QUADRUPOLE MASS FILTER DESIGN

AND CONSTRUCTION FOR

PLASMA ION ANALYSIS

Ву

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PRE FACE

Under the direction of Dr. F. C. Todd, the major advisor to this student, a quadrupole mass filter has been designed and is presently in use as an analytical tool for measuring properties of transient aluminum plasmas.

This device has been employed to determine the presence of different ionic species in a dense aluminum plasma produced by a spark gap in vacuum. It has also been used to some extent to study the velocity distribution of the plasma ions.

The student is grateful for the preliminary work done on this project by Mr. Larry J. Peery and for the many hours of consultation with Mr. William G. Robinson. For assistance in the design and contruction of the electronic components, many thanks are due Mr. John F. Stoops. Mr. Heinz Hall and Mr. M. Wayne Atkins were responsible for much of the construction of the quadrupole vacuum system.

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CHAPTER I

INTRODUCTION

One of the oldest disciplines in science is the field of electrical discharges in gases. Sir William Crookes, in 1879, considering the special properties of the matter in discharge tubes, tentatively advanced the idea that these excited gases should be considered a fourth state of matter. Compton and Langmuir (1930) introduced the special designation "plasma". Descriptively, the term simply denotes ionized gases. Depending on the degree of ionization, such gases exhibit similarities to metals, semiconductors, strong electrolytes and ordinary gases. The concept "fourth state of matter" thus derives from the extraordinary array of physical and chemical properties characteristics of a plasma. This classification is usually reserved for those cases wherein the densities of charges of each sign are approximately equal, i.e., the cases for which quasi-neutrality exit (Hellund, 1961).

Another source similarly defines the plasma as an electrically charged gas consisting of ions and electrons. It is therefore an electrical conductor. The distinction between a liquid conductor and a plasma is not very precise and can be most easily made in terms of particle densities. When speaking of a liquid conductor, one is usually talking in terms of the order of 10^{22} charged particles per cubic centimeter. When the term plasma was first applied, the number

of charged particles was of the order of 10¹⁸ and lower and neutral atoms were always present (Gartenhaus, 1964). A plasma may be thought of as a gaseous conductor. Neutral atoms are always present since plasmas emit light with the recombination of ions and electrons, and light is always emitted. This is experimentally verified by recording the emission of the characteristic radiation. A spectral analysis with a far ultraviolet spectrograph was made of the light from the breakdown of a spark gap in a vacuum. This spectra definitely shows that metastable atoms are present in the plasma (Carpenter, 1967). The presence of the neutrals has been further verified by the qualitative measurements taken with the quadrupole mass filter. This device was used to analyze both the vacuum spark gap breakdown and the laser impact in which aluminum was the principle plasma producing source.

The Plasma Group at Oklahoma State University, conducted by F. C. Todd, has concentrated its efforts on the study of transient, dense aluminum plasmas. The facilities for producing this type of plasma consist of essentially the following:

- (1) A Q-switched, twin ruby rod laser
- (2) An exploding wire device
- (3) A device to induce the vacuum breakdown of the gap between spectroscopically pure aluminum electrodes

The laser is capable of delivering a tremendous energy output to a relatively small target area in a very short time interval so that peak power outputs of the order of 0.33×10^9 watts have been attained. This power is used to create and sustain an aluminum plasma long enough for experimental investigations to be made.

The exploding wire facility produces a plasma by a pulse of

power with a duration of one microsecond. (This period is not to be confused with the life time of the plasma itself). This should enhance the resolution with which further velocity distribution investigations may be made. The device consist essentially of a vacuum chamber, into which is placed a short aluminum wire of one one-thousandth inch diameter. A high voltage power supply (100 KV) is used to drive a one microsecond pulse along a co-axial cable, which terminates in the small aluminum wire. The characteristic impedance of the cable is 50 ohms so a peak current of the order of 2,000 amperes is expected. The ambient resistance of the target wire is approximately 1.4 ohms, with an estimated average resistance during the pulse of five times this amount, or 7.0 ohms. The peak power input to the plasma could possibly attain a value of 28 X 10⁶ watts; however, the total energy into the plasma is only 28 watt-seconds (joules).

The vacuum spark gap apparatus consist of a vacuum envelope with a glass manifold. With the use of mechanical feedthroughs, the spectroscopically pure aluminum electrodes are positioned so that a gap width of the order of 1.0 mm is obtained. By means of the manifold on the vacuum envelope, a pulsed photomultiplier may be employed to monitor the visible and the ultraviolet light emission. A high voltage power supply is used to charge a 12.5 KV condenser, which is then allowed to discharge across the gap. The very high potential gradients at the electrode points causes a breakdown of the spark gap. The high current density arc at breakdown produces ions and electrons which, in fact, comprise the plasma. The light emission results from the downward transitions in the ionized, or excited atoms.

The analytical tools for investigating the properties of the

aluminum plasmas mentioned in the text above may be summarized by the following:

- (a) A vacuum spectrograph for the far ultaviolet (Payne, 1966).
- (b) A pulsed, high gain photomultiplier to record the intensity variation with time for a fraction of the visible plus the ultraviolet light emission (Brown, 1968)
- (c) The quadrupole mass filter

The purpose of this thesis is fourfold. ⁽¹⁾A description is given of the design and construction of the quadrupole mass filter. ⁽²⁾The results of the preliminary investigations of the spark discharge and laser impact are presented. ⁽³⁾The analytical study, the design and the construction details of a pulsed electrostatic lens are presented. This lens is to be used in conjunction with the quadrupole mass filter to study ion velocities. ⁽⁴⁾Improvements on existing methods and equipment for future investigations are suggested.

CHAPTER II

THEORETICAL DISCUSSION

Mass - Spectrometer Development

Since 1913, when J. J. Thomson developed the parabolic mass spectrometer employing parallel electrostatic and magnetic fields, many techniques have been developed for mass analysis as is apparent through examination of the literature (Mosharrafa, 1961). The most common types of mass - spectrometers are:

- (1) The Magnetic mass spectrometer
- (2) Time-of-flight mass spectrometer
- (3) The Quadrupole type spectrometer

The magnetic mass - spectrometer analyzes the mass of monoenergetic ion beams by using 60° , 90° or 180° homogeneous sector magnetic fields. In fact, sector fields up to five revolutions of 360° have been successfully used.

The time-of-flight mass - spectrometer utilizes the principle that the time needed for an ion with specific energy to traverse a drift space is dependent on the ionic mass.

A rather new type of mass - spectrometer was developed by W. Paul and others (1955) at the University of Bonn, Germany, since 1953. This spectrometer employs the "mass filtering" principle which concerns the ejecting of ions through a quadrupole rf field, with a dc field applied simultaneously.

This quadrupole mass-spectrometer or mass filter, as it may be more appropriately named, was chosen for the particular applications in this plasma group for a variety of reasons:

- (1) The resolution of the instrument is variable and can be changed very easily by simply changing the ratio of the applied dc voltage to the rf voltage amplitudes. This makes it possible to insure maximum efficiency and hence, higher sensitivity throughout the entire mass range. It should be noted, however, that for the application to the work reported here, only the single mass of aluminum (13) has been of interest.
- (2) Contrary to the other two types of spectrometers mentioned above, the quadrupole mass filter offers no velocity discrimination, i.e., the device will monitor ions of whatever velocity, so long as an upper limit is not exceeded. (This point will be further explained later in the text.)
- (3) The quadrupole requires no type of magnetic field. It is well known that stray magnetic fields greatly disturb the conditions of an active, as well as a passive plasma. This eliminates, almost entirely, the difficult shielding problems which plague the magnetic spectrometers.
- (4) A very tolerable acceptance angle of 30^o reduces, considerably, the necessity for entrance and exit slits and other complicated focusing and collimating requirements.

(5) An extra feature of being bakable insures the attain-

ability of a clean, high vacuum system.

The very nature of the transient plasmas that were produced in this investigation required that a detection system, coupled with the mass filter, be useful for fast scanning purposes. There are several methods available for ion detection and a few of them may be listed as an indication of the scope of endeavor in this research area:

Detector Systems

- (1) Farady cup: This method has an advantage of a high collection efficiency because of the large coverage space of the collector. However, it is much less sensitive than some of the other types and must be coupled with an electrometer or other similar instrument to detect small ion currents of the order of 10⁻¹² Amperes.
- (2) Electron Multiplier Oscilloscope: This method combines the use of an electron multiplier, which amplifies the ion current through secondary electron emission gain, with an oscilloscope, which is triggered by the multiplier output.

(3) Electron Multiplier - Electrometer - Recorder: In this method the current output from the multiplier is integrated, using a vibrating reed type electrometer. The signal is then recorded on a strip chart recorder.

Although there are several other methods of ion current detection, they are easily available in the current literature.

The electron multiplier - oscilloscope method was chosen because it is a very fast detection system. In addition, the high gain of the multiplier makes possible a reasonable oscilloscope display, which may be photographed as a permanent record of the output.

With the plasma - producing equipment being available, and with the choice of the ion analyzer and detector system having been made, the theory of such an instrument and its principle of operation can now be given.

Quadrupole Theory

A literature search by L. J. Peery (1967) proved to be fruitful, in that a wealth of reference material (Brubaker and Tuul, 1964; Woodward and Crawford, 1963) has been compiled which illustrates the adaptability and widening use of the quadrupole mass filter since its conception by Paul and Steinwedel (1953). Its role varies from a partial pressure analyzer (Gunther, 1960) and residual gas detector, to that of detecting ions in plasma analysis. Although the principle of operation is essentially the same for most of its applications, this report will be restricted to the latter.

The quadrupole mass filter employs electric fields which permit only those ions which have a particular charge-to-mass ratio to pass through it. In theory, all other ions, having a different ratio, are rejected. This mass filtering action is based on the behavior of the solutions of the equations of motion of the injected charged particles or ions.

The application of a voltage $(U + V \cos \omega t)$ on a hyperbolashaped quadrupole, as will be shown later in Figure 4, results in

the establishment of a potential distribution within the quadrupole region which can be written, neglecting end effects, as

$$\phi = (U + V \cos \omega t) \frac{x^2 - y^2}{r_o^2}$$
(2.1)

where:

Ø

- U = dc voltage
- V = rf voltage
- ω = driving frequency
- r_{o} = distance from the origin to the point of inter-

section of the hyperbolae with the x and y axes That this solution results is shown by solving the Laplace equation for hyperbolic fields.

$$\nabla^2 \phi = 0 \tag{2.2}$$

If we assume a solution,

$$\phi = \phi(t) (\alpha x^2 - \beta y^2 + \gamma z^2)$$
(2.3)

the substitution of it back into Laplaces' Equation (2.2) yields the following relation between the constants:

$$\alpha = \beta_{0} \pm \gamma_{1} = 0 \qquad (2.4)$$

If we consider that the tangential field at the hyperbolic surfaces is given,

$$\left(\frac{\partial \rho}{\partial z}\right)_{\text{surface}} = 0$$
 (2.5)

then

$$\phi(t) (2_{\gamma}z) = 0$$
 (2.6)

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Therefore Equation (2.3) becomes

 $\gamma = 0$

$$\phi = \phi(t) (\alpha x^2 - \beta y^2)$$
 (2.8)

Now apply the equations of the hyperbolic surfaces themselves,

$$\frac{1}{2} \frac{x^2}{r_0^2} + \frac{y^2}{r_0^2} = 1$$
(2.9)

to Equation (2.8). Equation (2.4) combined with Equations (2.8) and (2.9) now yields the value of the remaining constants.

$$\alpha = \beta = \frac{1}{r_{o}^2}$$
(2.10)

If the time-dependent field is given,

$$\phi(t) = U + V \cos \omega t \qquad (2.11)$$

the potential distribution for the region is then given

$$\phi = (U + V \cos \omega t) \frac{x^2 - y^2}{r_0^2}$$
(2.1)

as was intended to be shown.

