, 7.05, 7.05, 6.9
15.	2.85, 2.9, 2.78, 2.82, 2.9, 2.82, 2.8, 2.8, 2.85, 2.85, 2.85
16.	5.99, 5.92, 6.08, 6.05, 5.97, 6.05, 6.05, 6.05
17.	3.4, 3.4, 3.51, 3.37, 3.35, 3.35, 3.38, 3.37
18.	5.3, 5.35, 5.2, 5.2, 5.2, 5.22, 5.32, 5.29, 5.21, 5.21, 5.25, 5.25
19.	3.95, 3.85, 3.9, 4.05, 4.05, 3.9, 3.9, 4.0, 3.92, 3.97, 4.0, 3.92, 4.0

---

Figure 26. (Continued)

Resistor Circuit No.	Time Intervals
20.	4.6, 4.65, 4.6, 4.68, 4.68, 4.5, 4.58, 4.6, 4.57, 4.62, 4.51, 4.55, 4.58, 4.62, 4.6, 3.98, 4.82
21.	4.21, 4.3, 4.3, 4.3, 4.2, 4.3, 4.2, 4.32
22.	4.95, 4.92, 4.9, 4.5, 4.95, 4.95, 5.0, 4.96
23.	3.5, 3.65, 3.69, 3.7, 3.7, 3.62, 3.9
24.	5.78, 5.69, 5.68, 5.62, 5.65, 5.75, 5.7, 5.72, 5.85
25.	3.1, 3.1, 3.1, 3.1, 3.1, 3.12, 3.1
26.	6.5, 6.5, 6.55, 6.6, 6.5, 6.58, 6.68, 6.53, 6.6, 6.55, 6.32, 6.55
27.	2.6, 2.6, 2.57, 2.54, 2.55, 2.58, 2.58, 2.46, 2.6, 2.51
28.	7.5, 7.48, 7.5, 7.55, 7.25, 7.6, 7.45, 7.55, 7.4, 7.48
29.	2.2, 2.17, 2.2, 2.14, 2.13, 2.12, 2.2, 2.35, 2.28, 2.15, 2.13, 2.18, 2.34
30.	8.57, 8.4, 8.45, 8.72, 8.43, 8.51, 8.51, 8.6, 8.45, 8.6, 8.45, 8.51
31.	1.71, 1.7, 1.65, 1.64, 1.8, 1.95, 1.72, 1.7, 1.65
32.	10.1, 9.64, 10.2, 10.15, 10.0, 10.02, 10.0, 10.19, 10.05, 10.2, 10.15
33.	1.21, 1.3, 1.26, 1.3, 1.3, 1.26, 1.28, 1.28, 1.31
34.	11.9, 11.7, 12.0, 11.89, 11.9, 11.6, 11.85, 11.05, 11.91
35.	13.9, .90, .89, .92, .90, .90, .98, .95, .95, .92, .91, .95, .90
36.	14.0, 14.47, 14.05, 14.5, 14.35, 14.48, 14.6, 14.68, 14.25
37.	.55, .60, .55, .56, .60, .55, .58, .60, .60, .58, .60, .60
38.	18.6, 18.1, 18.45, 18.3, 18.3, 18.45, 19.0, 18.05, 18.6, 18.57, 18.46, 18.31, 18.4, 18.7, 18.4, 18.4, 18.78, 18.8, 8.61
39.	.20, .20, .20, .20, .20, .20, .18, .20, .20, .20
40.	28.71, 28.95, 28.9, 29.3, 28.65, 28.52, 29.0, 29.85, 28.79, 28.57, 29.1, 28.72, 28.81, 28.95, 29.6

---

Figure 26. (Continued)

