THE USE OF SIMULATION AND <u>CAN-Q</u> TO ANALYZE THE CLEANING AND LUBRICATING PROCESSES

OF COLD DRAWN TUBING

Ву

John Russell Lewis

Bachelor of Science in Industrial Engineering

Oklahoma State University

1982

Submitted to the Faculty of the Graduate College of the Oklahoma State University in partial fulfillment of the requirements for the Degree of Master of Science May, 1985





THE USE OF SIMULATION AND CAN-Q TO ANALYZE THE CLEANING AND LUBRICATING PROCESSES OF COLD DRAWN TUBING

Thesis Approved:

Thesis Adviser

Dean of the Graduate College

PREFACE

A simulation in SLAM and an analytical computer program called CAN-Q were used to study the feasibility of adding cranes to the cleaning and lubing tanks at Southwest Tube Manufacturing.

A comparison is made of the trade-offs and difficulties in using SLAM and CAN-Q in the study. This is accomplished by comparing outputs of both programs, determining confidence intervals and comparing this data with the actual system. A cost analysis is also done on the feasibility of adding the cranes to the tanks.

I wish to thank my major adviser, Dr. C. P. Koelling, for his guidance.

I also wish to thank my committee members, Dr. Philip Wolfe, and Dr. Carl B. Estes for their advisement in the course of this work.

Special thanks are due to Thomas M. Lewis and Thomas Box for the opportunity to do this project and their quidance in the accomplishment of the thesis.

For their constant support, thanks also goes out to my wife Judy, and my mother Carolyn.

iii

TABLE OF CONTENTS

Chapte	r	Page
I.	INTRODUCTION	, 1
II.	LITERATURE REVIEW	3
	Simulation	344
	Validation	6
	Advantages and Disadvantages	8 10
	Data Analysis	14 16 16
III.	CAN-Q	20 22
IV.	DATA COLLECTION AND ANALYSIS	30
	Observation and Data Collecting Data Analysis and Hypothesis Testing	30 34
v.	MODELING OF THE TANK SYSTEM	38
	Present System Model	38 40 41
VI.	TANK SIMULATION ANALYSIS	44
	Present System Model	44 44 46 49
	Two Crane One Operator Model	51 52
	Intervals	52
	Two Crane Two Operator Model	58 61 61

• •

	Two Crane Two Operator Output 62
	Intervals
	Operator Model
VII.	TANK SYSTEM ANALYSIS THROUGH CAN-Q
	CAN-Q Input
VIII.	COMPARISON OF CAN-Q AND SIMULATION
	Original System Simulation and CAN-Q 78 Two Crane One Operator Simulation and CAN-Q. 80 Two Crane Two Operator Simulation and CAN-Q. 81 Economic Analysis of Outputs by Simulation
	and CAN-Q
IX.	CONCLUSIONS
BIBLIO	GRAPHY
APPEND	IXES
	APPENDIX A - DATA COLLECTED AND CORRESPONDING HISTOGRAMS
	APPENDIX B - PRESENT SYSTEM SLAM ATTRIBUTES, LISTING, AND NETWORK
	APPENDIX C - TWO CRANE ONE OPERATOR SLAM ATTRIBUTES, LISTING, AND NETWORK 129
	APPENDIX D - TWO CRANE TWO OPERATOR SLAM ATTRIBUTES, LISTING, AND NETWORK 152
	APPENDIX E - OUTPUT OF PRESENT SYSTEM MODEL 167
	APPENDIX F - OUTPUT OF TWO CRANE ONE OPERATOR MODEL
	APPENDIX G - OUTPUT OF TWO CRANE TWO OPERATOR MODEL
	APPENDIX H - CAN-Q OUTPUT

Page

LIST OF TABLES

.

Table	P	age
I.	Moment Generating Functions	19
II.	Movement Time Between Tanks	31
III.	Standard Times for Hooking and Unhooking	34
IV.	Distributions for the Tank System	35
v.	Output for Present System Model	45
VI.	T-Test of Trip Output Vs. Actual Output	50
VII.	Output for Two Crane One Operator Model	53
VIII.	Gate Statistics for Two Crane One Operator Model	5 9
IX.	Output for Two Crane Two Operator Model	63
X.	Resource Output of Two Crane Two Operator Model.	68
XI.	CAN-Q Input	71
XII.	Routing for the Lube Operation	71
XIII.	Routing for the Phosphate Operation	72
XIV.	Routing for the Trick Operation	72
XV.	System Performance Summary	74
XVI.	Station Summary for Acid Tank	77
XVII.	Economic Analysis of Tank System	84

vi

.

LIST OF FIGURES

Figu	re	age
1.	Classification of Languages Used for Simulation (Relative Only)	13
2.	Typcial GERT Network	17
3.	GERT Node Types	18
4.	General Plant Layout and Material Flow	23
5.	Tank System	25
6.	Form Used for Dipping Times	32
7.	Tank Summary Report	33
8.	Work Order	36
9.	Crane Tank Assignment	42
10.	Confidence Interval for Trip Output in the Present System Model	47
11.	Confidence Interval for Tank Time of Present System Model	47
12.	Confidence Interval for Total Time Spent in the Present System Model	48
13.	Confidence Interval for Breakdowns of the Present System Model	48
14.	Confidence Interval for Ton Output of the Present System Model	49
15.	Confidence Interval for Trip Output of Two Crane One Operator Model	54
16.	Confidence Interval for Tank Time of Crane One of Two Crane One Operator Model	55
17.	Confidence Interval for Total Tank Time of Crane One of Two Crane One Operator Model	55

Figure

.

18.	Confidence Interval for Tank Time of Crane Two of Two Crane One Operator Model	56
19.	Confidence Interval for Total Tank Time of Crane Two of Two Crane One Operator Model	56
20.	Confidence Interval of Breakdowns for Crane One for Two Crane One Operator Model	57
21.	Confidence Interval of Breakdowns for Crane Two for Two Crane One Operator Model	58
22.	Confidence Interval of Ton Output for Two Crane One Operator Model	58
23.	Confidence Interval of Trip Output for Two Crane One Operator Model	64
24.	Confidence Interval of Tank Time for Two Crane Two Operator Model	64
25.	Confidence Interval of Total Time for Two Crane Two Operator Model	65
26.	Confidence Interval of Breakdowns for Crane One of Two Crane Two Operator Model	65
27.	Confidence Interval of Breakdowns for Crane Two of Two Crane Two Operator Model	66
28.	Confidence Interval of Ton Output for Two Crane Two Operator Model	67
29.	Confidence Interval of the Present System Output and CAN-Q Output	79
30.	Confidence Interval of the Present System Tank Time and CAN-Q Tank Time	79
31.	Confidence Interval of Two Crane One Operator Output and CAN-Q Output	80
32.	Confidence Interval of Two Crane One Operator Tank Time and CAN-Q Tank Time	81
33.	Confidence Interval of Two Crane Two Operator System Output and CAN-Q Output	82
34.	Confidence Interval of Two Crane Two Operator System Tank Time and CAN-Q Tank Time	83

Page

CHAPTER I

INTRODUCTION

One of the major problems in production planning today is bottlenecks or blockages of material flow through production operations. Southwest Tube in Sand Springs, Oklahoma has such a problem currently in their tank operation.

Southwest Tube produces hydraulic and mechanical tubing to specifications for customers. These tubes are cold-drawn and then heat treated through a furnace to a desired hardness. Before the tubes are cold-drawn, they must be chemically cleaned and lubricated. This operation is done in the tank system. Overhead cranes dip tubes in various tanks and then set them on a dryer after treatment. The tubes are then taken away to the cold-drawing production area. Currently the tanks cannot keep up with the production on the cold-drawing floor. This causes the floor to go idle waiting for more tubes.

One method to increase production is to increase the length of the work shift or add another shift. However, the tanks run 24 hours a day, seven days a week, so this plan has already been implemented. Another approach to the problem is the addition of cranes. This particular approach is the only feasible way that output can be increased

through the tanks.

An analysis must be made of the addition of cranes to the system to find if the new equipment will really increase production, and to decide if the addition of cranes will be economically feasible.

One approach that lends itself well to this type of problem is simulation, however, simulation can be a very expensive and time consuming technique. Another approach that may apply well to this type of problem is an analytical technique called CAN-Q. This method is less costly than simulation. The proposed research deals with the application of simulation and CAN-Q to this type of environment, particularly Southwest Tube's production problem, and the cost effectiveness of adding the cranes.

CHAPTER II

LITERATURE REVIEW

Simulation

Simulation has been defined by Shannon (18) as

the process of designing a computerized model of a system (or process) and conducting experiments with this model for the purpose of understanding the behavior of the system or of evaluating various strategies for the operation of the system (p. 24).

This particular definition of simulation seems to cover the more important aspects for the model building type of problem solving process. Of particular importance is the linking of simulation to the traditional model building approach to problem solving. This model building method, more commonly referred to as the scientific method, contains the following stages:

- 1. Observation of the system;
- Formulation of hypotheses or theories that account for the observed behavior;
- Prediction of the future behavior of the system based on the assumption that the hypotheses are correct; and
- Comparison of the predicted behavior with the actual behavior.

However, since the scientific method requires previous observations, which is impossible for certain systems

(especially those that do not exist), a slightly different approach to simulation is taken. This approach is called system methodology and consists of four phases: planning, modeling, validation and application.

Planning

The first phase in systems modeling is planning. It is at this phase that the modeler first encounters the system. The planner first determines a problem definition. Once the problem has been clearly defined, the modeler can collect pertinent data that might help in the problem solving process. The second stage in the planning process is to analyze the system to gain a thorough understanding of the system and the problem. Many simulation models fail because of an incomplete understanding of the system or the problem.

Modeling

The second phase in systems methodology is modeling. In this phase the analyst constructs a model from the system. The modeling of a system is made easier if: 1) physical laws are available that pertain to the system; 2) a pictorial or graphical representation can be made of the system; and 3) the variability of system inputs, elements, and outputs is manageable [Graybeal and Pooch (5)]. An analyst will try to simplify the system by using boundaries to limit the scope of the simulation within reasonable terms, limit the inputs and outputs to a level that will both be economical and maintain model integrity. The modeler will also draw a schematic or flow chart of the model so a better understanding of the model can be obtained. If the system is so complex that no representative model can be used, then a method of subsystem modeling is used. In this approach, the system is divided into smaller, less complex subsystems and an overall model is used to link the subsystems together.

Three approaches have been used in identifying subsystems [Graybeal and Pooch (5)]. The first type is the flow approach. This type of approach has been used to analyze systems that have a flow of physical or information items through the system. Subsystems are identified by grouping aspects of the system that produce a particular physical or information change in the flow entity. A second approach used to identify subsystems is the functional This type of approach is used when no observable approach. flowing entities can be found in a system. Instead, a logical sequence of functions being performed is identified and grouped into a particular subsystem containing all system characteristics that perform a certain function. The last method is called the state-change approach. This procedure is used in systems which are characterized by a large number of interdependent relationships and which must be examined at regular intervals to detect state changes. System characteristics that respond to the same stimulus or set of stimuli are then grouped to form a subsystem.

Once the subsystems have been identified they must be modeled. One task in modeling is choosing an appropriate simulation language. This depends on the type of modeling involved, the facilities available, and the analyst's knowledge of certain languages. After the language is chosen, a computer model of the system can be made.

Another task in the modeling phase is the estimation of the system variables and parameters. At this point real world data are summarized into a manageable statistical description of the system's characteristics. This is done by collecting data over some period of time and then computing a frequency distribution for the desired variables.

Validation

The next phase of system methodology is validation. A model is validated by proving that it is a correct representation of the real system. Certain techniques have proven useful in the simulation process. One technique is to compare the results of the simulation with results historically produced by the real system operating under the same conditions. A second technique is to use the simulation to predict results. The predictions are then compared with the results produced by the real system at some future period in time.

Naylor and Finger (12) use a three-step approach to validation of a simulation model. The first step is to

develop a model with high face validity. A model that is face valid seems reasonable to people who are knowledgeable about the system under study. This is accomplished through conversations with experts, observations of the system, general knowledge of the system, and intuition on how the system operates. In the second step the assumptions of the model are tested empirically. This includes adequacy of fit tests used to assess distributions used in the model. This step also uses sensitivity analysis to determine the level of detail in a simulation model. The final step determines how representative the simulation output data is. This is accomplished by comparing the output of the real system to the simulation model, using statistical tests such as the ttest.

Just as good experimental design can aid in the data collection of the modeling phase, so can validation aid in correctness of the simulation model. Most standard experimental designs require that observations be taken on the system variables that can be controlled. The simulation model must operate under identical conditions [Graybeal and Pooch (5)]. Only then can valid inferences be drawn about the relationship between the resulting output of the real system and the outputs of the simulation model.

Application

The final phase of systems analysis is application. After verification, the simulation can finally be employed

at four levels as described by Pritsker (16): 1) as explanatory devices to define a system or problem; 2) as analysis vehicles to determine critical elements, components, and issues; 3) as design assessors to synthesize and evaluate proposed solutions; and 4) as predictors to forecast and aid in planning future developments.

Simulation as a tool to solve complex problems has been growing by leaps and bounds with the improvement and reduction in cost in using the digital computer. Problems in fields as diverse as socio-economics, politics, lawenforcement, biology and nuclear engineering have been successfully solved with the use of simulation [Shannon (19)]. If simulation is so good, however, why is any other type of modeling used? The answer is that in problems where simulation is used, and even in cases in which it does apply, there may be easier and less expensive ways of solving the problem. Solberg and Ravindran (21) state that simulation is one of the easiest tools of management science to use, but probably one of the hardest to apply properly and perhaps the most difficult with which to draw accurate conclusions.

Advantages and Disadvantages

Adkins and Pooch (1) list five advantages of simulation modeling:

 It permits controlled experimentation. A simulation experiment can be run a number of times with varying

input parameters to test the behavior of the system under a variety of situations and conditions.

- It permits time compression. Operation of the system over extended periods of time can be simulated in only minutes with ultrafast computers.
- It permits sensitivity analysis by manipulation of input variables.
- 4. It does not disturb the real system. This is a great advantage, since most managers would be reluctant to try experimental strategies on an on-line system.
- 5. It is an effective training tool.

They also list four disadvantages to using the simulation approach to problem solving:

- A simulation model may become expensive in terms of manpower and computer time.
- 2. Extensive development time may be encountered.
- Hidden critical assumptions may cause the model to diverge from reality.
- 4. Model parameters may be difficult to initialize. These may require extensive time in collection, analysis, and interpretation.

Thus, even though simulation can be a useful tool, it also has its drawbacks. These should be noted in considering the simulation approach to any particular problem.

Classifications

Simulation models of systems can be classified as either discrete change or continuous change. Pritsker and Pegden (16) describe discrete simulation as when the dependent variables change discretely at specified points in simulated time. These points are referred to as event In continuous simulation the dependent variables of times. the model may change continuously over simulated time. This is accomplished through differential or difference equations. Both discrete models and continuous models can be combined in one model. In this type of "combined simulation" the dependent variables of a model may change discretely, continuously, or continuously with discrete jumps superimposed.

In discrete simulation, the goal is to reproduce the activities that entities in the model engage in, and thereby learn something about the behavior and performance of the system [Pritsker and Pedgen (16)]. According to Kiviat (8), a discrete simulation model can be formulated by what are known as the three alternative world views for discrete simulation modeling. These three views are referred to as the event, activity scanning, and process orientation.

In event orientation, a system is modeled by defining the changes that occur at event times. Events that can change the state of the system are determined and then a logical association is made with each event type.

In activity scanning orientation, activities in which

entities in the system engage are described. Prescribed conditions then cause an activity to start or end. The events which start or end the activity are not scheduled by the modeler, but are initiated from the conditions specified for the activity.

The last world view of discrete simulation is process orientation. In this view, sequences of elements occur in defined patterns.

In a continuous simulation model, the state of the system is represented by dependent variables which change continuously over time [Pugh (17)]. Models of continuous systems are frequently written in terms of the derivatives of what is known as the "state" variables. The state variables are the dependent variables that continuously change over time.

Combined discrete/continuous model variables may change both discretely and continuously. The system can be described in terms of entities, their associated attributes, and state variables.

Pritsker and Pegden (16) state that there are two types of events that can occur in combined simulations. Timeevents are those events which are scheduled to occur at specified points in time. The other type of events that can occur are state-events. These events are not scheduled, but occur when the system reaches a particular state.

According to Mize and Cox (11, p. 123), "the increase in the number, variety and complexity of system simulation

studies has motivated the development of general simulation languages." These languages are designed to take advantage of the common features of simulation studies. They are intended to simplify the programming of the model so the analyst can concentrate on the model building. Emshoff and Sisson (4) state that a user wants a simulation language that: 1) facilitates model formulation; 2) is easy to program; 3) provides good error diagnostics; and 4) is applicable to a wide range of problems.

The languages that were considered include:

- GASP a set of subroutines in FORTRAN that provides useful functions in simulation [Pritsker (15)];
- GPSS a complete language oriented toward problems in which items pass through a series of processing and/or storage functions [Dunning (3)];
- SIMSCRIPT a complete language oriented toward event-toevent simulations in which discrete logical processes are common [Markowitz (9)];
- CSMP a complete language oriented toward the solution of problems stated as nonlinear, integral-differential equations with continuous variables [IBM Corp. (7)];
- DYNAMO a complete language oriented toward expressing micro-economic models of firms by means of difference equations;
- SLAM a complete language that makes use of networks and user written FORTRAN subprograms in both continuous and discrete modeling [Pugh (17)].

Emshoff and Sisson (4) classify these languages in Figure 1 in terms of orientation and scope or generality of application. The trade-off between generality (depth of application) and problem orientation is clear.



Source: J. R. Emshoff and R. L. Sisson, <u>Design</u> and <u>Use of Computer Simulation Models</u> (1970), p. 34

Figure 1. Classification of Languages Used For Simulation (Relative Only)

FORTRAN and PL/I are also included as examples of multipurpose languages in which any sort of state-change process can be described. GASP and SIMSCRIPT differ from FORTRAN and PL/I in that GASP and SIMSCRIPT are not complete languages. Both languages (GASP and SIMSCRIPT) are very general, and both can do anything that can be done in FORTRAN or PL/I. GPSS is oriented more towards a particular kind of problem (queueing problems). Although it is problem oriented, GPSS has many features that permit it to be applied in a wide range of situations. Furthermore, the language can be augmented by subroutines written in Assembly language.

DYNAMO and CSMP are examples of languages oriented toward problems formulated in terms of nonlinear differential or difference equations. DYNAMO was developed for defining models of business and CSMP for engineering design applications. Neither language is very general, but both are quite useful in specifying simulation procedures for particular types of problems.

SLAM is probably the most versatile of all the language described. It can be as problem oriented as DYNAMO and as general as GASP or SIMSCRIPT. SLAM can simulate discrete, continuous, or combined discrete/continuous models. It can also interact with subroutines written in FORTRAN by the user to further extend the scope of the language.

Data Analysis

According to Mize and Cox (11, p. 84), "a sample is a subset of population, in simulation, a sample is usually utilized to represent the population as part of the input information into a more extensive model." Random samples of data must be taken to determine the behavior of the system. This data is usually then tested against a particular distribution for goodness-of-fit. Among different goodness of fit tests available, the Kolmogorov-Smirnov (K-S) test and the Chi-Square test are the most popular.

The K-S test [Massey (10)] consists of comparing the sample cumulative distribution functions with the theoretical cumulative distribution function at each sample observation. The test statistic is the maximum deviation between the two functions at any point in the sample. The statistic is then compared with a critical value, referenced by the size of the sample, and a chosen level of significance. At a given level of significance, the testing hypothesis may be rejected if the sample statistic is greater than the critical value.

In the Chi-Square test [Cochran (2)], the test statistic is the square of the summation of the observed data points in a particular cell minus the expected number of observations in that particular cell quantity squared, divided by the expected value for that particular cell. The test statistic is then compared with a critical value, referenced by the degrees of freedom and a chosen level of significance. As in the K-S test, the testing hypothesis may be rejected if the sample statistic is greater than the critical value.

Of the two tests, the K-S test is more powerful, and thus more likely to detect small differences in the actual and hypothesized distributions [Massey (10)]. The differences between the K-S test and the Chi-square test are

beyond the scope of this paper; for further discussion, refer to Massey (10).

The literature review has dealt primarily with the theoretical aspects of what simulation is, the different types of simulation including the world views, the different types of simulation languages, and fitting data to distributions for the simulation. Later, these aspects of simulation will be integrated and applied to a real world model in an industrial environment.

Alternatives to Simulation

Simulation is a very useful tool in system analysis, however, simulation can be very expensive and time consuming. Also, some companies may not have a computer accessible that is large enough to handle simulation computer models. There are a number of analytical methods today that provide an alternative to simulation. Two such methods, GERT and CAN-Q, will be discussed.

GERT

GERT (Graphical Evaluation and Review Technique) is a procedure that combines the disciplines of flowgraph theory, moment-generating functions, and PERT to obtain a solution to stochastic problems [Phillips and Garcia-Diaz (14)].

Figure 2 represents a typical GERT network. The nodes of the network can be interpreted as states of the system. The arcs represent transitions from one state to another.

Such transitions can be viewed as activities characterized by a unique probability density function and a probability of realization.



Source: D Phillips and A. Garcia-Diaz, Fundamentals of Network Analysis (1981), p. 14

Figure 2. Typical GERT Network

Each node performs two functions, an input function which indicates the condition under which the node can be realized, and an output function which indicates the branching condition following the node realization.

Two types of nodes are associated with GERT (Figure 3). Type a is a deterministic output and type b is a probabilistic output node. The deterministic node is realized when any arc leading into it is realized under the condition that only one arc can be realized at a time. All arcs emanating from the node are then undertaken. The input to the probabilistic node is the same as the deterministic node, however, only one arc emanating from this node is realized.



Figure 3. GERT Node Types

Time from node to node is described through momentgenerating functions (Table I). These functions can be manipulated in such a way as to determine moments of the distribution of time spent in moving from one node to another. First, a W function must be calculated. The W function of a given arc is defined as the product of the probability of undertaking the arc and the moment-generating function of the duration of the activity represented by the arc [for W calculations of loops, loops of order n and a closed flow graph refer to Phillips and Garcia-Diaz (14)]. An overall value of the moment generating functions can be calculated through

 $M_e = W_i(s)/p_e$

By then determining the jth partial derivative of $M_e(s)$ with respect to s, and setting s to zero, a mean can be obtained through

$$u_{je} = (d_j/d_{sj})[M_e(s)] |_{s=0}$$

1

In particular, the first moment about the origin, μ_{le} , produces the mean network realization time while the variance of the network realization time is obtained by computing μ_{2e} and subtracting it from the square of μ_{le} ; that is

$$\sigma^2 = \mu_{2e} - (\mu_{1e})^2$$

TABLE I

MOMENT GENERATING FUNCTIONS

Type of Distribution	$\mathcal{M}_{E}(s)$	Mean	Second Moment
Binomial (B)	$(pe^s+1-p)^n$	np	$np(np \pm 1 - p)$
Discrete (D)	$\frac{p_1e^{sT_1}-p_2e^{sT_2}-\cdots}{p_1-p_2-\cdots}$	$\frac{p_1T_1-p_2T_2-\cdots}{p_1-p_2-\cdots}$	$\frac{p_1 T_1^2 - p_2 T_2^2 - \cdots}{p_1 - p_2 - \cdots}$
Exponential (E)	$\left(1-\frac{s}{a}\right)^{-1}$	$\frac{1}{a}$	$\frac{2}{a^2}$
Gamma (GA)	$\left(1-\frac{s}{a}\right)^{-b}$	$\frac{b}{a}$	$\frac{b(b-1)}{a^2}$
Geometric (GE)	$\frac{pe^s}{1-e^s-pe^s}$	$\frac{1}{P}$	$\frac{2-p}{p^2}$
Negative binomial (NB)	$\left(\frac{p}{1-e^s+pe^s}\right)^r$	$\frac{r(1-p)}{p}$	$\frac{r(1-p)(1-r-rp)}{p^2}$
Normal (NO)	esm+(1,2)s ² o ²	'n	$m^2 - \sigma^2$
Poisson (P)	ex(e=1)	i.	$\lambda(1 - \lambda)$
Uniform (U)	$\frac{e^{sa} - e^{sb}}{(a - b)s}$	$\frac{a-b}{2}$	$\frac{a^2 - ab - 5^2}{3}$

Source: D. Phillips and A. Garcia-Diaz, Fundamentals of Network Analysis (1981), p. 14.

GERT, as an alternative method to simulation, can be used if no computer is available. GERT, however, is only useful for small networks. GERT also requires an intricate understanding of the system. Distributions must be determined for service times, and the system must be networked. Thus, a GERT analysis may well require as much involvement as would simulation analysis. Finally, analysis of GERT must be done through manipulating moment-generating functions. These manipulations can be prone to many errors. While GERT is an alternative method to simulation, GERT can be as costly and time consuming as simulation.

CAN-O

Another type of analytical method that can be utilized instead of simulation is CAN-Q. This tool was developed in the form of a computer program by James J. Solberg of Purdue University (20). CAN-Q is a mathematical model for analyzing work flow in a production system through queueing theory and Markov Chains. The computer program accomplishes all of the difficult computations involved in translating the natural description of a system, its resources, and the processes involved in converting raw materials to finished/ product.

To initiate CAN-Q, the user must simply input the number of stations, the mean service time of those stations, the number of services for each station, the number of $\zeta \in \mathcal{U} \in \mathcal{U}$ transports, the mean time of transportation, the number of products and their routing, and the number of entities desired in the system. CAN-Q takes this information and

stabrul 5° 23

produces detailed information for each station and product type including where the bottlenecks are located. Sensitivity analysis is also provided by the system.

To run CAN-Q, the user does not need a deep understanding of the system that is being studied, this eliminates the need for model building. The CAN-Q program also is not very long and therefore can run on a microcomputer. The elimination of model building, the reduced data gathering, and less computer time considerably lowers the cost of the system analysis as compared to using simulation. However, CAN-Q is unable to provide a complete digadu, picture of system behavior over time as simulation would. CAN-Q also provides no information about short-term behavior or extremes of system behavior that simulation could provide.

CHAPTER III

STATEMENT OF THE PROBLEM

Southwest Tube Manufacturing is a manufacturer of cold drawn tubing used in pressure and mechanical applications. Figure 4 represents the general plant layout and material flow through the plant. Bundles of tubes are transferred from the yard containing inventories of raw tube hollows to a holding area previous to the treating tanks. Tubes are either (1) cleaned and phosphated, (2) tricked, or (3) cleaned and lubed in the treating tanks. Two overhead cranes are used to service these tanks. Each crane services one side of the tanks. The tubes that are cleaned and phosphated and tricked exit the system at this point and are put back into storage.

The cleaned and lubed tubes are then moved to the pointer by overhead crane to allow pointing of the tubes. Pointing allows the grippers on the cold-draw benches to grab the tube through the die.

The tubes are then taken to the three draw benches by crane. The draw benches draw the tube through a die and over a mandrel to a specified outside and inside diameter. Next the tubes are taken by overhead crane to the annealing furnace where at a specified speed and temperature, they are softened to a desired hardness.



Figure 4. General Plant Layout and Material Flow

The tubes are then transferred by overhead crane to the straightener. The tubing is "straightened" by the straightener and is transferred by conveyer to the Eddie Current Tester, which uses a magnetic field to check for flaws in the tubing.

Final cutting is the next operation performed on the tubes. An overhead crane transfers the tubes from the Eddie Current Tester to the auto-saw. Here the tubes are cut to final length and bundled, then transferred by conveyers to the shipping area.