Having obtained the potential distribution, the electric field is then calculated component-wise using the familiar relation,

$$\overrightarrow{E} = -\nabla \phi$$
(2.12)

Hence:

$$E_{x} = -\frac{\partial \phi}{\partial x} = -2(U + V \cos \omega t) \frac{x}{r_{0}^{2}}$$
(2.13)

or

$$E_{x} = -\frac{\partial \phi}{\partial y} = 2(U + V \cos \omega t) \frac{y}{r_{a}^{2}}$$
(2.14)

and

$$\mathbf{E}_{\mathbf{z}} = \mathbf{0} \tag{2.15}$$

It is now desirable to analyze the motion of a positively charged particle which is injected into this time-varying field along the z-axis.

The equations in the x, y and z directions are given according to Newton's second law,

where: u = x, y or z

Z = degree of ionization

e = electronic charge

E = electric field strength

Along the x and y directions, the equations of motion are given, respectively,

$$m_{x} = Z e E_{x} = -2 Z e(U + V \cos \omega t) \frac{x}{r_{o}^{2}}$$
 (2.17)

$$m y = Z e E_y = 2 Z e(U + V \cos \omega t) \frac{y}{r_0^2}$$
 (2.18)

The motion along the z-axis is simply given,

$$m z = 0; m z = constant$$
 (2.19)

The last equation presents no problem, but for Equation (2.17) and (2.18), consider a change of variables,

$$\zeta = \omega t/2 \tag{2.20}$$

so that

$$\frac{\mathrm{dx}}{\mathrm{dt}} = \frac{\omega}{2} \frac{\mathrm{dx}}{\mathrm{d\zeta}} \tag{2.21}$$

and

$$\frac{d^2 x}{dt^2} = \frac{\omega}{2} \frac{d}{d\zeta} \left(\frac{\omega}{2} \frac{dx}{d\zeta}\right) = \frac{\omega^2}{4} \frac{d^2 x}{d\zeta^2}$$
(2.22)

If Equation (2.22) is now substituted into Equation (2.17), the following equation of motion in the x direction results.

$$\frac{m\omega^2}{4} \frac{d^2 x}{d\zeta^2} = -2 Z e(U + V \cos 2 \zeta) \frac{x}{r_0^2}$$
(2.23)

or

$$\frac{d^{2}x}{d\zeta^{2}} = -\left[\frac{8ZeU}{m\omega^{2}r_{0}^{2}} + \frac{8ZeV}{m\omega^{2}r_{0}^{2}}\cos 2\zeta\right]x \qquad (2.24)$$

Now define the "variable" constants,

$$a = \frac{+}{2} \frac{8ZeU}{m\omega^2 r^2}$$
(2.25)

and

$$q = \frac{+}{m\omega^2 r_0^2} \frac{4ZeV}{m\omega^2 r_0^2}$$
(2.26)

so that Equation (2.24) takes the following form.

$$\frac{d^2y}{d\zeta^2} + (a + 2 q \cos 2 \zeta) x = 0$$
 (2.27)

Beginning with Equation (2.18) and following the same procedure, the equation of motion for the y direction is obtained.

$$\frac{d^2 y}{d\zeta^2} = (a_0 + 2 q \cos 2 \zeta) y = 0$$
 (2.28)

The Equations (2.27) and (2.28) which describe the motion of

the charged particles in the electric field, given by Equation (2.12), are differential equations of the "Mathieu type." The behavior of the particles is thus governed by the properties of the solutions of these equations (McLachlan, 1964). The Mathieu equation is a linear, second order differential equation with constant, periodic coefficients. Either Equation (2.27) or (2.28) is considered to be in the normal form, if appropriate signs are assigned to the constants "a" and "q". This form was obtained by Mathieu, while solving for the vibrational modes of a stretched membrane with an elliptical boundary in 1868, and is given here by the following,

$$\frac{d^2 u}{d\psi^2} + (a - 2 q \cos 2\psi) u = 0$$
 (2.29)

Negative values of "q", or a phase shift or $\frac{+}{-}\pi/2$ applied to Equation (2.29) yields the equation describing the motion of the charged particles in the x - direction. Negative values of "a" yield the equation of motion in the y - direction.

The general solution to Equation (2.29) is given,

$$u = A e^{\mu \psi} \sum_{n=\infty}^{\infty} C_n e^{in\psi} + B e^{-\mu \psi} \sum_{n=\infty}^{\infty} C_n e^{-in\psi} \qquad (2.30)$$

(u) is bounded for values of (μ) which are pure imaginary; otherwise (u) will increase exponentially. For imaginary values of (μ) , the value of (u) will oscillate in some stable range, depending on the parameters, "a" and "q".

The ranges of stability for the solutions of the Mathieu equation are illustrated in Figure 1. From these curves, it is easily seen that the stability ranges are symmetric about q = 0. Now since



Figure 1. Mathieu Stability Ranges

"a" must satisfy stability requirements in both the x and y directions, then the graph may be folded along the a = 0 axis.

A blown-up version of the first stability range, thus obtained, is shown in Figure 2. As indicated on this graph, an operating point of a = 0.2 and 2 = 0.7 has been chosen for the applications in this work. This point yields an operating slope of a/q = 0.286, which compares favorably with a typical operating slope of a/q = 0.310used by the other experimenters in the field (Norgren and others, 1965).

It should be noted from Figure 2 that the operating point is not at the apex of the stability region. Although to use the apex as an operating point is desirable for some applications, such as isotope scanning where extremely high resolution is demanded, the resolution is quite sufficient at the point chosen for our purposes.

Attention should now be directed to the hyperbolic fields for which the above solutions apply. The quadrupole mass filter, itself, is not constructed of hyperbolic rods; rather, it is composed of field electrodes which are hollow, cylindrical rods, which are spaced and held in place according to the relation,

 $r = 1..15 r_0$

(2.31)

where: r = rod radius

 $\mathbf{r}_{o} =$ quadrupole field radius

It can be shown that this relation is essential for hyperbolic simulation, and is accurate to 1.0 percent.

The actual dimensions of the field rods will be dealt with in the next chapter. The important point to be made here is that the



foregoing derivations are completely valid for cylindrical electrodes, so long as the relation (2.31) is observed. Figures 3 and 4 illustrate this hyperbolic simuluation.

Since the resolution is obviously increased, that is the field has a greater chance to eject unwanted q/m ratios, with the number of cycles an ion experiences in this field, the frequency of the driving rf voltage is a determining factor. It should be noted that the length of the electrodes is also involved in chosing the proper frequency, as is illustrated by the following considerations.

Noting that,

$$\omega t = n 2 \pi$$
 (2.32)

| where | ω | = | 2 τ | r f | (| (2 | •3 | 33 |) |
|-------|---|---|-----|-----|---|----|----|----|---|
| | | | | | | - | | | - |

and $1 = v_{y} t$ (2.34)

| then $n = f 1/v_x$ | (2.35) |
|--------------------|--------|
|--------------------|--------|

where ω = angular driving frequency

1 = length of field; hence the length of the quadrupole electrodes

 v_{\downarrow} = velocity of incident ions in the x - direction

n = number of cycles

With Equation (2.35) in mind, the procedure is then to choose a convenient field length (1) and then determine an upper limit on the velocity of incident ions. For our purposes, an electrode length of 30.0 cm was chosen. It was estimated from preliminary calculations that a maximum incident velocity of the order of 10^7 cm/sec could be used for this value for frequency determining purposes. It was found that an rf driving frequency of 3.2 X 10^6 cycles/sec would



Figure 3. Actual Cylindrical Surfaces



Figure 4. Ideal Hyperbolic Surfaces

cause the ions to experience 9.6 cycles while traversing the electrode field at a velocity of 10^7 cm/sec.

It can be readily seen from Equation (2.35) that ions of lesser incident velocity will experience proportionally more cycles in the field; hence the reason for the upper velocity limit.

The ion trajectories in the quadrupole field are very complicated and will not be gone into at this point. However, a graphic illustration, after Dawson and Whetten (1968), is presented in Figure 5. In this figure some ion trajectories are shown as the displacement of an ion from the center in one direction as a function of time. The upper trajectory shows an unbounded ion whose displacement grows in time. The center ion has a path which is oscillatory through the center, but whose amplitude continues to increase. The lower ion path is bounded, representing an ion that is contained in the field. The important point to note here is not the details of each trajectory, but the fact that the lower trajectory is stable in the field for the proper parameter settings. The parameter settings are referring to the proper dc and rf voltage which, in turn, are determined by the values of "a" and "q" as given by Equations (2.25) and (2.26).

Let us now consider these parameters as they affect the selection of a particular ion from a plasma which contains several specie. If we choose, for example, to monitor only those aluminum ions which are missing one electron, i.e., Al II or Al⁺¹, then the necessary voltages are calculated in the following manner.

Using Equation (2.25), the values which have been determined are substituted to solve for U, the dc voltage. Rewriting this





equation yeilds,

$$U = \frac{+}{2} \frac{m\omega^2 r_0^2 a}{8Ze}$$
(2.36)

Since Al⁺¹ has been selected to be monitored, the degree of ionization, Z, assumes the value, Z = 1. (Al⁺¹ is a singly-ionized aluminum atom.) The remaining variable values are summarized below.

m = 27 amu = 4.48 X
$$10^{-26}$$
 kg
 $\omega^2 = (2 \pi f)^2$
f = 3.2 X 10^6 cycles/sec
 $\omega^2 = 4.04 X 10^{14} (rad/sec)^2$
 $r_0^2 = 3.31 X 10^{-5} (meters)^2$
a = 0.2
q = 0.7
e = 1.602 X 10^{-19} Coulombs

The voltage is then given the following value,

$$U = 93.63 \text{ volts}$$
 (2.38)

This same procedure is followed using Equations (2.26) and (2.37) to arrive at the necessary value for the rf voltage, which is given as,

$$V = 655.4 \text{ volts}$$
 (2.39)

If it is assumed that the mass of the aluminum ion is constant, regardless of the ionization, i.e., neglect the electronic mass in favor of the nucleus, then for the entire range of possible ions, $1 \stackrel{<}{=} Z \stackrel{<}{=} 13$, the proper voltages are determined with the following relations:

$$U = \frac{93.63}{Z}$$
 volts (2.40)

$$V = \frac{655.4}{Z} \text{ volts}$$
 (2.41)

where the value of V is one-half the peak-to-peak amplitude of the rf voltage.

In the following tables are presented the dc and rf voltages for each ionic specie of aluminum up to Al^{± 10}. In addition, the parameter values of "a" and "q" are given in each case to show the exclusion of all but one specie for a particular set of voltage values.

Notice that the accepted ion in each case corresponds to the values a = 0.2 and q = 0.7. If the values "a" and "q" for the rejected ions are compared with the stability region, given in Figure 2, it will be seen that the point corresponding to those coordinates lies outside the region.