Queue  
Length

Time Interval

---

0. 5.4, 5.7, 1.2, 1.1, 2.3, 11.1, 1.8, 5.65, 1.25,  
6.9, 16.7, 4.9, .40, 4.2, 5.3, 4.8, 6.6, 2.7, 6.5,  
19.2, .40, 1.2, .80, 3.4, 3.1, 2.1, 2.85, 2.1,  
.50, .10, 9.6, 2.2, .20, 14.7, 16.5, 2.1, 23.0,  
3.1, 13.0, .80, 3.5, 2.1, .30, 6.7, 9.9, 2.8, .90,  
13.6, 9.1, 5.1, 1.4, 4.9, 4.4, 8.9, 5.4, 6.3, 1.3,  
.40, 4.5, 2.3, 2.5, 10.5, 3.9, 3.85, 17.0, 12.6,  
5.0, 2.3, 10.0, .60, 11.6, 1.4, 3.1, 2.3, .40,  
2.4, .60, 5.5, 7.3, 1.7, 2.15, 22.2, 3.6, 1.2,  
19.8, 4.3, 5.9, 11.2, 6.6, 5.5, 1.9, 7.4, 6.7,  
8.9, 3.9, 11.9, 25.2, 1.2, .30, 13.9, 5.4, 9.4,  
4.6, 8.0, 5.4, 2.1, 3.0, 1.7, .70, 3.0, 14.3, 8.0,  
5.3, .20, 9.9, .8, 20.7, 2.2, 1.8, 3.7, 1.0, 1.7,  
.10, .40, 2.9, 20.3, 6.3, 6.4, 8.2, 18.3, 26.7,  
11.1, 3.3, 3.1, 3.9, 8.2, 6.9, .70, 3.1, .20, 5.2,  
8.6, 3.9, 20.7, 4.7, 10.2, 3.7, .20, 7.1, 4.4,  
13.0, 1.3, 5.5, 3.9, 20.6, 9.2, 11.2, 26.4, 4.0,  
6.0, 11.8, .10, 1.2, .40, 11.2, 4.8, 2.8, 18.5,  
2.7, 2.3, 1.6, 14.9, 11.2, 1.0, 14.5, 20.3, 3.7,  
7.8, .70, 4.6, .80, 6.8, 5.3, 16.9, 2.7, 4.1, .60,  
7.7, 6.8, 20.7, .30, 2.2, .70, 18.4, 1.6, 14.7,  
6.3, 1.4, 2.9, .20, .20, 8.8, 2.1, 5.4, 9., 1.5,  
3.8, 4.8, 2.2, 17.7, 28.5, 10.6, 7.4

1. 1.1, 1.4, 3.1, 1.7, 1.15, 3.15, 4.4, 2.1, 9.4,  
1.5, .20, 7.25, 1.85, 4.95, 1.7, .40, 4.5, 1.9,  
.90, .90, 1.0, 2.3, .50, 2.2, 1.95, .20, 5.7, 1.3,  
.70, 3.4, 6.9, 8.1, 3.1, 1.1, 2.25, 4.1, 1.5, 2.0,  
1.6, 3.1, 1.0, 1.1, 1.9, 4.0, .40, 8.4, 4.3, 5.35,  
5.6, 1.95, 1.3, .40, 1.2, .20, 1.0, 2.1, 1.7, 1.75,  
.70, .80, 3.4, 1.7, 1.6, .20, 1.4, .10, .60, 2.5,  
.30, 3.9, 1.1, 2.6, .60, .30, .50, 5.2, 3.40, 13.4,  
.68, 1.1, 1.6, 9.7, 1.7, 4.3, .45, 1.25, 2.3, 3.8,  
1.2, 2.3, .90, 3.1, 1.9, 1.2, 1.8, 4.3, .70, .80,  
5.7, 2.5, 5.4, 3.1, 2.0, 5.8, .20, .40, 1.4, 1.3,  
.90, 4.85, 5.8, 1.85, 1.0, 3.25, .20, 3.7, 2.4,  
2.1, 6.4, .50, .80, 1.6, .60, .70, 2.2, .70, 2.2,  
3.35, 5.8, 1.9, 1.65, 3.6, 3.75, 1.1, .50, 2.7,  
4.4, 1.2, 3.7, .20, 1.1, 1.2, 6.9, .70, 8.0, 4.6,  
2.2, 5.8, 17.3, .80, .90, 3.6, 3.5, 1.7, .80,  
5.3, 5.4, 11.7, 1.5, 2.1, 1.4, .20, 3.2, 1.8, 4.0,  
1.4, 2.9, 1.5, 2.0, 3.8, 26.8, 1.4, 15.8, 1.7,  
.30, 5.8, .20, 1.0, 2.8, 3.0, 5.4, 3.1, 3.1, 2.4,  
3.2, .20, 1.0, 3.7, 6.8, 1.5, .80, .30, 4.4, 8.5,  
5.5, 1.7, 3.9, 3.5, 1.8, 2.2, 2.5, 8.0, 9.9, 2.6,  
1.4, 5.1, .70, .40, 5.0, .80, .80, 2.3, .80, 1.6,  
7.0, 3.4, 2.0, 3.0, 1.9, 1.2, 1.9, 1.7, 14.3, 8.0,