Within this material flow, a major bottleneck occurs at the tank area. Even though two separate cranes service the tanks, bundles of tubes cannot be processed through the tanks fast enough to keep up with the production rate of the rest of the plant. This problem causes the manufacturing floor to go "dry" before the end of a working shift.

The tank area (Figure 5) contains eight treating tanks. These tanks include: caustic, a cold water rinse, sulfuric acid, hot water, phosphate, another cold water rinse, a neutralizer, and a soap-type lube.

For a normal clean and lube operation, movement through the tank area starts at the caustic tank, which contains a detergent to start the cleaning process of the tubes. A "trip" of tubes (a trip can contain one to four bundles) is dipped into the caustic tank, raised and then drained. The tubes are then lowered into the caustic tank (cranes stay connected to the trips while soaking), where they sit for

	Holding
Caustic	1
Cold Water	
Acid	
Hot Water	
Phosphate	
Cold Water	
Neutralizer	
Soap	
	Dryer

Figure 5.

Tank System

five minutes before being rinsed and drained. The "trip" is transferred to the cold water rinse, where the tubes are dipped, raised, and drained. A transfer is then made to the sulfuric acid tank. The tubes are set in this tank until all scale is removed. They are then raised, drained, and transferred to the cold water rinse for redipping. The "trip" is taken to the hot water rinse where they are dipped and drained. The next tank is the phosphate tank; the phosphate acts as a secondary lubricant, and leaves a surface that the primary lube can bond to. The tubes are dipped, drained, and set into the phosphate for five The "trip" is then drained and moved to the second minutes. cold water rinse, where the tubes are dipped and drained. The next tank is the neutralizer. This is used to remove any positive charge from the phosphate that would prevent the primary lubricant from bonding to the surface of the tube. The tubes are dipped and drained in the neutralizer, then taken to the final tank where they are lubed. The lubricant is of the "soap" type which clings to the phosphate secondary lubricant. The tubes are dipped into the lube, drained, and then set into the tank for five minutes. The tubes are then drained and taken to the dryers located next to the tanks. The dryers dry the tubing in preparation for drawing.

The other two types of operations, cleaning and phosphate, and tricking, are less frequent than the cleaning and lubing operation. In the cleaning and phosphate operation, the neutralizer and lube tank are skipped. In the "trick" operation, the phosphate, second cold water rinse, neutralizer, and lube tanks are skipped.

In solving this problem, management first tried what is known as the "pinning off" technique. This entails pinning off a "trip" in a tank. The operator then leaves that "trip" to go get another "trip". The operator would then "pin-off" that trip and get "trip" or move the previously "pinned-off" set of tubes. This type of approach was used to increase utilization time of the crane. This approach was abandoned because the time it took to pin-off was greater than the greatest time allowed in any one tank and actually decreased the efficiency of the tanks and produced a poorer quality lube because of violating time constraints in certain tanks.

Management is currently considering adding two more cranes to the system. They want to know how many more "trips" can be produced by adding these cranes. Management also wants to know the net present value of the project for one, three, and five year periods.

The problem could be approached as a transportation problem using the cranes as transports and the tanks as destinations. However, the system is subject to random variations, and there is already a set pattern moving through the tanks. This causes the transportation method to be useless.

Because of the complexity of the problem, simulation
appears to be the best tool.

The first step in simulating the system was data collection. This step was accomplished by observing and collecting pertinent data from the system. This data includes different types of trips, the breakdowns that occur, time spent in the tanks, and arrival times for bales of tubing. This data was collected from tank reports and actual observation of the system.

After the data was collected, the system was modeled in SLAM. In this stage, boundary lines were determined for the system, inputs and outputs were limited to what was pertinent to the system, and a SLAM network developed for the model. The data collected from the system was then organized into distributions. This was accomplished with a FORTRAN program developed and modified from Phillips (13), utilizing the K-S test.

The model was then validated by comparing the outputs to the real system. This was done with the Turing test [Shannon (19)], which involved showing the output from the real system and the output from the simulation to someone who is intimately familiar with the system, and asking him to differentiate between the two sets of outputs. If he succeeds, a question is raised on how the difference was noted. This provides insight on what might be wrong with the model. Finally, a t-test was performed on the model output, comparing the model outputs with the system outputs.

The next step involved adding two more cranes to the

model. An economic analysis was then performed on the output to see if adding the cranes was profitable. This was done by estimating the total profit per "trip." A tonnage was estimated per trip, and a total profit per ton was calculated. A present value was then calculated for periods of one year, three years, and five years.

After the simulation analysis, CAN-Q was applied to the tank problem. A comparison was made of the CAN-Q output to the real system and the simulation output to determine the accuracy of CAN-Q. This was accomplished by determining a confidence interval of the output rate of the system from the simulation output. This interval was compared with the output rate calculated by CAN-Q. From this information it was determined which type of method was more desirable in this type of production situation, CAN-Q, which is less expensive and faster to develop than simulation, or simulation which reflects the system variability and is more accurate than CAN-Q.

CHAPTER IV

DATA COLLECTION AND ANALYSIS

The first phase in the simulation of the tank system entailed observation of the tanks to determine the boundaries of the system and the data that needed to be collected for the system. The next step consisted of collection, analysis and hypothesis testing of this data so that a manageable statistical description of the system could be made.

Observation and Data Collecting

Through observation of the system, it was found that data needed to be collected on movement time of the cranes, dipping time in the various tanks, time per trip in the acid tank, time per trip in the dryer, and hooking and unhooking times per trip. Also needed was the type of operation traveling through the tanks, the number of breakdowns, and the time the cranes are down.

Collection of the movement time between tanks was accomplished with a stopwatch. Timing was initiated when horizontal movement started. Timing was stopped when horizontal movement ceased. Table II represents the movement times between all tanks. These times are averages of 20 observatons taken of the tanks.

TABLE II

MOVEMENT TIME BETWEEN TANKS

Dipping times were collected by both the operator and myself. Figure 6 contains the form used in the data collection. Dipping times were taken at random for different size tubing and recorded on the data sheet. Total times in the acid tank and on the dryer were also taken through this method and recorded on the data sheet.

Hooking and unhooking times were collected by observation of the operator. From these times a standard was calculated for the operator. A standard was also developed for a "pinning off" operation. This standard was done for a two crane two operator system which will be described later in this chapter. All standard times are located in Table III. Finally, the type of operation, the number of breakdowns and the length of down time was collected through the Tank Summary Sheet (Figure 7).

Date: 10-12-83

•

	₩.0. #	Bale #	Time	W.O. #	Bale #	Time	W.O. #	Bale #	Time	il
Dipping Caustic			52 Aec			512.			1.9:8	
Dipping Cold Water			33	ŝ		330			53	
Dipping Acid	n		50	a		50	đ		1.1.	
Dipping Hot Water	S.	<u> </u>	33	30	•	33	, ,		53	
Dipping Phosphate	त	Ť L	50	1	Ħ	52	202	Ó	70	
Dipping Neutralizer	0	1	60	0	-	52		#	77	
Dipping Lube	Q		51	0	-	50	ā		18.	
Acid Time Scale (Light, Medium,			9min.			15min			17 min	1
Heavy)		<u> </u>	rd.	•	١	Med.	-	-	med	
Drying Time			Durain			5 min	•		5 min	

· • . . .

Figure 6. Form Used for Dipping Times

		SOUTH	WEST TUBE	MANUFACTU	RING COMPANY	F	rod Time //	1.25
			OLD DRAW I	PRODUCTION TANKS	SUMMARY		. •	•
	DATE: 9-13-83	SHIF	T:	OPERATO	R: Inegle'r	<u>*C</u> SUPERV	ISOR: <u><u><u></u></u></u>	Seure
	WORK ORDER #	BALE #	START	FINISH	# PIECES	PROCESS LUBE	CLEAN PHOSPHATE	CLEAN
1	DQ-411:2-MU	: 17	24	Luna-	34			
2	D9-310-3	8	~	i	20			
3	19-310-3	14	-	5	20	-		
4	19-310-3	33	4	1-	13	i		
5	<u>D9-212-3</u>	(-2)	~	i	30 ToTAL	Ri-Lech	-	
6	<u>D9-105-3/14</u>		V		55			
7	<u>D9-150-3 MU</u>	1	~	1	19	1-		
8	19-310-3	7	~	\checkmark	20	-		
9	<u>D9-310-3</u>	6		~	20.			
-	<u>D9-310-3</u>	/3	-	~	20	~		
1	<u>D9-310-3</u>	2		2-	20			
2	09-310-3	_5	~	V	20	2		
3	19-310-3	10		~	20	~	~	
4	<u>D9-310-3</u>	12	L	r	20			
5	09-310-3	2/			20			۰.
6						·		
				.			•	
	14 Red						·	
	142 ,			·				
	1/ Auns							
- L !								

.

•

Figure 7. Tank Summary Report

.

TABLE III

STANDARD TIMES FOR HOOKING AND UNHOOKING

Staging Area6.71 minutesPinning Off2.00 minutesDrying Area2.30 minutes
--

Data Analysis and Hypothesis Testing

Analysis and hypothesis testing was done on the dipping times in the tanks, acid soaking time, and drying time of the tubes. All hypothesis testing was accomplished using the K-S test. A program initially developed by Phillips (13) was used for all hypothesis testing. The program was modified for user interaction, data insertion, and histogram manipulation for use on the Hewlett-Packard/3000. Appendix A contains the data collected, their respective histograms, and detailed results of the K-S test.

Table IV contains the final accepted distributions and parameters by the K-S tests.

The mean times differ for dipping in the various tanks because of the different properties of the liquids in each tank, such as viscosity and density. Dipping follows distributions because of the effects of the inside diameter and the length of the tubing. A larger inside diameter and a longer tube requires more time to be spent in filling and draining the tubes. The different degrees of scale on the tubes cause a distribution in the acid tank. When soaking in the acid, more time is needed to remove heavy scale. Drying times differ due to the number of pieces in a trip, the length of the tubes, and the inside diameter of the tubes. A longer period of time is needed for drying larger surface areas. Tonnage per trip was taken from the Tank Summary Report (Figure 7) and the Work Order (Figure 8).

TABLE IV

Туре	Distribution	Parameters					
Caustic Dipping Cold Water Dipping Acid Dipping Acid Soak Hot Water Dipping Phosphate Dipping Neutralizer Dipping Soap Dipping Drying Tons/Trip Breakdown Length	Normal Normal Normal Normal Normal Normal Exponential Gamma Exponen- tial	.014 mean, .0035 variance .0119 mean, .0035 variance .0139 mean, .0034 variance .1989 mean, .0034 variance .012 mean, .0034 variance .0145 mean, .00384 variance .0159 mean, .00384 variance .0139 mean, .00346 variance .1673 mean .42017 alpha, 3.183 beta					

DISTRIBUTIONS FOR THE TANK SYSTEM

Tonnage was calculated by multiplying the weight per foot of the tubes in the trip by the length of the tubes located in the Work Order, and multiplying this number by the number of pieces per trip taken from the Tank Summary Report.

SOUTHWEST TUBE MANUFACTURING COMPANY

INTERNAL WORK ORDER

Pes.	FOC	TAGE	0.D.	1 PMent	Len	gth	i	Specification		Nt . =1	
	50	00	.500	310	117-à	24'	AS-	rm A	513-5	,	.4214
					STEEL		ATION				
Pcs.	0.0.	Wall		ength	H	Net	Grade	Baie	Orawn	t Length	Wt./Ft.
23	1.820	1.115		کارہ	15824	WL	I NICA	0 1	162	22 4	
05	.750	liao	1	29	13820	Dain	WIG2	0 2	191	2a 10	1 2014
82	150	1120	6	219	1582)aw	lunioa	3 3	2410	372	2014
13	<u>06 ר.</u>	.123	<u> </u>	<u>je</u> RL	158ar	1012	VI 102	0 4	142	_ <u>20</u> §	8183
	6200						1				
	2ac		7								
		1			1		i		0 11	1.21	
					+						
					1						
	<u>.</u>				PC	INTER	l				
Baies	Die 1	Die 2	Die 3	Sales	Die-1	Die 2	Die 3	8	laies i Die	1 0ie 2	Die 3
-4	۲۲۵.	.575					1		-4 50	5.477	
					•			ANNEAL	1	- 1	
		h									
1012 ·		Mandret	Drawn	0.0.	O.D. Tol.	Ora	wn Wali		% A	led.	WL/FL
1 11	1215		1024	,		116	1122		279/10/	2% 20%	مر/ع حدر
		CUH	-POI	1ts	+Pro	in es	ZG A	nneal	i		
2 0	502	207	50		200/ 000	1.09	975	.305/.31	23%	36%	1,4212
1		-	PIT	BA	185	D-1	J IN	one	Pass	firs	F
1						Ī					1
rocaes Cu		R									
								•			
racese An	neeling	1660) • • • •	5'6"	FPM	89	Tubes P	Per Paw	19 20	6	(3). Per -
nai Annea			1000) • = @	5'2'	Υ FPN	. 89	Tubes Per Ro	<u>₩(, LC</u>	26	133. Per -
ycia Annei	ei: Zanes			•4	Zones			•\$/Zone	3		٦ [.]
Iraness To	T ener	, be j	Dere	ow_	<u></u> 3	80	7 Min./	<u></u>	Max./	Zear Inter	mai Use Or
Intten By 2	-inde	، ح	Lan	<u>e</u>	-	w.o. • _	011-60	18-2	_	₽ 9 Ç€	: <u>-</u>

Figure 8. Work Order

Finally, calculation of the probability of a breakdown, the probability of a lube operation, phosphate operation, and a trick operation was made through the Tank Summary Report. Tank Summary Reports for the previous three months were used to calculate these probabilities. Breakdowns, lube operations, phosphate operations, and trick operations were tallied and divided by the total number of trips. The probability of a breakdown is 0.17; the probabilities for a lube, phosphate and trick operation are 0.89, 0.043, and 0.067, respectively.

CHAPTER V

MODELING OF THE TANK SYSTEM

Three different versions of the tank system were developed for Southwest Tube. These versions include the present system, a two crane one operator system, and a two crane two operator system. Each of these models has the same two major assumptions. The first assumption is that there is an endless supply of tubing for trips. It was determined from the production planning department that the tanks never wait for material. Another major assumption made was that there is always room for more trips in the dryer.

This chapter describes in detail each system and how each system is modeled.

Present System Model

The present system, as previously described in Chapter III, is modeled completely in network SLAM (Appendix B). Presently, two cranes work the system. Each crane has responsibility for one side of the tank system. Since these cranes operate independently, only one crane will be considered in the network.

The model consists of two major networks. The first network consists of the actual operation of the crane

through the tanks. A create node creates one entity to run through the model. The entity is then determined to be a clean and phosphate trip, a tricked trip, or a clean and lube trip through probabilistic branching. All major attributes are then assigned to the entity. These attributes contain all service times through the tanks and the time an entity starts the tank operation. The entity then goes through the various services of the tanks, branching off to particular nodes depending on what type of operation is assigned to the entity. Resource gates throughout the system stop the flow if any breakdown should occur (breakdowns are modeled in the second network). The entity is then split at the end of the network after the entity is placed in the dryer for service. One entity continues service throughout the dryer and is terminated. The other entity is taken back to the beginning of the network after a crane move time to start through the system again. COLCT nodes are used at the end of the network to allow collection of the time in the system for each entity.

The second network consists of all breakdowns for the crane system. This network starts with a create node to loop one entity through the system.

Through probabilistic branching, it is determined if a breakdown will occur for a particular shift. A breakdown time and a service time are then determined for that particular breakdown. When a breakdown does occur, the resource CRI is closed until the repairs are made. The

resource gate is then opened so the cranes can continue through the system. The entity in the breakdown network then loops to the beginning for the next 12 hour shift.

Two Crane One Operator Model

This system is similar to the original system except for the addition of another crane (Appendix C). In this system one operator operates the two cranes through the tanks. One crane is moved while the other is in a soaking operation. This model includes four networks - one network for each crane, and one network for breakdowns of each crane.

Major problems arise in the modeling of the two crane system due to interference of the two cranes. This problem is solved by determining which crane will be ahead of the other and keeping it that way through a series of resources and gates controlled in the networks representing each crane.

The first network represents the crane that is always in front. The network is the same as the original model except for the resources and gates used to control interference. Gates are used to prevent movement of the other crane when a crane is being manipulated. Another set of gates and resources is used to prevent the overtaking of the first crane and to prevent the use of the same soaking tank. These gates and resources are used in front of the first cold water tank (because of the back-tracking out of the acid tank), in front of the phosphate tank, and in front of the soap tank. Gates and resources are also placed in the branching of the network for the trick trip and the clean and phosphate trip to prevent the second network from overtaking the first network. The ending of the two crane networks is similar to the original network except for the waiting of the first crane network for the second crane network to finish. This allows the operator to move the cranes together back to the beginning of the tanks.

The two networks that run the crane breakdowns are the same as the present system's crane breakdown network. Gates control resources in the corresponding networks to allow breakdowns of the two crane systems.

Two Crane Two Operator Model

This model utilizes three networks - one for the two cranes, and two for the breakdown of the cranes (Appendix D). Figure 9 represents the assignment of the two cranes to their prospective areas of the tank. It is desirable to have an even balance of time in the tanks for each assigned crane area. Given the present means and time in the soaking tanks, the hot water tank seems to be the best prospective dividing point for the crane assignment areas. The hot water tank will be the "pin-off point" for the cranes. The crane assigned to the first set of tanks in the sequence will "pin-off" a trip in the hot water tank after completion of the tank procedures in its area. This crane will then



Figure 9. Crane Tank Assignment

hook up with the bale in the hot water tank and complete the tank procedures in its assigned area. This crane will then return to the hot water tank to pick up another trip.

The SLAM model is similar to the Present System Model. The model is the same as the Present System Model until the hot water tank. At this point a resource is added to avoid interference between the two cranes. This resource requires the first crane to wait for the hot water tank to be empty. When the tank is empty a "pin-off" operation can then be performed. The entity is then split to allow the crane to return to the start of the network to pick up a new trip. The other entity continues on through the second crane area. This area begins with a resource to allow the trip to wait for the second crane to finish procedures with the previous entity. The entity then is serviced by the remaining tanks. After service, the entity is split. One entity goes through the dryer where statistics are collected and where the entity is terminated. The other entity releases the resource corresponding to waiting in the hot water tank after move time for the second crane. The entity is then terminated.

The two crane breakdown networks are exactly the same as the breakdown networks in the Two Crane One Operator Model.

CHAPTER VI

TANK SIMULATION ANALYSIS

This chapter contains a discussion of each type of model and its outputs. From these outputs confidence intervals are calculated. These intervals will be discussed and analyzed.

Present System Model

The Present System Model was run for a total of 3600 hours (30 12 hour shifts). The model was started in steadystate. Outputs for the 10 runs is located in Appendix E.

Present System Output

Table V represents the output for all 10 runs of the Present System Model. Trip output per run ranged between 433 and 446 trips, with an average of 439.6 trips. This caused the average output of trips per shift to range between 14.43 trips to 14.87 trips, with an average of 14.65 trips. The tank time (time through the tank system without the dryer) ranged between 0.81 and 0.83 hours, with an average of 0.82 hours. Total time in the system (time in the tank system including dryers) ranged between 0.94 and 0.98 hours, with an average of 0.97 hours. The number of breakdowns in the system contained a low value of 0 and a

TABLE	v
TUUUU	v

OUTFOI TON INDENI DIBIEH MODEL	OUTPUT	FOR	PRESENT	SYSTEM	MODEL
--------------------------------	--------	-----	---------	--------	-------

Run	1	2	3	4	5	6	7	8	9	10	Avg.
Trip Output	442	437	433	443	433	441	441	436	446	444	439.6
Output/Shift	14.73	14.57	14.43	14.76	14.43	14.7	14.7	14.53	14.87	14.8	14.65
Tank Time	.81	.82	.83	.81	.83	.82	.82	.82	.81	.81	.82
Total Time	.96	.98	.96	.94	.98	.97	.98	.97	.9 5	.96	.97
Number of Breakdowns	5	4	5	7	7	4	4	8	0	6	5
Ton Output	58 9	5 99. 7	557.6	621.7	593	616.5	577.5	593.8	571.3	567	588.7

high value of eight breakdowns, with an average of five. Ton outputs ranged from 557.6 to 621.7 tons, with an average of 588.7 tons.

Present System Confidence Intervals

A confidence interval was calculated for all the parameters in Table V to provide a more accurate view on exactly where the range of values lie for each type of parameter. Using a 95 percent confidence interval and the equation

$$\bar{x}$$
 (n) ± t_{R-1},.025 $\sqrt{\frac{s^2(n)}{n}}$

computations were made for the set of 10 runs. This equation assumes normality. X (n) is the mean of the distribution, s^2 is the variance, t_{R-1} is the factor corresponding to a 95% confidence interval.

Figure 10 shows the confidence interval for the trip output. It can be stated with 95% confidence that the interval of 429.78 and 449.4 contains the true mean for 30 shifts.

Figure 11 represents the confidence interval for tank time. With tank time, there is 95% confidence that the interval of 0.80 and 0.837 includes the true mean of time spent in the tanks.

The confidence interval for total time in the system including the dryer is represented in Figure 12. There is a

95% confidence that the interval bracketed by 0.94 and 1.00 contains the true mean of total time in the system.

N



Figure 10. Confidence Interval for Trip Output in the Present System Model



for Tank Time in the Present System Model



The number of breakdowns confidence interval is represented in Figure 13. It can be stated that there is a 95% confidence that the interval of 0.15 and 9.85 encases the mean number of breakdowns for a 30 shift period.



.15 breakdowns 5 breakdowns 9.85 breakdowns LOW MEAN HIGH

Figure 13. Confidence Interval for Breakdowns of the Present System Model Figure 14 represents the confidence interval for ton output. It can be stated that there is a 95% confidence that the interval of 544.1 and 633.33 bounds the true mean of tons for a 30 shift period.



Present System Final Analysis

To validate the simulation, a t-test was performed between the trip output and data collected for 10 different sets of 30 shifts each. Table VI represents the final results of this t-test.

Since t_0 is less than the critical t-test value of $t_{18,.025}$, the hypothesis that the mean of the actual output equals the simulation output cannot be rejected. This is a good indication that the model is valid.

TAB	LE	VI
-----	----	----

T-TEST OF TRIP OUTPUT VS. ACTUAL OUTPUT

.

.

-

Simulation Output	Actual Output
442 437 433 443	420 452 448 440
433 441 441 436 446 444	443 439 440 444 442 440
$\mu_1 = 439.6$ $s_1^2 = 18.84$	$\mu_2 = 440.8$ $s_2^2 = 63.16$
$H_0: \mu_1 = \mu_2$ $H_1: \mu_1 \neq \mu_2$	
$Sp^2 = \frac{(10-1)}{8} \frac{18.84 + (10)}{8}$	-1)(63.16) = 92.31
$t_0 = \frac{440.8 - 439.6}{92.31\sqrt{1/10 + 1/10}}$	= .029
t.025,18 = 2.101 t.025,18 > to	
Cannot Reject H _o	

Validation was also made through the Director of Cold-Draw Operations. Utilizing the Turing Test, a set of output from the actual system of the number of trips per shift and output of trips per shift was given to the Director of Cold-Draw Operations. No distinction could be made, thus validating the model further. The director was also given a list of mean times in the tanks and times taken with a stopwatch by the tank operator of time through the system. The director could not tell the difference between these times, either.

The data showing the number of breakdowns also seem to be valid. If there is a 17% chance of a breakdown during any shift, for a 30 shift period there should be approximately 5.1 breakdowns. The ton output also seems correct with a value of 588.7 tons. The average number of tons per shift is 1.337; multiplying this by the total number of trips, a number of 587.7 tons is obtained. This is well within the 95% confidence interval calculated for tons.

From the output, it seems that this is an extremely valid and accurate simulation model of the tank system. The next two sections deal with the addition of two cranes to the model and their effect on the output.

Two Crane One Operator Model

The Two Crane One Operator Model was run for a total of 360 hours, or 30 shifts as was the Present System Model.

Output for the 10 runs is located in Appendix F.

Two Crane One Operator Model Output

Table VII represents a summary of the output for all 10 runs. Trip output ranged between 769 and 797 total trips, with an average of 779.3 trips per 30 shift period. This caused the output per shift to range between 25.6 and 26.57 trips per shift, with a mean of 26 trips. The tank time for crane one had a low of 0.88 hours and a high of 0.91 hours, with a mean of 0.897 hours. The total time in the system including the dryer ranged between 1.04 and 1.1 hours, with an average of 1.06 hours. Tank time using crane two had a low of 0.90 hours and a high of 0.93 hours, with a mean of Total time in the system through crane two 0.92 hours. ranged between 1.05 and 1.1 hours, with a mean of 1.09 The number of breakdowns for crane one had a low of hours. 0 breakdowns, a high of 10 breakdowns, and an average of 5.2 breakdowns. The number of breakdowns for crane two ranged between 3 and 9, with a mean of 6.1. Ranges for the total ton output of the system fell between 1020 and 1111 tons, with a mean of 1053.3 tons.

Two Crane One Operator Confidence Intervals

A confidence interval of 95% is calculated for all parameters as in the Present System Model to provide a more accurate view of the range of values for the Two Crane One Operator Model.

TABLE VII

Run	1	2	3	4	5	6	7	8	9	10	Avg.
Trip Output	781	788	773	777	773	773	769	796	776	786	779.3
Output/Shift	26	26.3	25.8	25 .9	25.8	25 . 8	25 .6	26.6	25 .9	26.2	26.00
Tank Time System 1	.9 0	.90	•90	.89	.91	.903	.91	.88	.89	.89	.897
Total Time System 1	1.1	1.04	1.06	1.07	1.06	1.06	1.07	1.05	1.05	1.06	1.06
Tank Time System 2	.92	.91	.92	.92	.93	.93	.93	.9 0	.92	.91	.92
Total Time System 2	1.1	1.05	1.1	1.1	1.1	1.08	1.1	1.07	1.09	1.09	1.09
Number of Breakdowns System 1	3	10	4	4	7	5	9	0	5	5	5.2
Number of Breakdowns	6	7	5	7	7	9	3	5	7	5	6.1
Ton Output	1046	1059	1068	1040	1020	1020	1083	1111	1053	1033	1053.3

OUTPUT FOR TWO CRANE ONE OPERATOR MODEL

5 S Figure 15 represents the confidence interval of trip output in the system for this model. There is a 95% confidence level that the interval of 760.7 and 798 embraces the true mean for the total number of trips for a series of 30 shifts.



A 95% confidence interval for tank time using crane one is represented in Figure 16. It can be stated that there is a 95% confidence that the interval of 0.877 and 0.917 contains the true mean of tank time for crane one.

Figure 17 represents the 95% confidence interval for total time using crane one. There is a 95% confidence that the interval 1.025 and 1.094 includes the true mean for total time in the system.

Figure 18 represents the confidence interval for tank time using crane two. There is a 95% confidence that the interval of 0.897 and 0.942 contains the true mean of tank time using crane two.



One Operator Model



1.025 hours 1.06 hours 1.094 hours LOW MEAN HIGH

Figure 17. Confidence Interval for Total Tank Time of Crane One of Two Crane One Operator Model



Tank Time of Crane Two of Two Crane One Operator Model

Total time in the system utilizing crane two is represented by the confidence interval in Figure 19. There is a 95% confidence that the interval of 1.053 and 1.126 brackets the true mean of total time in the system.



Figure 20 represents the confidence interval for the number of breakdowns for crane one. It can be stated that there is a 95% confidence that the interval of 0 and 11.4 the true mean for the number of breakdowns for a 30 shift period.