TABLE I

z = 1

Ü = ± 93.63 volts

| V | Ξ | <u>+</u> | 655.4 | volts |
|---|---|----------|-------|-------|

| Z | а | q | Cla s sification |
|----------|------|--------------|-------------------------|
| 1 | 0.20 | 0.7 0 | accepted |
| 2 | 0.40 | 1.40 | rejected |
| 3 | 0.60 | 2.10 | rejected |
| <u> </u> | 0,80 | 2.80 | rejected |
| 5 | 1.00 | 3.50 | rejected |
| 6 | 1.20 | 4.20 | rejected |
| 7 | 1.40 | 4.90 | rejected |
| 8 | 1.60 | 5.60 | \mathbf{r} ejected |
| 9 | 1.80 | 6.30 | rejected |
| 10 | 2.00 | 7.00 | re jected |
| 11 | 2,20 | 7.70 | rejected |
| 12 | 2.40 | 8.40 | rejected |
| 13 | 2.60 | 9.10 | rejected |
| | | , · | 1000000 |

TABLE II

STABILITY PARAMETERS FOR AL +2

Z = 2

| U | Ξ | ± 46.82 | volts |
|---|---|----------------|-------|
| v | Ξ | ± 327.7 | volts |

| Z | a | q | Classification |
|----|------|-------|----------------|
| 1 | 0.10 | 0.35 | rejected |
| 2 | 0.20 | 0,.70 | accepted |
| 3 | 0.30 | 1.05 | rejected |
| 24 | 0.40 | 1.40 | rejected |
| 5 | 0.50 | 1.75 | rejected |
| 6 | 0.60 | 2.10 | rejected |
| 7 | 0.70 | 2.45 | rejected |
| 8 | 0.80 | 2.80 | rejected |
| 9 | 0.90 | 3.15 | rejected |
| 10 | 1.00 | 3.50 | rejected |
| 11 | 1.10 | 3.85 | rejected |
| 12 | 1.20 | 4.20 | rejected |
| 13 | 1.30 | 4.55 | rejected |

TABLE III

STABILITY PARAMETERS FOR AL +3

| • | Z | Ξ | 3 | |
|---|---|---|-------|-------|
| U | | Ż | 31.21 | volts |
| V | | ± | 218.5 | volts |

| 2 | а | q | Classification |
|-------|-------|------|-------------------|
| 1 | 0.07 | 0.23 | reject e d |
| 2 | 0.13 | 0.47 | rejected |
| 3 | 0.20 | 0.70 | accepted |
| 4 | 0.27 | 0.93 | rejected |
| 5 | 0.33 | 1.17 | rejected |
| 6 | 0.140 | 1.40 | rejected |
| 7 | 0.47 | 1.63 | rejected |
| 8 | 0.53 | 1.87 | rejected |
| 9 | 0.60 | 2.10 | rejected |
| 10 | 0.67 | 2.33 | rejected |
| 11 | 0.73 | 2.57 | rejected |
| 12 | 0.80 | 2.80 | rejected |
| 13 | 0.87 | 3.03 | rejected |

STABILITY PARAMETERS FOR AL +4

V

z = 4

U = ± 23.41 volts

| = ± | 163.85 | volts |
|-----|--------|-------|
|-----|--------|-------|

| 2 | а | ą | Classification |
|------------|-------|------|----------------|
| 1 | 0.05 | 0.18 | rejected |
| 2 | 0.10 | 0.35 | rejected |
| 3 | 0.15 | 0.53 | rejected |
| <u>)</u> , | 0.20 | 0.70 | accepted |
| 5 | 0.25 | 0.88 | rejected |
| 6 | 0.30 | 1.05 | rejected |
| 7 | 0.35 | 1.23 | rejected |
| 8 | 0.140 | 1.40 | rejected |
| 9 • | 0.45 | 1.58 | rejected |
| 10 | 0.50 | 1.76 | rejected |
| 11 | 0.55 | 1.93 | rejected |
| 12 | 0.60 | 2.11 | rejected |
| 13 | 0.65 | 2,28 | rejected |

STABILITY PARAMETERS FOR AL +5

| | Z | Ξ. | 5 | 1. A |
|---|---|----|-------|-------|
| U | 1 | ± | 18.73 | volts |
| V | = | Ŧ | 131.1 | volts |

| | | | · · · · |
|---|---------------|---------------|------------------|
| 2 | a | q | Classification |
| 1 | 0.04 | 0.14 | rejected |
| 2 | 0.08 | 0.28 | rejected |
| 3 | 0,12 | 0.42 | rejected |
| <u>}</u> | 0.16 | 0.56 | rejected |
| 5 | 0.20 | 0.70 | accepted |
| 6 | 0.24 | 0 . 8µ | re jected |
| 7 | 0.28 | 0.98 | rejected |
| 8 | 0.32 | 1.12 | rejected |
| 9 | 0.36 | 1.26 | rejected |
| 10 | 0.40 | 1.40 | rejected |
| 11 | 0 . 44 | 1.54 | rejected |
| 12 | 0.48 | 1.68 | rejected |
| 13 | 0.52 | 1.82 | rejected |
| A Contraction of the second states of the | | | |
TABLE VI

STABILITY PARAMETERS FOR AL +6

| Z | | = | 6 | |
|---|--|---|-------|-------|
| U | | ± | 15.61 | volts |

| V | (1996) (1996) | t | 109.2 | volts |
|---|------------------|---|-------|-------|
|---|------------------|---|-------|-------|

| | 1 | | | |
|----------|------|------|----------------|--|
| Z | а | q | Classification | |
| 1 | 0.03 | 0.12 | rejected | |
| 2 | 0.07 | 0.23 | rejected | |
| 3 | 0.10 | 0.35 | rejected | |
| <u>)</u> | 0.13 | 0.47 | rejected | |
| 5 | 0.17 | 0•59 | rejected | |
| 6 | 0.20 | 0.70 | accepted | |
| 7 | 0.23 | 0.82 | rejected | |
| 8 | 0.27 | 0•94 | rejected | |
| 9 | 0.30 | 1.05 | rejected | |
| 10 | 0.33 | 1.17 | rejected | |
| 11 | 0.37 | 1.29 | rejected | |
| 12 | 0.40 | 1.40 | rejected | |
| 13 | 0.43 | 1.52 | rejected | |

TABLE VII

STABILITY PARAMETERS FOR AL +7

Z = 7 $U = \pm 13.38 \text{ volts}$

| Ŷ | | 93.63 | volts | |
|---|--|-------|-------|--|
| | | | | |

| 2 | a | q | Classification |
|----------|------|------|----------------|
| 1 | 0.03 | 0.10 | rejected |
| 2 | 0.06 | 0,20 | rejected |
| 3 | 0.09 | 0.30 | rejected |
| 4 | 0.11 | 0.40 | rejected |
| 5 | 0.14 | 0.50 | rejected |
| 6 | 0.17 | 0.60 | rejected |
| 7 | 0.20 | 0.70 | accepted |
| 8 | 0.23 | 0.80 | rejected |
| 9 | 0.26 | 0.90 | rejected |
| 10 | 0.29 | 1.00 | rejected |
| 11 | 0.31 | 1.10 | rejected |
| 12 | 0.34 | 1.20 | rejected |
| 13 | 0.37 | 1,30 | rejected |
| | | | |

TABLE VIII

STABILITY PARAMETERS FOR AL +8

z = 8

U = ± 11.70 volts

V = ± 81.92 volts

| 2 | a | q | Classification |
|----------|------|-------|----------------|
| l | 0.03 | 0.09 | rejected |
| 2 | 0.05 | 0.18 | rejected |
| 3 | 0.08 | 0.26 | rejected |
| ц. Ц. | 0.10 | 0.35 | rejected |
| 5 | 0.13 | 0.111 | rejected |
| 6 | 0.15 | 0.53 | rejected |
| 7 | 0.18 | 0.61 | rejected |
| 8 | 0.20 | 0.70 | accepted |
| 9 | 0.23 | 0.79 | rejected |
| 10 | 0.25 | 0.88 | rejected |
| 11 | 0.28 | 0.96 | rejected |
| 12 | 0.30 | 1.05 | rejected |
| 13 | 0.33 | 1.14 | rejected |

TABLE IX

STABILITY PARAMETERS FOR AL +9

Z = 9 U = ± 10.40 volts V = ± 72.82 volts

| | | I | |
|----|------|------|----------------|
| Z | a | q | Classification |
| 1 | 0.02 | 0.08 | rejected |
| 2 | 0.04 | 0.16 | rejected |
| 3 | 0.07 | 0.23 | rejected |
| 4 | 0.09 | 0.31 | rejected |
| 5 | 0.11 | 0.39 | rejected |
| 6 | 0.13 | 0.47 | rejected |
| 7 | 0.16 | 0.54 | rejected |
| 8 | 0.18 | 0.62 | rejected |
| 9 | 0.20 | 0.70 | accepted |
| 10 | 0.22 | 0.78 | rejected |
| 11 | 0.24 | 0.86 | rejected |
| 12 | 0.27 | 0.93 | rejected |
| 13 | 0.29 | 1.01 | rejected |
| | | | |

TABLE X

STABILITY PARAMETERS FOR AL +10

| | Z | = | 10 | • • |
|---|---|---|-------|--------|
| ប | = | t | 9.36 | volts |
| V | | t | 65.54 | volts |

| | | | · · · · · | | |
|---|-----|------|-----------|----------------|--|
| | Z a | | q | Classification | |
| | 1 | 0.02 | 0.07 | rejected | |
| | 2 | 0.04 | 0.14 | rejected | |
| | 3 | 0.06 | 0.21 | rejected | |
| | 4 | 0.08 | 0.28 | rejected | |
| | 5 | 0.10 | 0.35 | rejected | |
| | 6 | 0.12 | 0.42 | rejected | |
| | 7 | 0.14 | 0.49 | rejected | |
| | 8 | 0.16 | 0.56 | rejected | |
| | 9 | 0.18 | 0.63 | rejected | |
| • | 10 | 0.20 | 0.70 | accepted | |
| | 11 | 0.22 | 0.77 | rejected | |
| | 12 | 0•24 | 0.84 | rejected | |
| | 13 | 0.26 | 0.91 | rejected | |
| | | | | | |

CHAPTER III

QUADRUPOLE DESIGN AND CONSTRUCTION

Introduction

The quadrupole mass filter was designed to fulfill a specific need for analyzing the charged particles, which along with the neutrals, constitute the aluminum plasmas. The aluminum ions were of principle interest, so the discussion of the theory has been restricted to that pertaining only to the ions. The requirements for ion filtering (Peery, 1967) were determined and are presented below:

- A field length of 30 cm which requires four poles of diameter 13.23 mm and separation 11.50 mm.
- (2) A radio frequency generator which operates at 3.2 mhz and which operates in the range from 0 to 1,000 volts peak to peak.

(3) A dc power supply which is variable from 0 to 150 volts. These requirements were basic to the design and each was met without difficulty. As was mentioned in Chapter II, the judicious spacing of the field rods or electrodes to maintain hyperbolic simulation yields the separation distance as given in (1) above. Figure 6 gives both a cross-sectional and a side view of the spacing arrangement. The nickel cylinders were obtained commercially and had an outside diameter of that given in (1) above. The spacer





is constructed of Delrin which was machined to hold the rods at the proper separation distances. Two such spacers were constructed and the cylinders were attached as shown in Figure 6. A calibration rod was carefully machined to a diameter of 11.50 mm and was used to hold the cylinders in place while the containing screws holding them to the spacers were adjusted. After the screws were tightened into place, the calibration rod was then removed, leaving the field radius at the proper value. The nickel cylinders, held in place by the Delrin spacers, then constitute the quadrupole lens system.

Quadrupole Power Supply

The power supply providing the high rf voltage was constructed according to the schematic shown in Figure 7. Included in the power supply is a power transformer which steps wall voltage up to 3 KV, which is then rectified using two mercury vapor diode tubes (866-A). The output is then fed to a class "C" oscillator circuit, which employes two oscillator tubes (4-65 A) and which provides 0 - 3000 VAC at 3.2 MHz. The same transformer provides 0 - 300 VDC. plus and minus, for superposition on the quadrupole electrodes. A large air condenser provides several continuously variable frequency settings, with 3.2 MHz at about mid-range. As will be noticed above, the design requirements for the power supply were exceeded so that a versatile piece of equipment was produced which may be used with the quadrupole lens to investigate elements other than aluminum. For all of the investigations done with the quadrupole mass filter, the frequency was maintained constant at 3.2 MHz. The maximum rf voltage required obtained for the Al⁺¹ specie of aluminum and had





the value 1310.8 volts peak-to-peak. The maximum dc voltage requirement for aluminum ions occurred for the $A1^{+1}$ specie also, and had the value 93.63 volts. As an indication of low voltage requirements, for the specie A1 XI, the values are given, respectively, 65.54 VAC peak-to-peak and 9.46 VDC.

In Figure 8 will be seen the diagram of the power supply as it was used to provide the necessary voltages on the quadrupole field electrodes.