---

Figure 27. Queue Length Data

Queue  
Length

Time Interval

1.4, 6.1, 2.1, 1.4, 1.1, 7.6, 2.9, 1.0, 2.9, 1.9,  
 1.2, 9.0, .70, .60, 1.32, .50, 3.0, .20, .20,  
 2.2, .40, 12.8, 2.9, 5.3, 3.6, .10, 1.0, .50,  
 4.3, 4.2, 7.0, 1.3, 3.9, 2.8, .40, 8.2, 4.8, 4.1,  
 1.5, 3.0, .20, 2.6, .40, 5.1, 2.4, 4.6, .60, 1.0,  
 .30, 3.4, .70, 3.4, 1.5, 5.0, 1.7, 1.4, 4.9, 4.7,  
 2.9, 2.8, 5.5, 1.2, 8.5, 1.8, 3.1, 2.4, 1.3, 2.15,  
 5.8, .30, 2.6, 5.3, 1.0, .20, 3.3, 2.1, 4.7, .40,  
 5.0, 1.4, .3, 6.0, 1.5, 1.5, 2.65, 7.0, 1.7, 1.9,  
 1.7, 1.1, 3.4, 3.4, .20, 1.6, .80, 10.9, 4.4,  
 6.9, 3.1, 3.1, 2.8, .20, .20, 9.4, .40, 3.5, 4.2,  
 1.7, .30, 1.3, 8.1, 1.2, .20, 2.5, 3.3, 4.7, .20,  
 2.4, 12.4, 5.5, .90, 1.9, 2.9, 3.8, 6.7, 2.5, .60,  
 2.7, 1.1, 3.1, 1.7, 1.8, 1.4, 1.3, .80, 4.4, 3.1,  
 3.1, 1.7, 1.1, .60, .50, 1.8, 1.5, 15.7, 1.0, 1.7,  
 8.2, 15.6, 4.0, 7.1, 1.8, 7.9, 18.0, 1.9, .70,  
 2.4, .20, .30, 4.25, .60, 1.7, .20, .20, 1.0, 5.1,  
 1.7, .20, .30, 6.5, 1.1, .50, 4.6, 3.5, .20, .10  
 2. 5.8, 2.4, 1.3, 5.9, 8.2, 1.6, .20, 1.2, .10, 7.9,  
 .60, 3.1, 1.1, 2.35, 3.7, .70, 7.9, .20, 1.5, 3.1,  
 3.7, .20, 1.5, 3.3, 1.4, 13.35, 2.4, 3.25, 5.4,  
 .30, 2.1, 5.4, .40, 2.7, .80, 4.6, 2.4, 5.3, 6.2,  
 6.2, 3.5, 1.21, 1.1, .60, 2.6, 2.1, 5.1, 2.7, .50,  
 1.5, 4.2, 6.6, .30, .60, .90, 3.75, 2.85, 2.9,  
 17.8, 2.0, .40, 8.6, .80, 3.1, .70, .40, 3.4, 1.8,  
 2.4, .80, 3.7, 2.0, 3.2, .40, 1.1, 3.3, 2.8, .10,  
 .60, 4.8, 7.0, 2.0, 1.6, 6.6, 3.6, .20, .80, 1.8,  
 11.7, 2.2, 1.4, 1.4, .20, .60, 8.1, 1.4, 2.6, 2.3,  
 .10, .40, 1.9, .50, 2.9, 10.7, 5.2, 1.8, 9.5, 2.8,  
 .50, 7.1, 2.9, 1.4, .90, 2.4, 1.2, 14.7, 2.8, 8.6,  
 1.0, .20, .80, 1.0, 1.7, .70, 2.8, 1.1, 2.4, 6.8,  
 2.1, .40, 2.1, 1.0, 4.8, 4.8, 1.7, .60, 4.4, 3.8,  
 1.8, 1.5, 1.3, 1.4, 5.8, .20, .30, .10, 2.4, 4.4,  
 .20, 3.0, 1.6, 2.4, 1.3, 4.1, 2.4, .60, .30, .40,  
 2.5, 8.6, .75, 1.4, 8.4, 1.0, 1.2, 4.7, .30, .40,  
 2.2, 3.3, 2.6, .60, 2.7, 2.1, 2.6, 3.7, 1.3, 5.8,  
 1.6, 4.9, 9.7, 4.3, 1.9, 2.8, 1.7, 8.4, .60, .20,  
 10.1, 1.9, 5.9, .10, 5.6, 1.6, 1.5, .90, 3.1,  
 10.8, .10, 14.0, 14.1, 1.3, 6.6, 2.0, .40, .60,  
 5.3, 2.3, 4.3, 1.2, 4.0, .40, 1.6, 2.6, 1.0, 1.6,  
 .90, .10, 1.3, 2.8, .70, .60, 4.0, 1.4, 2.3, .20,  
 .20, 1.6, 6.7, 1.2, .20, 5.8, 1.1, 1.6, 7.2, 2.9,  
 4.7, 1.1, .60, 1.3, 1.8, 3.1, 3.1, 3.8, 4.5, 2.4,  
 6.2, 2.8, 2.4, 2.2, 6.4, .20, 10.6, 1.0, 6.1, 1.6,  
 2.8, 2.6, 3.3, 5.1, 1.1, .80, .40, .40, 4.6, 3.7,  
 1.2, .60, .40, 2.8, 1.7, .40, .80, 11.0, .20, 2.2,