0 breakdowns 5.2 breakdowns 11.4 breakdowns LOW MEAN HIGH

Figure 20. Confidence Interval of Breakdowns for Crane One for Two Crane One Operator Model

The confidence interval for the number of breakdowns of crane two is represented in Figure 21. There is a 95% confidence that the interval of 2.53 and 9.67 includes the true mean of breakdowns for crane two for a 30 shift period.

Figure 22 represents the 95% confidence interval for the ton output of this model. It can be stated that for a 30 shift period the interval of 992.1 and 1114.5 contains the true mean for number of tons produced by the system.



2.53breakdowns6.1 9.67breakdowns LOW MEAN HIGH

Figure 21. Confidence Interval of Breakdowns for Crane Two for Two Crane One Operator Model



992.1 tons 1053.3 tons 1114.5 tons LOW MEAN HIGH

Figure 22. Confidence Interval of Ton Output for Two Crane One Operator Model

Gate Analysis of the Two Crane One

Operator Model

Gate statistics are located in Table VIII for the 10

TABLE VIII

GATE STATISTICS FOR TWO CRANE ONE OPERATOR MODEL

Run	1	2	3	4	5	6	7	8	9	10	Avg.
MOV	.426	.467	.3799	.3754	.4292	.4159	.4217	.4203	.4076	.3780	.4121
SC2	.633	.638	.6242	.6280	.6393	.6401	.6324	.6364	.6367	.6274	.6336
SC1	•526	.521	. 5366	.5274	•5285	•5342	.5312	•5233	.5330	.5308	. 529
C2	.897	.898	.8951	.89 57	.9009	.8875	.8824	.8952	.9 002	.9 015	. 895
P2	.914	.913	.9167	.9 185	.9178	.9164	.9135	.9173	.9162	.9161	.916
SO2	.878	.879	.8833	.8840	.8704	.8716	.8843	.8819	.8782	.8765	.879
ACID	.705	.693	.7118	.7114	.7077	.7178	.7138	.6997	.7145	.7086	.708
PASL	.699	.698	.7221	.7238	.6974	.7082	.7176	.7228	.7123	.7126	.711
PAS2	.872	.873	.8769	.8786	.8626	. 8659	.8741	. 8755	.8733	. 8692	.872

runs of this system. It is useful to take a look at these statistics to see how the system is operating in the case of crane interference for this model.

The MOV gate allows crane one to wait for crane two before moving back through the system. This gate is open an average of 41% of the time. This means that 59% of the time, crane one is waiting for crane two to finish.

SC1 and SC2 make sure that only one crane is being worked at a time. These values are 52.9% and 63.4% correspondingly of the time these gates are open. It would seem that these values should be approximately 50% apiece; however, when the two cranes are both in a soak tank, both gates may be open. As soon as a crane is finished soaking, it instantly closes the other crane's gate, thus preventing simultaneous movement.

C2, ACID, P2, and SO2 prevent two cranes using the same soak at the same time. The gate C2 controls the caustic tank and is open 89% of the time. The gate that controls the acid tank is open (ACID) 70.8% of the time. P2, which controls the phosphate tank, is open an average of 91.6% of the time, and SC1, which controls the soap tank, is open 87.9% of the time.

From the amount of time the gates are open, it is obvious that a bottleneck occurs at the acid tank with that particular gate being open only 70.8% of the time. This is because of the high service time associated with the acid tank.

Two Crane One Operator Final Analysis

Trip output for the Two Crane One Operator System was considerably higher at an average of 779.3 trips for a 30 shift period than the Present System Model at an average of 439.6 trips. This was because of the extra transport in the new model. The output was not doubled because of factors such as crane interference and waiting times.

The tank times in the Two Crane One Operator System were greater than that of the Present Model. However, there are two items in the two crane system which account for the higher output of the two crane system. The tank time of crane one always lags just behind that of crane two. This is because crane two has to wait until crane one is finished so both cranes can move across the system to pick up another trip. The same logic as above follows for the total time in the system.

The average number of breakdowns of 5.2 for crane one and 6.1 for crane two fall in the range of breakdowns for the 95% confidence interval for the Present System Model of 0.15 and 9.85 breakdowns.

The ton output is correspondingly higher with the new model to the increased number of trips.

Two Crane Two Operator Model

The Two Crane and Two Operator Model was run for 360 hours or 30 shifts, as the previous two models. Output for the 10 runs are located in Appendix G.

Two Crane Two Operator Output

Table IX represents a summary of the output for the Two Crane Two Operator System. Trip output averaged at 676.9 trips for a 30 shift period, with a high of 689 and a low of 664 trips. The corresponding output per shift ranged between 22.1 and 22.9 trips per shift, with an average of 22.6 trips. Average time in the tanks ranged between 0.87 and 0.91 hours, with an average of 0.89 hours. Corresponding total times had a high of 1.06 hours and a low of 1.03 hours. Number of breakdowns for crane one ranged between 2 and 22, with an average of 7.7. The number of breakdowns for crane two had a low of 2, a high of 9 and an average of 4.9 breakdowns. Ton output had a low of 884 and a high of 951 tons, with an average of 917.2 tons.

Two Crane Two Operator Confidence Intervals

To further investigate the range of the values for the Two Crane Two Operator Model, a 95% confidence interval was calculated as in the previous two models.

Figure 23 represents the confidence interval for trip output of this model. There is a 95% confidence that for a 30 shift period the interval of 658.1 and 695.7 encompasses the true mean for the number of trips.

The confidence interval that represents tank time in the system is pictured in Figure 24. It can be said that there is a 95% confidence that the interval of 0.861 and 0.92 bounds the true mean of time in the tanks.

г	A	в	L	Е	Ι	Х
---	---	---	---	---	---	---

1. Apr Apr		
· ·	TABLE IX	
OUT PU'	FOR TWO CRANE TWO OPERATOR MODEL	

Run	1	2	3	4	5	6	7	. 8	9	10	Avg.
Trip Output	667	678	664	686	674	670	689	672	684	685	676.9
Output/Shift	22.2	22.6	22.1	22.9	22.5	22.3	23	22.4	22.8	22.8	22.6
Tank Time	.91	.89	.89	.87	.89	.90	.87	.902	.88	.88	.89
Total Time	1.06	1.03	1.03	1.03	1.04	1.04	1.02	1.05	1.03	1.03	1.036
Number of Breakdowns System 1	12	5	22	5	8	9	2	9	3	2	7.7
Number of Breakdowns System 2	9	4	4	6	4	. 2	4	7	4	5	4.9
Ton Output	894	900	919	948	898	884	903	9 51	924	9 51	917.2


658.1 trips 676.9 trips 695.7 trips LOW MEAN HIGH

Figure 23. Confidence Interval of Trip Output for Two Crane Two Operator Model



For the total time in the system (Figure 25), it can be stated that there is a 95% confidence level that the interval of 1.011 and 1.061 includes the true mean of total time in the system.



Figure 26 represents the confidence interval for the number of breakdowns for crane one. This 95% confidence level states the interval of 0 and 20.6 encases the true mean for breakdowns.



The confidence interval that represents the number of breakdowns for crane two is represented by Figure 27. There is a 95% confidence level that the interval of 0.67 and 9.1 includes the true mean for breakdowns.



.67 breakdowns 4.9 breakdown9.1 breakdowns LOW MEAN HIGH

Figure 27. Confidence Interval of Breakdowns for Crane Two of Two Crane One Operator Model

Figure 28 represents the confidence interval for ton output. It can be stated that there is a 95% confidence that the interval of 862.77 and 971.62 encases the true mean for the number of tons in a 30 shift period.

Resource Analysis of Two Crane Two

Operator Model

Table X represents the percentage of time the resources WCl and WC2 were not in use. WCl represents the resource used in waiting for crane two to pick up a trip. WC2 represents the resource used in waiting for crane two to receive a trip from crane one.



WCl is available 83.5% of the time, which means crane one hardly ever waits for crane two. WC2 is available 29% of the time, which means crane two waits for crane one 71% of the time. This is caused by the imbalance of the tanks at the "pinning off" area. To remedy this type of imbalance the pinning off should be moved over to allow less time for the crane one system and more time for the crane two system. However, this cannot be accomplished. The next tank that can be utilized as a pinning off area is the acid tank. Pinning off cannot be done here because of safety reasons and backtracking problems.

		RESC	URCE OU	TPUT OF	TWO CRA	NE TWO	OPERATOR	MODEL			
Resource	1	2	3	4	5	6	7	8	9	10	Avg.
WC1	.8264	.8315	.8447	.8395	.8374	.8346	. 8357	.8272	.8347	.8356	.835
WC2	.2887	.2864	.3107	.2848	.2944	.29 52	. 2837	.2848	.2828	. 2856	.290

TABLE X								
RESOURCE		٥F	m ao	CDAND	TH			

Two Crane Two Operator Final Analysis

Trip output was higher with 676.9 trips than the Present System Model with an average of 439.6 trips for a 30 shift period. However, because of the imbalance of the system, the trip output was lower than that of the Two Crane One Operator Model with an average of 779.3 trips for a 30 shift period.

The tank time in the system was slightly greater than that of the original system, with an average of 0.89 hours versus 0.82 hours. This is due to the "pinning off" function in the hot water tank. Tank time of the Two Crane One Operator System was approximately equal to that of the Two Crane Two Operator System.

The number of breakdowns for both cranes fall within the range of the other two systems with values of 7.7 and 4.9, respectively.

The ton output was lower than the Two Crane One Operator System, due to the smaller number of trips for 30 shifts at 578.96 tons.

CHAPTER VII

TANK SYSTEM ANALYSIS THROUGH CAN-Q

CAN-Q Input

Can-Q is a computer program that utilizes Queueing Theory and Markov Chains to analyze systems. The program uses mean service and travel times as opposed to distributions used in simulation. The following chapter contains CAN-Q input and output for the tank system. All input is simply the mean of times taken for the input used in the simulation. Each tank is divided into a station, a mean processing time and the number of servers is input for each station. Average dipping times plus soaking time (if soaking is required) is used as input for each station. Table XI represents the final input for CAN-Q. A routing for each product type is also required for CAN-Q. In the tank simulation, three different product routings are required. These products are normal lube, phosphate, and trick. Table XII represents the routing for the lube operation, Table XIII represents the routing for the phosphate operation, and Table XIV represents the routing for the trick operation.

Another type of input required for CAN-Q is a transport time between stations. Only one transport time is allowed

TABLE XI

CAN-Q INPUT

•

Station	Processing Time	Number of Servers
<pre>1 Holding 2 Caustic 3 Cold Water I 4 Acid 5 Hot Water 6 Phosphate 7 Cold Water II 8 Neutralizer 9 Soap 10 Dry</pre>	6.71 minutes 6.68 minutes 0.714 minutes 12.768 minutes 0.72 minutes 6.74 minutes 0.714 minutes 1.908 minutes 6.668 minutes 2.3 minutes	1 1 1 1 1 1 1 1
Crane Move Time Number of Cranes in System	0.184 minutes 2	2

TABLE XII

ROUTING FOR THE LUBE OPERATION

Operation	Number	Station
1 2 3 4 5 6 7 8 9 10 11		Holding Caustic Cold Water Acid Cold Water Hot Water Phosphate Cold Water Neutralizer Soap Dry

TABLE XIII

Operation Numb	Der Station
1	Holding
2	Caustic
3	Cold Water
4	Acid
5	Cold Water
6	Hot Water
7	Phosphate
8	Cold Water II
9	Dry

ROUTING FOR PHOSPHATE OPERATION

TABLE XIV

.

ROUTING FOR TRICK OPERATION

Operation Number	Station
1	Holding
2	Caustic
3	Cold Water
4	Acid
5	Cold Water
6	Hot Water
7	Dry

.

in CAN-Q. This time for the tank system is the average time between stations, a value of 0.18 minutes.

The last type of input that must be made for CAN-Q is the number of items in the system. This determines how many items can be in the production at one time. The number of items must be two or greater.

CAN-Q Output Analysis

Output for CAN-Q (Appendix H) contains a routing for each product type, input data summary, system performance measures, summary for each station, and sensitivity information. However, the only information that is valuable in determining the final analysis of the tank system is located in the summary of each station and the system performance measures, the routings and input data section are mainly used for data input verification. The sensitivity information is useful if product types or service times can be changed.

System Performance Measures

The System Performance Measures section contains the most valuable information on the system for the tanks.

Table XV contains the final information from the System Performance Measures Section. Production rate is the first value given. For two items (items represent cranes) in the system, the production rate is 2.192 items per hour. Production rates by product type are also given; these are

TABLE XV

SYSTEM PERFORMANCE SUMMARY

SYSTEM PERFORMANCE MEASURES

PRODUCTION RATE = 2.192 ITEMS PER HOUR

PRODUCTION RATES BY PRODUCT TYPE

	NUMBER	VALUE
LUBE	1,951	1.951
РНО	.088	. 088
TRI	.153	. 153

TOTAL VALUE = 2,192

AVERAGE TIME IN SYSTEM = 54.74 MINUTES

PROCESSING 45.14 TRAVELING 1.92 WAITING 7.69

FUNCTIONS OF N, NUMBER OF ITEMS IN THE SYSTEM

N	PRODUCTION RATE	AVERAGE TIME IN THE SYS	STEM
1 2 3 4 5	1.275 2.192 2.854 3.332 3.674	47.056 54.744 63.063 72.029 81.649	
5 7	3.917 4.085	91,917 102,804	
•	•		
INF	4,412	INF	

THE BOTTLENECK STATION IS 4

simply the fraction of the product type in the system multiplied by the overall production rate. An average time in the system is then given. This value is 54.74 minutes. This time is then broken down into actual processing time at 45.14 minutes, traveling time at 1.92 minutes, and waiting time at 7.69 minutes. Finally a production rate and an average time in the system is given for different numbers of items in the system. For one item in the system, the production rate is 1.275 items per hour with an average time in the system of 47.056 minutes.

The only way to compare the one and two crane systems is through the production rate and average time in the system. This is because CAN-Q will not accept a number in the system less than two. However, a good picture of the increase in the system by adding one crane is given through this information. There is an increase in production of almost one item per hour by adding an extra crane. Average time in the system increases by 7.7 minutes because of waiting for processing, but there are two items being processed, increasing the output of the system.

Finally, information is given on where the bottleneck is located in the system. The bottleneck in the tanks is located at the acid tank, station four.

Station Summary

The Station Summary contains information dealing with each particular station. The most useful summary is

contained within the station containing the bottleneck of the system. Station four is the bottleneck located in the tank system.

Station four is the station that is used for the dipping and soaking of the bales in acid (Table XVI). Server utilization for this particular station is approximately 49.7%. The average number of items in process and waiting for this station is 1.281, the average number of items in process is 0.497, and the average number of items waiting is 0.784. Average time spent per operation at this station is 35.061 minutes. Processing time takes 13.6 minutes of this time, while waiting takes 21.461 minutes. The fraction of time there are zero items at the station is 0.5031. The fraction of the time there is one item at the station is 0.4969.

TABLE XVI

STATION SUMMARY FOR ACID TANK

SUMMARY FOR S	TATION NUMBER 4	: ACID		
NUMBER OF Servers	SERVER UTILIZATION	AVE. NO. Busy serv	OF VER S	
1	. 497	. 497		
STEADY ST	ATE AVERAGE NUMBE	R OF :		
	ITEMS WAITI ITEMS IN PR ITEMS WAITI	NG 1 OCESS NG	.281 .497 .784	
AVERAGE T	THE SPENT AT THIS	STATION	PER OPERATION	PER ITEM
	TOTAL TIME (MINU Processing Waiting	TES)	35.061 13.600 21.461	35.061 13.600 21.461
. · · ·				
FRACTION	OF TIME X ITEM	S AT STATION	X ITEMS EX	CEEDED
X = X = X =	0 1 2	.5031 .4969 .1436	.4965 .000 ↓↓ ↓	9] ŧ

,

.

CHAPTER VIII

COMPARISON OF CAN-Q AND SIMULATION

This chapter compares the CAN-Q output with the simulation output. This is accomplished through the use of confidence intervals. An economic analysis is also done on the outputs of both the SLAM model and CAN-Q to determine if the addition of the cranes is economically feasible.

Original System Simulation and CAN-Q

In comparing the Present System Simulation with CAN-Q, only two numbers from the output of CAN-Q will be compared to the simulation output: time spent in the system, and output. Comparisons will be made through confidence intervals calculated from the simulation output.

The production rate calculated through CAN-Q is 1.275 items per hour. Multiplying this number by 360 an output of 459 items is obtained. Figure 29 shows where this number lies compared with the simulation's 95% confidence interval. The number is slightly high, probably because breakdowns cannot be modeled into the system. Taking an average output per day shows how close the production rate for the simulation and CAN-Q really are. CAN-Q's output per day is 15.3 trips, while the average number of trips per day for the simulation model is 14.65 trips.



Average time in the tank is 47.056 minutes, or 0.784 hours. Figure 30 shows where this value lies when compared with the simulation's 95% confidence interval for tank time in the Present System Model. This number is slightly lower because of the inability of CAN-Q to handle breakdowns.



Figure 30. Confidence Interval of the Present System Tank Time and CAN-Q Tank Time

Two Crane One Operator Simulation and CAN-Q

Output from the Two Crane One Operator System Simulation is extremely close to that of CAN-Q. Figure 31 represents the 95% confidence interval of the production for 360 hours. The production for CAN-Q of 789.12 trips for 360 hours lies almost midway between the mean of 779.3 trips and the upper limit value of 798 trips with respect to the simulation's output. The CAN-Q output of the production is slightly higher because of the inability to model Another reason the output might be slightly breakdowns. higher is because of the lack of ability for CAN-Q to model crane interference. This is especially true at the drying portion of the tanks. CAN-Q does not allow one crane to wait until the other crane is finished so they both may move back to the beginning of the tanks.



igure 31. Confidence Interval of Two Crane One Operator Output and CAN-Q Output

The average time of the system, however, is also slightly higher than the average tank time for the Two Crane One Operator Model (Figure 32). This is possibly due to random variation in the simulation model.



.877 hours .897 .912 .917 hours LOW MEAN CAN-Q HIGH

Figure 32. Confidence Interval of Two Crane One Operator Tank Time and CAN-Q Tank Time

Two Crane Two Operator Simulation and CAN-Q

The difference between this simulation and CAN-Q is greater than the difference found for the other models. Figure 33 depicts where the value of production output falls for 360 hours calculated through CAN-Q with respect to a confidence interval derived from the Two Crane Two Operator Simulation Model. CAN-Q's value of 789.12 trips lies well above the confidence interval upper value of 695.7 trips. This is due to the inefficiency of the Two Crane Two Operator Model to utilize the second crane.



Average time in the system of CAN-Q, however, does fall within this simulation's 95% confidence interval of tank time (Figure 34). This value of 0.912 hours is slightly greater than the mean value given through the simulation of 0.89 hours. This is also probably due to random variation in the simulation model.

Economic Analysis of Outputs by Simulation and CAN-Q

A net present worth was calculated for a one, three, and five year period using the averages for tonnage generated by the simulation models, and average output per trip from data collection.



In the economic analysis, each net present worth represents the added income above the original model. This means that the total tonnage for each proposed system was adjusted by subtracting the present system's tonnage from them. Management stated that the Minimum Attractive Rate of Return for the company is 12%, and the profit after overhead generated per ton is approximately \$100.00. Table XVII represents the final tabulations for the Two Crane One Operator Model and the Two Crane Two Operator Model.

The Two Crane One Operator Model had no personnel cost. This is because the same operator operates the added crane.

TABLE XVII

	Dorgonnel	D	Income Generated	NPW Ab	ove Original	System
	Personner	Equipment	Above Original Model	l year	3 year	5 year
ator	-	25,000	1,126,700	981,030	2,681,108	4,036,528
tem	-	50,000	2,253,400	1,962,061	5,362,216	8,073,056
	101 400	05 000				

ECONOMIC ANALYSIS OF TANK SYSTEM

Two Cranes One Operator	-	25,000	1,126,700	981,030	2,681,108	4,036,528
Full System	-	50,000	2,253,400	1,962,061	5,362,216	8,073,056
Two Cranes Two Operators	101,400	25,000	695,760	596,244	1,646,076	2,483,076
Full System	202,800	50,000	1,391,520	1,192,488	3,292,152	4,966,152
CAN-O						
One Operator	-	25,000	1,071,059	931,349	2,547,470	3,835,954
Full System	-	50,000	2,142,117	1,862,697	5,094,940	7,671,907
CAN-Q						
Two Operators	101,400	25,000	969,659	840,809	2,303,927	3,470,427
Full System	202,800	50,000	1,939,318	1,681,618	4,607,854	6,940,854

*Tonnage/year * 100.00 - Operator Cost

12% MARR

System

Equipment cost per crane after installation is approximately \$25,000.00. The total income generated per year is \$1,126,700 for adding a crane to one half of the system and \$2,253,400 for adding cranes to both halves of the system (the simulation only simulated one side of the tanks). Net present worth for one half of the system was \$981,030, \$2,681,108, and \$4,036,528 for a one, three and five year period, respectively. The net present worth for a one, three and five year period for the full system was \$1,962,061, \$5,362,216, and \$8,073,056, respectively.

The Two Crane Two Operator Model incurred the cost of This amounted to \$101,400 as estimated by personnel. This includes operators for the day and night management. shift for both the weekend and the weekday crew. Equipment cost is the same as the previous system at \$25,000 per crane after installation. Income generated per year from the addition of the cranes was \$797,100 for half the system, and \$1,594,200 for the full system. Net present worth for half the system was \$596,244, \$1,646,076, and \$2,483,076 for a one, three and five year period, respectively. The full system generated a net present worth of \$1,192,488, \$3,292,152, and \$4,966,152 for a one, three and five year system, respectively.

CAN-Q, utilizing an average tone output of 1.337 tons per trip and costs incurred for equipment, yields a present value of \$931,349, \$2,547,470, and \$3,835,954 for one, three and five years for half of the system. The full system

yields present values of \$1,862,697, \$5,094,940, and \$7,671,097 for one, three and five years, respectively.

The CAN-Q net present value for two operators is \$840,809, \$2,303,927, \$3,470,427 for one, three and five years. These values are for one half of the system. The full system present value for two operators is \$1,681,618, \$4,607,854, and \$6,940,854 for one, three and five years, respectively.

Clearly, the Two Crane One Operator system is best in an economical sense for both the simulation and CAN-Q. However, CAN-Q cannot distinguish between the two types of models run by the simulation. All values from both outputs of CAN-Q and simulation are very close, though, and the way in which CAN-Q operates is closer to the Two Crane One Operator Model than the Two Crane Two Operator Model.

CHAPTER IX

CONCLUSIONS

In making management decisions, both CAN-Q and simulation can be very valuable. In this particular situation many trade-offs are involved in using the two different techniques.

Simulation requires extensive system analysis and data collection while CAN-Q requires no modeling and very little data collection. This particular simulation project had a data collection period and system analysis of approximately three months. Another two months was required to build and verify these models. CAN-Q would take approximately two weeks of data collection and no distribution testing, plus no modeling.

Simulation requires expertise while CAN-Q does not. This means that management can utilize CAN-Q without an expert in modeling. For simulation, management will either hire someone or have someone else within the company with the expertise run the simulation for them.

Simulation requires a special software package and in most cases, at least a mini-computer to handle this type of software. CAN-Q is approximately 500 lines in length and can fit on a micro-computer.

CAN-Q only gives means, and not ranges. Simulation

does give means and ranges for the poorest and best performance of a particular system. In this particular problem, though, system variability was not very high.

The most important factor in the difference between CAN-Q and simulation is accuracy as compared to the real system. Both CAN-Q and simulation showed the proposed addition of the cranes as extremely attractive. CAN-Q did not show, as the simulation did, the optimum arrangement of the cranes and how many operators were needed. The simulation showed clearly that the optimum system was a two crane one operator type of setup, while CAN-Q basically showed only that adding an extra crane would be profitable. CAN-Q also could not analyze the breakdowns of the system. In this case, there was not a large difference in the numbers; however, in a system where frequent breakdowns could occur, CAN-Q may become more inaccurate.

CAN-Q may also be a valuable tool in verifying and validating a simulation. In this particular case, values of simulation and CAN-Q were comparable. Even if values in CAN-Q deviate from the values of simulation, and these deviations can be accounted for, CAN-Q can be a quick way to see if a modeler is on the right track with a simulation model.

The bottom line between simulation and CAN-Q is accuracy versus cost. In this case, both types of analysis revealed it was profitable to add another crane. However, simulation told exactly how to situate the crane while CAN-Q

did not. Simulation also enabled the modeling of breakdowns while CAN-Q could not. CAN-Q, though, takes much less time to develop. In this particular case it would take five to seven months to develop the simulation, compared to two weeks for CAN-Q.

Finally, both the simulation and CAN-Q showed it was extremely profitable to add the cranes. Even though CAN-Q was very close to the simulation's findings, the simulation showed it was most profitable to add an extra crane with one operator.

There are trade-offs in using simulation and CAN-Q. Further research should be done on different types of systems to see if CAN-Q or simulation is more appropriate in different situations.

BIBLIOGRAPHY

- 1. Adkins, G. and Pooch, V. W. "Computer Simulation: A Tutorial." <u>Computer</u>, 10, no. 4 (April 1977), pp. 12-17.
- Cochran, W. G. "The X² Test of Goodness of Fit." <u>Annals of Mathematical Statistics</u>, 23 (1952), pp. 315-345.
- 3. Dunning, K. A. <u>Getting Started in GPSS</u>. Engineering Press, San Jose, Calif., 1981.
- Emshoff, J. R. and Sisson, R. L. <u>Design and Use of</u> <u>Computer Simulation Models</u>. The Macmillan Co., 1970.
- 5. Graybeal, W. J. and Pooch, V. W. <u>Simulation:</u> <u>Principles and Methods</u>. Winthrop Publishers, Cambridge, Mass., 1980.
- Hillier, F. S. and Lieberman, G. J. <u>Introduction to</u> <u>Operations Research</u>. Holden-Day, San Francisco, Calif., 1980.
- 7. IBM Corp. <u>System/360</u> <u>Continuous System Modeling</u> <u>Program</u>. New York, 1967.
- 8. Kiviat, P. J. <u>Digital Event Simulation: Modeling</u> <u>Concepts</u>. The Rand Corporation, Santa Monica, Calif., 1967.
- 9. Markowitz, H. "SIMSCRIPT." <u>Encyclopedia of Computer</u> <u>Science and Technology</u>, J. Belzer, A. G. Holzman, and A. Kent, Editors, Marcel Dekker, 1978.
- 10. Massey, F. S. "The Kolmogorov-Smirnov Test for Goodness of Fit." <u>Journal of American Statistics</u> <u>Association</u>, 4 (1951), pp. 68-78.
- 11. Mize, J. H. and Fox, J. G. <u>Essentials of Simulation</u>. Prentice Hall, Englewood Cliffs, New Jersey, 1968.
- 12. Naylor, T. H. and Finger, J. M. "Verification of Computer Simulation Models." <u>Management Science</u>., 14:92-101 (1967).