Quadrupole Vacuum System

The vacuum system for the quadrupole mass filter consists essentially of a nickel plated cylinder of 4.0 in inside diameter and 15.0 inches in length. This vacuum envelope has a flange opening at a point half way between the two ends, onto which is bolted a diffusion pump. At one end of the envelope is a one and three-fourths inch opening which provides an entrance to the glass manifold. At the other end of the envelope is attached a 7.0 inch spacer which was constructed to allow enough room inside the vacuum system for the electron multiplier. This causes the over-all length of the envelope to be in the neighborhood of 22.0 inches. At the end of this spacer is bolted a flange plate to close the system. Electrical feedthroughs built into this flange plate permit the transmission of power to the quadrupole electrodes and electron multiplier inside the vacuum system, as well as the transmission of the multiplier output signal to the 585 Tektronic oscilloscope. A diagram of the quadrupole assembly inside the vacuum envelope is given in Figure 9.

The diffusion pump was obtained from the Consolidated Vacuum



Figure 8. Diagram of Quadrupole Electrode Arrangement





Corporation and is properly described as a fractionating oil diffusion pump, type MCF-300. This type requires 225 cc of vacuum pump fluid to operate and the type used was Convoil-20. It contains an external heater rated at 750 watts and is conveniently operated at line voltage. Cooling is provided by water coils through which the flow rate should be adjusted to 0.20 gallons per minute. One nice feature of this pump is that it may be turned on as soon as the fore pump pressure reaches a value of 500 microns or lower. This allows a faster evacuating rate, without the problem of contaminating the system with oil. It should be noted, however, that a baffle was constructed and placed between the envelope and the diffusion pump as an added precaution. The mechanical fore pump used with this system was a Duo Seal, type 1402, obtained from the Welch Scientific Company. The pressure of the system was monitored using two methods. A CVC thermocouple gauge tube, GTC-004, was used to measure pressure from atmospheric down to 1.0 micron. An ion tube, GIC-015-2, was used to measure pressures of 1.0 microns and lower. The output of both of these was taken from a CVC Ionization Gauge, type GIC-100.

Electron Multiplier

The detector system, mentioned before in the text, consist of an uncased, twenty stage copper-beryllium multiplier and the 585 Tektronic oscilloscope. The stages or Dynodes of the multiplier act as secondary electron emitters, as well as electron accelerators. The gain of this device depends on several factors, among which include the pressure and the accelerating voltage between successive dynodes. For the investigations completed with the quadrupole system,

voltages of the order of from 800-1000 volts were used from the 0-2.5KV power supply. With a voltage of 1000 volts supplied to the multiplier, the gain may be conservatively given as 1.0 million. The ions from the plasma source strike the first dynode, i.e., the cathode. Electrons are emitted from the surface of this dynode via secondary emission and are accelerated to the second dynode whereupon more electrons are emitted. This process continues until the secondary electron current, which is the output of the last dynode, or anode, is fed across a load resistor to the oscilloscope. No detailed discussion on the electron multiplier will be given here since the literature (Allen, 1939) available contains literally volumes on the subject. A schematic diagram of the type of multiplier used by this student is presented in Figure 10.

Data Collection

The 585 oscilloscope is used with a Tektronic type 86 plugin unit which has high gain and a rise time of the order of 4.0 nanoseconds. This instrument provides fixed deflection factors from 0.01 volts per centimeter to 50.0 volts per centimeter. Also a variable sweep speed of from 2.0 seconds per centimeter to 50.0 nanoseconds per centimeter are provided. The additional features of single sweep and delayed sweep capability were invaluable to our data collection techniques.

A Tektronic type C-12 camera was used to take pictures of the oscilloscope traces for permanent records. Two types of film were used for our purposes. Both are commercially available from Polaroid and are given as type 47, 3000 ASA, and type 410, 10,000 ASA. The

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¥.,



Figure 10. Schematic of Electron Multiplier

later type of film was found to be especially well suited to the rapid scan speeds used to monitor the initial bursts of ions, as well as the earlier light pulse from both the breakdown of the spark electrodes and the laser impact on aluminum. These photographs are then enlarged for study and several of the curves taken directly from these are presented in Chapter V.

In Figure 11 is presented a block diagram of the quadrupole assembly in the operational mode for analyzing the spark discharge. The high voltage power supply in the upper left of the diagram is used to charge a General Electric pyranol capacitor, which is rated at 1.0 microfarads and 12.5 kilovolts. This capacitor is then discharged across the aluminum electrodes, producing the plasma to be analyzed. The mechanical feedthroughs are used to vary the spark gap separation. The optimum gap width was found to be of the order of 1.0 mm. The power supply in the upper center-left provides the accelerating voltage for the electron multiplier. This is a positive ground power supply and is rated at from 0-2.5 kilovolts. The power supply at the upper center-right provides the rf and dc voltages for the quadrupole field electrodes. The oscilloscope in the upper right monitors the magnitude of the rf voltage, the dc voltage and the frequency of the rf voltage. Although this power supply has been calibrated, the scope allows a constant check to insure that the proper values are maintained throughout the data-collecting process. The oscilloscope in the lower right of the figure monitors the output of the electron multiplier. The C-12 camera is attached to this scope.

A photograph of the quadrupole assembly is presented in Figure



Figure 11. Block Diagram of Quadrupole Mass Filter and Support Equipment

12. This photograph shows the vacuum system, the vertical glass manifold which contains the spectroscopically pure aluminum electrodes and some of the support equipment necessary for operation. Figure 13 provides a picture of the quadrupole field electrodes in a glass insulator sleeve. Also shown in this photograph, immediately to the right of the field electrodes, is the uncased electron multiplier. The flange plate with electrical feedthroughs are shown at the extreme right. At the extreme left will be seen two typical aluminum spark electrodes which are tapered to a point. The device attached to the front of the field electrodes is a pulsed electrostatic lens, which will be discussed in Chapter IV. It should be noted that for all the investigations reported in Chapter V, this device was not inserted between the plasma source and the mass filter.



Figure 12. Photograph of the Quadrupole Assembly



Figure 13. Quadrupole Field Electrodes and the Electron Multiplier

CHAPTER IV

THE PULSED ELECTROSTATIC LENS

Background Discussion

The work associated with analyzing beams of charged particles has nearly always been involved, in some way, with the focusing or collimating of such beams. In many instances, a combination of electric and magnetic fields has been employed for this purpose, depending on the particular requirements. In the case of magnetic mass spectrometers, a magnetic field is necessary to alter the trajectories of charge particles so that they may be identified. In the study of elementary particles, huge magnets are used to contain the particles as they are accelerated to great velocities. It will be remembered that in the Millikan oil drop experiment of 1917, parallel plates were employed to create an electric field to counter the gravitational force on the charged oil drops. Then from pith balls to electronic tubes to synchrocyclotrons, the use of electromagnetic fields to control the trajectories of charged particles is well known.

It has already been discussed in Chapter II how alternating electric fields are employed in the mass filter to control the trajectories of aluminum ions as they traverse the quadrupole field. The need for additional control over the ions to be monitored will immediately be seen upon further investigation of the procedure of

plasma ion analysis.

Consider this simplified process of plasma production and emission. In the case of spark gap breakdown, energy is supplied to the plasma at the time of breakdown for approximately the duration of the capacitor discharge, thereby ionizing the vaporized atoms, as well as energizing the neutral atoms to a metastable state. Immediately thereafter, many of these metastable atoms undergo downward transitions in which light is produced. The resulting emission of the plasma which enters the quadrupole mass filter then consists, not only of ions, but of light and metastable atoms. The filtering action of the quadrupole will eliminate the undesired ionic species, but the light and uncharged metastable atoms pass through the filter undeflected. The light emission in the ultraviolet region and the metastable atoms which strike the first dynode of the electron multiplier, produce secondary electrons, just as do the ions.

The difficulty in reducing the data, as regards a quantitative measurement of relative ionic density and of ionic velocity distributions, can be recognized when the fact, that the light and metastable atoms are superposed on the output, is considered. It was precisely this fact that led to the initiation of the electrostatic lens system.

The desire to remove the neutral atoms and light from the ion beam, prompted the conception of several types of electric and/or magnetic fields to use for this purpose. The disadvantage of some of these lies in their distortion of the velocity distribution, as well as in their inability to handle several ionic specie in sucession. A variety of electrode geometries and voltage values were

considered and the final design is presented later in the test.

It was decided to eliminate the use of magnetic fields entirely and to design a device which could be used to focus all of the ions along a direction with as wide an angular separation from the light and neturals as practical. Since as in the quadrupole itself, the light and neutrals are unaffected by electric fields, they are allowed to pass through the lens along a straight line from the plasma source, while the ion trajectories are curved to the extent of the magnitude of the applied voltage to the lens electrodes.

Design and Construction

One of the fundamental requirements, considered in the design of the lens, was that all ions considered, regardless of their velocity, exit the lens at very closely the same angle and along the same direction. Of course, the ions enter the lens from the plasma source along with the light and neutrals. A simple parallel plate design was taken as a starting guide, but it was quickly seen that because of the velocity range of from 700 to 7000 meters per second of the ions, the angular exit spread was impossible to cope with. This was, of course, due to the ions, although of the same charge, spending different times in the uniform electric field of definite length. In order to overcome this difficult, a non-uniform field, resulting from an asymmetrical electrode geometry, was found to be suitable in theory, but the foreseen difficulty with construction of the electrodes and the problem of fringing discouraged this design.

A return to the basic parallel plate was the answer to our design questions. The key to the solution was to construct a solid

base plate, but to substitute discrete wire electrodes for the opposing plate. The obvious advantage in this arrangement is that a different voltage may be placed on each of the wire electrodes, thereby producing the desired electric field gradient necessary to focus the ions, regardless of their velocities.

Figure 14 shows the field electrode wires and the base ground plate as they are held in place by the Delrin insulator. It was found that if the electric field of the electrostatic lens was applied for 1.0 microseconds, the 7000 meter per second ions would travel a distance of 7.0 mm in this time interval. Since the slower ions will travel distances, proportionally shorter than this, the effective field length of the lens was designed to be approximately 8.5 mm. It will be seen in Figure 14 that there are eleven field electrodes. Only the central five of these electrodes provide the critical electric field gradient. Three electrodes on either side of these central five were inserted to provide a means to maintain a fairly uniform, i.e., parallel, field in the central effective region of the lens. This seems to be the solution to the fringing problem. The potential on the first three electrodes is maintained at the same potential as that on the first effective electrode. The potential on the last three electrodes, which are closer to the exit of the lens, is maintained at the same potential as that on the fifth or last effective electrode. The base plate is always maintained at ground potential.

The name, pulsed electrostatic lens, derives from the fact that the effective field is acting only for a very short interval of time, which in this case is 1.0 microsecond. This of course demands that







the applied field be synchronized with the entry of the ions into the lens.

Electrostatic Lens Theory

Consider the emission of ions from a plasma which is then directed into the region of an electric field, produced by the electrostatic lens. The construction of the lens with spaced electrodes necessitates the use of two equations of motion since the ions directly above a wire electrode are in the region of a constant electric field, whereas an ion between two electrodes is in the region of a space dependent field.

From Coulomb's law and Newton's second law the basic equation of motion is determined:

| → → F=neE | (41) |
|--|-------|
| $\overrightarrow{F} = \mathbf{m} \mathbf{a}$ | (4.2) |

where: n = degree of ionization

Then the equation becomes:

or

$$\frac{\overline{d^2 y}}{d^2 t} = \frac{w}{y} = \frac{n \ e \ E}{m}$$
(4.4)

Now since the electric field is given:

$$\vec{E} = \vec{E}_{y} \vec{j}$$
(4.5)

one is concerned only with the vertical displacement of the ion in

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the field. The velocity in the x-direction, i.e., the initial direction of ion travel, is unaltered by the field.

Then for an on-axis entry of the ions, i.e., with no initial vertical displacement, the equation of motion is then the solution to Equation (4.4).