Figure 27. (Continued)

Queue Length

Time Interval

---

	3.7,	4.8,	3.3,	.50,	.10,	3.4,	2.2,	.60,	2.1,	4.4,
	2.0,	1.6,	5.8,	2.5,	5.9,	.20,	3.5,	7.7,	2.5,	3.9,
	.60,	5.8,	.90,	2.0,	.70,	3.7,	.20,	2.3,	1.0,	.40,
	.50,	3.1,	1.2,	4.8,	1.1,	1.8,	.50,	3.1,	5.4,	.50,
	1.3,	.50,	6.1,	1.5,	4.3,	.20,	4.5,	1.7		
3.	1.1,	1.2,	.40,	.40,	3.7,	.10,	.90,	7.7,	2.05,	4.2,
	1.3,	1.0,	6.4,	5.8,	.90,	.80,	.80,	2.6,	.40,	1.75,
	5.1,	5.3,	.50,	3.5,	8.0,	.70,	1.8,	5.7,	4.7,	2.0,
	13.2,	1.7,	1.6,	1.4,	4.15,	2.2,	2.4,	1.6,	7.2,	.70,
	2.6,	9.8,	1.4,	.30,	6.2,	16.0,	.90,	.60,	8.1,	1.2,
	5.2,	6.9,	1.4,	2.0,	8.5,	.60,	.10,	6.7,	1.7,	10.8,
	1.4,	5.5,	2.65,	2.3,	.60,	5.1,	2.3,	4.3,	5.0,	.20,
	4.8,	4.8,	6.8,	2.4,	3.7,	.20,	5.2,	2.2,	.90,	.30,
	.20,	2.6,	.10,	.40,	.10,	.40,	9.1,	10.9,	12.6,	
	.90,	.10,	1.0,	1.0,	1.7,	.90,	.10,	1.1,	3.9,	1.1,
	5.8,	5.2,	.90,	4.3,	.40,	2.7,	1.2,	2.9,	5.5,	5.2,
	.40,	1.3,	2.5,	7.25,	.30,	1.2,	1.9,	4.4,	.40,	2.3,
	4.4,	3.4,	.80,	1.5,	6.9,	3.8,	4.2,	3.5,	.20,	5.8,
	6.8,	.40,	.90,	.40,	3.8,	.80,	2.2,	.20,	.80,	9.6,
	.20,	21.2,	3.5,	.20,	.20,	.40,	2.0,	2.0,	.70,	.30,
	3.8,	5.8,	2.5,	3.6,	1.0,	2.9,	6.5,	5.8,	1.0,	2.0,
	12.2,	.20,	9.9,	1.3,	1.1,	6.5,	6.6,	2.1,	.20,	1.8,
	5.0,	3.0,	.20,	6.0,	2.5,	.20,	4.3,	2.3,	.20,	7.6,
	1.8,	3.2,	3.0,	1.5,	.20,	.90,	3.0,	7.1,	4.5,	6.8,
	6.8,	3.2,	1.5,	4.0,	.20,	6.0,	6.4,	.10,	12.5,	.90,
	4.4,	2.8,	1.2,	.40,	7.8,	1.5,	.20,	5.0,	2.2,	4.8,
	2.2,	.20,	2.9,	3.4,	1.0,	.20,	2.6,	6.2,	.40,	10.7,
	2.5,	2.1,	5.1,	12.7,	9.6,	7.6,	1.0,	7.6,	8.0,	1.7,
	.90,	2.5,	1.6,	2.7,	1.7,	1.8,	2.6,	6.2		
4.	5.1,	1.7,	19.85,	.50,	3.5,	11.3,	4.4,	.50,	.10,	
	7.5,	.20,	1.1,	1.1,	.60,	7.6,	1.0,	3.4,	1.8,	.90,
	.60,	1.2,	1.25,	6.0,	4.2,	1.1,	1.5,	4.1,	.70,	.40,
	13.25,	2.5,	.40,	2.4,	1.1,	3.2,	.80,	2.4,	.20,	
	3.2,	3.2,	5.6,	4.8,	.70,	1.2,	.30,	.60,	4.1,	1.0,
	1.8,	2.2,	3.0,	4.3,	6.1,	4.1,	1.7,	1.8,	6.2,	3.2,
	3.9,	1.1,	1.9,	8.8,	.31,	1.6,	7.0,	.20,	5.9,	.80,
	1.1,	4.2,	2.5,	1.4,	.10,	1.8,	3.6,	.50,	.20,	.30,
	.60,	6.0,	.20,	4.7,	.70,	.20,	1.9,	.10,	.80,	7.1,
	.20,	1.4,	9.7,	5.8,	9.7,	1.5,	15.9,	2.7,	2.1,	.60,
	4.1,	.30,	.30,	1.0,	1.3,	8.6,	.70,	1.5,	2.0,	.50,
	1.0,	.30,	2.3,	3.5,	2.1,	1.1,	5.8,	1.4,	.50,	4.3,
	2.6,	1.1,	1.2,	.60,	1.6,	4.1,	1.1,	.10,	16.0,	6.6,
	1.7,	.20,	3.3,	1.2,	4.7,	3.5,	1.1,	2.4,	7.0,	.70,
	.10,	1.5,	8.3,	.60,	7.1,	2.7,	6.1,	.50,	.40,	2.9,
	.30,	2.0,	4.7							