- 13. Phillips, D. <u>Applied Goodness of Fit Testing</u>. American Institute of Industrial Engineers Inc., Norcross, Georgia, 1972.
- 14. Phillips, D. and Garcia-Diaz, A. <u>Fundamentals of</u> <u>Network Analysis</u>. Prentice-Hall, Englewood Cliffs, New Jersey, 1981.
- 15. Pritsker, A. A. "GASP." <u>Encyclopedia of Computer</u> <u>Science and Technology</u>, J. Belzer, A. G. Holzman, and A. Kent, Editors. Marcel Dekker, 1977.
- 16. Pritsker, A. A. and Pedgen, C. D. <u>Introduction to</u> <u>Simulation and SLAM</u>. Systems Publishing, Cambridge, Mass., 1980.
- 17. Pugh, A. L. <u>Dynamo User's Manual</u>. The MIT Press, Cambridge, Mass., 1976.
- 18. Shannon, R. E. "Simulation: A Survey with Research Suggestions." <u>AIIE Transactions</u>, 7, no. 3 (September 1975), pp. 209-301.
- 19. Shannon, R. E. <u>Systems Simulation: The Art and</u> <u>Science</u>. Prentice Hall, Englewood Cliffs, New Jersey, 1975.
- 20. Solberg, J. J. <u>The Optimal Planning of Computer Manu-</u> <u>facturing Systems</u>. NSF Grant No. APR74 15256, Report No. 9, 1980.
- 21. Solberg, J. J. and Ravindran, A. <u>Operation Research</u> <u>Principles and Practice</u>. John Wiley and Sons, New York, 1976.

APPENDIXES

APPENDIX A

DATA COLLECTED AND CORRESPONDING

HISTOGRAMS

CAUSTIC DIPPING

-

,

ORDERED DATA

.008 .007 .012 .012 .013 .014 .014 .016 .017 .018	.009 .010 .012 .013 .013 .014 .017 .017 .017	.009 .010 .012 .013 .013 .014 .017 .017 .017	.007 .012 .012 .013 .013 .014 .015 .017 .017 .023	.009 .012 .012 .013 .014 .015 .017 .018 .023
--	--	--	--	--



HYPOTHESIS STATEMENT

NULL HYPOTHESIS= POPULATION IS NORMAL WITH TRUE MEAN= .0140 ALTERNATIVE HYPOTHESIS= POPULATION IS NOT NORMAL WITH TRUE HEAN= .0140

×**** NUMBER OF ODSERVATIONS= 45

CELLS	RANGE FROM	OBSERVED To	OBSERVED FREQUEN 77	CUMULATIVE Orserved Frequency	THEORETICAL FREQUENCY	CUMULATIVE Theoretical Frequency	KOLMOGOROV - Smirnov Statistic
1 2 3 4 5 5 7 8 7 8 9 10	-979.97902 .00950 .01100 .01250 .01400 .01550 .01550 .01700 .01850 .02000 .02150	$\begin{array}{ccccc} .00730 & 6.0 \\ .01100 & 2.0 \\ .01250 & 8.0 \\ .01400 & 12.0 \\ .01330 & 2.0 \\ .01700 & 9.0 \\ .01850 & 2.0 \\ .02000 & 2.0 \\ .02150 & .0 \\ .02300 & 2.0 \\ \end{array}$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$.13333 .17778 .35554 .62222 .66667 .86667 .91111 .95556 .95556 1.00000	.04423 .15120 .13624 .16333 .16418 .13839 .09782 .05799 .02881 .01201	.04423 .19543 .33168 .49500 .65918 .79758 .89540 .95338 .98219 .99420	.08710 .01765 .02388 .12722 .00748 .04909 .01571 .00218 .02264 .00530

THE KOLMOGOROV - SMIRNOV STATISTIC =

KOLMOGOROV - SMIRNOV TEST

DEGREES	0F	FREEDOM=	10		
MU=		.014044445	SIGMA	2≈	.000012589

9 ທ

.12722

COLD WATER DIPPING

ORDERED DATA

.

.005 .008 .009 .010 .012 .012 .014 .014 .014	.004 .009 .009 .010 .012 .012 .014 .014 .015 .017	.005 .009 .009 .010 .012 .013 .014 .015 .017	.007 .002 .010 .011 .012 .013 .014 .015 .020	.003 .007 .010 .011 .012 .014 .014 .015 .021
--	--	--	--	--



HYPOTHESIS STATEMENT

NULL HYPOTHESIS= POPULATION IS NORMAL WITH TRUE MEAN= .0119 ALTERNATIVE HYPOTHESIS= POPULATION IS NOT NORMAL WITH TRUE MEAN= .0119

•

NUMBER OF OBSERVATIONS= 45

CELLS	RANGE FROM	OBSE TO	RVED	OBSERVED FREQUENCY	CUMULATIVE Observed Frequency	THEORETICAL FREQUENCY	CUNULATIVE Theoretical Frequency	KOLMOGOROV - SMIRNOV STATISTIC
1 2 3 4 5 6 7 8 9 7 8 9 10	-977.99902 .00750 .00900 .01050 .01200 .01350 .01500 .01650 .01800 .01950	.00750 .00700 .01050 .01200 .01350 .01350 .01450 .01450 .01250 .02100	$\begin{array}{c} 4.00000\\ 7.00000\\ 5.00000\\ 2.00000\\ 2.00000\\ 11.00000\\ 1.00000\\ 2.00000\\ 1.00000\\ 2.00000\\ 2.00000\\ 2.00000\\ 2.00000\\ 2.00000\end{array}$.08089 .20000 .11111 .20000 .04444 .24444 .02222 .04444 .00000 .04444	.08887 .28887 .40000 .60000 .64444 .83837 .91111 .95556 .95556 1.00000	.04433 .15748 .14221 .16880 .16650 .13648 .07276 .05262 .02475 .00967	.04433 .20181 .34402 .51281 .67931 .81579 .90875 .96136 .98611 .99578	.04456 .03703 .05598 .03719 .03487 .07310 .00236 .00581 .03055 .00422

KOLMOGOROV - SMIRNOV TEST

.

THE KOLMOGOROV - SHIRNOV STATISTIC = .08719

DEGREES	OF	FREEDOM=	10		
MU#		.011888888	SIGMA	2=	. 0

.000011965

ACID DIPPING

ORDERED DATA

.008	.008	.008	.007	.009
.009	.011	.011	.011	.011
.012	.012	.012	.012	.012
.012	.013	.013	.013	.013
.014	.014	.014	.014	.014
.014	.014	.015	.015	.016
.015	.016	.016	.016	.016
.017	.017	.017	.017	.017
.017	.013	.017	.022	.023



CLASS

START	. 008	STOP	. 024	SIZE OF INTERVAL	.0016
CALCULA	TED MEA	N=	.01391	CALCULATED VARIANCE =	.00001
HOULD YO	U LIKE	TO CHA	NGE THE	THE NUMBER OF CELLS ?	

•

HYPOTHESIS STATEMENT

NULL HYPOTHESIS= POPULATION IS NORMAL WITH TRUE MEAN= .0139 ALTERNATIVE HYPOTHESIG= POPULATION IS NOT NORMAL WITH TRUE MEAN= .0139

.

***** 45

NUMBER OF OBSERVATIONS=

CELLS	RANGE FROM	OBS TO	ERVED	OBSERVED FREQUENCY	CUMULATIVE Deserved Frequency	THEORETICAL FREQUENCY	CUNULATIVE THEORETICAL FREQUENCY	KOLMOGOROV - Smirnov Statistic
1 2 3 4 5 6 7 8	-979.99902 .00950 .01100 .01250 .01400 .01550 .01700 .01850	,00250 .01100 .01250 .01400 .01550 .01700 .01050	6.00000 4.00000 6.00000 11.00000 2.00000 12.00000 1.00000	.13333 .00807 .13333 .24444 .04444 .26567 .02222 .02222	.13333 .22222 .35556 .60000 .64444 .91111 .93333	.04181 .15529 .14270 .17058 .16867 .13797 .09336	.04181 .19710 .33980 .51038 .67905 .61702 .91038	.07152 .02512 .01575 .03762 .03460 .07407 .02296
9 10	.02000 .02150	.02150	.00000 2.00000	.00000	.95556	.02419 .00927	.96263 .98683 .99609	.00703 .03127 .00371

KOLMOGOROV - SHIRNOV TEST

.

THE KOLMOGOROV - SMIRNOV STATISTIC = .09409

DEGREES	OF	FREEDOM=	10)		
MU =		.013911	108 \$	IGMA	2=	.000011674
ACID SOAK

.

ORDERED DATA

.117 .150 .167 .183 .200 .200 .217 .233 .250	.117 .150 .200 .200 .200 .217 .233 .250	.117 .167 .183 .200 .200 .200 .200 .233 .250 .250	,117 ,167 ,200 ,200 ,217 ,233 ,250 ,250	.150 .167 .200 .200 .217 .233 .250 .283
--	--	--	--	--



HYPOTHESIS STATEMENT

NULL HYPOTHESIS= POPULATION IS NORMAL WITH TRUE MEAN= ALTERNATIVE HYPOTHESIS= .1989 POPULATION IS NOT NORMAL WITH TRUE MEAN= .1989

**** NUMBER OF OBSERVATIONS= 45

KOLMOGOROV - SMIRNOV TEST CELLS RANGE OBSERVED OBSERVED FROM CUMULATIVE THEORETICAL то CUNULATIVE FREQUENCY KOLMOGOROV -OBSERVED FREQUENCY THEORETICAL SMIRNOV FREQUENCY FREQUENCY STATISTIC 1 ~999.99902 .13360 4.00000 2 .08889 .13360 .08889 .15020 .02137 3.00000 .02187 3 4 .05667 .06702 .15020 .15556 .16680 .09335 .00000 .11522 .00000 .04034 .16680 .15556 .18340 .09938 9.00000 .21460 5 .20000 .05905 .18340 .35556 .20000 .13663 12.00000 .35128 .26667 ó .20000 .62222 .00428 .21660 .15942 .00000 .51070 7 .00000 .11153 .21660 .62222 .23320 .15770 9.00000 .66840 8 .20000 .04617 .23320 .82222 .24980 .13232 .00000 .80071 9 .00000 .02151 .24980 .92222 .26640 .09416 7.00000 .89487 10006 10 .07265 .26640 .97778 .28300 .05683 1.00000 .95170 .02222 1.00000 .02608 .02709 .98078 .01922

DEGREES OF FREEDOM= 10 祖リニ .198911071 SIGMA 2=

.001649856

THE KOLMOGOROV - SMIRNOV STATISTIC -

HOT WATER DIPPING

ORDERED DATA

.006	.006	,006	.005	.008
.008	.009	.009	.009	.007
.009	.009	.010	.010	.010
.010	.010	.011	.011	.012
.012	.012	.012	.012	.012
.012	.013	.013	.014	.014
.014	.014	,014	.014	.015
.015	.015	.015	.015	.016
.016	.016	,016	.019	.021



HYPOTHESIS STATEMENT

•

NULL HYPOTHESIS= POPULATION IS NORMAL WITH TRUE MEAN= .0120 ALTERNATIVE HYPOTHESIS= POPULATION IS NOT NORMAL WITH TRUE MEAN= .0120

******* NUMBER OF OBSERVATIONS= 45

		к	OLMOGOROV - SMIR	NOV TEST			
1 2 3 4 5 6 7 8 9 20	RANGE FROM -979.99902 .00750 .00750 .01050 .01200 .01200 .01350 .01500 .01550 .01600 .01950	OBSERVED TO .00750 4.00000 .00900 8.00000 .01030 5.00000 .01200 9.00000 .01300 2.00000 .01500 11.00000 .01650 4.00000 .01800 .00000 .01950 1.00000	OBSERVED FREQUENCY .06889 .17778 .117778 .11111 .20000 .04444 .24444 .08089 .00000 .02222 .02222	CUMULATIVE OBSERVED FREQUENCY .08089 .26667 .37778 .57778 .62222 .86667 .95556 .95556 .97778 1.00000	THEORETICAL FREQUENCY . 04059 . 15191 . 14069 . 16940 . 16940 . 13952 . 09544 . 05407 . 02537 . 00986	CUMULATIVE THEORETICAL FREQUENCY .04059 .19250 .33319 .50259 .67151 .81103 .91647 .96053 .98590 .0053	KOLHOGOROV - SMIRNOV STATISTIC .04830 .07417 .04459 .07519 .04929 .05564 .04909 .00493 .00812
					.00986	.99576	. 004

DEGREES	ΰF	FREEDOM=	10			
mu		.011977775	5	IGMA	2=	

.000011749

THE KOLHOGOROV - SMIRNOV STATISTIC =

PHOSPHATE DIPPING

ORDERED DATA

.020 .021 .022 .025 .033	.010 .011 .011 .011 .01 .011 .011 .012 .012 .01 .012 .012 .012 .013 .01 .013 .014 .014 .014 .014 .014 .015 .015 .01
--------------------------	---



HYPOTHESIS STATEMENT

· • . ·

NULL HYPOTHESIS= POPULATION IS NORMAL WITH TRUE MEAN= .0145 ALTERNATIVE HYPOTHESIS= POPULATION IS NOT NORMAL WITH TRUE MEAN= .0145

45

NUMBER OF OBSERVATIONS=

CELLS	RANGE From	OBS To	ERVED	OBSERVED Frequincy	CUMULATIVE Observed Frequency	THEORETICAL FREQUENCY	CUHULATIVE Theoretical Frequency	KOLMOGOROV – Smirnov Statistic
1	-979.99902	.00950	4.00000	.08839	.08887	.05877	. 05877	.03012
2	.00960	.01220	14.00000	.31111	.40000	.25742	.31619	.08331
3	.01220	.01480	7.00000	.20000	. 60000	.20974	.52592	,07408
4	.01480	.01740	12.00000	.26667	.86667	.20263	.72855	.13611
5	.01740	.02000	2.00000	.04444	.91111	, 14676	.87531	.03530
6	. 02000	.02260	2.00000	. 04444	.95556	.07963	.95499	.00057
7	.02260	.02520	1,00000	. 02222	.97778	.03242	.98741	.00963
8	.02520	.02780	. 80000	. 00000	.97778	.00789	,99730	.01952
9	.02780	.03040	.00000	.00000	.97778	,00226	, 99956	.02178
10	.03040	.03300	1.00000	.02222	1.00000	.00039	.99995	.00005

KOLMOGOROV - SMIRNOV TEST

.

٠

THE KOLMOGOROV - SMIRNOV STATISTIC = .13811

.

١

DEGREES	OF	FREEDOM=	10		
NU=		.014488893	SIGMA	2=	.000022892

ORDERED DATA

,010	,010	.011	.011	.011
.011	.012	.012	.012	.01
.012	.014	.014	,014	.014
.014	.014	.014	,014	.014
.014	.015	.015	.016	.015
.016	.017	.017	.017	.017
017	.019	.019	.019	.019
020	.020	,020	.020	.020
.020	.020	,021	.025	.026



HYPOTHESIS STATEMENT

NULL HYPOTHESIS= POPULATION IS NORMAL WITH TRUE MEAN= .0159 ALTERNATIVE HYPOTHESIS= POPULATION IS NOT NORMAL WITH TRUE MEAN= .0159

KOLMOGOROV - SMIRNOV TEST

CELLS	RANGE FROM	OBSERVED To	OBSERVED FREQUENCY	CUMULATIVE Observed Frequency	THEORETICAL FREQUENCY	CUMULATIVE Theoretical Frequency	KOLMOGOROV - Smirnov Stafistic
1 2 3 4 5 5 5 7 8 9 10	979.99902 .01160 .01320 .01480 .01640 .01800 .01800 .01760 .02120 .02280 .02440	$\begin{array}{cccccc} .01160 & 6.0000 \\ .01320 & 5.00000 \\ .01480 & 10.00000 \\ .01480 & 5.00000 \\ .01800 & 5.00000 \\ .01960 & 4.00000 \\ .02120 & 8.00000 \\ .02260 & .00000 \\ .02440 & .00000 \\ .02600 & 2.00000 \end{array}$.13333 .11111 .22222 .11111 .11111 .08899 .17778 .00000 .00000 .00444	.13333 .24444 .46667 .57778 .68889 .77778 .95556 .95556 .95556 .95556 1,00000	.06310 .17941 .14617 .16412 .15544 .12418 .08368 .04756 .02200 .00922	.06310 .24250 .38868 .55280 .70823 .83241 .91609 .96365 .98646 .99568	.07024 .00194 .0799 .02498 .01935 .05463 .03947 .00310 .03090 .00432

.

THE KOLMOGOROV - SMIRNOV STATISTIC # .07799

DEGREES	OF	FREEDOM=	10		
MU-		.015888888	SIGMA	2=	.000014828

SOAP DIPPING

ORDERED DATA

.

.007 .009 .012 .012 .013 .014 .014	.008 .011 .012 .012 .013 .014 .014	.009 .011 .012 .013 .013 .014 .014	.009 .012 .012 .013 .014 .014 .014	.009 .012 .012 .013 .013 .014 .014 .016
.016	.016	.016	.017	.017
.017	.017	.017	.017	.017
.017	.019	.019	.022	.023



,

张张兴尔们站来来接着我来来来来来来来来来来来来来来来来来来来来来来来来来来来来

HYPOTHESIS STATEMENT

NULL HYPOTHESIS= POPULATION IS NORMAL WITH TRUE MEAN= .0139 ALTERNATIVE HYPOTHESIS= POPULATION IS NOT NORMAL WITH TRUE MEAN= .0139

NUMBER OF OBSERVATIONS= 45

CELLO				GITAN	NUV IESI			
UELL3	FROM	ANGE TO	OBSERVED	OBSERVED FREQUENCY	CUMULATIVE OBSERVED ERFOLIENCY	THEORETICAL FREQUENCY	CUMULATIVE THEORETICAL	KOLMOGOROV - SMTRNOV
1 2 3 4 5 6 7 8 9 10	-999,99902 .00860 .01020 .01180 .01340 .01500 .01660 .01620 .01980 .02140	.003. .010/ .0113 .013 .015(.015(.0162 .0182 .0182 .0183 .0214 .0230	$\begin{array}{cccccccccccccccccccccccccccccccccccc$.04444 .08897 .04444 .33333 .13333 .08887 .17778 .04444 .00000 .04444	.04444 .13333 .17778 .51111 .64444 .73333 .91111 .95556 .95556 1.00000	.02298 .11895 .12912 .17028 .18208 .15786 .11057 .04325 .02923 .01075	FREQUENCY .02298 .14194 .27105 .44133 .62341 .78127 .89224 .95549 .98471 .99566	STATISTIC .02;46 .00060 .09328 .06978 .02104 .04793 .01887 .01887 .00807 .00976 .02916 .02916

KOLMOGOROV - SMIRNOV TEST

DEGREES OF FREEDOM= 10 MU= .013911109 SIGMA 2=

.000011992

.09328

THE KOLMOGOROV - SMIRNOV STATISTIC =

DRYING

ORDERED DATA

.050 .083 .083 .083 .083 .083 .083 .083 .083 .083 .117 .117 .133 .133 .167 .167 .167 .167 .250 .250	.083 .083 .083 .083 .133 .133 .133 .167 .167 .250	.083 .083 .083 .100 .133 .133 .167 .167 .167	.083 .083 .083 .117 .133 .167 .167 .183 1.833
--	--	--	---



HYPOTHESIS STATEMENT

NULL HYPOTHESIS= POPULATION IS EXP WITH TRUE MEAN= .1673 ALTERNATIVE HYPOTHESIS= POPULATION IS NOT EXP WITH TRUE MEAN= .1673

.

NUMBER OF OBSERVATIONS= 45

CELLS	RAN FROM	IGE TO	OBSERVED	OBSERVED FREQUENCY	CUMULATIVE Observed Frequency	THEORETICAL Frequency	CUMULATIVE THEORETICAL FREQUENCY	KOLMOGOROV - Smirnov Statistic
1	.00000	, 2283(D 40.00000	. 58887	.86889	.74450	.74450	11179
2	. 22830	. 40660	4.00000	.03369	97778	16748	01100	14437
3	. 40660	.53490	.00000	.00000	.97778	.05770	94949	100000
4	. 58490	.76320	.00000	. 0 0 0 0 0	.97778	.01998	00055	
5	,76320	.94150	.00000	.00000	.97778	.00685	00640	.01173
6	.94150	1.11980	.00000	. 00000	97778	00000	00074	.01062
7	1.11980	1.27810	.00000	. 00000	.97778	000000	90057	.02078
8	1.29810	1,47640	.00000	. 00000	.97779	00001	00005	102180
9	1.47640	1.65470	.00000		\$7778	00020	.7770J	.02203
10	1.65470	1,83300	.00000	. 0 0 0 0 0	.97778	.00003	.99998	.02217

KOLMOGOROV - SMIRNOV TEST

THE KOLMOGOROV - SMIRNOV STATISTIC = .14439

DEGREES OF FREEDOM= 10 THETA= .167311072

••••

TONS/TRIP

ORDERED DATA

,257	.318	.329	, 347	.381
.410	. 477	.533	.533	.540
.553	. 582	. 588	. 510	,659
.685	,706	.709	.721	.739
.764	.764	.795	.304	.838
.841	, 841	.841	.869	.869
.918	.948	, 963	1.010	1.023
1.051	1.059	1,063	1,080	1.080
1.111	1.124	1.142	1.142	1.155
1.156	1.172	1.211	1.211	1.211
1.216	1.332	1.332	1.332	1.332
1.441	1.441	1.442	1.512	1.525
1.650	1.682	1,695	1.695	1.746
1.756	1.780	1.814	1.893	1.913
1.920	2,241	2.241	2.258	2.345
2.345	2.400	2.416	2.457	2.521
2.909	2.982	2.982	3.009	3.012
3.025	3.025			



HYPOTHESIS STATEMENT

NULL HYPOTHESIS= POPULATION IS GANNA WITH TRUE MEAN= 1.3374 ALTERNATIVE HYPOTHESIS= POPULATION IS NOT GAMMA WITH TRUE MEAN= 1.3374

NUMBER OF OBSERVATIONS= 87

KOLMOGOROV - SMIRNOV TEST

CELLS	RANGE F'ROM	TO OF	SERVED	OBSERVED FREQUENCY	CUMULATIVE Observed Frequency	1HEORETICAL FREQUENCY	CUNULATIVE Theoretical Frequency	KOLMOGOROV - Shirnov Statistic
1	.00000	. 53380	9.00000	.10345	.10345	.01743	.01743	.08602
2	.53380	.81050	15.00000	, 17241	.27586	.24699	.26442	.01144
3	.81060	1.08740	16,00000	.18371	. 45977	.16973	,43414	.02563
4	1.03740	1.36420	15.00000	.17241	.63218	.15421	.58835	.04383
5	1.36420	1.64100	5.00000	.05747	.68966	, 12485	.71320	.02355
6	1.64100	1,91780	10.00000	.11494	.80460	.09367	.80688	.00228
7	1,91780	2.19460	1.00000	.01149	.81609	.06659	.87346	.05737
8	2.19460	2,47140	8.08000	.09195	.90805	.04546	.91893	.01038
9	2.47140	2.74820	1.00000	,01149	.91954	.03009	.94901	.02947
10	2.74820	3.02500	7.00000	.08045	1.00000	.01942	.96843	.03157

THE KOLMOGOROV - SMIRNOV STATISTIC - .08602

PEGREES	OF	FREEDOM=	10		
агьна=		3.1829	27132	BETA=	,420165420

BREAKDOWN LENGTH

ORDERED DATA

,006	.006	.006	.007	.003
.008	.009	.009	.009	.009
.009	.009	.009	.010	.010
.010	.010	.010	.011	.011
.012	.012	.012	.012	.012
.012	.012	.013	.013	.014
.014	.014	.014	.014	.014
.014	.015	.015	.015	.015
.016	.017	,017	.020	.021



HYPOTHESIS STATEMENT

NULL HYPOTHESIS= POPULATION IS NORMAL WITH TRUE MEAN= .0119 ALTERNATIVE HYPOTHESIG= POPULATION IS NOT NORMAL WITH TRUE MEAN= .0119

-

NUMBER OF OBSERVATIONS= 45

KOLMOGOROV – SMIRNOV TEST

.

CELLS	RANGE FROM	OBSERVED TO	OBSERVED FREQUENCY	CUMULATIVE Observed Frequency	THEORETICAL FREQUENCY	CUMULATIVE THEORETICAL FREQUENCY	KOLMOGOROV – Smirnov Statistic
1 2 3 4 5 5 5 5 7 8 7 8 9 10	999.99902 .00750 .01050 .01200 .01350 .01500 .01500 .01650 .01800 .01950	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$.08889 .28389 .40000 .60000 .64444 .83389 .91111 .95556 .95556 1.00000	.04433 .15748 .14221 .14680 .16650 .13348 .09226 .05262 .02475 .00967	.04433 .20181 .34402 .51281 .67931 .81579 .90875 .96136 .98611 .99578	.04456 .08706 .05598 .08719 .03487 .07310 .00236 .00561 .03055 .00422

THE KOLMOGOROV - SMIRNOV STATISTIC = .08719

.

DEGREES	0F	FREEDOM=	10		
hiU=		.011888888) SIGMA	2=	

APPENDIX B

PRESENT SYSTEM SLAM ATTRIBUTES,

LISTING, AND NETWORK

ATTRIBUTE DESCRIPTION OF PRESENT SYSTEM

Attribute

•

Description

1 2 3 4	Type of Operation Caustic Dipping Cold Water Dipping Acid Dipping
5	Acid Soak
6	Hot Water Dipping
7	Phosphate Dipping
8	Neutralizer Dipping
9	Soap Dipping
10	Drying
11	Breakdown Time
12	Breakdown Length
13	Time an Entity Starts in the System
14	Tons/Trip

```
GEN, J. R. LEWIS, TANKS, 1/04/84, 10;
LIMITS, 2, 14, 100;
1
2
3
   INIT,0,360;
    INTLC, XX(1)=0;
4
    INTLC,XX(2)=0;
5
    TIMST,XX(1),NUMBER IN SYS. 1;
TIMST,XX(2),NUMBER OF BRKDWNS.;
6
7
    TIMST, XX(3), TON OUTPUT, ;
8
9
    NETWORK;
10
           GATE/CR1, OPEN, 1;
           CREATE:
11
    ST
           GOON, 1;
12
13
           ACT,,.89,LUB;
           ACT,,.043,PHO;
14
           ACT,,.067,TRI;
15
16
    LUB
           ASSIGN, ATRIB(1)=1;
           ACT...TAN;
17
           ASSIGN, ATRIB(1)=2;
    PHO
18
19
           ACT, ., TAN;
           ASSIGN, ATRIB(1)=3;
    TRI
20
           ACT,,,TAN;
21
           ASSIGN, ATRIB(2)=2*RNORM(.014,.0035,1);
22
    TAN
           ASSIGN, ATRIB(3)=RNDRM(.0119,.0035,2);
23
           ASSIGN, ATRIB(4)=2*RNORM(.0139,.0034,3);
24
           ASSIGN,ATRIB(5)=RNORM(.1989,.0406,4);
ASSIGN,ATRIB(5)=RNORM(.012,.0034,5);
25
26
           ASSIGN,ATRIB(7)=2*RNORM(.0145,.0048,6);
27
           ASSIGN, ATRIB(8)=RNORM(.0159,.00384,7);
28
           ASSIGN, ATRIB(9)=2*RNDRM(.0139,.00346,8);
29
           ASSIGN, ATRIB(10)=EXPON(.1673,9);
30
            ASSIGN, ATRIB(13)=TNOW;
31
            ASSIGN, ATRIB(14)=GAMMA(.42017,3.18293,5);
32
33
            ACT;
           GOON:
34
            ACT, 198+ATRIB(2);
                                                         CAUSTIC DIP AND SOAK
35
36
            AWAIT, CR1;
                                                         COLD WATER RINSE
            ACT,.00083+ATRIB(3);
37
            AWAIT, CR1;
38
                                                         ACID DIP AND SOAK
            ACT..00125+ATRIB(4)+ATRIB(5);
39
            AWAIT, CR1;
40
            ACT, 00125+ATRIB(3);
                                                         COLD WATER RINSE
41
42
            AWAIT, CR1;
                                                         HOT WATER RINSE
            ACT, .005+ATRIB(6);
43
            AWAIT, CR1, 1;
44
            ACT, ATRIB(1).EQ.3,T;
45
                                                         PHOSPHATE
            ACT, .0852+ATRIB(7);
46
47
            AWAIT, CR1;
            ACT, .0019+ATRIB(3);
                                                         COLD WATER RINSE
48
            AWAIT, CR1, 1;
49
            ACT,,ATRIB(1).EQ.2,P;
50
                                                         NEUTRALIZER
            ACT, .0006+ATRIB(8);
51
            AWAIT, CR1;
52
                                                         SOAP
            ACT, .085+ATRIB(9), ,DRY;
53
    Т
54
            GOON;
                                                         TRICK
            ACT, .0058, ,DRY;
55
     Ρ
            GOON:
56
                                                          PHOSPHATE
            ACT, .0021, .DRY;
57
            AWAIT, CR1;
58
    DRY
59
            ACT, .04;
            AWAIT, CR1, 2:
60
            ACT., EN:
ACT, 0158;
61
62
```

÷

_

63		AWAIT, CR1:	
64		COLCT, INT(13), TANK TIME, 15/.5/	1.
65		ACTST:	••
66	EN	GOON:	
67		ACT, ATRIB(10):	
68		COLCT, INT(13), TOTAL TIME, 15/.5/	. 1:
69		ASSIGN, $XX(1) = XX(1) + 1$:	
70		ASSIGN, $XX(3) = XX(3) + ATRIB(14)$:	
71		TERM;	
72		CREATE;	NETWORK TO RUN BREAKDOWNS
73	SH	GOON, 1;	
74		ACT., 83,GD;	
75		ACT, 17, DN;	DETERMINE IF BRKDWN OCCUPS
76	GD	GOON;	
77		ACT, 12, , SH;	
78	DN	ASSIGN, ATRIB(11)=UNFRM(0, 12, 10)	:
79		ASSIGN, ATRIB(12)=EXPON(1,023,9)	
80		ASSIGN, XX(2) = XX(2) + 1.1:	,
81		ACT, ATRIB(11);	
82		CLOSE, CR1;	
83		GOON, 1;	
84		ACT., ATRIB(11)+ATRIB(12).GT. 12.8	
85		ACT, ATRIB(12);	~
86		OPEN, CR1;	
87		ACT, 12-ATRIB(11)-ATRIB(12), SH;	
88	ε	GOON;	
89		OPEN, CR1;	•
90		ACT,,,SH;	
91		END;	
92	FIN;		



.