Solving for the vertical displacement (y) in Equation (4.4),

$$\frac{d\mathbf{y}}{dt} = \mathbf{y} = \frac{ne}{m} \int_{0}^{t} E dt$$
(4.6)

$$=\frac{\mathrm{ne}}{\mathrm{m}}$$
 Et + $(\frac{\mathrm{dy}}{\mathrm{dt}})_{\mathrm{o}}$

where: $E = \frac{V}{d} = constant$

V = accelerating potential
d = vertical field separation

then:

$$y = \frac{ne}{m} E \int_{0}^{t} t dt + \int_{0}^{t} \left(\frac{dy}{dt}\right)_{0} dt \qquad (4.7)$$

or

$$y = \frac{ne}{m} E \frac{t^2}{2} + (\frac{dy}{dt})_0 t + y_0$$
 (4.8)

is given as a function of time in terms of the electric field (E), the degree of ionization (n), the electronic charge (e), the ionic mass (m), the initial vertical velocity $((dy/dt)_{o})$ and the initial vertical displacement (y_{o}) .

Through an obvious change of variables,

$$v = \frac{(x - x_0)}{t}$$
(4.9)

where: v = velocity in x-direction

Equation (4.8) becomes:

$$y = \frac{n \ e \ E}{2 \ m} \left(\frac{x \ - \ x_{0}}{v}\right)^{2} + \frac{x}{y_{0}} \frac{(x \ - \ x_{0})}{v} + y_{0}$$
(4.10)

where: $y_{0} = \left(\frac{dy}{dt}\right)_{0}$

Now with the equation in this form, the slope of the ion trajectory is determined for any horizontal displacement. This slope is given:

$$\frac{dy}{dx} = \frac{n \ e \ E}{2 \ m} \frac{2(x \ - \ x_{o})}{v^{2}} + \frac{y_{o}}{v}$$
(4.11)

The Equations (4.10) and (4.11) give the vertical displacement and slope of the ion trajectory for any horizontal displacement into the electric field. It is desirable to know the slope of the trajectory in terms of angular degrees above the horizontal or initial direction travel. This is given by the familiar form:

TAN
$$\theta = \frac{dy}{dx}$$

or

$$\theta = ARC TAN \frac{dy}{dx}$$
 (4.12)

Therefore from Equation (4.11) the following expression for the slope is obtained:

$$\vartheta = \operatorname{ARC} \operatorname{TAN} \left[\frac{n \ e \ E}{2 \ m} \frac{2(x \ - \ x_{o})}{v^{2}} + \frac{y_{o}}{v} \right]$$
 (4.13)

The equations derived above are for a charged particle in the

parallel plate capacitor. They hold for the period in which the ions are directly above the electrode wires of the lens system.

In traversing the entire lens, the ions intermittently pass through regions between electrodes where the electric field is not constant, but an increasing function of (x). The equation of motion for the ions in this region differ from those derived above to the extent that E = E(x).

i.e.,
$$y(t) = \frac{n \ e \ E(x)}{m} = \frac{n \ e \ V(x)}{md}$$
 (4.14)
where: $V(x) = V_{\perp} + \alpha \ x$ (4.15)

 $V(x) = V_0 + \alpha x$ where:

and:
$$\alpha = \frac{\partial V}{\partial x}$$
,

1

the special increase of the potential in the direction of ion travel. Solving for (y) in Equation (4.14), the equation of motion is obtained:

$$\mathbf{y}(t) = \frac{\mathrm{ne}}{\mathrm{md}} \int_{0}^{t} (\mathbf{V}_{0} + \alpha \mathbf{x}) dt$$
 (4.16)

$$u = \frac{ne}{md} \int_{0}^{t} (V_{0} + \alpha v t) dt$$

so that:

$$\hat{\mathbf{y}}(t) = \frac{\mathrm{ne}}{\mathrm{md}} \left[\mathbf{V}_{\mathrm{o}} t + \frac{\alpha \mathbf{v} t^2}{2} \right] + \hat{\mathbf{y}}_{\mathrm{o}}$$
 (4.17)

and

$$y(t) = \frac{ne}{md} \int_{0}^{t} (V_{0} t + \frac{\alpha v t^{2}}{2}) dt + \int_{0}^{t} y_{0} dt$$
 (4.18)

or

$$y(t) = \frac{ne}{md} \left[\frac{v_{o}t^{2}}{2} + \frac{\alpha v t^{3}}{6} \right] + y_{o}t + y_{o}$$
(4.19)

With a change in variables, the equation of motion yields the vertical displacement as a function of (x) for the space dependent region of the electric field.

$$y(x) = \frac{ne}{md} \left[\frac{V_o (x - x_o)^2}{2 v^2} + \frac{\alpha (x - x_o)^3}{6 v^2} \right] + \frac{y_o (x - x_o)}{v} + y_o$$
(4.20)

The slope is then given, similar to Equation (4.11) by the following:

$$\frac{dy(x)}{dx} = \frac{ne}{md} \left[\frac{v_o(x - x_o)}{v^2} + \frac{\dot{\alpha}(x - x_o)^2}{2 v^2} \right] + \frac{\dot{y}_o}{v}$$
(4.21)

or

$$\Theta = ARC TAN \left[\frac{ne}{md} \left[\frac{V_o (x - x_o)}{v^2} + \frac{\alpha (x - x_o)^2}{2 v^2} \right] \frac{\dot{y}_o}{v} \right]$$
(4.22)

Thus the ion trajectories are specified at any point through the lens system by Equations (4.10) and (4.12) over an electrode region and by Equations (4.20) and (4.22) over a space region.

Slopes of the Ion Trajectories

The equations derived above were used to predict the motion of

any ion, regardless of its charge or entrance velocity. The mass of of the ions was taken as that of aluminum.

In the velocity range from 700 m/sec to 7000 m/sec the final vertical deflection and slope of each ion specie has been calculated. The minimum vertical deflection for the 1000 m/sec ion has the value of 0.1171 mm and the maximum deflection occurs for the 7000 m/sec ion and has the value of 0.5948 mm.

A computer program was used to calculate the optimum voltages required to maintain a constant 15.00 degree slope. Using this value of the slope as optimum, the following deviations were calculated.

The maximum value for the slope occurred for the 2500 m/sec ion and is given: 17.13 degrees

The minimum value for the slope occurred for the 3500 m/sec ion and is given: 12.64 degrees

The deviation from the optimum slope is then given:

+ 2.13 and - 2.36 degrees

It should be noted here that actually two programs were run. One held the slope or angle from the horizontal constant at 15.0 degrees and inquired the necessary voltages to maintain this value assuming a linear continuous potential gradient in the direction of ion travel. This gave the approximate voltage values to be on the field wires. These values are approximate since the actual electric field created in the region by the several wires and ground plate is not continuous, but stepwise increasing.

The continuous program was used as a guide to set the voltages on the wires and to estimate the potential gradient for the region between the wires. These values were then used in the second pro-

gram to calculate the voltages on the wires so that the constant electric field in the region directly over the wires and the linearly increasing field in the region between the wires would be such as to yield values for the slopes of the ion trajectories as close to 15.0 degrees as possible. Several programs were written, based on the solutions for the equations of motion and two of them are presented in the Appendix. Also two pages of computer output data are presented there as typical examples.

It can be seen that the angular spread for the entire range of velocities is only 4.49 degrees. Using the relation

 π radians = 180 degrees

and

(4.23)

arc length = r θ ,

a conservative angular spread of 5.0 degrees yields an approximate spread of only 0.873 cm after 10.0 cm of travel from the exit of the electrostatic lens system, i.e.,

> arc length = 10.0 cm X 0.0873arc length = 0.873 cm

The diameter of the quadrupole aperture is 1.15 cm. This means that at a distance of 10.0 cm, the quadrupole should be in a position to accept all ions that pass through the lens in the prescribed manner.

The field wires or electrodes are situated so that the separation between them and the base ground plate is constant at 4.0 cm.

The electrodes themselves are 0.5 mm in diameter and the longitudinal center-to-center separation of the electrodes is 2.0 mm. The electrodes are constructed of high purity nickel (Ni #200, 99%), as is the base ground plate.

The voltage values for the five (5) electrodes as well as the potential gradients are shown in Table XI.

In this table, electrode number 1 corresponds to the wire electrode nearest to the entrance of the electrostatic lens. Electrode number 5 is very near the exit of the lens. ALPHA I corresponds to the potential gradient in the direction of ion travel, for values of displacement into the field of from 0.0 to 2.5 mm. ALPHA II corresponds to values in the 2.5 to 8.0 mm range.

Figure 15 is presented as a graphic illustration of the potential distribution on the five effective field electrodes. It may also be taken as proportional to the electric field strength in the region, since the distance from all the electrodes to the base ground plate is the same.

The curve number 1 represents the potential distribution of the lens electrodes necessary to direct ion number 1, or $A1^{\pm 1}$, toward the aperture of the quadrupole mass filter. Curve number 2 represents the potential distribution necessary to direct ion number 2, or $A1^{\pm 3}$ toward the quadrupole, etc.

A single power supply may be used to provide the different voltages to all five of the effective field electrodes, if an appropriate voltage divider is employed. Such a voltage divider is presented in Figure 16. For design purposes, only the first five specie of aluminum ions were considered. The voltage on the fifth effective electrode, necessary to curve the trajectory of the fastest AI^{+1} ion by 15 degrees, was calculated to be 125.0 volts. Therefore the highest voltage required of the power supply has been determined. The lower

TABLE XI

VOLTAGE VALUES AND POTENTIAL GRADIENTS

| | | and the second sec | | | | and a state of the second second second | |
|-----|--------------------------|--|--------------------------|--------------------------|--------------------------|---|--------|
| ION | ELECTRODE #1 volts | EIECTRODE #2 volts | ELECTRODE #3 volts | ELECTRODE #4 volts | ELECTRODE #5 volts | ALPHA I volts/mm | & II |
| 1 | 3.00 | 20.00 | 55.00 | 90.00 | 125.00 | 8.947 | 18.420 |
| 2 | 1.50 | 10.00 | 27.50 | 45.00 | 62.50 | 4+474 | 9.210 |
| 3 | 1.00 | 6.67 | 18.33 | 30.00 | 41.67 | 2.982 | 6.140 |
| Ц | 0.75 | 5.00 | 13.75 | 22.50 | 31.25 | 2.237 | 4.605 |
| 5 | 0.60 | 4.00 | ́ш.∞ | 18.00 | 25.00 | 1.789 | 3.684 |
| | | | | | | | |







Figure 16. Voltage Divider for Electrostatic Lens Power Supply
voltages for the other electrodes are taken from the voltage divider.

The switch at the center of the left terminal block in Figure 16 is set for Al II, i.e., in the number 1 position. The terminal numbers on the switch correspond to the potential curves in Figure 15. The voltage divider output terminal letters correspond to the five effective field electrodes.

The position of the pulsed electrostatic lens, as it will be used to extract the ions from the plasma emission is shown in Figure 17. The plasma source, at the extreme right, emits a composition of light, neutral atoms and ions through the entrance slit. The light and neutral atoms pass through the lens undeflected, but the ions are accelerated directly at the quadrupole mass filter aperture.

Summary

The design and construction of the pulsed electrostatic lens has been completed and will soon be used as an integral part of the quadrupole mass filter assembly. The design of the pulsed power supply for the lens is under way and the delay circuits to synchronize the pulse with the arrival of the ions to the lens, are already available. In order to place a pulse of 125.0 volts for 1.0 microsecond on the voltage divider, which in turn, supplies the electrodes of the lens system, a Schmitt trigger circuit may be employed. The Schmitt trigger is a modified cathode-coupled bistable multivibrator, which is widely used as a voltage discriminator (Malmstadt and others, 1962). This trigger is useful as a "squaring circuit" and is often used in a sine-square generator to convert the output of a sine-wave oscillator to a square wave.