---

Figure 27. (Continued)

Queue Length	Time Interval
5.	2.2, 1.8, .20, 7.0, 6.5, 1.5, 4.75, .70, 2.3, .70, 6.5, 1.5, 4.75, .70, 2.3, .70, 3.1, .60, .15, 1.4, 1.5, 1.9, 1.4, 1.1, 2.2, .40, .70, .60, 2.9, .60, 1.0, 1.7, .40, 10.5, 1.7, 5.0, 1.0, 1.1, 1.3, 3.6, 1.5, 1.1, 3.7, .30, .30, .80, 2.1, 3.6, .20, .20, 11.2, 1.5, 4.3, 1.4, .90, 1.2, .30, .50, 4.1, .60, 1.1, 2.4, 11.8, 2.5, .40, 5.7, 1.0, 3.8, .50, 3.2, 3.7, 2.9, 3.7, 2.6, .10, 4.1, 1.2, 2.0, .60, 1.2, 2.7, 2.1, 4.2, 1.3, 1.1, 7.4, 1.8, 10.4, .60, 10.4, .60, 10.4, .80, 3.0, 2.2, 2.1, .20, .30, .80, 4.4, 6.9, 1.3, 5.5, 10.5, 2.9, 1.6, 1.0, 5.3, 1.6, 2.6
6.	1.7, 2.4, 6.9, 6.25, 2.25, 1.0, 5.3, 2.9, 10.8, .60, 1.5, 1.75, 1.7, .20, .20, 1.5, 2.6, 2.8, .40, .70, .70, 1.6, 3.2, 20.6, .50, 1.7, 3.6, 1.7, 6.4, 3.8, 2.0, 9.5, .75, 8.1, .40, 7.7, .20, 3.0, 4.7, 1.7, 2.95, 1.7, 1.1, 2.9, 2.45, 3.9, 4.3, 1.8, .90, 2.0, 1.7, 1.8, 13.8, 6.1, 6.7, 1.2, .80, .50, .70, 3.1, 3.1, 1.2, 3.0, .80, .90, .30, 3.5, 1.0, 1.4, 10.3, .20, 1.0, .90, .90, 2.6, .10, .20, 2.7, .60, 5.2, 12.7, .80, 11.0, .60, 1.4, 3.5, .30, .20, .20, 3.5, 1.0, 12.0, .60, 15.9, 1.1, 3.8, 8.6, 3.1
7.	9.4, 3.4, 1.7, 6.1, 5.9, 5.3, 1.75, 4.65, .50, .40, .40, .70, .40, 1.1, 3.5, 6.7, 1.4, 12.3, 7.5, 3.5, 3.7, 7.9, 2.1, .20, 1.4, .50, .80, 5.7, .50, 1.1, 4.1, 5.9, 2.9, 8.1, 1.0, .15, 5.8, 1.0, 1.1, .50, 3.3, 5.4, 5.2, 3.6, 2.6, 3.8, .20, 2.4, .40, 2.6, 2.4, .20, .60, 1.8, 2.4, 1.3, 1.0, 4.3, .30, 7.5, 8.6, 2.8, 2.4, 11.8, 4.7, 2.2, 1.0, 1.9, 2.4, 5.1, 2.2, 2.0, 3.8, 6.2, 2.3, 7.8, 1.6, 2.0, .70, .50
8.	6.1, 2.0, .90, .60, 4.1, .60, 1.5, 2.9, 2.6, 5.9, 3.0, 3.2, 2.6, 2.2, 1.3, 4.8, 4.9, 2.1, 6.0, 1.0, .20, 2.65, 2.1, 1.4, 1.2, 2.5, 3.15, 1.6, 4.5, 1.8, 3.0, .90, 2.0, 1.6, 6.1, 4.7, 2.4, 1.0, .30, .20, 3.0, 2.8, .30, 4.4, 1.8, 8.4
9.	1.35, 1.7, 4.5, .60, .60, 2.2, 1.2, .20, 5.8, .20, .30, 2.6, .80, 5.9, 1.6, 8.5, .60, 2.7, .20, 3.4, 3.4, 3.1, 4.1
10.	1.6, .80, .20, 6.4, 7.9, 2.7, 4.4, 1.2, 3.5, 2.6, .20
11.	1.3, 1.5, 2.4, 1.1, .90, .30, .50, 4.6
12.	.40, .70, 4.3, 8.1, 1.6, .80, 1.2, .20
13.	3.2, 5.4, 2.65, .80, .80, 7.75, 3.7, .80, 1.2
14.	10.9, 1.6, .90, 3.9, 1.4, 2.0, 2.0, 6.7, 6.1, 2.4, 1.8, 3.5, .30
15.	2.9, 7.0, 2.7, 2.5, 3.2, 1.1, .40, .90, 2.2, 1.6, 10.4