-



æ .















APPENDIX C

۰.

TWO CRANE ONE OPERATOR SLAM ATTRIBUTES,

LISTING, AND NETWORK

ATTRIBUTE DESCRIPTION OF TWO CRANE ONE OPERATOR MODEL

•

Attribute

Description

1 2 3 4 5 6 7	Type of Operation, Crane 1 Caustic Dipping, Crane 1 Cold Water Dipping, Crane 1 Acid Dipping, Crane 1 Acid Soak, Crane 1 Hot Water Dipping, Crane 1 Phosphate Dipping, Crane 1
8	Neutralizer Dipping, Crane 1
9	Soap Dipping, Crane 1
10	Drying, Crane 1
11	Breakdown Time, Crane 1
12	Breakdown Length, Crane l
13	Type of Operation, Crane 2
14	Caustic Dipping, Crane 2
15	Cold Water Dipping, Crane 2
16	Acid Dipping, Crane 2
17	Acid Soak, Crane 2
18	Hot Water Dipping, Crane 2
19	Phosphate Dipping, Crane 2
20	Neutralizer Dipping, Crane 2
21	Soap Dipping, Crane 2
22	Drying, Crane 2
23	Breakdown Time, Crane 2
24	Breakdown Length, Crane 2
25	Time Entity Starts in System, Crane 1
26	Time Entity Starts in System, Crane 2
29	Tons/Trip, Crane l
30	Tons/Trip, Crane 2

1	GEN,	J. R. LEWIS. TANKS, 1/04/84 10.			
2	LIMI	ITS, 11, 30, 10:			
3	INIT	T.0.360:			
4	INTL	LC.XX(1)=0			
5	INTI	$C_{X}(2)=0$			
Ē	TNITI	(2) - 0,			
7	TIMO	$= (1, A \land (3) = 0)$			
,	TIMO	T XX(1), NUMBER IN STS. 1;			
ŝ	11003	ST, XX(2), NUMBER OF BRKDWNS.;			
9	TIMS	ST, XX(3), NUMBER OF BRKDWNS IN SYS 2;			
10	TIMS	ST, XX(4), TON OUTPUT;			
11	NETW	VORK;			
12		GATE/CR1, OPEN, 1;			
13		GATE/CR2. OPEN. 2:			
14		GATE/MOV.CLOSE.3:			
15		GATE/SC2 CLOSE 4			
16		GATE/C2 OPEN 5.			
17		GATE/P2 OPEN C.			
18		GATE/F2, OPEN 7			
10		GATE/SO2.UPEN,/;			
20		GATE/SCI, UPEN, 8;			
20		GATE/ACID, OPEN, 9;			
21		GATE/PAS1, OPEN, 10;			
22		GATE/PAS2, OPEN, 11;			
23		CREATE;			
24	ST	GOON, 1;			
25		ACT89.LUB:			
26		ACT 043 . PHO:			
27		ACT			
28	LUB	ASSIGN ATRIR(1)-1.			
29		ACT TAN.			
30	рно	ASSIGN ATDID(4)-0			
24	FILU	ASSIGN, AIRIB $(1)=2$;			
20	-	ACT, , , IAN;			
32	IRI	ASSIGN, ATRIB(1)=3;			
33		ACT,,,TAN;			
34	TAN	ASSIGN, ATRIB(2)=2*RNORM(.0140035.1)	•		
35		ASSIGN, ATRIB(3)=RNORM(.0119.0035.2)	•		
36		ASSIGN, ATRIB(4)=2*RNORM(.0139 0034 3) .		
37		ASSIGN, ATRIB(5)=RNORM(1989 0406 4).			
38		ASSIGN, ATRIB(6)=RNOPM(012 0024 E)			
39		ASSIGN ATRIB(7) = 2*PNOPM(0145 0049)	、		
40		ASSIGN ATRIB(9)-PNORM(0450 00004 7));		
41		ASSIGN ATRIB(0)-0*0N00M(0199, 00384, /)	:		
42		ASSIGN, ATRIB(9) = 2 - RNURM(.0139,.00346, ASSIGN, ATRIB(40) = 5 - 5 - 5 - 5 - 5 - 5 - 5 - 5 - 5 - 5	8);		
43		ASSIGN, ATRIB(10) = EXPUN(.1673,9);			
10		ASSIGN, ATRIB(25)=INUW;			
44		ASSIGN, A(RIB(29)=GAMMA(.42017,3.18293	,5);		1
40		AWAII, SC1;			
46		ACT;			
47		CLOSE, SC2;			
48		ACT, 114+ATRIB(2);			
49		AWAIT, CR1:			
50		OPEN. SC2:			
51		CLOSE C2:			
52		ACT 083	~		
53		AWAIT CP1.	CAUS	FIC SO	AK
54		AWATT SC1.			
55					
50		OPEN CO.			
57		UFEN, 62;			
57		AU1, .00083+ATRIB(3);	COLD	WATER	RINSE
38		AWAIT, CR1;			
59		ACT, .00125+ATRIB(4);	ACID	DIP A	ND SOAK
60		OPEN, SC2;			JUAN
61		CLOSE, ACID;			
62		ACT, ATRIB(5):			

÷

63 64 65 66		AWAIT,SC1; CLOSE,SC2; AWAIT,CR1; ACT00125+AT2IB(3);	COL
67		AWAIT, CR1;	0021
68		ACT, .005+ATRIB(6);	нот
69 70		OPEN,ACID; CLOSE DAS1:	
71		AWAIT.CR1.1:	
72		ACT,,ATRIB(1).EQ.3,T;	
73		ACT, .0019+ATRIB(7);	
75		AWAII, CRT; OPEN SC2.	
76		CLOSE, P2;	
77		ACT, .083;	PHOS
78		AWAIT, CR1;	
80		AWAIT.SC1:	
81		CLOSE, SC2;	
82		ACT, .0019+ATRIB(3);	COLD
83 84		CLOSE, PAS2;	
85		ACT. ATRIB(1).EQ.2.P:	
86		ACT, .0006+ATRIB(8);	NEU1
87		AWAIT, CR1;	
88		ACI, OOI/HAIRIB(9);	SOAF
90		OPEN, SC2;	
91		CLOSE, SO2;	
92		ACT, .083;	SOAF
94		ACTDRY:	
95	т	GOON;	
96		ACT, .0058;	TRIC
97		AWAIT, CR1; OPEN SC2;	
99		ACTDRY:	
100	Ρ	GOON;	
101		ACT, .0021;	PHOS
102		AWALF,CR1; Open Sc2.	
104		ACT, DRY;	
105	DRY	GOON;	
106		OPEN, PAS1;	
108		ACT. 04:	
109		AWAIT, CR1;	
110		OPEN, 502;	
111		AWAIT,SC1; CLOSE SC2;	
113		OPEN. SC2:	
114		COLCT, INT(25), TANK TIME SYS 1, 15/.5/.	1;
115		GOON, 2;	
110		ACT:	
118		AWAIT, MOV;	
119		CLOSE, SC2;	
120		CLUSE,MOV; ACT 0158	
122		AWAIT.CR1:	
123		ACT,,,ST;	
124	EN	GOON;	
125		COLCT.INT(25).TOTAL TIME SYS 1 15/ 5/	1.1.
127	OUT	ASSIGN, XX(1)=XX(1)+1;	• • •
128		ASSIGN,XX(4)=XX(4)+ATRIB(29)+ATRIB(30);

COLD WATER RINSE HOT WATER RINSE

PHOSPHATE SOAK

COLD WATER RINSE

NEUTRALIZER

SOAP

SOAP SOAK

TRICK

PHOSPHATE

129 TERM; 130 CREATE; NETWORK TO RUN BREAKDOWNS 131 SH GOON, 1; 132 ACT.,.83,GD; 133 ACT, .. 17, DN; DETERMINE IF BRKDWN OCCURS 134 GD GOON: 135 ACT, 12,, SH; DN ASSIGN, ATRIB(11)=UNFRM(0, 12, 10); 136 137 ASSIGN, ATRIB(12)=EXPON(1.023,9); ASSIGN, XX(2)=XX(2)+1, 1; 138 139 ACT, ATRIB(11); 140 CLOSE, CR1; 141 ACT, ATRIB(12); 142 OPEN, CR1; ACT, 12-ATRIB(11)-ATRIB(12), , SH; 143 144 CREATE: 145 ST2 GOON, 1; ACT,,.89,LU2; 146 147 ACT., .043, PH2; 148 ACT, .. 067, TR2; LU2 149 ASSIGN, ATRIB(13)=1; 150 ACT, , , TA2; ASSIGN, ATRIB(13)=2; 151 PH2 152 ACT,,,TA2; 153 TR2 ASSIGN, ATRIB(13)=3; 154 ACT,,,TA2; 155 TA2 ASSIGN, ATRIB(14)=2*RNORM(.014,.0035,1); 156 ASSIGN, ATRIB(15)=RNORM(.0119,.0035,2); 157 ASSIGN, ATRIB(16)=2*RNORM(.0139,.0034,3); ASSIGN, ATRIB(17)=RNORM(.1989,.0406,4); 158 159 ASSIGN, ATRIB(18)=RNORM(.012,.0034,5); 160 ASSIGN, ATRIB(19)=2*RNORM(.0145,.0048,6); 161 ASSIGN, ATRIB(20)=RNORM(.0159,.00384,7); 162 ASSIGN,ATRIB(21)=2*RNORM(.0139,.00346,8); 163 ASSIGN, ATRIB(22)=EXPON(.1673,9); 164 ASSIGN, ATRIB(26)=TNOW; ASSIGN, ATRIB(30)=GAMMA(.42017,3.18293,5); 165 166 AWAIT, SC2; 167 CLOSE, SC1; 168 ACT..114; AWAIT, CR2; 169 170 OPEN, SC1; AWAIT, C2; 171 AWAIT, SC2; CLOSE, SC1; 172 173 174 ACT.ATRIB(14): 175 GOON; 176 ACT, .083; CAUSTIC 177 OPEN, SC1; 178 AWAIT, CR2; AWAIT, ACID; 179 180 AWAIT, SC2; CLOSE, SC1; 181 182 ACT,.00083+ATRIB(15); COLD WATER RINSE 183 AWAIT, CR2; ACT, .00125+ATRIB(16); OPEN, SC1; 184 ACID DIP AND SOAK 185 186 ACT, ATRIB(17); AWAIT, SC2; 187 CLOSE, SC1; 188 189 AWAIT, CR2; 190 ACT, .00125+ATRIB(15); COLD WATER RINSE 191 AWAIT, CR2; 192 ACT, .005+ATRIB(18); HOT WATER RINSE AWAIT, CR2, 1; 193 194 ACT, ATRIB(13).EQ.3,T2;

195		ACT;	
196		AWAIT, P2;	9
197		AWAIT, SC2;	
198		CLOSE, SC1;	
199		ACT, .0019+ATRIB(19);	PHOSPHATE
200		AWAIT, CR2;	
201		OPEN, SC1;	
202		ACT,.083;	PHOSPHATE SOAK
203		AWAIT, CR2;	
204		AWAIT, SC2;	
205		CLOSE, SC1;	
206		ACT,.0019+ATRIB(15);	COLD WATER RINSE
207		AWAIT, CR2, 1;	
208		ACT,,ATRIB(13).EQ.2,PP;	
209		ACT, .0006+ATRIB(20);	NEUTRALIZER
210		OPEN, SC1;	
211		AWAIT, CR2;	
212		AWAIT, SO2;	
213		AWAIT, SC2;	
214		CLOSE, SC1;	594 9
215		ACT, .0017+ATRIB(21);	SUAP
216		AWAIT, CR2;	
217		OPEN, SC1;	SOAD SOAK
218		ACT, .083;	SUAP SUAK
219		AWAII, CR2;	
220		ACT,,,UR2;	
221	12	GUUN;	
222		UPEN, SUI;	
223		AWAIT COD	
224		AWA11,502; CLOSE 501.	
225			TRICK
226		AU1, .0038;	IRICA
227		AWALI, UKZ; ODEN SC1.	
220		ACT DD2.	
223	00	AC1,,,DK2, COON+	
230	FF	ODEN SC1.	
231		AWATT DAS2.	
232		AWAIT SCO.	
234			
235		ACT 0021:	PHOSPHATE
236		AWAIT CR2:	
237		OPEN. SC1:	
238		ACT DR2.	
239	DR2	GOON:	
240	0	AWAIT.SC2:	
241		CLOSE, SC1:	
242		ACT04:	
243		AWAIT.CR2:	
244		OPEN. SC1:	•
245		COLCT. INT(26). TANK TIME SYS 2. 15/.5/.1:	
246		GOON, 2:	
247		ACT E2:	
248		ACT:	
249		OPEN, MOV;	
250		ACT, ST2:	
251	E2	GOON:	
252		ACT, ATRIB(22);	
253	•	COLCT, INT(26), TOTAL TIME SYS 2, 15/.5/.	1;
254		ACT,,,OUT;	
255		CREATE; NETWORK	K TO RUN BREAKDOWNS
256	SH2	GOON, 1;	
257		ACT,,.83,GD2;	
258		ACT.,.17,DN2; DETER	WINE IF BRKDWN OCCURS
259	GD2	GOON;	
260		ACT, 12,,SH2;	

•

261	DN2	ASSIGN,ATRIB(27)=UNFRM(0,12,10):
262		ASSIGN, ATRIB(28)=EXPON(1.023.9):
263		ASSIGN, XX(3) = XX(3) + 1, 1;
264		ACT, ATRIB(27):
265		CLOSE, CR2;
266		ACT, ATRIB(28);
267		OPEN, CR2:
268		ACT, 12-ATRIB(27)-ATRIB(28)SH2:
269		END;
270	FIN;	

٠.,


				Real Property lies and statements		
CR1	OPEN	1		S02	OPEN	7
CR2	OPEN	2		SC1	OPEN	8
MOV	CLOSE	3		ACID	OPEN	9
SC2	CLOSE	4		PAS1	OPEN	10
C2	OPEN	<u></u> 5	1	PAS2	OPEN	11
P2	OPEN	6				











.









•







.







,





APPENDIX D

TWO CRANE TWO OPERATOR SLAM ATTRIBUTES, LISTING, AND NETWORK

ATTRIBUTE DESCRIPTION OF TWO CRANE TWO OPERATOR MODEL

Attribute

Description

1	Type of Operation
2	Caustic Dipping
3	Cold Water Dipping
4	Acid Dipping
5	Acid Soak
6	Hot Water Dipping
7	Phosphate Dipping
8	Neutralizer Dipping
9	Soap Dipping
10	Drying
11	Breakdown Time, Crane 1
12	Breakdown Length, Crane 1
13	Time an Entity Starts in the System
14	Breakdown Time, Crane 2
15	Breakdown Length, Crane 2
16	Tons/Trip

GEN, J. R. LEWIS, TANKS, 1/04/84, 10; 1 LIMITS, 4, 16, 10; 2 з INIT,0,360; 4 INTLC,XX(1)=0; 5 INTLC,XX(2)=0: INTLC,XX(3)=0; TIMST,XX(1),NUMBER IN SYS. 1; 6 7 TIMST, XX(2), NUMBER OF BRKDWNS.; 8 9 TIMST, XX(3), NUMBER OF BRKDOWNS 2; 10 TIMST, XX(4), TON OUTPUT; NETWORK; 11 RESOURCE/WC1,2; 12 RESOURCE/WC2,3; 13 14 GATE/CR1, OPEN, 1; 15 GATE/CR2, OPEN, 4; CREATE; 16 17 ST GOON, 1; 18 ACT., .89,LUB; 19 ACT.,.043,PHO; 20 ACT,,.067,TRI; 21 LUB ASSIGN, ATRIB(1)=1; 22 ACT,,,TAN; ASSIGN,ATRIB(1)=2; PHO 23 ACT,,,TAN: ASSIGN,ATRIB(1)=3; 24 25 TRI 26 ACT,...TAN; 27 TAN ASSIGN, ATRIB(2)=2*RNORM(.014,.0035,1); ASSIGN, ATRIB(3)=RNORM(.0119,.0035,2); 28 ASSIGN,ATRIB(4)=2*RNORM(.0139,.0034,3); 29 30 ASSIGN, ATRIB(5)=RNORM(.1989,.0406,4); ASSIGN, ATRIB(6)=RNORM(.012,.0034,5); 31 32 ASSIGN, ATRIB(7)=2*RNORM(.0145,.0048,6); 33 ASSIGN, ATRIB(8)=RNORM(.0159,.00384.7); 34 ASSIGN, ATRIB(9)=2*RNORM(.0139,.00346,8); ASSIGN, ATRIB(10)=EXPON(.1673,9); 35 36 ASSIGN, ATRIB(13)=TNOW; ASSIGN, ATRIB(16)=GAMMA(.42017,3.18293,5); 37 38 ACT; 39 GOON; 40 ACT, 198+ATRIB(2); CAUSTIC DIP AND SOAK 41 AWAIT, CR1; ACT, .00083+ATRIB(3); COLD WATER RINSE 42 43 AWAIT, CR1; ACT, .00125+ATRIB(4)+ATRIB(5); 44 ACID DIP AND SOAK 45 AWAIT, CR1; 46 ACT, .00125+ATRIB(3); COLD WATER RINSE 47 AWAIT, CR1; AWAIT, WC1; 48 49 ACT, .033; GOON, 2; 50 ACT, .00871, .ST; 51 52 ACT: 53 AWAIT, WC2; ACT, .033+.005+ATRIB(6); 54 55 FREE, WC1; 56 AWAIT, CR2, 1; ACT, , ATRIB(3).EQ.3,T: 57 ACT, .0852+ATRIB(7); 58 PHOSPHATE 59 AWAIT, CR2; ACT, .0019+ATRIB(3); COLD WATER RINSE 60 ÷., AWAIT, CR2, 1; 61 ACT,,ATRIB(1).EQ.2,P; 62

63		ACT,.0006+ATRIB(8);	NEUTRALIZER
64 65		AWAII,CR2; ACT. 085+ATRIB(9) DRY:	SUVB
66	т	GOON;	JUAF
67	-	ACT, .0058, ,DRY;	TRICK
68 69	Р	GUUN; ACT 0021 DBY:	DHOSPHATE
70	DRY	AWAIT, CR2;	PRUSPRATE
71		ACT, .04;	
72		AWAIT, CR2, 2;	
73		ACT, ,, EN;	
75		AWAIT.CR2:	
76		COLCT, INT(13), TANK TIME, 15/.5/.	1:
77		ACT,.0158;	
78		FREE, WC2;	
79 80	EN	IERM; GOON-	
81		ACT.ATRIB(10):	
82		COLCT, INT(13), TOTAL TIME, 15/.5/	.1;
83		ASSIGN, XX(1) = XX(1) + 1;	
84		ASSIGN,XX(4)=XX(4)+ATRIB(16);	
86		CREATE	NETWORK TO PUN REAKDOWNS
87	SH	GOON, 1;	NETWORK TO KOR SKEAKDOWAS
88		ACT,,.83,GD;	• •
89	00	ACT, , . 17, DN;	DETERMINE IF BRKDWN OCCURS
90	GU	GUUN; ACT 12 SH-	
92	DN	ASSIGN.ATRIB(11) = UNFRM(0, 12, 10)	
93		ASSIGN, ATRIB(12)=EXPON(1.023,9)	;
94		ASSIGN, XX(2)=XX(2)+1,1;	
95		ACT, ATRIB(11);	
90		ACT ATPIR(11)+ATPIR(12) GT 12	E •
98		ACT.ATRIB(12):	-,
99		OPEN, CR1;	
100	-	ACT, 12-ATRIB(11)-ATRIB(12), , SH;	
101	E	GUON:	
102		ACTSH:	
104		CREATE;	NETWORK TO RUN BREAKDOWNS
105	SH2	GOON, 1;	
106		ACT,	
107	602	ACT,,.17,DN2; GOON:	DETERMINE IF BRKDWN OCCURS
109	002	ACT. 12 SH2:	
110	DN2	ASSIGN, ATRIB(14)=UNFRM(0, 12, 10)	;
111		ASSIGN, ATRIB(15)=EXPON(1.023,9)	;
112		ASSIGN, XX(3) = XX(3) + 1, 1;	
114		CLOSE.CR2:	
115		ACT,,ATRIB(14)+ATRIB(15).GT.12,	EE;
116		ACT, ATRIB(15);	
117	•	OPEN, CR2;	
110	FF	ACT, 12-ATRIB(14)-ATRIB(15), , SH2	
120		OPEN.CR2:	
121		ACT, , , SH;	
122		END;	
123	FIN;		



CR1	OPEN	1	WC1(1)	3
CRŻ	OPEN	4	WC2(1)	4

۰.



.







THIP CH. EQ.2 Ĵ

િ











,



APPENDIX E

OUTPUT OF PRESENT SYSTEM MODEL

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 1 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	Value	DEVIATION	VARIATION	VALUE	VALUE	Observations
TANK TIME	0.8124E+00	0.6126E-01	0.7541E-01	0.6025E+00	0.1336E+01	443
TOTAL TIME	0.9637E+00	0.1812E+00	0.1880E+00	0.6467E+00	0.2792E+01	442

****STATISTICS FOR TIME-PERSISTENT VARIABLES****

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	VALUE	DEVIATION	VALUE	VALUE	Interval	VALUE
NUMBER IN SYS. 1	0.2209E+03	0.1280E+03	0.0000E+00	0.4420E+03	0.3600E+03	0.4420E+03
NUMBER OF BRKDWN	0.3076E+01	0.1244E+01	0.0000E+00	0.5000E+01	0.3600E+03	0.5000E+01
TON OUTPUT	0.2985E+03	0.1687E+03	0.0000E+00	0.5890E+03	0.3600E+03	0.5890E+03

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0024	0.0490	1	0	0 0002
2		0.0000	0.0000	Ó	ŏ	0.0000
3	CALENDAR	2.2023	0.4130	4	3	0.1041

****GATE STATISTICS****

i -

GATE	GATE	CURRENT.	PCT. OF	
NUMBER	LABEL	STATUS	TIME OPEN	
1	CR 1	OPEN	0.9965	

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 2 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN VALUE	STANDARD DEVIATION	COEFF. OF VARIATION	MINIMUM VALUE	MAXIMUM VALUE	NUMBER OF OBSERVATIONS
TANK TIME	0.8228E+00	0.1782E+00	0.2166E+00	0.6231E+00	0.3733E+01	437
TOTAL TIME	0.9757E+00	0.1959E+00	0.2008E+00	0.7017E+00	0.2656E+01	437

****STATISTICS FOR TIME-PERSISTENT VARIABLES****

	MEAN VALUE	STANDARD Deviation	MINIMUM VALUE	MAXIMUM VALUE	TIME Interval	CURRENT VALUE
NUMBER IN SYS. 1	0.2182E+03	0.1275E+03	0.0000E+00	0.4370E+03	0.3600E+03	0.4370E+03
NUMBER OF BRKDWN	0.1900E+01	0.1012E+01	0.0000E+00	0.4000E+01	0.3600E+03	0.4000E+01
TON OUTPUT	0.2956E+03	0.1746E+03	0.0000E+00	0.5997E+03	0.3600E+03	0.5997E+03

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0172	0.1301	1	ο	0.0013
2		0.0000	0.0000	0	ο.	0.0000
3	CALENDAR	2.1950	0.4422	4	2	0.1051

****GATE STATISTICS****

GATE	GATE	CURRENT	PCT OF	
NUMBER	Label	STATUS	TIME OPEN	
1	CR 1	OPEN	0.9821	

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 3 OF 10

.

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	Value	DEVIATION	VARIATION	VALUE	VALUE	Observations
TANK TIME	0.8303E+00	0.2452E+00	0.2953E+00	0.6283E+00	0.3793E+01	433
TOTAL TIME	0.9622E+00	0.2777E+00	0.2886E+00	0.6746E+00	0.3828E+01	433

STATISTICS FOR TIME-PERSISTENT VARIABLES

•	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	Value	DEVIATION	VALUE	VALUE	INTERVAL	VALUE
NUMBER IN SYS. 1	0.2182E+03	0.1247E+03	0.0000E+00	0.4330E+03	0.3600E+03	0.4330E+03
NUMBER OF BRKDWN	0.1933E+01	0.1482E+01	0.0000E+00	0.5000E+01	0.3600E+03	0.5000E+01
Ton Output	0.2752E+03	0.1573E+03	0.0000E+00	0.5576E+03	0.3600E+03	0.5576E+03

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0304	0.1716	1	0	0.0000
3	CALENDAR	0.0000 2.1467	0.0000 0.4337	0 3	0	0.0023
	GATE STA	TISTICS			2	0.1037

CURRENT	PCT.	OF
STATUS	TIME	OPEN
	CURRENT STATUS	CURRENT PCT. STATUS TIME

1 CR1 OPEN 0.9687

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 4 OF 10

1

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	VALUE	DEVIATION	Variation	VALUE	VALUE	Observations
TANK TIME	0.8107E+00	0.1099E+00	0.1356E+00	0.6395E+00	0.2559E+01	444
TOTAL TIME	0.9413E+00	0.1804E+00	0.1916E+00	0.6375E+00	0.2554E+01	443

****STATISTICS FOR TIME-PERSISTENT VARIABLES****

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	VALUE	Deviation	VALUE	VALUE	Interval	VALUE
NUMBER IN SYS. 1	0.2223E+03	0.1281E+03	0.0000E+00	0.4430E+03	0.3600E+03	0.4430E+03
NUMBER OF BRKDWN	0.2772E+01	0.2050E+01	0.0000E+00	0.7000E+01	0.3600E+03	0.7000E+01
TON OUTPUT	0.3108E+03	0.1779E+03	0.0000E+00	0.6217E+03	0.3600E+03	0.6217E+03

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0080	0.0888	1	0	0.0006
2		0.0000	0.0000	0	ō	0.0000
3	CALENDAR	2.1716	0.4008	4	3	0.1024

****GATE STATISTICS****

GATE	GATE	CURRENT	PCT.	OF
NUMBER	LABEL	STATUS	TIME	OPEN

1 CR1 OPEN 0.9907
SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984 RUN NUMBER 5 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

• .