Figure 17. Electrostatic Lens in Operational Configuration

The vacuum spark discharge will be used to calibrate the delay system and to obtain proficiency in reducing the data. This data will be in the form of photographs, similar to the ones taken in the initial quadrupole experiments. It is hoped that with the electrostatic lens, velocity distributions of the ions from both the laser impact and the exploding wire plasmas can be obtained. The device should also enhance the resolution with which the relative ionic density of the plasma can be determined.

CHAPTER V

RESULTS AND CONCLUSIONS

The design and construction of the quadrupole mass filter assembly was completed in late 1967 and the preliminary testing began in early 1968. The mechanical components of the assembly behaved well, but some difficulty was encountered in constructing a stable, class "C" oscillator. Much effort was expended in balancing the oscillator circuits and it was found that additional trimmer capacitors were necessary for balance. A new oscillator tube that was defective added to the instability. Both oscillator tubes were replaced and the power supply was operational. The power supplies for the discharge condenser and the electron multiplier gave no difficulty.

The quadrupole lens and the electron multiplier were placed into the vacuum system and were then ready to analyze the plasma ions. The aluminum spark gap, used to produce the plasma, was the same one used by Vernon D. Brown in his measurements of the emitted light. Payne has used the same spark at the same rated voltage and current to obtain spectrographs of the emitted light in the far ultraviolet, i.e., spectral lines are identified as being from Al IV, Al V, etc. Measurements of the ion content have been taken for three settings of the voltage across the gap. The most reproducible data was obtained with the 1.0 microfarad condenser charged to 10,000 volts. This was the same rating that was employed by Brown and Payne for

their measurements.

Procedure

In a typical data run, the quadrupole power supply is turned on for a period of approximately 30 minutes to allow the oscillator and rectifier tubes to warm up. During this period, the oscilloscopes are also turned on so that they will become completely stabilized before they are needed. The aluminum electrodes are aligned in the glass vacuum manifold and the pressure of the system is constantly monitored to insure that approximately 10^{-5} Torr is maintained. Next, the electron multiplier is turned on and the voltage is set to about 800 volts.

The quadrupole power supply is then set at the proper rf and dc voltages to obtain a particular ion. The high voltage power supply is turned on and set at 10,000 volts in order to charge the condenser. This condenser is then allowed to discharge through the spark gap. The resulting trace on the output oscilloscope is photographed.

Discussion of Spark Discharge Data

The variables to be considered in analyzing the curves, which are shown in this chapter, are given below. The electron multiplier is electrically biased to receive no electrons, so that they are not considered. The variables are identified in the following list.

- (1) Light from the spark breakdown
- (2) Excited atoms which are neutral, i.e., atoms that have been excited to a metastable state
- (3) Singly ionized aluminum ions

- (4) Doubly ionized aluminum ions
- (5) Triply ionized aluminum ions
- (6) Quadruply ionized aluminum ions
- (7) Quintuply ionized aluminum ions

The variables appear in different combinations which may be selected, in part, by changing the fields in the quadrupole mass filter and by chance location of the position on the tapered electrodes at which the spark occurs. Since the ions travel a known distance, which is approximately 34.0 cm, the initial arrival time of each specie of ion at the electron multiplier is indicated by the curves for that particular specie of ion. The initial response of the quadrupole mass filter is to the ultraviolet light from the spark and this is an accurate indication of time zero. The time interval which is measured between zero time and the arrival of 10 percent of the ions of one specie is the time that is required for the ions to traverse the distance of 34.0 cm. This velocity corresponds, to a first approximation, to the random velocity of the ions. If this assumption is accepted, the relation, $1/2 \text{ m v}^2 = 3/2 \text{ k}$ T, permits one to know the (kinetic energy) temperature of the ions. The time of arrival of the different ions permits one to compare the temperature (kinetic energy) of the different ions and of the excited (metastable) atoms.

Provided the ions of different species, such as $A1^{+2}$, $A1^{+3}$, ..., and excited atoms, have the same random velocity, the discharge is in kinetic equilibrium. It is entirely feasible for the different specie to be in kinetic equilibrium although from the set of measurements that have been obtained for conditions equivalent to those of Payne and Brown, there cannot be equilibrium between the ionization energy

and the kinetic energy. Figure 18 gives the ionic energy as a function of the random velocity.

A considerable amount of information may be dedcued from the data, and a considerable amount of interpretation is required. Some of the problems in the interpretation have been encountered before in the data from the spark breakdown, taken by Carpenter and Brown.

The shape of all the curves that are presented in Figure 19 is controlled and dominated by the light emission. The electron multiplier responds by producing a current for ultraviolet photons, as well as for some of the photons of shorter wavelength in the visible. For the set of curves at the top of Figure 19, the lower solid curve represents the light emission and provides a base curve for reference. The curves superposed on the light emission provide a sample comparison of all the ions with no ions. The curve for all ions was obtained by turning the quadrupole fields completely off. Therefore all ions, regardless of their charge, were allowed to pass through the lens as there is no filtering action. The dotted curve represents only neutral, metastable aluminum atoms and the light emission. To obtain this curve, the quadrupole power supply was set at values for which no ion could penetrate the field.

Several interesting features were illustrated for the light emitted by the spark discharge. The curve for the light alone is obtained occasionally and its occurrence is determined by chance. It is believed that this curve results when the spark is such that the ions are emitted away from the aperture of the quadrupole lens. Its reproducibility with respect to the oscillations in the first few microseconds and with respect to its amplitude, lend credence to this



VELOCITY

Figure 18. Graph of Random Ionic Energy Versus Velocity





interpretation. The first oscillation on these curves was masked by noise and no attempt was made to interpret this region. From the curve for the light emission, the plasma continues to emit light, as well as ions, for the entire time that the curves were recorded, i.e., for over 200 microseconds.

The oscillations have a duration of about 10 microseconds. Since each half cycle of voltage should produce of power input, as in any electric circuit, the frequency of the oscillation is about 50 khz. This is the natural frequency for the condenser discharge through the spark. These oscillations are of considerable amplitude for a period of about 40 microseconds, which indicates that the condenser discharge is completed in this time. This is significant for the formation of the stable plasma, since the plasma is not fully formed and therefore is not very stable until the discharge is complete.

This interpretation finds some substantiation in the nonreproducible regions of the curves, where the arrival of the ions and metastable atoms at the multiplier is first indicated. This region of the curves is also of approximately 40 microseconds duration. This duration corresponds very well, as it should, with the creation time of the plasma.

Note that the ions and neutrals begin to arrive at the multiplier between 60 and 70 microseconds after the breakdown begins. The intensity from the excited atoms and the ions is the difference between the ordinate of this curve and the ordinate for the photons.

On the lower set of curves in Figure 19, it is readily seen that the base for the photon emission is practically identical to that in the upper set. The dotted curve corresponds to the $A1^{+1}$ ions,

whereas the solid curve represents the Al^{+2} ions. It must be remembered that the neutrals are also included in these amplitudes. The curves are so designated because the voltage parameters "a" and "q" have been set to select only the Al^{+1} and Al^{+2} ions, respectively. Maximum amplitude is attained for each ionic specie when the voltages are set at the calculated values.

The random velocities of the ions and/or the metastable atoms may be taken, to a good approximation, directly from the Intensity versus Time plots. In the upper set of curves, velocities of the order of 5 X 10^5 centimeters per second were recorded for metastable atoms, while velocities of 4 X 10^5 centimeters per second and lower are shown in the figure for the all-ions configuration.

Both the Al⁺¹ and Al⁺² curves indicate ionic velocities of the order of 5 X 10⁵ centimeters per second, which corresponds to an energy of 3.5 eV. It must again be emphasized that this measured value is considerably higher than would be expected in the plasma proper. The measured value of 6.0 eV corresponds roughly to a plasma energy of the order of one (1) eV, or a temperature of approximately 12,000 Kelvin degrees.

Additional information on other ionic species is given in Figure 20. The set of curves at the top of this figure compare $A1^{+3}$ with $A1^{+4}$ and a measure of $A1^{+5}$ is presented in the lower set. The presence of these specie is firmly established by the interpretation of the emitted spectra in the far ultraviolet by Carpenter.

As of this writing, no quantitative evidence is available from the quadrupole data to substantiate the qualitative conclusion that the specie, $A1^{+3}$ is the most abundant. However, measurements with the



Figure 20. Spark Discharge Curves for A1 +3, A1 +4 and A1 +5

spectrograph appear to support this preliminary evaluation of the data.

Discussion of Laser Impact Data

The quadrupole mass filter was employed to analyze the emission of ions and light from an aluminum plasma that was produced by laser beam impact. The design and construction of the laser was completed by Peery (1967). Mr. W. G. Robinson made modifications on the laser assembly and through his efforts, operation in the Q-switched mode was achieved. The laser is fired by charging a large condenser bank with a high voltage power supply and then allowing the bank to discharge through helical flash lamps. These lamps optically excite the twin ruby rods. The resulting giant laser beam is then focused onto the aluminum target. The plasma, thus created, is allowed to expand freely into a vacuum. The ions, metastable atoms and the light emission is monitored with the quadrupole mass filter.

The aluminum target was positioned, in vacuum, so that approximately the same drift space existed as that for the spark discharge. Since the plasma is produced in about 30 nanoseconds and emission in the ultraviolet continues for only about 2 microseconds, the curve may, with some hesitation, be interpreted as velocity distributions. It is not clear as to the meaning of a lack of emission during the time of flight. The pressure of the vacuum chamber, containing the aluminum target, was maintained at about 10^{-5} Torr.

Some typical examples of the data obtained with the quadrupole in the initial analysis of the plasma, produced by the laser, are presented in the following figures. The dominating feature in Figure 21 is the ultraviolet light emission. The peak amplitude of this



Figure 21. Laser Impact Emission of All Aluminum Ions, Metastable Atoms and Light

emission is reached after about 0.25 microsecond and it has decayed to nearly zero amplitude after 2.0 microseconds. This emission duration is significant since it may very well indicate the production time of the plasma. To obtain this curve, the quadrupole power supply was turned completely off, allowing all specie of ions to pass through the mass filter along with the metastable atoms and light.

Figure 22 shows a curve obtained under similar conditions, but with the time scale increased by a factor of ten. Notice first of all that what is believed to be the ultraviolet emission cut-off also occurs at approximately 2.5 microseconds. What is considered to be the initial burst of ions begins immediately after the decay of the light emission, or at about 2.0 to 2.5 microseconds after impact.

Figure 23 is presented for comparison with the subsequent curves and is a result of similar conditions as for Figures 21 and 22, but with an increased voltage scale.

The quadrupole was set to reject all ions except $A1^{+2}$ and the laser was fired in the usual manner. The resulting trace, shown in Figure 24, gives an indication of the $A1^{+2}$ ions, metastable atoms and light.

Two curves are presented for $A1^{\pm 3}$ in Figures 25 and 26. A comparison of these will show that while the data is highly reproducible with respect to the initial light emission and the arrival of the first ions and/or neutrals, the obvious difference in amplitudes indicates that no two impact phenomena are identical, however, similar they are.

An indication of the Al^{+4} ions is shown in Figure 27. The variance in the amplitudes of the curves for identical















Figure 25. Laser Impact Emission of Al ± 3 , Metastable Atoms and Light



Figure 26. Laser Impact Emission of Al +3, Metastable Atoms and Light Indicating Increased Ionic Concentration



Figure 27. Laser Impact Emission of Al +4, Metastable Atoms and Light

quadrupole field values will necessitate a statistical a statistical evaluation of the data, with regard to the relative concentration of each specie, but from the curves presented here, significant information regarding the velocities of the ions and neutral atoms may be gathered.

If the peak, beginning at 2.5 microseconds in Figure 23, may be accurately designated as the arrival of aluminum ions from the target area, then their velocity has a measured value of the order of 10⁷ centimeters per second. This velocity corresponds to an energy of 1.4 keV and a Boltzmann temperature of 10,800,000 Kelvin degrees. The burst of ions corresponding to the peak beginning at about 20 microseconds, yields values for the velocity of the order of 1.7 X 10⁶ centimeters per second. Velocities of approximately this value correspond to ionic energies of between 20 and 50 eV and to temperatures in the 300,000 Kelvin degree range.