Figure 27. (Continued)



Queue Length	Time Interval
16.	.30, .30, 4.7, .20, 4.5, 3.7, .10, 4.9, .90
17.	6.2, 1.4, 1.2, 2.0, .20, .80, 2.1, 2.7, 1.7, .70, 3.7
18.	4.8, 7.1, 1.3, .10, 1.42, 1.5, 2.2
19.	4.6, .20, 1.7, 4.2
20.	2.1, .70, .20
21.	1.6

## Queue Data Collected 9-25-65

Number in System	No. of Occurrences	Observation Totals Occurrences
0	213	1374.4
1	399	1182.05
2	324	916.9
3	237	789.65
4	151	438.26
5	102	262.8
6	98	308.9
7	82	257.35
8	46	122.0
9	23	55.55
10	11	31.5
11	8	12.6
12	8	17.3
13	9	27.3
14	13	43.6
15	11	34.9
16	9	19.3
17	11	22.7
18	7	18.42
19	4	10.7
20	3	3.0
21	1	1.6

Figure 27. (Continued)

Resistor Circuit No.	Up Section			Arrival Section			Down Section			Total Down Section	Total Arrival Section
	Date			Total Up Section							
	9-2	9-10	9-25		9-2	9-10	9-25				
1.	3	12	11	26	5	9	11	25	51		
2.	1	11	10	22	4	8	10	22	44		
3.	4	13	12	29	4	17	11	32	61		
4.	6	9	8	22	1	12	12	25	47		
5.	5	11	10	26	7	3	9	19	45		
6.	5	10	11	24	3	7	13	23	47		
7.	5	14	17	36	9	10	11	30	66		
8.	5	14	9	24	2	14	9	25	49		
9.	14	18	12	44	6	11	9	26	68		
10.	9	9	15	33	2	12	9	23	56		
11.	5	14	15	34	3	14	12	29	63		
12.	5	7	15	26	4	17	13	34	60		
13.	5	10	11	26	6	7	12	25	51		
14.	3	9	11	23	4	12	10	24	47		
15.	1	12	3	16	3	9	11	23	39		
16.	6	12	12	28	3	12	7	22	50		
17.	5	13	11	29	2	10	8	20	49		
18.	1	11	7	19	8	8	7	23	42		
19.	6	13	14	33	8	11	13	32	65		
20.	5	11	13	29	4	11	8	23	52		
21.	8	7	11	26	2	13	17	32	58		
22.	3	14	12	29	5	13	8	26	55		
23.	3	12	11	26	3	9	12	24	50		
24.	11	12	14	37	4	6	9	19	56		
25.	6	7	7	20	8	10	8	26	46		
26.	3	11	12	26	3	12	21	36	62		