****STATISTICS FOR VARIABLES BASED ON OBSERVATION****

	MEAN VALUE	STANDARD DEVIATION	COEFF. OF VARIATION	MINIMUM VALUE	MAXIMUM VALUE	NUMBER OF Observations
TANK TIME	0.8291E+00	0.2331E+00	0.2812E+00	0.6207E+00	0.3886E+01	434
TOTAL TIME	0.9779E+00	0.3025E+00	0.3094E+00	0.6733E+00	0.4074E+01	433

****STATISTICS FOR TIME-PERSISTENT VARIABLES****

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	Value	DEVIATION	VALUE	VALUE	INTERVAL	VALUE
NUMBER IN SYS. 1	0.2175E+03	0.1243E+03	0.0000E+00	0.4330E+03	0.3600E+03	0.4330E+03
NUMBER OF BRKDWN	0.3168E+01	0.2698E+01	0.0000E+00	0.7000E+01	0.3600E+03	0.7000E+01
TON OUTPUT	0.2977E+03	0.1740E+03	0.0000E+00	0.5930E+03	0.3600E+C3	0.5930E+03

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0270	0.1621	1	0	0.0020
2		0.0000	0.0000	0	0	0.0000
3	CALENDAR	2.1709	0.4469	4	3	0.1046

****GATE STATISTICS****

GATE	GATE	CURRENT	PCT. OF
NUMBER	LABEL	STATUS	TIME OPEN
t	CR 1	OPEN	0.9706

SIMULATION PROJECT TANKS	BY J. R. LEWIS	
DATE 1/ 4/1984	RUN NUMBER 6 OF	10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

****STATISTICS FOR VARIABLES BASED ON OBSERVATION****

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	Value	DEVIATION	VARIATION	Value	VALUE	Observations
TANK TIME	0.8154E+00	0.1074E+00	0.1317E+00	0.5873E+00	0.2359E+01	44 1
TOTAL TIME	0.9669E+00	0.1914E+00	0.1979E+00	0.6018E+00	0.2467E+01	44 1

****STATISTICS FOR TIME-PERSISTENT VARIABLES****

	MEAN VALUE	STANDARD DEVIATION	MINIMUM	MAXIMUM VALUE	TIME Interval	CURRENT VALUE
NUMBER IN SYS. 1	0.2201E+03	0.1272E+03	0.0000E+00	0.4410E+03	0.3600E+03	0.4410E+03
NUMBER OF BRKDWN	0.2567E+01	0.1499E+01	0.0000E+00	0.4000E+01	0.3600E+03	0.4000E+01
TON OUTPUT	0.3111E+03	0.1800E+03	0.0000E+00	0.6165E+03	0.3600E+03	0.6165E+03

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0093	0.0959	1	0	0.0007
2		0.0000	0.0000	0	0	0.0000
3	CALENDAR	2.1950	0.4233	4	2	0.1042

****GATE STATISTICS****

GATE	GATE	CURRENT	PCT.	OF	
NUMBER	LABEL	STATUS	TIME	OPEN	

1 CR1 OPEN 0.9900

173

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 7 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	VALUE	DEVIATION	VARIATION	VALUE	Value	Observations
TANK TIME	0.8155E+00	0.1357E+00	0.1664E+00	0.5966E+00	0.3069E+01	441
TOTAL TIME	0.9761E+00	0.2214E+00	0.2268E+00	0.5904E+00	0.3290E+01	441

STATISTICS FOR TIME-PERSISTENT VARIABLES

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	Value	DEVIATION	VALUE	Value	Interval	VALUE
NUMBER IN SYS. 1	0.2211E+03	0.1273E+03	0.0000E+00	0.4410E+03	0.3600E+03	0.4410E+03
NUMBER OF BRKDWN	0.1733E+01	0.1482E+01	0.0000E+00	0.4000E+01	0.3600E+03	0.4000E+01
TON OUTPUT	0.2911E+03	0.1679E+03	0.0000E+00	0.5775E+03	0.3600E+03	0.5775E+03

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0123	0.1102	1	0	0.0009
2		0.0000	0.0000	Ó	ŏ	0,0000
3	CALENDAR	2.2031	0.4366	4	2	0.1046
	GATE ST	ATISTICS		•		
	0.175		T 05			

GATE NUMBER	GATE Label	STATUS	PCT. OF TIME OPEN	
1	CR 1	OPEN	0.9872	

SIMULATION PROJECT	TANKS	BY
--------------------	-------	----

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 8 OF 10

.

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	VALUE	Deviation	VARIATION	VALUE	VALUE	Observations
TANK TIME	0.8239E+00	0.1477E+00	0.1793E+00	0.5925E+00	0.2509E+01	436
TOTAL TIME	0.9714E+00	0.2126E+00	0.2189E+00	0.6758E+00	0.2499E+01	436

STATISTICS FOR TIME-PERSISTENT VARIABLES

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	VALUE	DEVIATION	VALUE	VALUE	Interval	VALUE
NUMBER IN SYS. 1	0.2187E+03	0.1262E+03	0.0000E+00	0.4360E+03	0.3600E+03	0.4360E+03
NUMBER OF BRKDWN	0.3300E+01	0.2492E+01	0.000.0E+00	0.8000E+01	0.3600E+03	0.8000E+01
TON OUTPUT	0.2971E+03	0.1737E+03	0.0000E+00	0.5938E+03	0.3600E+03	0.5938E+03

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0210	0.1435	1	0	0.0016
2		0.0000	0.0000	ò	õ	0.0000
3	CALENDAR	2.1761	0.4394	4	ž	0.1042
	GATE ST	ATISTICS				

GATE	GATE	CURRENT	PCT.	OF
NUMBER	LABEL	STATUS	TIME	OPEN

.

1 CR1 OPEN 0.9773

175

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 9 OF 10

.

٨

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	Value	DEVIATION	VARIATION	VALUE	VALUE	Observations
TANK TIME	0.8062E+00	0.5387E-01	0.6682E-01	Q.5956E+00	0.9220E+00	446
TOTAL TIME	0.9506E+00	0.1650E+00	0.1735E+00	0.6528E+00	0.1915E+01	446

****STATISTICS FOR TIME-PERSISTENT VARIABLES****

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	Value	Deviation	VALUE	VALUE	Interval	VALUE
NUMBER IN SYS. 1	0.2225E+03	0.1292E+03	0.0000E+00	0.4460E+03	0.3600E+03	0.4460E+03
NUMBER OF BRKDWN	0.0000E+00	0.0000E+00	0.0000E+00	0.0000E+00	0.3600E+03	0.0000E+00
TON OUTPUT	0.2849E+03	0.1630E+03	0.0000E+00	0.5713E+03	0.3600E+03	0.5713E+03

FILE STATISTICS

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0000	0.0000	0	0	0.0000
2		0.0000	0.0000	0	õ	0,0000
3	CALENDAR	2.1977	0 4024	4	2	0.1034
	GATE S	STATISTICS				

GATE	GATE	CURRENT	PCT. OF
NUMBER	LABEL	STATUS	TIME OPEN
1	CRI	OPEN	1.0000

·• . . .

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 10 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	Value	Deviation	VARIATION	VALUE	VALUE	Observations
TANK TIME	0.8097E+00	0.7790E-01	0.9621E-01	0.6215E+00	0.1688E+01	444
TOTAL TIME	0.9630E+00	0.1949E+00	0.2024E+00	0.6205E+00	0.2077E+01	444

****STATISTICS FOR TIME-PERSISTENT VARIABLES****

	MEAN VALUE	STANDARD DEVIATION	MINIMUM	MAXIMUM VALUE	TIME INTERVAL	CURRENT VALUE
NUMBER IN SYS. 1	0.2213E+03	0.1282E+03	0.0000E+00	0.4440E+03	0.3600E+03	0.4440E+03
NUMBER OF BRKDWN	0.2940E+01	0.2208E+01	0.0000E+00	0.6000E+01	0.3600E+03	0.6000E+01
TON OUTPUT	0.2930E+03	0.1612E+03	0.0000E+00	0.5670E+03	0.3600E+03	0.5670E+03

****FILE STATISTICS****

FILE	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD Deviation	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0056	0.0746	1	0	0.0004
2		0.0000	0,0000	Å	ŏ	0.0004
Э	CALENDAR	2 2024	0.4108	0	0	0.0000
	GATE S	STATISTICS	0.4190	4	2	0.1037

GATE	GATE	CURRENT	PCT.	OF	
NUMBER	LABEL	STATUS	Time	OPEN	

1 CR1 OPEN 0.9925

APPENDIX F

OUTPUT OF TWO CRANE ONE OPERATOR MODEL

•

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 1 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN			SHOLD ON DESE	RVATION**	
T 4 4 1 4 -	VALUE	STANDARD DEVIATION	COEFF. OF VARIATION		MAXIMUM	NUMBER OF
TANK TIME SYS 1 TOTAL TIME SYS 1	0.8981E+00 0.1064E+01	0.2038E+00	0.2269E+00	0 51225400	VALUE	OBSERVATIONS
TANK TIME SYS 2 TOTAL TIME SYS 2	0.9157E+00 0.1093E+01	0.2112E+00 0.2792E+00	0.2473E+00 0.2307E+00	0.5514E+00 0.4894E+00	0.3451E+01 0.3632E+01 0.3480E+04	389 389
		0.27022100	0.2555E+00	0.5238E+00	0.3942E+01	393 392

	MCAN			VARIABLI	=2**	
	VALUE	STANDARD DEVIATION	MINIMUM VALUE		TIME	CURRENT
NUMBER IN SYS. 1 NUMBER OF BRKDWN NUMBER OF BRKDWN TON OUTPUT	0.3892E+03 0.1633E+01 0.3933E+01 0.5217E+03	0.2270E+03 0.7063E+00 0.1750E+01 0.3014E+03	0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00	0.7810E+03 0.3000E+01 0.6000E+01 0.1046E+04	INTERVAL 0.3600E+03 0.3600E+03 0.3600E+03 0.3600E+03	VALUE 0.7810E+03 0.3000E+01 0.6000E+01 0.1046E+01
				0.10462+04	0.3600E+03	0.1046E+04

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1 2	AWAIT AWAIT	0.0070	0.0835	1	0	0.0005
3	AWAIT	0.0105	0.1022	1	0 0	0.0009
5	AWAIT	0.1163	0.3206 0.0000	1	0	0.0135
6 7	AWAIT AWAIT	0.0028 0.0037	0.0530	1	ŏ	0.0028
8 9	AWAIT AWAIT	0.1225	0.3279		0	0.0038
10	AWAIT	0.0005	0.0227	1	0	0.0162 0.0074
12	CALENDAR	4.0777	0.0000 0.6887	0 7	0 5	0.0000 0.0539

****GATE STATISTICS****

GATE NUMBER	GATE Label	CURRENT STATUS	PCT. OF TIME OPEN
1	CR 1	OPEN	0.9919
2	CR2	OPEN	0.9871
3	MOV	OPEN	0.4263
4	SC2	CLOSED	0.6328
5	C2	OPEN	0.8973
6	P2	OPEN	0.9138
7	SO2	OPEN	0.8782
8	SC 1	CLOSED	0.5258
9	ACID	OPEN	0.7046
10	PASI	CLOSED	0.6987
11	PAS2	CLOSED	0.8717

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

.

RUN NUMBER 2 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	VALUE	DEVIATION	VARIATION	VALUE	VALUE	OBSERVATIONS
TANK TIME SYS 1	0.8956E+00	0.1914E+00	0.2137E+00	0.4717E+00	0.2656E+01	393
TOTAL TIME SYS 1	0.1047E+01	0.2381E+00	0.2274E+00	0.5956E+00	0.2740E+01	393
TANK TIME SYS 2	0.9089E+00	0.2177E+00	0.2395E+00	0.4939E+00	0.3007E+01	396
TOTAL TIME SYS 2	0.1057E+01	0.2599E+00	0.2460E+00	0.5093E+00	0.3063E+01	395

	MEAN VALUE	STANDARD DEVIATION	MINIMUM VALUE	MAXIMUM VALUE	TIME INTERVAL	
NUMBER IN SYS. 1	0.3954E+03	0.2279E+03	0.0000E+00	0.7880E+03	0.3600E+03	0.7880E+03
NUMBER OF BRKDWN	0.5433E+01	0.3052E+01	0.0000E+00	0.1000E+02	0.3600E+03	0.1000E+02
NUMBER OF BRKDWN	0.2733E+01	0.2016E+01	0.0000E+00	0.7000E+01	0.3600E+03	0.7000E+01
TON OUTPUT	0.5239E+03	0.3016E+03	0.0000E+00	0.1059E+04	0.3600E+03	0.1059E+04

			orwitalit(· 3 · ·		
FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE
1 2 3 4 5 6 7 8 9 10 11 12	AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT CALENDAR	0.0147 0.0157 0.0036 0.1138 0.0000 0.0030 0.0016 0.1223 0.0199 0.0000 0.0000 4.0312	0.1204 0.1242 0.0602 0.3175 0.0000 0.0548 0.0405 0.3276 0.1397 0.0056 0.0000 0.6987	1 1 1 1 1 1 1 0 6	0 0 0 0 0 0 1 0 0 0 4	0.0010 0.0011 0.0033 0.0131 0.0000 0.0029 0.0017 0.0227 0.0181 0.0004 0.0000 0.0530

.

FILE STATISTICS

GATE STATISTICS

-

• . .

GATE NUMBER	GATE Label	CURRENT STATUS	PCT. OF TIME OPEN
1	CR 1	OPEN	0 9925
2	CR2	OPEN	0.9835
3	MOV	ODEN	0.9827
4	SC2	ODEN	0.4668
5	C2	OPEN	0.6376
ã	D7	UPEN	0.8976
7	F 2	OPEN	0.9132
<i>'</i>	502	OPEN	0.8795
8	SC 1	CLOSED	0 5200
9	ACID	CLOSED	0.5208
10	PASI	ODEN	0.6933
11	PASO	OPEN	0.6985
••	1432	OPEN	0.8729

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

•

RUN NUMBER 3 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

****STATISTICS FOR VARIABLES BASED ON OBSERVATION****

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	Value	DEVIATION	VARIATION	VALUE	VALUE	OBSERVATIONS
TANK TIME SYS 1	0.8982E+00	0.1930E+00	0.2149E+00	0.4824E+00	0.2855E+01	383
TOTAL TIME SYS 1	0.1058E+01	0.2800E+00	0.2647E+00	0.4939E+00	0.3377E+01	383
TANK TIME SYS 2	0.9222E+00	0.2529E+00	0.2743E+00	0.4597E+00	0.2994E+01	390
TOTAL TIME SYS 2	0.1084E+01	0.2958E+00	0.2729E+00	0.6697E+00	0.3184E+01	390

	MEAN Value	STANDARD DEVIATION	MINIMUM VALUE	MAXIMUM VALUE	TIME Interval	
NUMBER IN SYS. 1	0.3835E+03	0.2232E+03	0.0000E+00	0.7730E+03	0.3600E+03	0.7730E+03
NUMBER OF BRKDWN	0.2300E+01	0.1345E+01	0.0000E+00	0.4000E+01	0.3600E+03	0.4000E+01
NUMBER OF BRKDWN	0.2633E+01	0.1516E+01	0.0000E+00	0.5000E+01	0.3600E+03	0.5000E+01
TON OUTPUT	0.5284E+03	0.3088E+03	0.0000E+00	0.1068E+04	0.3600E+03	0.1068E+04

****FILE STATISTICS****

ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
AWAIT	0.0144	0.1192	•	0	0.0040
AWAIT	0.0183	0.1341	i	ŏ	. 0.0010
AWAIT	0.0211	0 1436	4	0	0.0014
AWAIT	0,1345	0 3412		0	0.0198
AWAIT	0.0000	0,0000		0	0.0158
AWAIT	0.0026	0.0505		0	0.0000
AWAIT	0 0034	0.0505		0	0.0026
AWAIT	0 1241	0.0388	1	0	0.0037
AWAIT	0.0110	0.3297	1	0	0.0236
AWATT	0.0006	0.1041		0	0.0101
AWAIT	0.0000	0.0252	1	0	0.0074
	4.0405	0.0000	0	0	0.0000
GALLINDAR	4.0135	0.7236	7	4	0.0537
	ASSOCIATED NODE TYPE AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT CALENDAR	ASSOCIATED AVERAGE NODE TYPE LENGTH AWAIT 0.0144 AWAIT 0.0183 AWAIT 0.0211 AWAIT 0.1345 AWAIT 0.0000 AWAIT 0.0026 AWAIT 0.0034 AWAIT 0.1241 AWAIT 0.0110 AWAIT 0.0110 AWAIT 0.0006 AWAIT 0.0000 CALENDAR 4.0135	ASSOCIATED NODE TYPE AVERAGE LENGTH STANDARD DEVIATION AWAIT 0.0144 0.1192 AWAIT 0.0183 0.1341 AWAIT 0.0211 0.1436 AWAIT 0.1345 0.3412 AWAIT 0.0000 0.0000 AWAIT 0.0026 0.0505 AWAIT 0.1241 0.3297 AWAIT 0.0110 0.1041 AWAIT 0.0006 0.0252 AWAIT 0.0000 0.0000 CAUAT 0.0252 0.7236	ASSOCIATED NODE TYPE AVERAGE LENGTH STANDARD DEVIATION MAXIMUM LENGTH AWAIT 0.0144 0.1192 1 AWAIT 0.0183 0.1341 1 AWAIT 0.0211 0.1436 1 AWAIT 0.1345 0.3412 1 AWAIT 0.0000 0.0000 1 AWAIT 0.0026 0.0505 1 AWAIT 0.1241 0.3297 1 AWAIT 0.0110 0.1041 1 AWAIT 0.0252 1 AWAIT 0.0000 0.0000 0 AWAIT 0.1241 0.3297 1 AWAIT 0.0100 0.1041 1 AWAIT 0.0006 0.0252 1 AWAIT 0.0000 0.00000 0 CALENDAR 4.0135 0.7236 7	ASSOCIATED NODE TYPE AVERAGE LENGTH STANDARD DEVIATION MAXIMUM LENGTH CURRENT LENGTH AWAIT 0.0144 0.1192 1 0 AWAIT 0.0183 0.1341 1 0 AWAIT 0.0211 0.1436 1 0 AWAIT 0.1345 0.3412 1 0 AWAIT 0.0000 0.0000 1 0 AWAIT 0.0026 0.0505 1 0 AWAIT 0.0034 0.0586 1 0 AWAIT 0.1241 0.3297 1 0 AWAIT 0.0110 0.1041 1 0 AWAIT 0.0006 0.0252 1 0 AWAIT 0.0000 0.0000 0 0 AWAIT 0.0000 0.0000 0 0

****GATE STATISTICS****

GATE NUMBER	GATE Label	CURRENT STATUS	PCT. OF TIME OPEN
1	CR 1	OPEN	0.9853
2	CR2	OPEN	0.9797
3	MOV	OPEN	0.3799
4	SC2	OPEN	0.6242
5	C2	OPEN	0.8951
6	P2	CLOSED	0.9167
7	S02	OPEN	0.8833
8	SC 1	OPEN	0.5366
9	ACID	OPEN	0.7118
10	PASI	CLOSED	0.7221
11	PAS2	OPEN	0.8769

SIMULATION PROJECT TANKS	BY J. R. LEW	ts	
DATE 1/ 4/1984	RUN NUMBER	4 OF	10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	VALUE	DEVIATION	VARIATION	VALUE	VALUE	OBSERVATIONS
TANK TIME SYS 1	0.8898E+00	0.1634E+00	0.1837E+00	0.4939E+00	0.2609E+01	388
TOTAL TIME SYS 1	0.1071E+01	0.2505E+00	0.2339E+00	0.5500E+00	0.2662E+01	388
TANK TIME SYS 2	0.9234E+00	0.1927E+00	0.2087E+00	0.4742E+00	0.2896E+01	389
TOTAL TIME SYS 2	0.1089E+01	0.2515E+00	0.2310E+00	0.5510E+00	0.2956E+01	389

STATISTICS FOR TIME-PERSISTENT VARIABLES

•

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	Value	DEVIATION	VALUE	VALUE	INTERVAL	VALUE
NUMBER IN SYS. 1	0.3938E+03	0.2246E+03	0.0000E+00	0.7770E+03	0.3600E+03	0.7770E+03
NUMBER OF BRKDWN	0.2900E+01	0.9781E+00	0.0000E+00	0.4000E+01	0.3600E+03	0.4000E+01
NUMBER OF BRKDWN	0.2267E+01	0.2632E+01	0.0000E+00	0.7000E+01	0.3600E+03	0.7000E+01
TON OUTPUT	0.5345E+03	0.2990E+03	0.0000E+00	0.1040E+04	0.3600E+03	0.1040E+04

185

FILE	ASSOCIATED	AVERAGE	STANDARD	MAXIMUM	CURRENT	AVERAGE
NUMBER	Node type	LENGTH	DEVIATION	LENGTH	LENGTH	WAITING TIME
1 2 3 4 5 6 7 8 9 10 11 12	AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT CALENDAR	0.0036 0.0208 0.0219 0.1188 0.0012 0.0033 0.0048 0.1310 0.0123 0.0000 0.0000 4.0544	0.0601 0.1427 0.1464 0.3235 0.0346 0.0575 0.0691 0.3374 0.1100 0.0000 0.0000 0.6930	1 1 1 1 1 1 0 0 7	0 0 0 0 0 0 0 1 0 0 0 3	0.0002 0.0015 0.0203 0.0139 0.0011 0.0032 0.0049 0.0247 0.0113 0.0000 0.0000 0.0000 0.0539

•

****FILE STATISTICS****

GATE STATISTICS

GATE NUMBER	GATE	CURRENT STATUS	PCT. OF TIME OPEN
1	CR1	OPEN	0 9951
2	CR2	OPEN	0.3331
3	MOV	CLOSED	0 3754
4	SC2	OPEN	0.6280
5	C2	OPEN	0 8957
6	P2	OPEN	0.9185
7	SO2	OPEN	0.8840
8	SC 1	CLOSED	0.5274
9	ACID	OPEN	0.7114
10	PAS1	CLOSED	0.7238
11	PAS2	OPEN	0.8786

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 6 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN Value	STANDARD DEVIATION	COEFF. OF VARIATION	MINIMUM Value	MAXIMUM VALUE	NUMBER OF OBSERVATIONS
TANK TIME SYS 1	0.9031E+00	0.2244E+00	0.2485E+00	0.4776E+00	0.3717E+01	385
TOTAL TIME SYS 1	0.1064E+01	0.2816E+00	0.2647E+00	0.5576E+00	0.4129E+01	385
TANK TIME SYS 2	0.9258E+00	0.2468E+00	0.2665E+00	0.4580E+00	0.3729E+01	388
TOTAL TIME SYS 2	0.1086E+01	0.2902E+00	0.2671E+00	0.4875E+00	0.3774E+01	388

	MEAN VALUE	STANDARD DEVIATION	MINIMUM VALUE	MAXIMUM VALUE	TIME INTERVAL	CURRENT
NUMBER IN SYS. 1	0.3854E+03	0.2232E+03	0.0000E+00	0.7730E+03	0.3600E+03	0.7730E+03
NUMBER OF BRKDWN	0.2700E+01	0.1509E+01	0.0000E+00	0.5000E+01	0.3600E+03	0.50002+01
NUMBER OF BRKDWN	0.4322E+01	0.3412E+01	0.0000E+00	0.9000E+01	0.3600E+03	0.9000E+01
TON OUTPUT	0.5036E+03	0.2848E+03	0.0000E+00	0.1020E+04	0.3600E+03	0.1020E+04

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0162	0.1263	•	0	0.0011
2	AWAIT	0.0173	0 1302	-	0	0.0011
3	AWAIT	0.0140	0.1502		0	0.0013
Ā	AWATT	0.0140	0.11//	1	0	0.0131
-	AWAIT	0.1190	0.3238	1	0	0.0140
5	AWAII	0.0051	0.0712	1	Ó	0.0047
6	AWAIT	0.0023	0.0477	. i	õ	0.0047
7	AWAIT	0.0108	0 1034		, v	0.0023
8	AWATT	0 1268	0.1034	1	0	0.0113
ā	AWATT	0.1208	0.3328	1	0	0.0240
10	AWAII	0.0127	0.1120	1	0	0.0118
10	AWAII	0.0011	0.0336	1	Ō	0.0146
11	AWAIT	0.0000	0.0000	ò	õ	0.0148
12	CALENDAR	4.0177	0.7123	7	· 4	0.0000

GATE STATISTICS

GATE NUMBER	GATE Label	CURRENT STATUS	PCT. OF TIME OPEN
1	CR 1	OPEN	0.9832
2	CR2	OPEN	0.9804
Э	MOV	CLOSED	0.4159
4	SC2	CLOSED	0.6401
5	C2	OPEN	0.8875
6	P2	OPEN	0.9164
7	S02	OPEN	0.8716
8	SC 1	OPEN	0.5342
9	ACID	CLOSED	0.7178
10	PASI	OPEN	0.7082
11	PAS2	OPEN	0.8659

١

SIMULATION PROJECT TANKS

BY J. R. LEWIS

.

DATE 1/ 4/1984

.

.

• . . .