Observations of the continuous spectrum from the sun and the application of the laws of radiation indicate that the effective, surface temperature of the sun is about 6,000 Kelvin degrees. Dr. L. W. Schroeder, of the Astrophysics Group at Oklahoma State University, indicates that the interior temperatures of the sun have been reported to be of the order of 15 to 20 Kelvin degrees. Using these values as a yard stick, the extremely high temperatures of the plasma may be appreciated.

The study of sodium plasmas, carried out by researchers at the Honeywell Corporate Research Center, Hopkins, Minnesota, has produced plasma energies of 20 to 30 eV (ready, 1967). These results correspond to temperatures in the 300,000 degree range, measured in

Dr. Todd's group here at Oklahoma State.

Summary

The results of the quadrupole mass filter analysis of the spark discharge and the laser impact have provided some experimental verification of the theoretical work, currently being done by this group. The work has not only been rewarding in terms of the initial results, but the results themselves have provided an incentive to further investigate the properties of transient plasmas.

It is hoped that in the near future, an analysis of the exploding wire plasma may give an even better understanding of the behavior of the ions, metastable atoms and light. The exploding wire assembly was constructed by Mr. J. A. Yoder and tests are currently being made to determine its operational characteristics.

One major advantage the exploding wire offers is the very short production time of the plasma. A production time of the order of 1.0 microsecond will not only decrease the uncertainty with which velocity distribution measurements can be made, but it presents the possibility of attaining a plasma in equilibrium. The two other methods of plasma production, mentioned in this report, do not.

Other planned experiments include the addition of the pulsed electrostatic lens to the quadrupole assembly. The exciting prospect of analyzing the individual ion velocity distributions with the aid of this device promises to make a major contribution to the state of the art of plasma physics.

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APPENDIX

The equations of motion for the ions that traverse the electrostatic lens are given in Chapter IV. Because of the many calculations to be made to determine the field dimensions and the voltage values for the lens electrodes, two computer programs were written so that the behavior of the ions could be determined for a variety of initial conditions. Among these conditions are included the electric field width, the field length, the diameter of the lens electrode wires, the spacing of the wires and the voltage to be applied to each electrode. Also a factor, which was considered in the calculations, was the electric field gradient in the direction of ion travel. It should be noted that several pulse intervals, from 1.0 to 10.0 microseconds, were considered. The best solutions were obtained for 1.0 microsecond.

The programs were written in the FORTRAN IV computer language and were run on the IBM 360 computer, model 50.

Continuous Program

The initial programs were written to inquire of the equations of motion, the positions and slopes of the ions after a predetermined time in the field. In this type program, the electric field was specified as continuously increasing in the direction of ion travel. Several values of the field were introduced in the program to obtain exit slopes that were consistent with the geometry of both the pro-

posed lens and that of the existing quadrupole. It must be remembered that the field gradient is the factor involved for extracting the ions from the lens at the same angle. The electric field, necessary to deflect a slow ion a given angle will hardly affect the trajectory of an ion whose velocity is a factor of ten greater. Since all the ions, regardless of their velocity, must pass through the same field, the field value at the end of the lens must be large enough to deflect the faster ions the same angle as the lower field, at the front of the lens deflects the slower ions. Also this field must be turned off by the time the slower ions reach the end of the lens so they will not be deflected further.

A typical program of the continuous type is presented in Table XII. A sample page of the computer output for this program is presented in Table XIII. For this program, the velocity ranged from 700 to 7000 meters per second in 10.0 meter per second intervals. It is assumed that all ions, regardless of their velocity are present at x = 0 for t = 0. This point represents the entrance to the lens. It will be noticed in this program that the slope, or angle THETA, is held constant at 15.0 degrees. The program then gives the voltage values along the route of ion travel which are necessary to give the 15.0 degree deflection. In the illustration given, the potential is specified at the point the ions have reached at the end of the 1.0 microsecond interval. The value of the field gradient at this same point is also specified.

Discontinuous Program

The values of the field gradient from the continuous program

TABLE XII

TYPICAL CONTINUOUS PROGRAM FOR ELECTROSTATIC LENS

| | \$JOB 2233-40031 H WAYNE WILLIS |
|-----|--|
| 1 | 1 FORMAT{////,2X,5HAN = ,E10.4,3X,5HAK = ,E10.4,3X,4HT = ,E10.4,3X, |
| | 16HPTO = ,E10.4,3X,4HV = ,E10.4,3X,5HDV = ,E10.4,3X,5HVF = ,E10.4, |
| | $2/3X, 4HW = E10.4, 20X, 8HALPHA = E10.4}$ |
| 2 | 2 FORMAT(/,4X,14,5X,6(E12.4),22X,E12.4) |
| 3 | 3 FORMAT (///, 7X, 1HM, 10X, 1HY, 11X, 1HS, 9X, 5HTHETA, 8X, 2HPT, 11X, 1HX, 11X, |
| • | 15HALPHA, 35X, 1HV) |
| 4 | 4 FORMAT(5X,E10.4) |
| 5 | READ(5,4) AN,AK,T,PTO,V,DV,VF,W,ALPHA |
| 6 | 9 WRITE(6,1) AN,AK,T,PTO,V,DV,VF,W,ALPHA |
| 7 | V=7.0E 02 |
| 8 | M=1 |
| 9 | DVC=DV |
| 10 | PT=PTO |
| 11 | 10 WRITE(6,3) |
| _12 | 11 X=V+T |
| 13 | S={{AN+AK}+{2.0+PT0+X+ALPHA+X+X}}/{V+V+W} |
| 14 | Y=({AN+AK}+(PTO+X+X+ALPHA+(X+X+X)/3+0})/(V+V+W) |
| 15 | THETA=ATAN(S)*57.29578 |
| 16 | PT=PTO+ALPHA*X |
| 17 | WRITE(6,2) M, Y, S, THETA, PT, X, ALPHA, V |
| 18 | M=M+1 |
| 19 | IF(V.GE.VF) GD10 50 |
| 20 | IF(V.GE.1000.0) DV0=10.0*DV |
| 21 | V=V+DVO |
| 22 | |
| 23 | 50 IF (AN. GE. 5.0) GUIU 60 |
| 24 | AN=AN+1.0 |
| 25 | 1F(AN = EQ. 2.0) ALPHA=3.0 E 03 |
| 20 | $\frac{1\Gamma(AN+CV+3+J)}{\Gamma(AN+CV+1)} = \frac{1}{2} \frac{1}{$ |
| 21 | $1 \Gamma(AN + CQ + 4 + 0) ALPHA=1 + 2 C O = 1$ |
| 28 | $\frac{1\Gamma(AN \cdot CV \cdot 2 \cdot U) ALPHA=1 \cdot 2 \in U3}{COTO O}$ |
| 29 | |
| | |
| 31 | ENU |

\$ENTRY

TABLE XIII

ì

SAMPLE COMPUTER OUTPUT FOR CONTINUOUS PROGRAM

| = 0.300 = 0.400 | <u>DOE 01 AK = 0</u> DOE-01 | <u>1786E_07</u> | T = 0.1000E S = 0.2679E 0 | 05 PTO = (| .5000E 00 | V = 0.7000E 04 | DV = 0.1000E 02 | VF = 0.7000E |
|--------------------|--------------------------------|-----------------|------------------------------|------------|------------|----------------|--|--------------|
| M | Y | s | THETA | PT | x | ALPHA | | v |
| 1 | 0.8483E-04 | 0.2679E 00 | 0.1500E 02 | 0.9000E 00 | 0.7000E-03 | 0.5714E 03 | | 0.7000E 03 |
| 2 | 0.8573E-04 | 0.2679E 00 | 0.1500E 02 | 0.9200E 00 | 0.7100E-03 | 0.5915E 03 | · · · · · · · · · · · · · · · · · · · | 0.7100E 03 |
| 3 | 0.8662E-04 | 0.2679E 00 | 0.1500E 02 | 0.9400E 00 | 0.7200E-03 | 0.6111E 03 | | 0.7200E 03 |
| 4 | 0.8751E-04 | 0.2679E 00 | 0.1500E 02 | 0.9600E 00 | 0.7300E-03 | 0.6301E 03 | · · · · · · · · · · · · · · · · · · · | 0.7300E 03 |
| 5 | 0.8841E-04 | 0.2679E 00 | 0.1500E 02 | 0.9800E 00 | 0.7400E-03 | 0.6486E 03 | · · · · | 0.7400E 03 |
| 6 | 0.8930E-04 | 0.2679E 00 | 0.1500E 02 | 0.1000E 01 | 0.7500E-03 | 0.6667E 03 | | 0.7500E 03 |
| 7 | 0.9019E-04 | 0.2679E 00 | 0.1500E 02 | 0.1020E 01 | 0.7600E-03 | 0.6842E 03 | | 0.7600E 03 |
| 9 | 0.9109E-04 | 0.2679E 00 | 0.1500E 02 | 0.1040E D1 | 0.7700E-03 | 0.7013E 03 | ···· ·· ······························ | 0.7700E 03 |
| 9 | 0.9198E-04 | 0.2679E 00 | 0.1500E 02 | 0.1060E 01 | 0.7800E-03 | 0.7179E 03 | | 0.7800E 03 |
| 10 | 0.9287E-04 | 0.2679E 00 | 0.1500E 02 | 0.1080E 01 | 0.7900E-03 | 0.7342E 03 | | 0.7900E 03 |
| 11 | 0.9376E-04 | 0.2679E 00 | 0.1500E 02 | 0.1100E 01 | 0.8000E-03 | 0.7500E 03 | | 0.8000E 03 |
| 12 | 0.9466E-04 | 0.2679E 00 | 0.1500E 02 | 0.1120E 01 | 0.8100E-03 | 0.7654E 03 | | 0.8100E 03 |
| 13 | 0.9555E-04 | 0.2679E 00 | 0.1500E 02 | 0.1140E 01 | 0-8200E-03 | 0.7805E 03 | | 0.8200E 03 |
| 14 | 0.9644E-04 | 0.2679E 00 | 0.1500E 02 | 0.1160E 01 | 0-8300E-03 | 0.7952E 03 | | 0.8300E 03 |
| 15 | 0.9734E-04 | 0.2679E 00 | 0.1500E 02 | 0.1180E 01 | 0.8400E-03 | 0.8095E 03 | | 0.8400E 03 |
| 16 | 0.9823E-04 | 0.2679E 00 | 0.1500E 02 | 0.1200E 01 | 0.8500E-03 | 0.8235E 03 | · · · · · · · · · · · · · · · · · · · | 0.8500E 03 |
| 17 | 0.9912E-04 | 0.2679E 00 | 0.1500E 02 | 0.1220E 01 | 0.8600E-03 | 0.8372E 03 | | 0.8600E 03 |
| 18 | 0-1000E-03 | 0.2679E 00 | 0.1500E 02 | 0.1240E 01 | 0.8700E-03 | 0.8506E 03 | | 0.8700E 03 |
| 19 | 0.1009E-03 | 0.2679E 00 | 0.1500E 02 | 0.1260E 01 | 0.8800E-03 | 0.8636E 03 | | 0.8800E 03 |
| 20 | 0.1018E-03 | 0.2679E 00 | 0.1500E 02 | 0.1280E 01 | 0.8900E-03 | 0.8764E 03 | | 0.8900E 03 |
| 21 | 0.1027E-03 | 0.2679E 00 | 0.1500E 02 | 0.1300E 01 | 0.9000E-03 | 0.8889E 03 | | C. 900CE 03 |
| 22 | 0.1036E-03 | 0.2679E 00 | 0.1500E 02 | 0.1320E 01 | 0.9100E-03 | 0.9011E 03 | | 0.9100E 03 |
| 23 | 0.1045E-03 | 0.2679E 00 | 0.1500E 02 | 0.1340E 01 | 0.9200E-03 | 0.9130E 03 | | 0.9200E 03 |
| 24 | 0.1054E-03 | 0.2679E 00 | 0.1500E 02 | 0.1360E 01 | 0.9300E-03 | 0.9247E 03 | | 0.9300E 03 |
| 25 | 0.1063E-03 | 0.2679E 00 | 0.1500E 02 | 0.1380E 01 | 0.9400E-03 | 0.9362E 03 | | 0.9400E 03 |
| 26 | 0.1072E-03 | 0.2679E 00 | 0.1500E 02 | 0.1400E 01 | 0.9500E-03 | 0.9474E 03 | | 0.9500E 03 |

were used as guides for simulating this field as closely as possible with a discontinuous field. It should be explained here that the field is discontinuous, so far as the field gradient is concerned. This results from the use of the discrete electrodes, instead of a single continuous one, to produce the high gradients necessary. The value of the field, directly over the electrodes, is approximately uniform and constant. The value of the field between the electrodes is very nearly linearly increasing. By the judicious appointment of voltages to the individual electrodes, the field values and gradients of the continuous case were closely simulated. This is to say that these values were calculated, using the computer programs, which were necessary to deflect the ions approximately 15.0 degrees from the direction of entry. A typical discontinuous program is presented in Table XIV. For these programs, the ions are considered to traverse, not one, but several electric fields as they pass through the lens. Because of this, the initial conditions at the beginning of each new field must be provided for each ion of a different charge and velocity. For: all the ions, the initial conditions at the first field were considered to be that an on-axis entry was made into the lens, with zero vertical velocity. Table XV is submitted to show a typical page of computer results for this program.