Figure 28. Compiled Data - Number of Occurrences of Resistor Circuits

Resistor Circuit No.	Up Section			Total Up Section	Down Section			Total Down Section	Total Arrival Section
	9-2	9-10	9-25		9-2	9-10	9-25		
27.	3	13	13	29	2	10	12	24	53
28.	7	12	10	29	3	9	10	22	51
29.	5	13	12	30	7	18	20	45	75
30.	2	9	13	24	9	16	12	37	61
31.	3	9	10	22	5	10	12	27	49
32.	8	7	7	22	2	12	11	25	47
33.	5	16	13	34	5	11	9	25	59
34.	5	10	9	24	3	9	9	21	45
35.	5	11	10	26	7	5	10	22	48
36.	0	12	8	20	5	16	9	30	50
37.	6	9	11	26	1	9	11	21	47
38.	7	14	12	33	2	15	19	37	70
39.	1	6	8	15	6	12	15	31	46
40.	4	6	14	24	7	9	15	31	55
Service Section									Total Service Section
1.	9	10	10	29	6	13	14	33	62
2.	6	11	10	27	3	13	15	31	58
3.	6	15	9	30	4	10	13	27	57
4.	5	12	8	25	4	13	13	30	55
5.	7	11	12	30	6	14	7	27	57
6.	3	13	13	29	4	14	11	29	58

Figure 28.. (Continued)

Resistor Circuit No.	Up Section			Total Up Section	Down Section			Total Down Section	Total Service Section
	9-2	9-10	9-25		9-2	9-10	9-25		
7.	3	14	8	25	6	9	10	25	50
8.	6	12	6	24	7	16	8	32	56
9.	6	12	14	32	3	6	7	16	48
10.	5	7	9	21	3	13	12	28	49
11.	5	14	20	39	2	12	11	25	64
12.	7	4	14	25	3	16	13	32	57
13.	2	12	12	26	6	10	16	32	58
14.	4	6	16	26	3	14	11	28	54
15.	6	8	15	29	5	7	6	18	47
16.	6	16	9	31	2	14	13	29	60
17.	4	13	7	24	3	4	10	17	41
18.	2	12	11	25	3	9	8	20	45
19.	5	8	16	29	3	10	17	30	59
20.	7	13	9	29	8	10	17	35	64
21.	3	12	10	25	2	11	12	25	50
22.	3	9	9	21	9	15	7	31	52
23.	9	13	11	33	3	11	11	25	58
24.	3	10	12	25	4	8	14	26	51
25.	7	14	11	32	2	10	12	24	56
26.	5	9	13	27	3	8	11	22	49
27.	3	11	17	31	4	14	14	32	63
28.	6	13	7	26	3	12	11	26	52
29.	6	11	11	26	4	10	13	27	55
30.	1	14	12	27	5		18	23	60
31.	8	12	15	35	7	14	8	29	64
32.	4	8	7	19	8	12	4	24	43

Figure 28. (Continued)

Resistor Circuit No.	Up Section			Total Up Section	Down Section			Total Down Section	Total Service Section
	9-2	9-10	9-25		9-2	9-10	9-25		
33.	4	15	10	29	2	8	13	23	52
34.	5	13	10	28	3	11	5	19	47
35.	3	5	18	26	5	14	8	27	53
36.	6	10	8	24	8	6	7	21	45
37.	4	15	14	23	5	8	16	29	52
38.	3	11	8	22	2	19	12	33	55
39.	6	7	11	24	3	10	13	26	50
40.	1	14	15	30	3	8	15	26	56

Figure 28. (Continued)

APPENDIX C  
CUMULATIVE DISTRIBUTION VALUES

$F(t)$		Exponential Times (sec)				Resistor Circuit Number
		Service Dist. $\mu_s = .10$		Arrival Dist. $\mu_a = .075$		
Class Limit	Class Mid-Point	Class Limit	Class Mid-Point	Class Limit	Class Mid-Point	
.0000		0		0		1, (2 = $\infty$ )
	.0250		.253		.337	
.0500		.513		.684		3
	.0625		.645		.860	
.0750		.780		1.040		4
	.0875		.915		1.220	
.1000		1.045		1.393		5
	.1125		1.194		1.592	
.1250		1.335		1.780		6
	.1375		1.479		1.972	
.1500		1.625		2.167		7
	.1625		1.773		2.364	
.1750		1.924		2.565		8
	.1825		2.076		2.768	
.2000		2.231		2.975		9
	.2125		2.389		3.185	
.2250		2.549		3.399		10
	.2375		2.712		3.616	
.2500		2.877		3.836		11
	.2625		3.113		4.151	
.2750		3.216		4.288		12
	.2875		3.390		4.520	
.3000		3.567		4.756		13
	.3125		3.747		4.996	
.3250		3.930		5.240		14
	.3375		4.117		5.489	
.3500		4.3808		5.744		15
	.3625		4.502		6.003	
.3750		4.700		6.267		16
	.3875		4.902		6.536	
.4000		5.108		6.811		17
	.4125		5.319		7.092	
.4250		5.534		7.379		18
	.4375		5.754		7.672	
.4500		5.978		7.971		19
	.4625		6.208		8.277	
.4720		6.444		8.592		20
	.4875		6.684		8.912	
.5000		6.931		9.241		21
	.5125		7.185		9.580	
.5250		7.444		9.925		22
	.5375		7.711		10.281	
.5500		7.985		10.647		23
	.5625		8.267		11.023	