RUN NUMBER 7 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

****STATISTICS FOR VARIABLES BASED ON OBSERVATION****

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	VALUE	Deviation	VARIATION	VALUE	VALUE	Observations
TANK TIME SYS 1	0.9090E+00	0.3077E+00	0.3385E+00	0.4865E+00	0.5284E+01	383
TOTAL TIME SYS 1	0.1074E+01	0.3403E+00	0.3169E+00	0.4987E+00	0.5303E+01	383
TANK TIME SYS 2	0.9322E+00	0.3016E+00	0.3235E+00	0.4863E+00	0.5009E+01	386
TOTAL TIME SYS 2	0.1104E+01	0.3558E+00	0.3223E+00	0.5235E+00	0.5400E+01	386

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	VALUE	DEVIATION	VALUE	VALUE	INTERVAL	VALUE
NUMBER IN SYS. 1	0.3805E+03	0.2200E+03	0.0000E+00	0.7690E+03	0.3600E+03	0.7690E+03
NUMBER OF BRKDWN	0.5823E+01	0.2257E+01	0.0000E+00	0.9000E+01	0.3600E+03	0.9000E+01
NUMBER OF BRKDWN	0.1767E+01	0.1202E+01	0.0000E+00	0.3000E+01	0.3600E+03	0.3000E+01
TON OUTPUT	0.5384E+03	0.3112E+03	0.0000E+00	0.1083E+04	0.3600E+03	0.1083E+04

FILE STATISTICS

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0283	0.1659	1	0	0.0020
2	AWAIT	0.0118	0.1079	1	ŏ	0.0009
3	AWAIT	0.0127	0.1121	1	ō	0.0120
4	AWAIT	0.1221	0.3274	t	ō	0.0144
5	AWAIT	0.0156	0.1241	1	ō	0.0146
6	AWAIT	0.0061	0.0776	1	ō	0.0060
7	AWAIT	0.0041	0.0636	1	Ō	0.0042
8	AWAIT	0.1238	0.3293	1	Õ	0.0236
9	AWAIT	0.0130	0.1133	1	Ō	0.0121
10	AWAIT	0.0007	0.0258	1	Ō	0.0109
11	AWAIT	0.0000	0.0000	Ó	õ	0.0000
12	CALENDAR	4.0194	0.7330	7	4	0.0540

****GATE STATISTICS****

GATE	GATE	CURRENT	PCT. OF
NUMBER	LABEL	STATUS	TIME OPEN
1	CR 1	OPEN	0.9705
2	CR2	OPEN	0.9878
3	MOV	OPEN	0.4217
4	SC2	OPEN	0.6324
5	C2	OPEN	0.8824
6	P2	OPEN	0.9135
7	SO2	CLOSED	0.8843
8	SC1	CLOSED	0.5312
9	ACID	OPEN	0.7138
10	PASI	CLOSED	0.7176
11	PAS2	CLOSED	0.8741

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 8 OF 13

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN VALUE	STANDARD DEVIATION	COEFF. OF VARIATION	MINIMUM	MAXIMUM VALUE	NUMBER OF OBSERVATIONS
TANK TIME SYS 1	0.8813E+00	0.1414E+00	0.1604E+00	0.4098E+00	0.2575E+01	396
TOTAL TIME SYS 1	0.1050E+01	0.2107E+00	0.2007E+00	0.4964E+00	0.2607E+01	396
TANK TIME SYS 2	0.8973E+00	0.1478E+00	0.1647E+00	0.5352E+00	0.2565E+01	401
TOTAL TIME SYS 2	0.1070E+01	0.2271E+00	0.2123E+00	0.5713E+00	0.2621E+01	401

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	Value	DEVIATION	VALUE	Value	INTERVAL	VALUE
NUMBER IN SYS. 1	0.3971E+03	0.2310E+03	0.0000E+00	0.7970E+03	0.3600E+03	0.7970E+03
NUMBER OF BRKDWN	0.0000E+00	0.0000E+00	0.0000E+00	0.0000E+00	0.3600E+03	0.0000E+00
NUMBER OF BRKDWN	0.2123E+01	0.1303E+01	0.0000E+00	0.5000E+01	0.3600E+03	0.5000E+01
TON OUTPUT	0.5368E+03	0.3210E+03	0.0000E+00	0.1111E+04	0.3600E+03	0.1111E+04

FILE STATISTICS

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1 2 3 4 5 6 7 8 9 10 11	AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT	0.0000 0.0095 0.0119 0.1140 0.0000 0.0017 0.0024 0.1248 0.0150 0.0000 0.0002	0.0000 0.0970 0.1083 0.3179 0.0000 0.0417 0.3305 0.1214 0.0000 0.0131	0 1 1 1 1 1 1 0 1		0.0000 0.0007 0.0108 0.0130 0.0000 0.0017 0.0024 0.0231 0.0134 0.0000 0.0029
12	CALENUAR	4.0959	0.6648	7	4	0.0534

GATE STATISTICS

GATE NUMBER	GATE Label	CURRENT STATUS	PCT. OF Time open
1	CR 1	OPEN	1.0000
2	CR2	OPEN	0.9891
3	MOV	OPEN	0.4203
4	SC2	OPEN	0.6364
5	C2	OPEN	0.8952
6	P2	OPEN	0.9173
7	SO2	OPEN	0.8819
8	SC 1	CLOSED	0.5233
9	ACID	CLOSED	0.6997
10	PAS1	OPEN	0.7228
11	PAS2	OPEN	0.8755

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

.

RUN NUMBER 9 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

****STATISTICS FOR VARIABLES BASED ON OBSERVATION****

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	Value	DEVIATION	VARIATION	VALUE	VALUE	OBSERVATIONS
TANK TIME SYS 1	0.8891E+00	0.1561E+00	0.1755E+00	0.4810E+00	0.2874E+01	386
TOTAL TIME SYS 1	0.1049E+01	0.2132E+00	0.2033E+00	0.5877E+00	0.2965E+01	386
TANK TIME SYS 2	0.9225E+00	0.3141E+00	0.3404E+00	0.4619E+00	0.5947E+01	390
TOTAL TIME SYS 2	0.1089E+01	0.3523E+00	0.3234E+00	0.5431E+00	0.6240E+01	390

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	Value	DEVIATION	VALUE	VALUE	INTERVAL	VALUE
NUMBER IN SYS. 1	0.3849E+03	0.2238E+03	0.0000E+00	0.7760E+03	0.3600E+03	0.7760E+03
NUMBER OF BRKDWN	0.3000E+01	0.1826E+01	0.0000E+00	0.5000E+01	0.3600E+03	0.5000E+01
NUMBER OF BRKDWN	0.3695E+01	0.1888E+01	0.0000E+00	0.7000E+01	0.3600E+03	0.7000E+01
TON OUTPUT	0.5220E+03	0.3032E+03	0.0000E+00	0.1053E+04	0.3600E+03	0.1053E+04

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1 2 3 4 5 6 7 8 9 10 11	AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT AWAIT	0.0037 0.0285 0.0283 0.1204 0.0000 0.0030 0.0061 0.1224 0.0138 0.0007 0.0000	0.0606 0.1663 0.1657 0.3254 0.0000 0.0551 0.0776 0.3278 0.1165 0.0265	1 1 1 1 1 1 1 1	0 0 0 0 0 0 1 0 0	0.0003 0.0021 0.0264 0.0141 0.0000 0.0030 0.0064 0.0231 0.0127 0.0097
12	CALENDAR	4.0236	0.7076	0 7	0 3	0.0000 0.0535

GATE STATISTICS

1

.

٠.,

GATE NUMBER	GATE Label	CURRENT STATUS	PCT. DF Time open
1	CR 1	OPEN	0.9921
2	CR2	OPEN	0.9707
3	MOV	OPEN	0.4076
4	SC2	OPEN	0.6367
5	C2	OPEN	0.9002
6	P2	OPEN	0.9162
7	SO2	OPEN	0.8782
8	SC 1	CLOSED	0.5330
9	ACID	CLOSED	0.7145
10	PAS1	OPEN	0.7123
11	PAS2	OPEN	0.8733

SIMULATION PROJECT TANKS BY J. R. LEWIS

DATE 1/ 4/1984

.

,

RUN NUMBER 10 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	VALUE	DEVIATION	VARIATION	VALUE	VALUE	Observations
TANK TIME SYS 1	0.8905E+00	0.1146E+00	0.1287E+00	0.4781E+00	0.1874E+01	391
TOTAL TIME SYS 1	0.1058E+01	0.2048E+00	0.1935E+00	0.5300E+00	0.2293E+01	391
TANK TIME SYS 2	0.9102E+00	0.1424E+00	0.1565E+00	0.4736E+00	0.2043E+01	395
TOTAL TIME SYS 2	0.1089E+01	0.2209E+00	0.2027E+00	0.4744E+00	0.2125E+01	395

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	Value	DEVIATION	VALUE	VALUE	INTERVAL	VALUE
NUMBER IN SYS. 1	0.3930E+03	0.2280E+03	0.0000E+00	0.7860E+03	0.3600E+03	0.7860E+03
NUMBER OF BRKDWN	0.1400E+01	0.1541E+01	0.0000E+00	0.5000E+01	0.3600E+03	0.5000E+01
NUMBER OF BRKDWN	0.3200E+01	0.1447E+01	0.0000E+00	0.5000E+01	0.3600E+03	0.5000E+01
TON OUTPUT	0.5205E+03	0.3026E+03	0.0000E+00	0.1033E+04	0.3600E+03	0.1033E+04

FILE STATISTICS

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT	AVERAGE WAITING TIME
1	AWAIT	0.0048	0.0692	1	0	0,0003
2	AWAIT	0.0055	0.0742		ŏ	0.0003
3	AWAIT	0.0157	0.1243	4	ŏ	0.0004
4	AWAIT	0.1271	0.3331	-	1	0.0145
5	AWAIT	0.0000	0,0000			0.0147
6	AWAIT	0.0029	0.0540	1	0	0.0000
7	AWAIT	0.0065	0 0802	1	0	0.0028
8	AWAIT	0.1226	0 3280		0	0.0066
9	AWAIT	0.0108	0 1035	4	0	0.0229
10	AWAIT	0,0006	0.0245		0	0.0098
11	AWAIT	0.0001	0.0245		0	0.0099
12	CALENDAR	4.0801	0.6568	7	0	0.0029
			010000	,	3	0.0536

****GATE STATISTICS****

GATE	GATE	CURRENT	PCT. OF
NUMBER	LABEL	STATUS	TIME OPEN
1	CR 1	OPEN	0.9947
2	CR2	OPEN	0.9943
Э	MOV	CLOSED	0.3780
4	SC2	CLOSED	0.6274
5	C2	OPEN	0.9015
6	P2	OPEN	0.9161
7	S02	OPEN	0.8765
8	SC 1	OPEN	0.5308
9	ACID	OPEN	0.7086
10	PAS1	OPEN	0.7126
11	PAS2	OPEN	0.8692

APPENDIX G

•

OUTPUT OF TWO CRANE TWO OPERATOR MODEL

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 1 OF 10

1

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

T	MEAN VALUE	STANDARD DEVIATION	COEFF OF VARIATION	MINIMUM VALUE	MAXIMUM VALUE	NUMBER OF
TANK TIME	0.9073E+00	0.1893E+00	0.2087E+00	0.6633E+00	0.2458E+01	668
TOTAL TIME	0.1063E+01	0.2507E+00	0.2359E+00	0.7410E+00	0.2771E+01	667

STATISTICS FOR TIME-PERSISTENT VARIABLES

	MEAN VALUE	STANDARD DEVIATION	MINIMUM VALUE	MAXIMUM VALUE	TIME INTERVAL	CURRENT
NUMBER IN SYS. 1	0.3349E+03	0.1930E+03	0.0000E+00	0.6670E+03	0.3600E+03	0.6670E+03
NUMBER OF BRKDWN	0.6320E+01	0.2823E+01	0.0000E+00	0.1200E+02	0.3600E+03	0.1200E+02
NUMBER OF BRKDOW	0.4095E+01	0.2533E+01	0.0000E+00	0.9000E+01	0.3600E+03	0.9000E+01
TON OUTPUT	0.4490E+03	0.2551E+03	0.0000E+00	0.8937E+03	0.3600E+03	0.8937E+03

FILE STATISTICS

.

ETLE

FILE	ASSOCIATED	AVERAGE	STANDARD	MAXIMUM	CURRENT	AVERAGE
NUMBER	Node type	LENGTH	DEVIATION	LENGTH	LENGTH	WAITING TIME
1 2 3 4 5	AWAIT AWAIT AWAIT AWAIT CALENDAR	0.0195 0.0072 0.0199 0.0163 5.8586	0.1384 0.0847 0.1397 0.1266 0.7462	1 1 1 8	0 0 0 7	0.0026 0.0039 0.0107 0.0013 0.1288

198

RESOURCE STATISTICS

RESOURCE	RESOURCE	CURRENT	AVERAGE	STANDARD	MAXIMUM	CURRENT
NUMBER	LABEL	CAPACITY	UTILIZATION	DEVIATION	UTILIZATION	UTILIZATION
1	WC1	1	0.1736	0. 3787	1	0
2	WC2	1	0.7113	0.4532	1	

RESOURCE	RESOURCE	CURRENT	AVERAGE	MINIMUM	MAXIMUM
NUMBER	LABEL	AVAILABLE	AVAILABLE	AVAILABLE	AVAILABLE
1	WC1	1	0.8264	0	1
2	WC2	0	0.2887	0	

GATE STATISTICS

GATE	GATE	CURRENT	PCT. OF
NUMBER	Label	STATUS	Time open
1	CR1	OPEN	0.9775
2	CR2	OPEN	0.9829

.

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 2 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	VALUE	DEVIATION	VARIATION	VALUE	VALUE	OBSERVATIONS
TANK TIME	0.8901E+00	0.1422E+00	0.1598E+00	0.6964E+00	0.2516E+01	678
TOTAL TIME	0.1030E+01	0.1961E+00	0.1904E+00	0.7128E+00	0.2557E+01	678

STATISTICS FOR TIME-PERSISTENT VARIABLES

	MEAN Value	STANDARD DEVIATION	MINIMUM VALUE	MAXIMUM VALUE	TIME INTERVAL	CURRENT VALUE
NUMBER IN SYS. 1	0.3365E+03	0.1957E+03	0.0000E+00	0.6780E+03	0.3600E+03	0.6780E+03
NUMBER OF BRKDWN	0.3000E+01	0.1549E+01	0.0000E+00	0.5000E+01	0.3600E+03	0.5000E+01
NUMBER OF BRKDOW	0.2433E+01	0.1687E+01	0.0000E+00	0.4000E+01	0.3600E+03	0.4000E+01
TON OUTPUT	0.4464E+03	0.2549E+03	0.0000E+00	0.9008E+03	0.3600E+03	0.9008E+03

****FILE STATISTICS****

FILE	ASSOCIATED	AVERAGE	STANDARD	MAXIMUM	CURRENT	AVERAGE
NUMBER	NODE TYPE	LENGTH	DEVIATION	LENGTH	LENGTH	WAITING TIME
1 2 3 4 5	AWAIT AWAIT AWAIT AWAIT CALENDAR	0.0097 0.0037 0.0119 0.0103 3.9816	0.0982 0.0608 0.1085 0.1009 0.5857	1 1 1 6	0 0 0 4	0.0013 0.0020 0.0063 0.0008 0.0871

RESOURCE STATISTICS

RESOURCE	RESOURCE	CURRENT	AVERAGE	STANDARD	MAXIMUM	CURRENT
NUMBER	LABEL	CAPACITY	UTILIZATION	DEVIATION	UTILIZATION	UTILIZATION
1 2	WC1 WC2	1 1	0.1685 0.7136	0.3743 0.4521	1	0

RESOURCE	RESOURCE	CURRENT AVAILABLE	AVERAGE AVAILABLE	MINIMUM AVAILABLE	MAXIMUM AVAILABLE	
1 2	WC1 WC2	1 0	0.8315 0.2864	0	1	

GATE STATISTICS

GATE	GATE	CURRENT	PCT. OF
NUMBER	L abel	STATUS	TIME OPEN
1	CR1	OPEN	0.9890
2	CR2	OPEN	
			0.9694

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 3 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	Value	DEVIATION	VARIATION	VALUE	Value	OBSERVATIONS
TANK TIME	0.8912E+00	0.1962E+00	0.2202E+00	0.6823E+00	0.4425E+01	664
TOTAL TIME	0.1032E+01	0.2611E+00	0.2530E+00	0.7111E+00	0.4548E+01	664

STATISTICS FOR TIME-PERSISTENT VARIABLES

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	Value	DEVIATION	VALUE	VALUE	Interval	VALUE
NUMBER IN SYS. 1	0.3360E+03	0.1913E+03	0.0000E+00	0.6640E+03	0.3600E+03	0.6640E+03
NUMBER OF BRKDWN	0.9563E+01	0.6280E+01	0.0000E+00	0.2200E+02	0.3600E+03	0.2200E+02
NUMBER OF BRKDOW	0.2167E+01	0.1157E+01	0.0000E+00	0.4000E+01	0.3600E+03	0.4000E+01
TON OUTPUT	0.4641E+03	0.2639E+03	0.0000E+00	0.9193E+03	0.3600E+03	0.9193E+03

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0345	0.1824	1	0	0.0047
2	AWAIT	0.0000	0.0000	i	õ	0.0047
Э	AWAIT	0.0020	0.0445	÷	ŏ	0.0000
4	AWAIT	0.0027	0.0517		0	0.0011
5	CALENDAR	5.6135	1 1599		0	0.0002
			1.1000	3	1	U. 1240

RESOURCE STATISTICS

0 0

1

RESOURCE	RESOURCE	CURRENT	AVERAGE	STANDARD	MAXIMUM	CURRENT
NUMBER	LABEL	CAPACITY	UTILIZATION	DEVIATION	UTILIZATION	UTILIZATION
1	WC1	1	0.1553	0.3622	1	0
2	WC2	1	0.6893	0.4628		1
RESOURCE	RESOURCE	CURRENT	AVERAGE	MINIMUM	MAXIMUM	
NUMBER	LABEL	AVAILABLE	AVAILABLE	AVAILABLE	AVAILABLE	

0.8447 0.3107

GATE STATISTICS

1

Ó

1 2 WC1 WC2

GATE	GATE	CURRENT	PCT. OF
NUMBER	LABEL	STATUS	Time open
1	CR1	OPEN	0.9595
2	CR2	OPEN	0.995 8

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 4 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	VALUE	DEVIATION	VARIATION	VALUE	VALUE	Observations
TANK TIME	0.8747E+00	0.5970E-01	0.6826E-01	0.6349E+00	0.1285E+01	687
TOTAL TIME	0.1026E+01	0.1742E+00	0.1697E+00	0.6412E+00	0.1813E+01	686

STATISTICS FOR TIME-PERSISTENT VARIABLES

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	VALUE	DEVIATION	VALUE	VALUE	INTERVAL	VALUE
NUMBER IN SYS. 1	0.3431E+03	0.1984E+03	0.0000E+00	0.6860E+03	0.3600E+03	0.6860E+03
NUMBER OF BRKDWN	0.2134E+01	0.1157E+01	0.0000E+00	0.5000E+01	0.3600E+03	0.5000E+01
NUMBER OF BRKDOW	0.3167E+01	0.1985E+01	0.0000E+00	0.6000E+01	0.3600E+03	0.6000E+01
TON OUTPUT	0.4786E+03	0.2756E+03	0.0000E+00	0.9479E+03	0.3600E+03	0.9479E+03

FILE STATISTICS

FILE	ASSOCIATED	AVERAGE	STANDARD	MAXIMUM	CURRENT	AVERAGE
NUMBER	Node type	LENGTH	DEVIATION	LENGTH	LENGTH	WAITING TIME
1 2 3 4 5	AWAIT AWAIT AWAIT AWAIT CALENDAR	0.0018 0.0000 0.0021 0.0030 5.0104	0.0428 0.0000 0.0453 0.0544 0.6299	t 1 1 1 8	0 0 0 7	0.0002 0.0000 0.0011 0.0002 0.1078

RESOURCE STATISTICS

-

RESOURCE NUMBER	RESOURCE LABEL	CURRENT CAPACITY	AVERAGE UTILIZATION	STANDARD DEVIATION	MAXIMUM UTILIZATION	CURRENT
1	WC 1		• · · ·			UTILIZATION
2	WC2	1	0.1605	0.3671	1	
		•	0.7152	0.4513	1	
						•

RESOURCE	RESOURCE	CURRENT	AVERAGE	MINIMUM	MAXIMUM
NUMBER	LABEL	AVAILABLE	AVAILABLE	AVAILABLE	AVAILABLE
1	WC 1	0	0.8395	0	1
2	WC2	0	0.2848	0	

GATE STATISTICS

GATE	GATE	CURRENT	PCT. OF
NUMBER	Label	STATUS	Time open
1	CR1	OPEN	0.9965
2	CR2	OPEN	0.9963

.

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 5 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	CGEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	VALUE	DEVIATION	VARIATION	VALUE	VALUE	Observations
TANK TIME	0.8895E+00	0.1644E+00	0.1848E+00	0.6489E+00	0.3044E+01	674
TOTAL TIME	0.1044E+01	0.2319E+00	0.2221E+00	0.6864E+00	0.3094E+01	674

****STATISTICS FOR TIME-PERSISTENT VARIABLES****

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	Value	DEVIATION	VALUE	VALUE	INTERVAL	VALUE
NUMBER IN SYS. 1	0.3341E+03	0.1954E+03	0.0000E+00	0.6740E+03	0.3600E+03	0.6740E+03
NUMBER OF BRKDWN	0.4967E+01	0.2168E+01	0.0000E+00	0.8000E+01	0.3600E+03	0.8000E+01
NUMBER OF BRKDOW	0.2833E+01	0.1267E+01	0.0000E+00	0.4000E+01	0.3600E+03	0.4000E+01
TON OUTPUT	0.4404E+03	0.2590E+03	0.0000E+00	0.8982E+03	0.3600E+03	0.8982E+03

FILE STATISTICS

FILE	ASSOCIATED	AVERAGE	STANDARD	MAXIMUM	CURRENT	AVERAGE
NUMBER	NODE TYPE	LENGTH	DEVIATION	LENGTH	LENGTH	WAITING TIME
1 2 3 4 5	AWAIT AWAIT AWAIT AWAIT CALENDAR	0.0209 0.0009 0.0068 0.0056 3.9960	0.1431 0.0297 0.0822 0.0746 0.6190	1 1 1 6	0 0 0 3	0.0028 0.0005 0.0036 0.0004 0.0879

RESOURCE STATISTICS

•

RESOURCE	RESOURCE	CURRENT	AVERAGE	STANDARD	MAXIMUM	CURRENT
NUMBER	LABEL	CAPACITY	UTILIZATION	DEVIATION	UTILIZATION	
1	WC1	1	0.1626	0.3690	1	1
2	WC2	1	0.7056	0.4558		0

RESOURCE	RESOURCE	CURRENT	AVERAGE	MINIMUM	MAXIMUM
NUMBER	LABEL	AVAILABLE	AVAILABLE	AVAILABLE	AVAILABLE
1	WC1	0	0. 8374	0	1
2	WC2	1	0.2944	0	

****GATE STATISTICS****

.

• • •

GATE	GATE	CURRENT	PCT. OF
NUMBER	Label	STATUS	TIME OPEN
1	CR 1	OPEN	0.9772
2	CR2	Open	0.9934
SLAM SUMMARY REPORT

SIMULATION PROJECT	TANKS	BY J.	R.	LEWIS

DATE 1/ 4/1984

١

1

.

RUN NUMBER 6 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

****STATISTICS FOR VARIABLES BASED ON OBSERVATION****

	MEAN VALUE	STANDARD DEVIATION	COEFF. OF VARIATION	MINIMUM VALUE	MAXIMUM VALUE	NUMBER OF OBSERVATIONS
TANK TIME	0.8955E+00	0.2201E+00	0.2458E+00	0.6513E+00	0.4002E+01	671
TOTAL TIME	0.1044E+01	0.2793E+00	0.2676E+00	0.6369E+00	0.4066E+01	670

****STATISTICS FOR TIME-PERSISTENT VARIABLES****

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	Value	DEVIATION	VALUE	VALUE	Interval	VALUE
NUMBER IN SYS. 1	0.3346E+03	0.1925E+03	0.0000E+00	0.6700E+03	0.3600E+03	0.6700E+03
NUMBER OF BRKDWN	0.4669E+01	0.3006E+01	0.0000E+00	0.9000E+01	0.3600E+03	0.9000E+01
NUMBER OF BRKDOW	0.5667E+00	0.8439E+00	0.0000E+00	0.2000E+01	0.3600E+03	0.2000E+01
Ton Output	0.4391E+03	0.2475E+03	0.0000E+00	0.8835E+03	0.3600E+03	0.8835E+03

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0215	0.1450	1	0	0.0029
2	AWAIT	0.0062	0.0787	1	0	0.0033
3	AWAIT	0.0109	0.1038	1	0	0.0058
4	AWAIT	0.0097	0.0983	1	0	0.0008
5	CALENDAR	4.6390	0.7524	7	6	0.1023

RESOURCE STATISTICS

.

RESOURCE	RESOURCE	CURRENT	AVERAGE	STANDARD	MAXIMUM	CURRENT
NUMBER	LABEL	CAPACITY	UTILIZATION	DEVIATION	UTILIZATION	UTILIZATION
1	WC1	1	0.1654	0.3716	· 1	0
2	WC2	1	0.7048	0.4562	1	1

RESOURCE	RESOURCE	CURRENT	AVERAGE	MINIMUM	MAXIMUM
NUMBER	LABEL	AVAILABLE	AVAILABLE	AVAILABLE	AVAILABLE
1	WC1	1	0.8346 0.2952	0	1

****GATE STATISTICS****

GATE	GATE	CURRENT	PCT. OF
NUMBER	Label	STATUS	TIME OPEN
1	CR 1	OPEN	0.9761
2	CR2	OPEN	0.9899

SLAM SUMMARY REPORT

SIMULATION PROJECT TANKS	BY J. R. LEWIS	
DATE 1/ 4/1984	RUN NUMBER 7 OF	10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

****STATISTICS FOR VARIABLES BASED ON OBSERVATION****

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	Value	DEVIATION	VARIATION	VALUE	VALUE	OBSERVATIONS
TANK TIME	0.8734E+00	0.7591E-01	0.8690E-01	0.6677E+00	0.1725E+01	690
TOTAL TIME	0.1016E+01	0.1761E+00	0.1734E+00	0.7128E+00	0.2150E+01	689

****STATISTICS FOR TIME-PERSISTENT VARIABLES****

	MEAN VALUE	STANDARD DEVIATION	MINIMUM VALUE	MAXIMUM VALUE	TIME INTERVAL	CURRENT VALUE
NUMBER IN SYS. 1	0.3442E+03	0.1998E+03	0.0000E+00	0.6890E+03	0.3600F+03	0 68905+03
NUMBER OF BRKDWN	0.2667E+00	0.4422E+00	0.0000E+00	0.2000E+01	0.3600E+03	0.2000E+01
NUMBER OF BRKDOW	0.6667E+00	0.1075E+01	0.0000E+00	0.4000E+01	0.3600E+03	0.4000E+01
TON OUTPUT	0.4366E+03	0.2569E+03	0.0000E+00	0.9029E+03	0.3600E+03	0.9029E+03

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node Type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0000	0.0000	0	0	0.0000
2	AWAIT	0.0010	0.0312	1	ŏ	0.0005
з	AWAIT	0.0059	0.0765	i	õ	0.0031
4	AWAIT	0.0048	0.0689	i	ŏ	0.0004
5	CALENDAR	4.0126	0.5589	7	4	0.0864

****RESOURCE STATISTICS****

RESOURCE	RESOURCE	CURRENT	AVERAGE	STANDARD	MAXIMUM	CURRENT
NUMBER	LABEL	CAPACITY	UTILIZATION	DEVIATION	UTILIZATION	UTILIZATION
1	WC1	1	0.1643	0.3706	1	0
2	WC2	1	0.7163	0.4508	1	0

RESOURCE	RESOURCE	CURRENT	AVERAGE	MINIMUM	MAXIMUM	
NUMBER	LABEL	AVAILABLE	AVAILABLE	AVAILABLE	AVAILABLE	
1 2	WC 1 WC 2	1 1	0. 8357 0.2837	0 0	1	

****GATE STATISTICS****

GATE	GATE	CURRENT	PCT. OF
NUMBER	Label	STATUS	TIME OPEN
1	CR 1	OPEN	0.9995
2	CR2	OPEN	0.9937

SLAM SUMMARY REPORT

SIMULATION PROJECT TANKS BY J. R. LEWIS

DATE 1/ 4/1984

.