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TABLE XIV

TYPICAL DISCONTINUOUS PROGRAM FOR ELECTROSTATIC LENS

| | \$JOB 2233-40031 H WAYNE WILLIS | 56 | 60 R=XL |
|------------|--|------|--|
| 1 | 1 FORMAT{////,2X,5HAN = .E10.4,3X,5HAK = .E10.4,3X,4HT = E10.4,3X,6H | 57 | IF(L.E0.2) R=0 |
| | 1PT(I = ,E10.4,3X,5HV = ,E10.4,3X,4HW = ,E10.4,3X,4HG = ,E10.4,/,2X | 58 | 4 X = 4 X + P. |
| | 2,4HH = E10.4.3X,5HDI = E10.4.3X,6HDPI = E10.4.3X,5HDV = F10.4. | 59 | 6010 50 |
| | 33x.5HVF = .F10.4.3x.5HTF = .F10.4) | 60 | 70 WPITE(6.2) N.Y.S.THETA.PT.AY.AT.PTS.V |
| | 2 FORMAT1/-4X-14-5X-6(F12-4)-3X-F12-4-4X-F12-43 | 61 | TELV GE.VE3 GOTO BO |
| 3 | 3 FORMAT(///.TY.)HM.INY.IHY.IYY.IHS.9Y.SHTHETA.BY.2407.0Y.2464.0Y.24 | 4.2 | 161V CE 1000 010V0= 10 0+0V |
| · · · | | 02 | 1-10-00-010-010-00-00-00-00-00-00-00-00- |
| | | 65 | |
| | PERSTALLONICE PTO NO. 1 C. LOT DOT DU 15 TO | -04 | 6010 12 |
| , | ACADISISIANIANIISISISIS REGISISISINI UNUPIJUYATIA | 65 | 80 IF(AN.GE.5.0) 6010 90 |
| <u>e</u> | 9 V=VU | 66 | AN≈AN+1.0 |
| | DA0=9A | 67 | GCTO 9 |
| В. | 10 WRITE(6,1) AN, AK, T, PIO, V, W, G, H, DT, DPT, DVD, VF, TF | 68 | 90 STOP ~ |
| 9 | 11 WRITE(6,3) | 69 | END |
| 10 | 12 AX=0.0 | | |
| 11 | P S = 0 • 0 | | |
| _12 | P Y=0.0 | 70 | SUBROUTINE EVOD(M.LOAD) |
| 13 | PTS=C+0 | 71 | FH=(FLOAT(M))/2+0 |
| 14 | 20 PT=PT0 | 72 | MU=IFIX(FM) |
| 15 | P1=PT-DPT | 73 | F3=FLOAT(MO) |
| 16 | X = V ≠ T | 74 | F4=FM-F3 |
| 17 | 2=X/(5+H) | 75 | [F(F4.GT.0.4) GOTO 200 |
| 18 | I = I F T X (7) | 76 | 1 040=2 |
| 19 | F = F(DAT(1)) | 77 | 5010 300 |
| 20 | | 76 | 200 1040=1 |
| 55 | | | 300 PETUPN |
| 21 | | 19 | SOU RETORIC |
| | | . •v | ENU |
| 23 | | | |
| 24 | | | |
| 25 | $J = 2 \neq j + l_{i}$ | , | ENIRT |
| .26 | | | |
| 27 | 1+1X+L1+G1 GUTU 60 | | |
| 2.8 | 30 CALL EVOUP, LOAD | | |
| 29 | IF(LOAD.EG.2) SOTO 40 | | |
| 30 | | | |
| 31 | AX={FLGAT{M+1}/2+0}*{G+H}-H | | |
| 32 | GOTO 50 | | |
| 33 | 40 R=H | | |
| 34 | AX=(FLCAT(H)/2.0)*(G+H) | | |
| 35 | 50 4T=4X/V | | |
| 36 | CALL EVOD(M,LOAD) | | |
| 37 | IFILOAD-EQ-2) GOTO 55 | | |
| 38 | T = P + T + O = T | | |
| 39 | E=PI/x | | |
| 40 | [[]4={ | | |
| 41 | $Y = (C \cap M + PS) = R + PY$ | | |
| 42 | 5=2.0+CCH+P5 | | |
| 43 | 6010 50 | | |
| 44 | 55 RCM=((AN+AK)/((V=+2)=W))+(PT=R) | | |
| 45 | <pre>SIM=(/1/waski///(v==2)*/(OPT/H)*(R==2)</pre> | | |
| 46 | Y={K0H+PS}#R+{S}H#R}/3.0+PY | | |
| 27 | | | |
| 42 | | | |
| 4 C 4 C | 5 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 | | |
| 47 | $\frac{1}{2} \sum_{i=1}^{n} \frac{1}{2} \sum_{i=1}^{n} \frac{1}$ | | |
| | TELM - EX-UT GOLD FU | | |
| 51 | | | |
| 52 | | | |
| 53 | M=M+1 | | |
| . 54 | IF(K.f0.J) GDT0 60 | | |
| 55 | GETE 30 | | |

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SAMPLE COMPUTER OUTPUT FOR DISCONTINUOUS PROGRAM

<u>AN = 0.5000E 01 AK = 0.1786F 07 T = 0.1000E-05 PT0 = 0.3000E 01 V = 0.7000E 03 H = 0.4000E-01 G = 0.5000E-03</u> H = 0.1500E-02 DT = 0.1000E-05 DPT = 0.0000E 00 DV = 0.1000E 02 VF = 0.7000E 04 TF = 0.1000E-05

| 4 | Y | S | THETA | PT | AX | A Y | PTS | v |
|---|------------|------------|------------|------------|------------|------------|------------|-----------|
| 2 | 0.1252E-03 | 0.3060E 00 | 0.1701E 02 | 0.6000E 00 | 0.7000E-03 | 0.1000E-05 | 0.9579E 00 | 5.7030E (|
| 2 | 0.1247E-03 | 0.3007E 00 | 0.1673E 02 | 0.6000E 00 | 0.7100E-03 | 0.1000E-05 | 0.9758E 00 | 0,7130E (|
| ! | 0.1242E-03 | 0.2957E 00 | 0.1647E 02 | 0.6000E 00 | 0.7200E-03 | 0.1000E-05 | 0.9937E 00 | 0.7200E (|
| ! | 0.12375-03 | 0.2910E 00 | 0.1623E 02 | 0.6000E 00 | 0.7300E-03 | 0.1000E-05 | 0.1012E 01 | 0.7300E (|
| | 0.1232E-03 | 0.2866E 00 | 0.1599E 02 | 0.6300E 00 | 0.7400E-03 | 0.1000E-05 | 0.1029E 01 | 0.7400E 0 |
| | 0.1228E-03 | 0.2825E 00 | 0.1578E 02 | 0.6000E 00 | 0.7500E-03 | 0.1000E-05 | 0.1047E 01 | 0.7500E (|
| | 0.1223E-03 | 0.2787E 00 | 0.1557E 02 | 0.6000E 00 | 0.7600E-03 | 0.1000E-05 | 0.1065E 01 | 0.7600E C |
| | 0.1219E+03 | 0.2750E 00 | 0.1538E 02 | 0.6000E 00 | 0.7700E-03 | 0.1000E-05 | 0.1083E 01 | 0.7700E |
| | 0.1215E-03 | 0.2716E 00 | 0.1520E 02 | 0.6000E 00 | 0.7800E-03 | 0.1000E-05 | 0.1101E 01 | 0.7800E (|
| | 0.12116-03 | 0.2685E 00 | 0.1503E 02 | 0.6000E 00 | 0.7900E-03 | 0.1000E-05 | 0.1119E 01 | 0.7930E (|
| | 0.1207E-03 | 0.2655E 00 | 0.1487E 02 | 0.6000E 00 | 0.8000E-03 | 0.1000E-05 | 0.1137E 01 | 0.8000E (|
| ! | 0.1204E-03 | 0.2627E 00 | 0.1472E 02 | 0.6000E 00 | 0.8100E-03 | 0.1000E-05 | 0.1155E 01 | 0.8100E (|
| ! | 0.12005-03 | 0.2600E 00 | 0.1458E 02 | 0.6000E 00 | 0.8200E-03 | 0.1000E-05 | C.1173E 01 | 0.8200E (|
| 2 | 0.1197E-03 | 0.2576E 00 | 0.1444E 02 | 0.6000E 00 | 0.8300E-03 | 0.1000E-05 | 0.1191E 01 | 0.8300E (|
| | 0.11945-03 | 0.2553E 00 | 0.1432E 02 | 0.6000E 30 | 0.84008-03 | 0.1000E-05 | 0.1208E 01 | 0.8400E 0 |
| , | 0.1191E-03 | 0.2531E 00 | 0.1420F 02 | 0.6000E 00 | 0,8500F-03 | 0.10005-05 | 0.1226E 01 | 0.8500E 0 |
| 2 | 0.11895-03 | 0.25118 00 | 0.14105 02 | 0.6000E 00 | 0.8600E-03 | 0.1000E-05 | 0.12445 01 | 0.8600E 0 |
| ? | 0.1186E-03 | 0.2492E 00 | 0.1399E 02 | 0.6000E 00 | 0.8700E-03 | 0.1000E-05 | 0.1262E 01 | 0.8703F (|
| | 0.1184E-03 | 0.2475E 00 | 0.1390E 02 | 0.6000E 00 | 0.8800E-03 | 0.1000E-05 | 0.1280E 01 | 0.8830E 0 |
| 2 | 0.1182E-03 | 0.2458E 00 | 0.1381E 02 | 0.6000E 00 | 0.8900E-03 | 0.1000E-05 | 0.1299E 01 | 0.8900E (|
| 2 | 0.11805-03 | 0.2443E 00 | 0.1373E D2 | 0.6000E 00 | 0.9000E-03 | C.1000E-05 | 0.1316E 91 | 0.9000E (|
| | 0.1178E-03 | 0.2428E 00 | 0.1365E 02 | 0.6000E 00 | 0.9100E-03 | 0.1000E-05 | 0.1334E 01 | 0.9100E (|
| ; | 0.1177E-03 | 0.2415E 00 | 0.1358E 02 | 0.6000E 00 | 0.9200E-03 | 0.1000E-05 | 0.1352E 01 | 0.9200E C |

VITA 🎶

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