Figure 29. Cumulative Distribution Values

$F(t)$		Exponential Times (sec)				Resistor Circuit Number
		Service Dist. $\mu_s = .10$		Arrival Dist. $\mu_a = .075$		
Class Limit	Class Mid-Point	Class Limit	Class Mid-Point	Class Limit	Class Mid-Point	
.5750		8.557		11.409		
	.5875		8.855		11.807	24
.6000		9.163		12.217		
	.6125		9.480		12.640	25
.6250		9.808		13.077		
	.6375		10.147		13.529	26
.6500		10.498		13.997		
	.6625		10.862		14.483	27
.6750		11.239		14.985		
	.6875		11.632		15.509	28
.7000		12.040		16.053		
	.7125		12.465		16.620	29
.7250		12.910		17.213		
	.7375		13.375		17.833	30
.7500		13.863		18.484		
	.7625		14.376		19.668	31
.7750		14.917		19.889		
	.7875		15.488		20.651	32
.8000		16.094		21.459		
	.8125		16.740		22.320	33
.8250		17.430		23.240		
	.8375		18.171		24.228	34
.8500		18.971		25.295		
	.8625		19.841		26.455	35
.8750		20.794		27.725		
	.8875		21.848		29.131	36
.9000		23.026		30.701		
	.9125		24.361		32.481	37
.9250		25.803		34.537		
	.9375		27.726		36.968	38
.9500		29.957		39.943		
	.9675		32.834		43.778	39
.9750		36.885		49.185		
	.9875		43.820		58.427	40
1.0000		$\infty$		$\infty$		

Figure 29. (Continued)



VITA

Charles Louis Burford

Candidate for the Degree of

Doctor of Philosophy

**Thesis:** REFINEMENT OF A SINGLE FACILITY ELECTRONIC  
QUEUEING SIMULATOR AND THE DEVELOPMENT OF  
AN AUGMENTED QUEUEING SYSTEM SIMULATOR

**Major Field:** Engineering

**Biographical:**

**Personal Data:** Born in Ft. Worth, Texas, September 16,  
1930, the son of Louis T. and Nell H. Burford.

**Education:** Attended public school in Ft. Worth,  
Texas; graduated from Amon Carter High School,  
Ft. Worth, Texas, in 1949. Attended Arlington  
State College from 1949 to 1951, majoring in  
Engineering; received the Bachelor of Science  
degree from Texas Technological College, with a  
major in Mechanical Engineering, in 1954; re-  
ceived the Master of Science degree from Okla-  
homa State University, with a major in Industrial  
Engineering and Management, in 1962; completed  
requirements for the Doctor of Philosophy degree,  
with a major in Industrial Engineering and Man-  
agement, in July, 1966.

**Professional experience:** Worked as a Junior Engineer  
at Convair, Ft. Worth, Texas, from August 1954  
to December 1954; served as a Company Grade Of-  
ficer in the Corp of Engineers, U. S. Army, from  
December 1954 to December 1956; taught as an  
Instructor in the Department of Industrial Engi-  
neering, Texas Technological College, Lubbock,  
Texas, from February 1957 to June 1961; taught  
as a part-time Instructor in the School of Indus-  
trial Engineering and Management, Stillwater,  
Oklahoma from September 1961 to February 1962;  
served as a Research Assistant in the School of  
Industrial Engineering and Management, Oklahoma  
State University from September 1962 to Septem-  
ber 1963; taught as an Assistant Professor in  
the School of Industrial Engineering, Purdue  
University, Lafayette, Indiana from February 1964  
to June 1964; taught as Assistant Professor in the  
Department of Industrial Engineering Texas Tech-  
nological College, Lubbock, Texas, from June  
1964 to the present.