RUN NUMBER 8 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	VALUE	Deviation	VARIATION	VALUE	VALUE	OBSERVATIONS
TANK TIME	0.9027E+00	0.2554E+00	0.2829E+00	0.6697E+00	0.3728E+01	672
TOTAL TIME	0.1058E+01	0.3159E+00	0.2987E+00	0.7036E+00	0.4079E+01	672

****STATISTICS FOR TIME-PERSISTENT VARIABLES****

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	Value	DEVIATION	VALUE	Value	Interval	VALUE
NUMBER IN SYS. 1	0.3382E+03	0.1956E+03	0.0000E+00	0.6720E+03	0.3600E+03	0.6720E+03
NUMBER OF BRKDWN	0.3928E+01	0.2165E+01	0.0000E+00	0.9000E+01	0.3600E+03	0.9000E+01
NUMBER OF BRKDOW	0.4131E+01	0.2391E+01	0.0000E+00	0.7000E+01	0.3600E+03	0.7000E+01
TON OUTPUT	0.4844E+03	0.2770E+03	0.0000E+00	0.9518E+03	0.3600E+03	0.9518E+03

****FILE STATISTICS****

FILE NUMBER	ASSOCIATED Node type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0179	0.1325	+	0	0.0004
2	AWAIT	0.0094	0,0966		0	0.0024
3	AWATT	0.0404	0.0000		0	0.0050
	AWALL	0.0181	0.1335	1	· 0	0.0097
4	AWAIT	0.0160	0.1254	1	0	0.0040
5	CALENDAR	1 0997	0 7000		0	0.0012
-	SALENDAN ,	4.3087	0.7668	8	7	0.1095

RESOURCE STATISTICS

RESOURCE NUMBER	RESOURCE LABEL	CURRENT CAPACITY	AVERAGE UTILIZATION	STANDARD Deviation	MAXIMUM UTILIZATION	CURRENT UTILIZATION
1	WC 1	1	0.1728	0 3781	4	0
2	WC2	1	0.7152	0.4513	1	1
						•

RESOURCE	RESOURCE	CURRENT	AVERAGE	MINIMUM	MAXIMUM
NUMBER	LABEL	AVAILABLE	AVAILABLE	AVAILABLE	AVAILABLE
1 2	WC 1 WC2	1	0.8272 0.2848	0	1

****GATE STATISTICS****

GATE	GATE	CURRENT	PCT. OF
NUMBER	Label	STATUS	TIME OPEN
1	CR 1	OPEN	0.9796
2	CR2	OPEN	0.9827

SLAM SUMMARY REPORT

SIMULATION PROJECT TANKS

BY J. R. LEWIS

DATE 1/ 4/1984

RUN NUMBER 9 OF 10

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN VALUE	STANDARD DEVIATION	COEFF. OF VARIATION	MINIMUM VALUE	MAXIMUM VALUE	NUMBER OF
TANK TIME	0.8829E+00	0.1064E+00	0.1205E+00	0.6187E+00	0.1994E+01	684
TOTAL TIME	0.1039E+01	0.1945E+00	0.1871E+00	0.7133E+00	0.2154E+01	684

STATISTICS FOR TIME-PERSISTENT VARIABLES

	MEAN VALUE	STANDARD DEVIATION	MINIMUM VALUE	MAXIMUM VALUE	T I ME I NTERVAI	
NUMBER IN SYS. 1 NUMBER OF BRKDWN NUMBER OF BRKDOW TON OUTPUT	0.3404E+03 0.1767E+01 0.1733E+01 0.4509E+03	0.1986E+03 0.6155E+00 0.1413E+01 0.2690E+03	0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00	0.6840E+03 0.3000E+01 0.4000E+01 0.9239E+03	0.3600E+03 0.3600E+03 0.3600E+03 0.3600E+03	0.6840E+03 0.3000E+01 0.4000E+01 0.9239E+03

****FILE STATISTICS****

.

FILE	ASSOCIATED	AVERAGE	STANDARD	MAXIMUM	CURRENT	AVERAGE
NUMBER	Node type	LENGTH	DEVIATION	LENGTH	LENGTH	WAITING TIMF
1 2 3 4 5	AWAIT AWAIT AWAIT AWAIT CALENDAR	0.0036 0.0032 0.0079 0.0068 4.0289	0.0597 0.0564 0.0884 0.0823 0.5689	1 1 1 6	0 0 0 3	0.0005 0.0017 0.0041 0.0005 0.0875

RESOURCE STATISTICS

.

RESOURCE	RESOURCE	CURRENT	AVERAGE	STANDARD	MAXIMUM	CURRENT
NUMBER	LABEL	CAPACITY	UTILIZATION	DEVIATION	UTILIZATION	UTILIZATION
1	WC1	1	0.1653	0.3714	1	0
2	WC2	1	0.7172	0.4504	1	0

RESOURCE NUMBER	RESOURCE LABEL	CURRENT AVAILABLE	AVERAGE AVAILABLE	MINIMUM AVAILABLE	MAXIMUM AVAILABLE
1	WC 1	1	0.8347	0	1
2	WC2	1	0.2828	0	1

****GATE STATISTICS****

GATE	GATE	CURRENT	PCT. OF
NUMBER	Label	STATUS	TIME OPEN
1	CR1	OPEN	0.9952
2	CR2	OPEN	0.9926

SLAM SUMMARY REPORT

SIMULATION PROJECT TANKS	BY J. R. LEWIS		
DATE 1/ 4/1984	RUN NUMBER 10 OF	10	

.

CURRENT TIME 0.3600E+03 STATISTICAL ARRAYS CLEARED AT TIME 0.0000E+00

STATISTICS FOR VARIABLES BASED ON OBSERVATION

	MEAN	STANDARD	COEFF. OF	MINIMUM	MAXIMUM	NUMBER OF
	VALUE	DEVIATION	VARIATION	VALUE	VALUE	Observations
TANK TIME	0.8785E+00	0.1250E+00	0.1423E+00	0.6739E+00	0.3411E+01	685
TOTAL TIME	0.1025E+01	0.1945E+00	0.1898E+00	0.6992E+00	0.3492E+01	685

STATISTICS FOR TIME-PERSISTENT VARIABLES

	MEAN	STANDARD	MINIMUM	MAXIMUM	TIME	CURRENT
	VALUE	DEVIATION	VALUE	VALUE	INTERVAL	VALUE
NUMBER IN SYS. 1 NUMBER OF BRKDWN NUMBER OF BRKDOW TON OUTPUT	0.3390E+03 0.1300E+01 0.2333E+01 0.4842E+03	0.1983E+03 0.8622E+00 0.1274E+01 0.2720E+03	0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00	0.6850E+03 0.2000E+01 0.5000E+01 0.9511E+03	0.3600E+03 0.3600E+03 0.3600E+03 0.3600E+03 0.3600E+03	0.6850E+03 0.2000E+01 0.5000E+01 0.9511E+03

****FILE STATISTICS****

.

FILE NUMBER	ASSOCIATED Node Type	AVERAGE LENGTH	STANDARD DEVIATION	MAXIMUM LENGTH	CURRENT LENGTH	AVERAGE WAITING TIME
1	AWAIT	0.0075	0.0865	1	0	0.0010
2	AWAIT	0.0007	0.0264	1	õ	0.0004
3	AWAIT	0.0062	0.0787	1	ŏ	0.0033
4	AWAIT	0.0047	0.0683	i	ŏ	0.0004
5	CALENDAR	4.0085	0.5704	6	4	0.0869

RESOURCE STATISTICS

RESOURCE	RESOURCE	CURRENT	AVERAGE	STANDARD	MAXIMUM	CURRENT
NUMBER	LABEL	Capacity	UTILIZATION	DEVIATION	UTILIZATION	UTILIZATION
1	WC1	1	0.1644	0.3707	1	0
2	WC2	1	0.7144	0.4517	1	1

RESOURCE	RESOURCE	CURRENT	AVERAGE	MINIMUM	MAXIMUM
NUMBER	LABEL	AVAILABLE	AVAILABLE	AVAILABLE	AVAILABLE
1	WC1	1	0.8356	0	1
2	WC2	0	0.2856	0	

****GATE STATISTICS****

GATE	GATE	CURRENT	PCT. OF
NUMBER	LABEL	STATUS	TIME OPEN
1	CR1	OPEN	0.9921
2	CR2	OPEN	0.9942

APPENDIX H

۰.

CAN-Q OUTPUT

•

ROUTING FOR PRODUCT TYPE: LUBE

1

•••

OPERATION NUMBER	STATION NUMBER	PROCESSING TIME	OPERATION FREQUENCY
1	1	6.710	1.000
2	2	6.680	1.000
3	3	.710	1.000
4	4	13.600	1.000
5	3	.710	1.000
6	5	.720	1.000
7 .	6	6.740	1.000
8	7	.710	1.000
9	8	.950	1.000
10	9	6.670	1.000
11	10	2.300	1.000

WORKLOAD SUMMARY FOR THIS PRODUCT TYPE

ST	ATION	NUMBER OF VISIIS	VISIT FREQUENCY	TOTAL PROCESS TIME	AVERAGE PROCESS TIME	RELATIVE WORKLOAD
· 1	HOLD	1.000	.091	6.710	6.710	.610
2	CAUS	1.000	.021	6.680	6.680	407
3	CW I	2.000	. 182	1.420	.710	1007
4	ACID	1.000	.021	13.600	13.600	1.236
5	HW	1.000	.091	.720	. 720	045
6	PHOS	1.000	.091	6.740	6.740	.613
7	CW II	1.000	.091	.710	.710	045
8	NEUT	1.000	.021	.950	.950	184
ዎ	SOAP	1,000	.091	6.670	6.670	. 60.5
10	DRY	1.000	.091	2.300	2.300	.209

AVERAGE NUMBER OF OPERATIONS TO COMPLETE ONE 11.000 Desired fraction of production = .890

VALUE OF ONE ITEM = 1.00

"ROUTING FOR PRODUCT TYPE: PHO

`

• .* .

OPERATION NUMBER	STATION NUMBER	PROCESSING TIME	OPERATION FREQUENCY
1	. 1	6.710	1.000
2	2	6,680	1.000
3	3	.710	1.000
4	4	13.600	1.000
5	3	,710	1,000
6	5	.720	1.000
7	6	6.740	1.000
8	7	.710	1,000
9	10	2.300	1,000

WORKLOAD SUMMARY FOR THIS PRODUCT TYPE

ST	ATION	NUMBER OF VISITS	VISIT FREQUENCY	TOTAL PROCESS TIME	AVERAGE PROCESS TIME	RELATIVE WORKLOAD
1	HOLD	1.000	. 1 1 1	6.710	6.710	.746
2	CAUS	1.000	.111	6.680	6.680	.742
3	CW I	2.000	.222	1.420	.710	, 156
4	ACID	1.000	.111	13.600	13.600	1.511
5	HW	1.000	. 111	.720	.720	. 080
6	PHOS	1,000	.111	6.740	6.740	.749
7	CW II	1.000	.111	.710	.710	.079
10	DRY	1.000	.111	2.300	2,300	.256

.

AVERAGE NUMBER OF OPERATIONS TO COMPLETE ONE 9.000 Desired fraction of production = .040

VALUE OF ONE ITEM = 1.00

•

ROUTING FOR PRODUCT TYPE: TRI

OPERATION	STATION	PROCESSING	OPERATION
NUMBER	NUMBER	Time	FREQUENCY
1	1	6.710	1,000
2	2	6.680	1,000
3	3	.710	1,000
4	4	13.600	1,000
5	3	.710	1,000
6	5	.720	1,000
7	10	2.300	1,000

WORKLOAD SUMMARY FOR THIS PRODUCT TYPE

ទា	ATION	NUMBER OF VISITS	VISIT FREQUENCY	TOTAL PROCESS TIME	AVERAGE PROCESS 1IME	RELATIVE WORKLOAD
1 2 3 4 5 10	HOLD Caus Cw I Acid Hw Dry	1.000 1.000 2.000 1.000 1.000 1.000	.143 .143 .286 .143 .143 .143 .143	6.710 6.680 1.420 13.600 .720 2.300	6.710 6.680 .710 13.600 .720 2.300	.959 .954 .203 1.943, .103 .329

AVERAGE NUMBER OF OPERATIONS TO COMPLETE ONE 7.000 Desired Fraction of Production = .070

VALUE OF ONE ITEM = 1.00

INPUT DATA SUMMARY

.

	STATION	NUMBER OF SERVERS	VISIT FREQUENCY	AVERAGE PROCESSING TIME	RELATIVE WORKLOAD	WORKLOAD PER SERVER
1	HOLD	1	.09398	6.71000	.63064	.6306
-						
2	CAUS	1	.09398	6.68000	, 62782	.6278
3	CW I	1	.18797	.71000	. 13346	.1335
4	ACID	1	.09378	13.60000	1.27820	1.2782
E			40700	20000	A / 8 / 8	
	nw	1	.09390	.72000	. 06767	. 0677
6	PHOS	1	.08741	6.74000	.58912	, 5891
7	CW II	1	.08741	.71000	.06206	.0421
8	NEUT	1	.08365	95000	07946	079%
		-	100000	170000	.07740	10770
9	SOAP	1	.08365	6.67000	.55792	. 5579
10	DR Y	1	.09398	2.30000	.21617	.2162
11	CRANE	1	. 09398	.18000	. 18000	. 1800

NUMBER OF ITEMS IN SYSTEM = 2

MEAN NUMBER OF OPERATIONS TO COMPLETE AN ITEM 10.64000

222

SYSTEM PERFORMANCE NEASURES

.

PRODUCTION RATE = 2.192 ITEMS PER HOUR

PRODUCTION RATES BY PRODUCT TYPE

LUBE	NUMBER 1.951	VALUE
РНО	.088	.088
TRI	.153	.153

TOTAL VALUE = 2,192

AVERAGE TINE IN SYSTEM = 54.74 MINUTES

PROCESSING	45.14
TRAVELING	1,92
WAITING	7.69

FUNCTIONS OF N, NUMBER OF ITEMS IN THE SYSTEM

N	PRODUCTION RATE	AVERAGE TIME IN THE	SYSTEM
1	1 975	42 05	
ż	2.192	47.000 54.744	
3	2.854	63 063	
4	3.332	72.029	
5	3.674	81.649	
5	3.917	91,917	
7	4.085	102.804	
•			
•	•	•	
•	•		
INF	4.412	INF	

THE BOTTLENECK STATION IS 4

SUMMARY FOR STATION NUMBER 1 : HOLD

NUMBER OF SERVERS	SERVER UTILIZATION	AVE, NO. OF Busy servers
1	.245	.245
STEADY STATE	AVERAGE NUMBER	OF 1
	ITEMS WAITING	. 560
	ITEMS IN PROC ITEMS WAITING	EGS .245 .315
AVERAGE FIME	SPENT AT THIS S	TATION PER OPERATION
TOT	AL TIME (MINUTE: PROCESSING WAITING	5) 15.334 6.710 8.623

FRACTION OF TIME	X ITEMS AT STATION	X ITEMS EXCEEDED
X = 0	.7549	·2451
X = 1	.2451	.0000
X = 2	.0350	######

PER ITEM

15,334 6,710 8,624

SUMMARY FOR STATION NUMBER 2 | CAUS

NUMBER OF	SERVER	AVE, ND, OF
Servers	UTILIZATION	Busy servers

1 . 244

STEADY STATE AVERAGE NUMBER OF 1

•

I TEMS	WAITING	557
ITENS	IN PROCESS	244
ITEMS	WAITING	.313

AVERAGE TIME SPENT AT THIS STATION	PER OPERATION	PER ITEN
TOTAL TIME (MINUTES)	15.257	15,257
PROCESSING	6.680	6,680
WAITING	8.577	8,577

.244

FRACTION OF TIME	X ITEMS AT STATION	X ITEMS EXCEEDED
X = 0	.7560	.2440
X = 1	.2440	.0000
X = 2	.0346	*****

SUMMARY FOR STATION NUMBER 3 : CW I

NUMBER OF	SERVER	AVE. NO. OF
Servers	UTILIZATION	BUSY SERVERS

1 .052 .052

STEADY STATE AVERAGE NUMBER OF :

÷

ITEMS	WAITING	.107
ITEMS	IN PROCESS	.052
ITEMS	WAITING	.055

AVERAGE TIME SPENT AT THIS STATION	PER OPERATION	PER ITEM
TOTAL TIME (MINUTES)	1.463	2.926
PROCESSING	.710	1.420
WAITING	.753	1.506

•.

FRACTION d	F TIME	X ITEMS AT STATION	X ITEMS EXCEEDED
X =	0	.7481	.0519
X =	1	.0519	.0000
X =	2	.0016	#####

SUMMARY FOR STATION NUMBER 4 | ACID

NUMBER OF SERVERS	SERVER UTILIZATION	AVE, NO, OF Busy Servers	
1	. 497	. 497	
STEADY STATE	AVERAGE NUMBER O	iF i	
	ITEMS WAITING	1.201	
	ITEMS WAITING	.784	
AVERAGE TIME	SPENT AT THIS ST	ATION PER OPERATION	PER ITEN
та	TAL TIME (MINUTES)	35.061	35.041
	WAITING	13.600 21.461	13.600 21.461

,

FRACTION OF TIME	X ITEMS AT STATION	X ITEM6 EXCEEDED
X = 0	.5031	• 4969
X = 1	.4969	• 0000
X = 2	.1436	1355

1

SUMMARY FOR STATION NUMBER 5 ; HW

· .

.

٨	IUMBER OF SERVERS	SERVER UTILIZATION B	AVE. NO, OF JUSY SERVERS	
	1	.026	.026	
5	STEADY STATE	AVERAGE NUMBER OF	:	
		ITENS WAITING	. 053	
		ITEMS IN PROCESS ITEMS WAITING	.026 .027	
A	VERAGE TIME	SPENT AT THIS STAT	ION PER OPERATION	PER ITEM
	τo	TAL TIME (MINUTES) PROCESSING WAITING	1.462 .720 .742	1,462 ,720 ,742

FRACTION OF TIME	X ITEMS AT STATION	X ITEMS EXCEEDED
X = 0	.9737	.0263
X = 1	.0263	.0000
X = 2	.0004	#####

SUMMARY FOR STATION NUMBER 6 ; PHOS

NUMBER OF SERVERB	SERVER UTILIZATION	AVE. NO. OF BUSY SERVERS
. 1	.229	.229
STEADY STATE	AVERAGE NUMBER	OF 1

ITEMS	WAITING	.519
TTEMS	IN PROCESS	.229
ITEMS	WAITING	.290

AVERAGE	TIME SPENT AT THIS STATION	PER OPERATION	PER ITEM
	TOTAL TIME (MINUTES)	15.276	14.206
	Procedsing	6.740	6.268
	Waiting	8.536	7.938

FRACTION OF TIME	X ITEMS AT STATION	X ITEMS EXCEEDED
X = 0	.7710	.2290
X = 1	.2290	.0000
X = 2	.0305	######

SUMMARY FUR STATION NUMBER 7 : CW II

NUMBER OF SERVER	AVE. ND. OF
SERVERS UTILIZATION	BUSY SERVERS

1 .024 .024

STEADY STATE AVERAGE NUMBER OF 1

ITEMS	WAITING	. 049
ITEMS	IN PROCESS	024
ITENS	WAITING	.025

AVERAGE TIME SPENT AT THIS STATION	PER OPERATION	PER ITEM
TOTAL TIME (MINUTES)	1,440	1.339
PROCESSING	,710	.660
WAITING	,730	.679

FRACTION OF TIME	X ITEMS AT STATION	X ITEMS EXCEEDED
$\begin{array}{rcl} X &= & 0 \\ X &= & 1 \\ X &= & 2 \end{array}$,9759 ,0241 ,0003	.0241 .0000 #####

SUBHARY FOR STATION NUMBER 9 1 SUAP

NUMBER OF SERVERS	SERVER UTILIZATION	AVE. NO. OF Busy servers
1	.217	.217
STEADY STATE	AVERAGE NUMBER	OF I
	ITEMS WAITING	. 488
	ITEMS IN PROC ITEMS WAITING	ESS .217 .272
AVERAGE TIME	SPENT AT THIS S	TATION PER OPERAT

GE	TIME SPENT AT THIS STATION	PER OPERATION	PER ITEM
	TOTAL TIME (MINUTES)	15.023	13.370
	PROCESSING	6.670	5.936
	WAITING	8.353 •	7.434

FRACTION	UF	TIME	X ITEMS AT STATION	X ITEMS EXCEEDED
X =	0		.7031	.2169
X =	1		.2169	.0000
X =	2		.0274	#####

SUMMARY FOR STATION NUMBER 8 : NEUT

NUMBER OF	SERVER	AVE. NO. OF
SERVERS	UTILIZATION	BUSY SERVERS

1 .031 .031

STEADY STATE AVERAGE NUMBER OF 1

ITEMS WAITING ITEMS IN PROCESS ITEMS WAITING	.043 .031 .032	
AVERAGE FIME SPENT AT THIS STATION	PER OPERATION	PER ITEM
TOTAL TIME (MINUTES) Processing Waiting	1,934 ,950 ,984	1.721 .846 .976

FRACTION OF TIM	E X ITEMS AT STATION	X ITEMS EXCEEDED
X = 0	. 9691	. 0309
X = 1	.0309	. 0 0 0 0
X = 2	.0006	****

SUMMARY FOR STATION NUMBER 10 (DRY

•

NUMBER OF Servers	SERVER UT1LI2ATION	AVE. ND, OF Busy servers	
. 1	. 084	. 084	
STEADY STATE	AVERAGE NUMBER	OF :	
	ITEMS WAITING	.176	
	ITEMS IN PROU ITEMS WAITING	.084	
AVERAGE 11hE	SPENT AT THIS S	GTATION PER	R OPERATION
TO	TAL TIME (MINUTE	(S)	4.825
	PROCESSING WAITING		2.300 2.525

.

PER ITEM

4.825 2.300 2.525

FRACTION OF TIM	E X ITEMS AT STATION	X ITEMS EXCEEDED
X = 0	.9160	,0840
X = 1	.0840	.0000
X = 2	.0041	#####

SUMMARY FOR STATION NUMBER 11 1 CRANE

NUMBER OF SERVERS	SERVER A UTILIZATION B	VE. NO. OF USY SERVERS	
1	.070	.070	
STEADY STATE	AVERAGE NUMBER OF		
	ITEMS WAITING ITEMS IN PROCESS ITEMS WAITING	.146 .070 .076	
AVERAGE TIME	SPENT AT THIS STATI	ON PER OPERATION	PER ITE
ТОТ	AL TIME (MINUTES) PROCESSING WAITING	.375 .180 .195	3.986 1.915 2.071

FRACTION OF TIME	X ITEMS AT STATION	X ITENS EXCEEDED
X = 0	.9300	.0700
X = 1	.0700	.0000
X = 2	.028	#####

234

••

١

ITEM

>

5

SENSITIVITY INFORMATION

A ONE MINUTE DECREASE IN	WILL INCREASE THE	
PROCESSING TIME AT STATION	PRODUCTION RATE	
1 HOLD	.136 UNITS/HOUR (6.2235 PERCENT)
2 CAUS	136 UNITS/HOUR (6,2189 PERCENT)
3 CW I	.237 UNITS/HOUR (10.8042 PERCENT)
4 ACID	,160 UNITC/HOUR (7.2934 PERCENT	Ś
5 HW	116 UNITS/HOUR (5.2934 PERCENT	ś
6 PHOS	125 UNITS/HOUR (5.7241 REPORT	Ś
7 CW II	108 UNITS/HOUR (4.9142 PERCENT)	ś
B NEUT	104 UNITS/HOUR (4.7285 PERCENT	'n
9 SOAP	119 UNITS/HOUR (5.4320 PERCENT)	Ś
· 10 DRY	121 UNITS/HOUR (5.5387 PERCENT	Ś
11 CRANE	1.278 UNITS/HOUR (58.2965 PERCENT)	,

A ONE PERCENT DECREASE IN PROCESSIN ATION

ING T	IME	AT	STA
1	HOI	LD	
2	CAL	JS	
3	េស	I	
4	AC:	D	
5	:16		
6	PHC	JS	
7	C₩	II	
3	NEL	JT	
9	SO	AP	
10	DRY	(
11	CRA	ANE	
INUTE	E DE	ECRE	ASE

A ONE MI IN RELATIVE UTILIZATION AT STATION 1 HOLD

2	CAUS
3	CW I
4	ACID
5	ны
6	PHOS
7	CW II
8	NEUT
9	SUAP
10	DRY
11	CRANE

A DECREASE OF	.01 IN THE
PROPORTION OF	PRODUCT TYPE
LUBE	
PHO	
TRI	

	1./01	UNIISZHOUR	(77.6018	PERCENT)
	1.235	UNITS/HOUR	(56.3218	PERCENT)
	1.436	IMITS/HOUR	(65.4884	PERCENT)
	1.232	UNITS/HOUR	(56.2232	PERCENT)
	1.239	UNITS/HOUR	(56.5292	PERCENT)
	1.424	UNITS/HOUR	(64,9401	PERCENT)
	1.292	UNITS/HOUR	(58,9323	PERCENT)
	1.278	UNITS/HOUR	(53.2965	PERCENT)
ТНЕ Т ТҮРЕ	ພ: .065 .055 .045	ILL INCREASE FRODUCTION ITEMS/HOUR ITEMS/HOUR ITEMS/HOUR	E THE N RATE BY (2.9771 (2.5195 (2.0671	PERCENT PERCENT PERCENT)))

WILL INCREASE THE

.009 UNITS/HOUR (.4176 PERCENT) .009 UNITS/HOUR (.4154 PERCENT) .002 UNITS/HOUR (.0767 PERCENT)

.003 UNITS/HOUR (.1274 PERCENT)

WILL INCREASE THE PRODUCTION RATE BY 1.452 UNITS/HOUR (56.2184 PERCENT) 1.450 UNITS/HOUR (66.1688 PERCENT) 1.260 UNITS/HOUR (57.4784 PERCENT) 1.701 UNITS/HOUR (77.6018 PERCENT)

.9919 PERCENT)

.3858 PERCENT) .0349 PERCENT

.0449 PERCENT) .3623 PERCENT)

.1049 PERCENT)

.0381 PERCENT

PRODUCTION RATE

.022 UNITS/HOUR (.001 UNITS/HOUR (.008 UNITS/HOUR (.001 UNITS/HOUR (

.001 UNITS/HOUR (.008 UNITS/HOUR (

.002 UNITS/HOUR (

A DECREASE OF	.01 IN THE	WILL INCREASE THE
PROPORTION OF	PRODUCT TYPE	VALUE OF PRODUCTION PLAN BY
LUBE		.043 ITEMS/HOUR (1.9771 PERCENT)
PHO		.033 ITEMS/HOUR (1.5195 PERCENT)
TRI	and a second	.023 ITEMS/HOUR (1.0671 PERCENT)

VITA \mathcal{L}

John Russell Lewis

Candidate for the Degree of

Master of Science

Thesis: THE USE OF SIMULATION AND CAN-Q TO ANALYZE THE CLEANING AND LUBRICATING PROCESSES OF COLD DRAWN TUBING

Major Field: Industrial Engineering

Biographical:

- Personal Data: Born in Sioux City, Iowa, August 11, 1959, the son of Thomas M. and Carolyn C. Lewis.
- Education: Graduated from West DePere High School, DePere, Wisconsin, in May, 1977; received Bachelor of Science Degree in Industrial Engineering from Oklahoma State University in December, 1983; completed requirements for the Master of Science Degree at Oklahoma State University in May 1985.
- Professional Experience: Teaching assistant, Department of Industrial Engineering, Oklahoma State University, January 1984 to May, 1984; consulting industrial engineer, Southwest Tube Manufacturing, Sand Springs, Oklahoma, June, 1981 to May, 1984.